

iCubFwdKinModel::readPose

```
graph LR; A[iCubFwdKinModel::readPose] --> B[iCubFwdKinModel::readRootToEE]; B --> C[iCubFwdKinModel::readTorso];
```

The diagram illustrates a sequence of three method calls in a forward kinematics model. It consists of three rectangular boxes arranged horizontally. The first box, on the left, is shaded gray and contains the text 'iCubFwdKinModel::readPose'. A blue arrow points from the right side of this box to the left side of the second box. The second box is white with a black border and contains the text 'iCubFwdKinModel::readRootToEE'. Another blue arrow points from the right side of the second box to the left side of the third box. The third box is also white with a black border and contains the text 'iCubFwdKinModel::readTorso'.

iCubFwdKinModel::readRootToEE

iCubFwdKinModel::readTorso