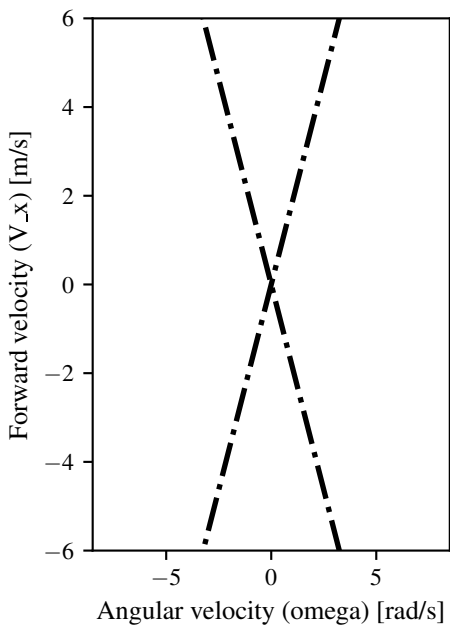
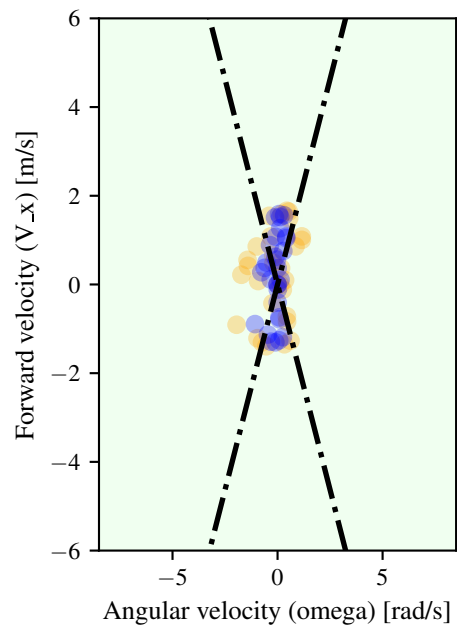


Robotist nicolassamson with a maximum linear sampling speed of 2.0 m/s  
Cmd vs steady-state results for all\_types\_of\_terrain

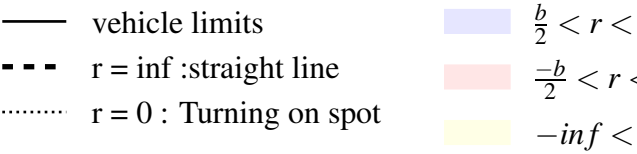
Body vel on grass



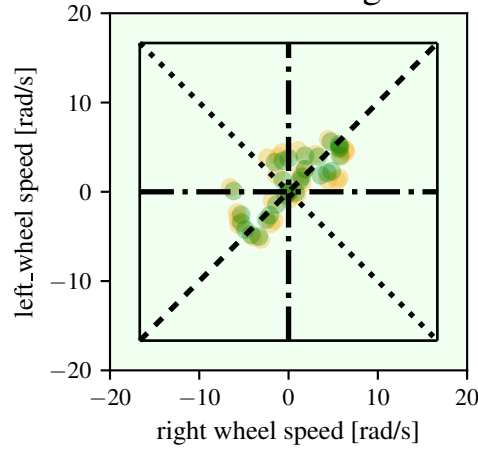
Command

Mean of body steady-state speed

Mean of wheel steady-state speed



Wheels vel on grass



Graph analyzer helper

