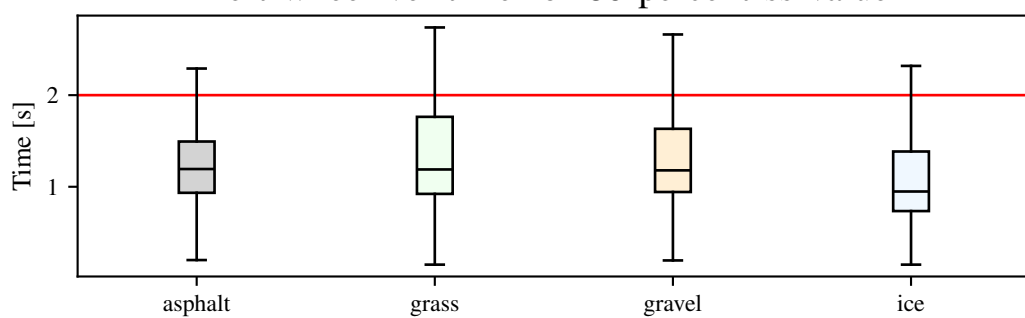
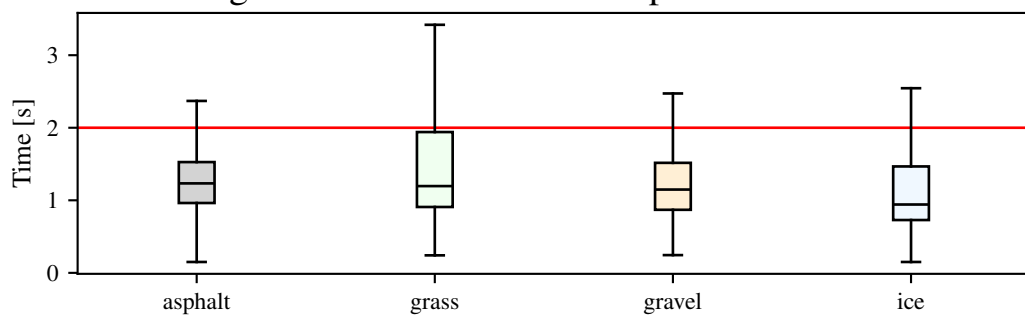


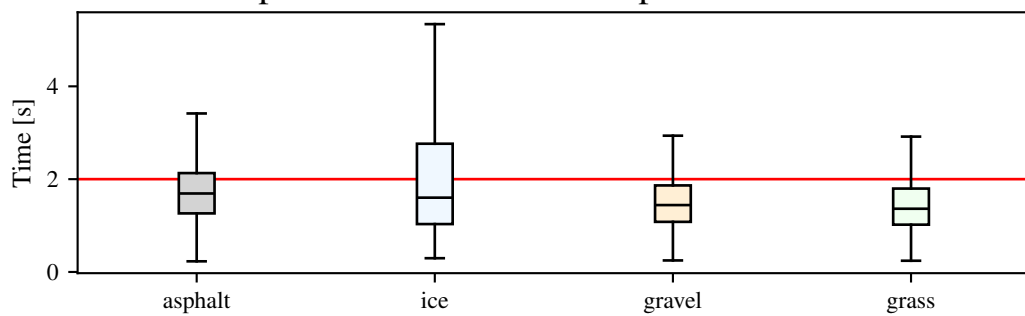
left\_wheel\_vel\_time\_for\_86\_percent\_ss\_value



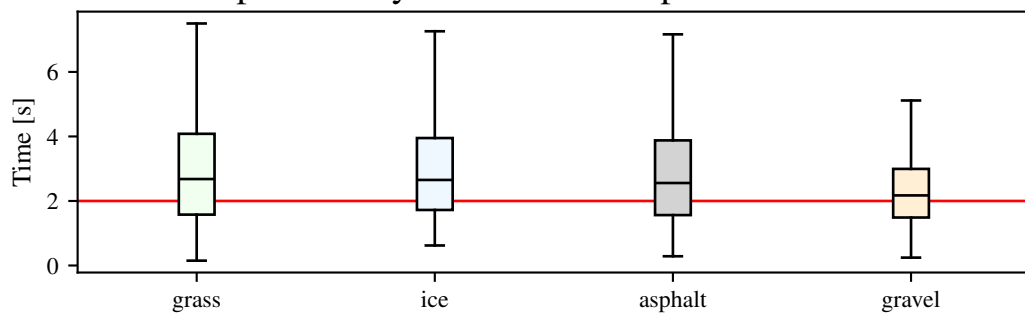
right\_wheel\_vel\_time\_for\_86\_percent\_ss\_value



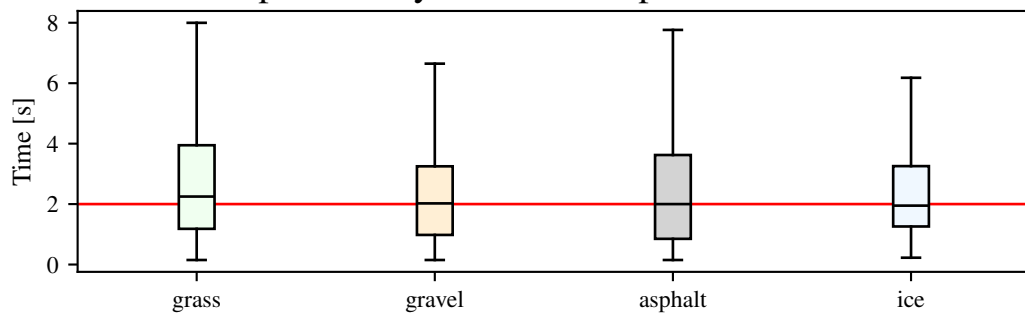
step\_frame\_vx\_time\_for\_86\_percent\_ss\_value



step\_frame\_vyaw\_time\_for\_86\_percent\_ss\_value



step\_frame\_vy\_time\_for\_86\_percent\_ss\_value



diff\_body\_wheel\_time\_for\_86\_percent\_ss\_value

