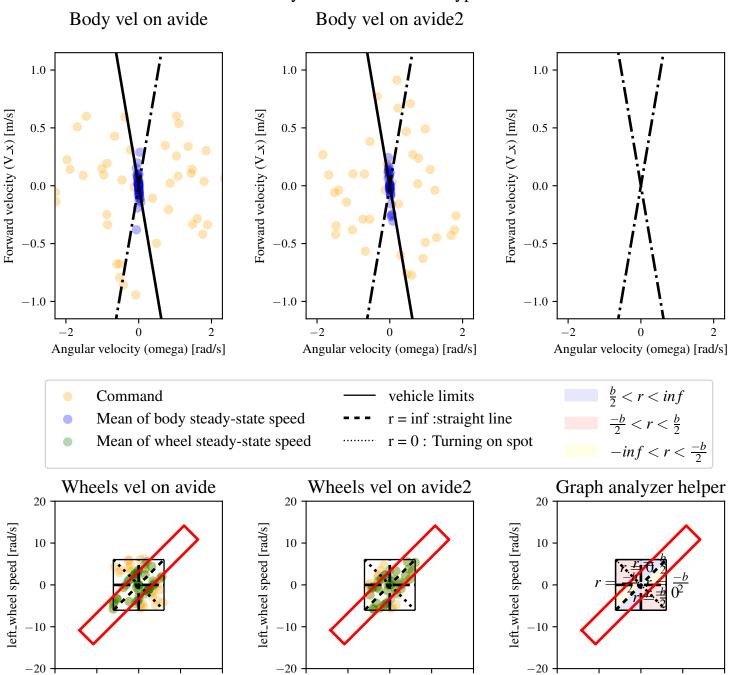
Roboticist nicolassamson with the robot husky m/s Cmd vs steady-state results for all_types_of_terrain



-20

-10

0

right wheel speed [rad/s]

10

20

-20

-10

0

right wheel speed [rad/s]

10

20

-20

-10

0

right wheel speed [rad/s]

10

20