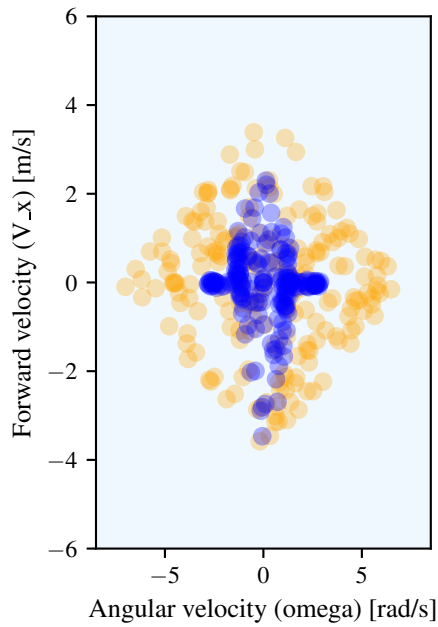
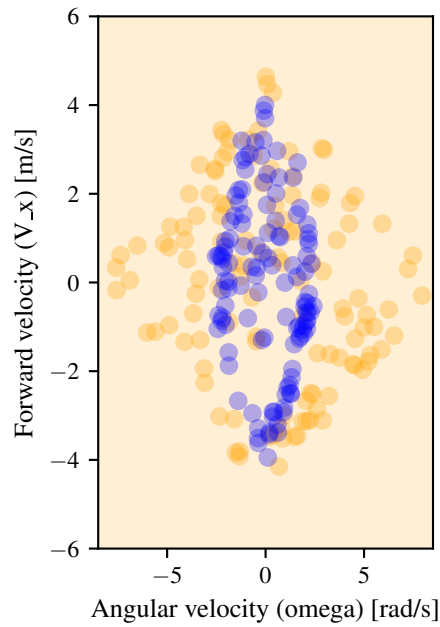


Robotist dominicbaril with a maximum linear sampling speed of 5.0 m/s  
Cmd vs steady-state results for all\_types\_of\_terrain

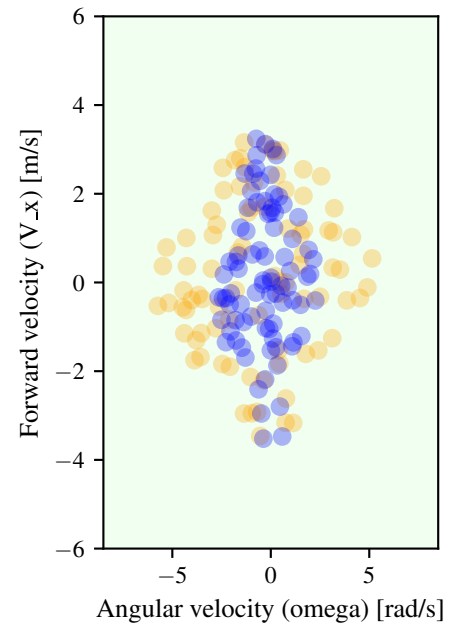
Body vel on ice



Body vel on gravel



Body vel on grass

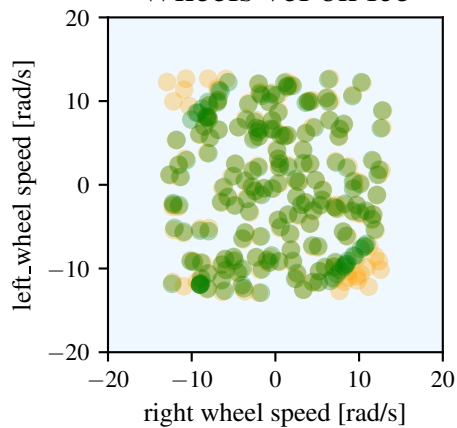


Command

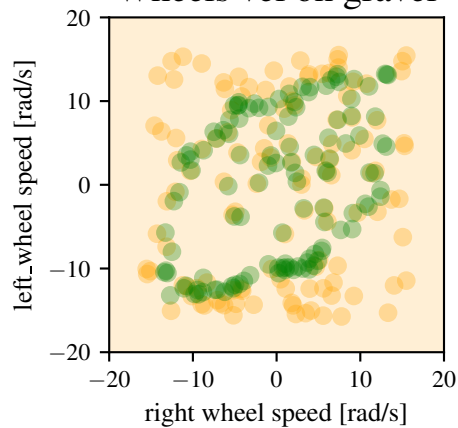
Mean of body steady-state speed

Mean of wheel steady-state speed

Wheels vel on ice



Wheels vel on gravel



Wheels vel on grass

