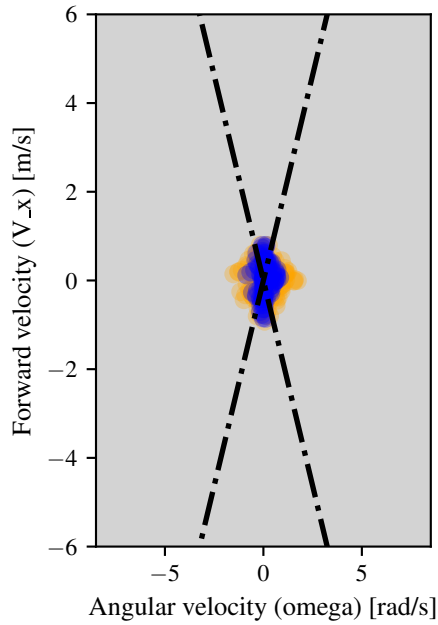
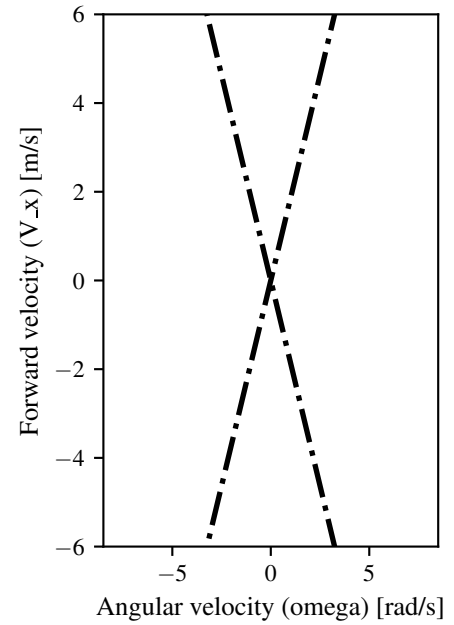
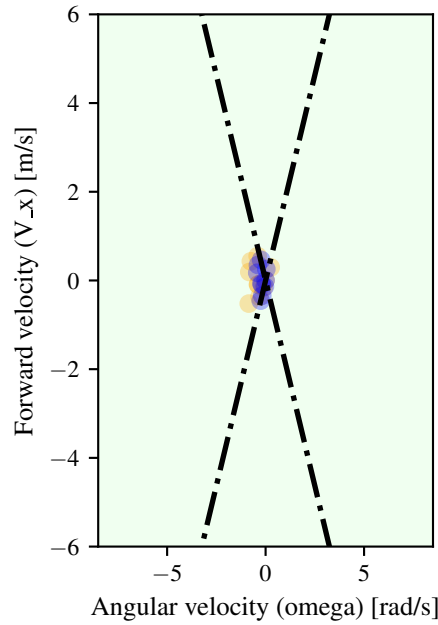


All roboticist with a maximum linear sampling speed of 1.0 m/s
Cmd vs steady-state results for all_types_of_terrain

Body vel on asphalt



Body vel on grass



● Command

● Mean of body steady-state speed

● Mean of wheel steady-state speed

— vehicle limits

- - - r = inf :straight line

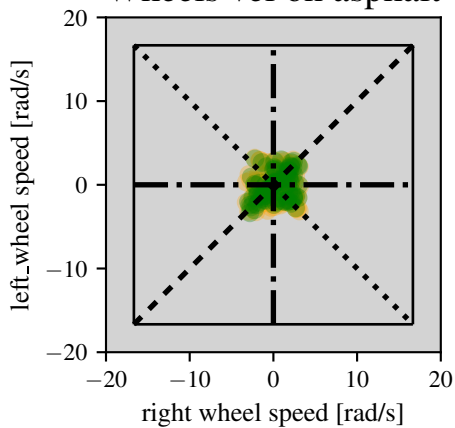
..... r = 0 : Turning on spot

$\frac{b}{2} < r < \inf$

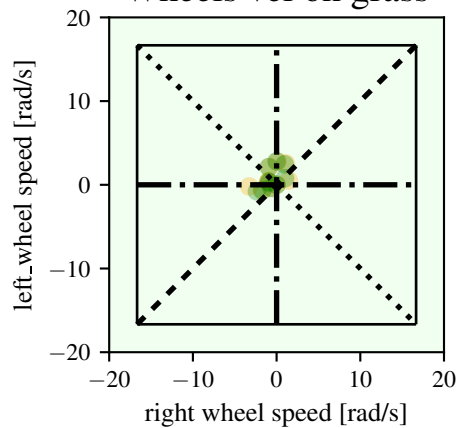
$-\frac{b}{2} < r < \frac{b}{2}$

$-\inf < r < -\frac{b}{2}$

Wheels vel on asphalt



Wheels vel on grass



Graph analyzer helper

