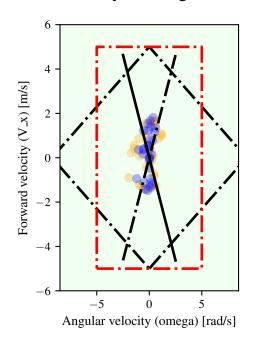
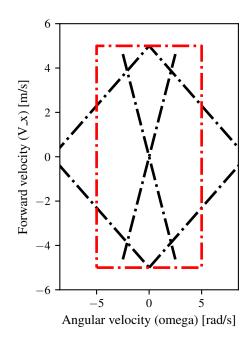
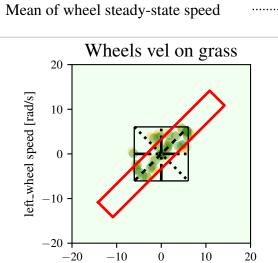
## All roboticist with a maximum linear sampling speed of 2.0 m/s Cmd vs steady-state results for all\_types\_of\_terrain

Body vel on grass



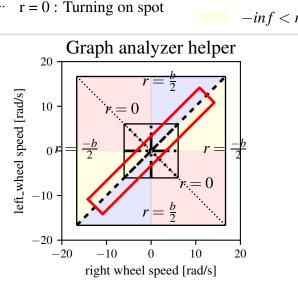




right wheel speed [rad/s]

Mean of body steady-state speed

Command



vehicle limits

 $r = \inf$ : straight line r = 0: Turning on spot