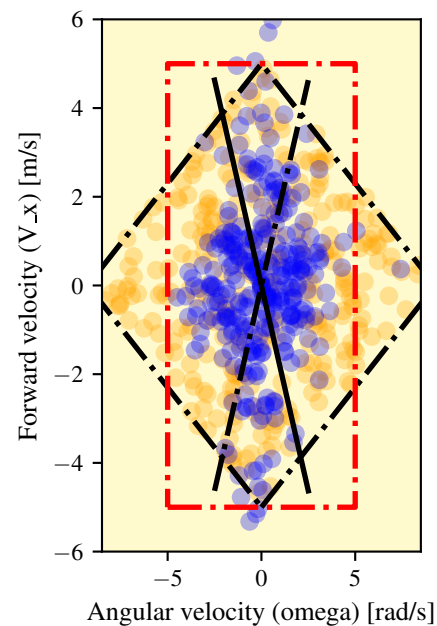
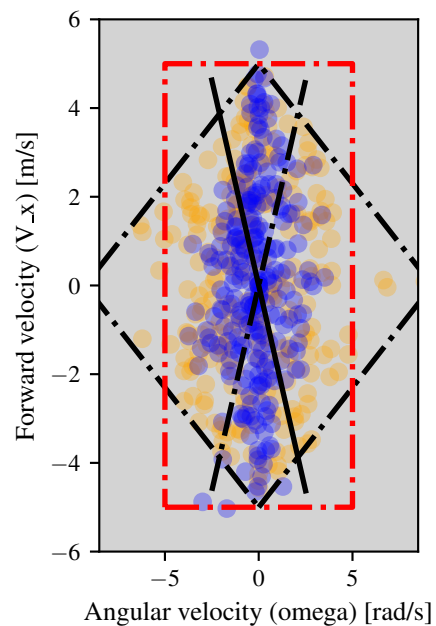


Robotist nicolassamson with a maximum linear sampling speed of 5.0 m/s
Cmd vs steady-state results for all_types_of_terrain

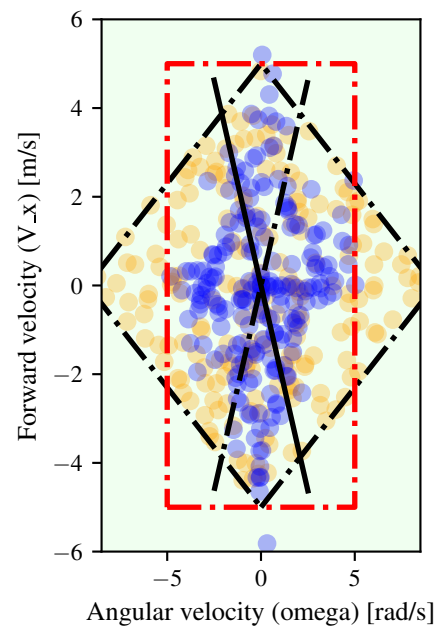
Body vel on sand



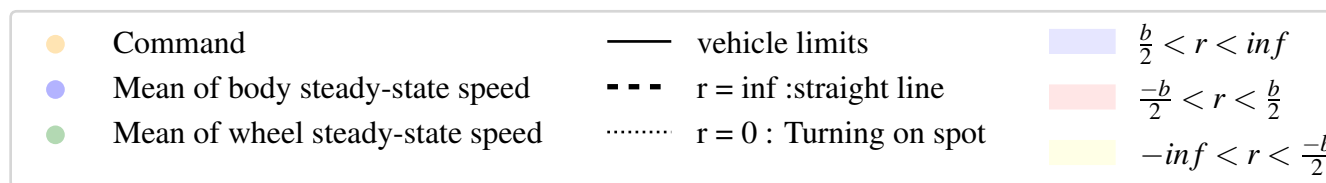
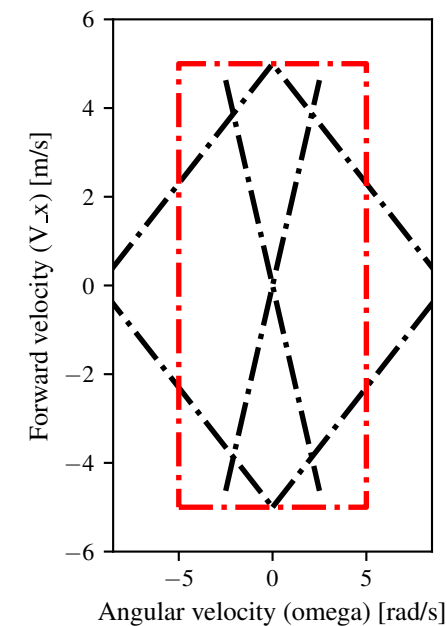
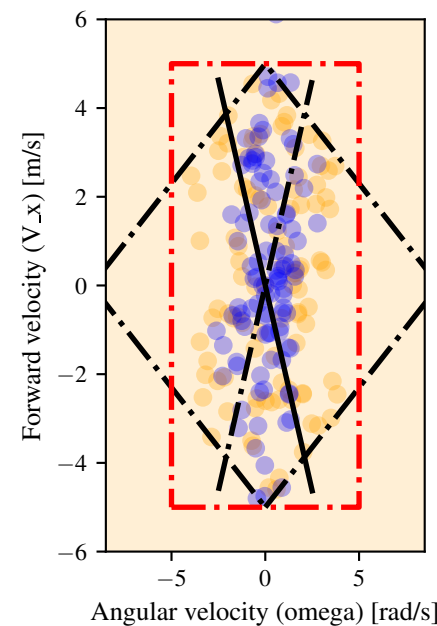
Body vel on asphalt



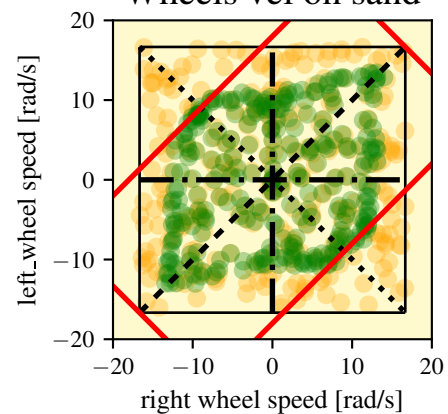
Body vel on grass



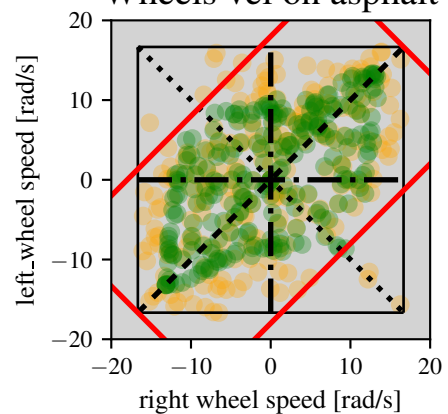
Body vel on gravel



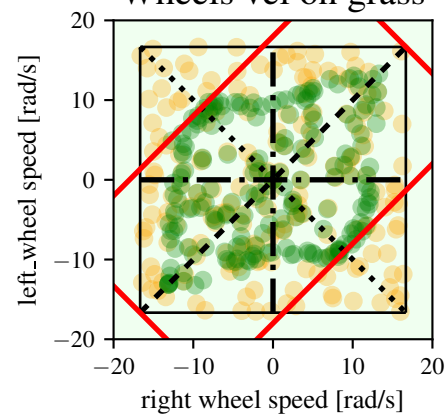
Wheels vel on sand



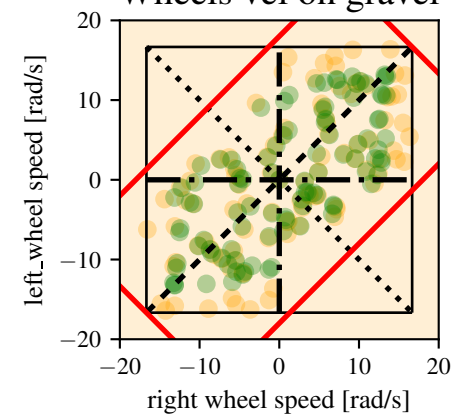
Wheels vel on asphalt



Wheels vel on grass



Wheels vel on gravel



Graph analyzer helper

