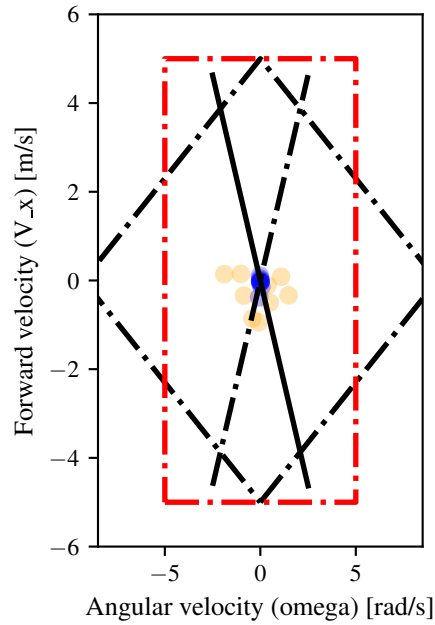
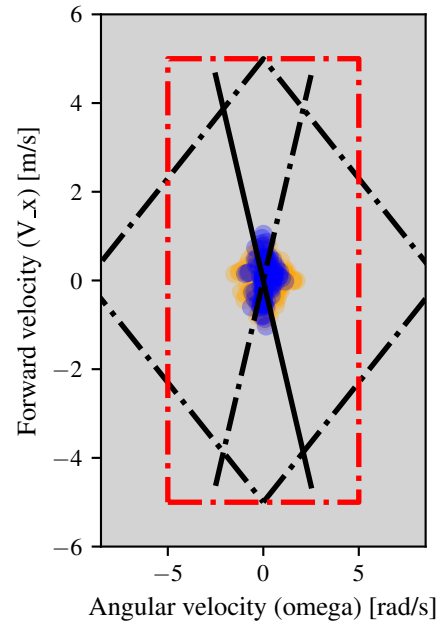


All roboticist with a maximum linear sampling speed of 1.0 m/s  
Cmd vs steady-state results for all\_types\_of\_terrain

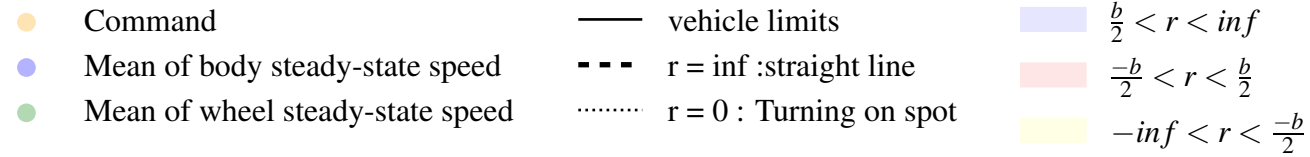
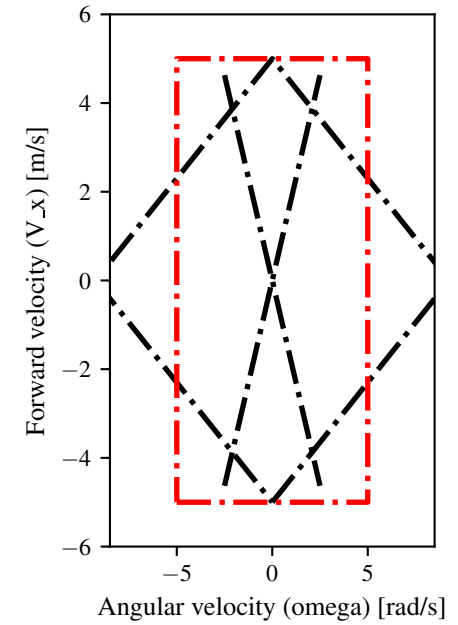
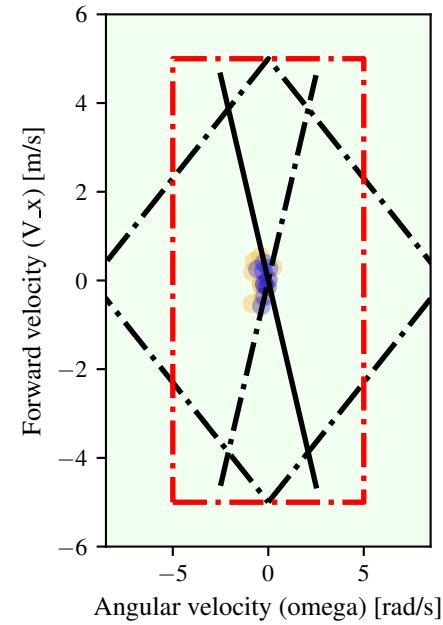
Body vel on avide



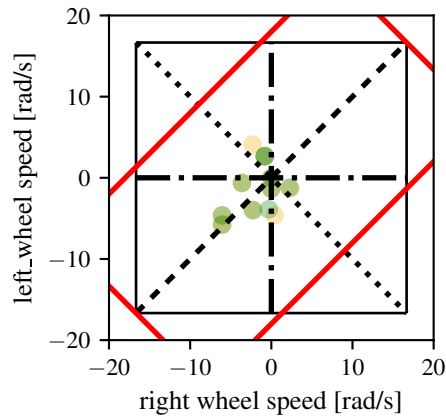
Body vel on asphalt



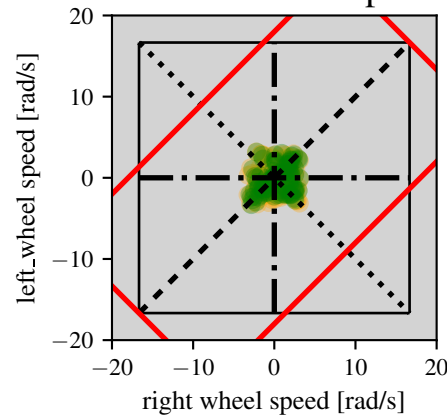
Body vel on grass



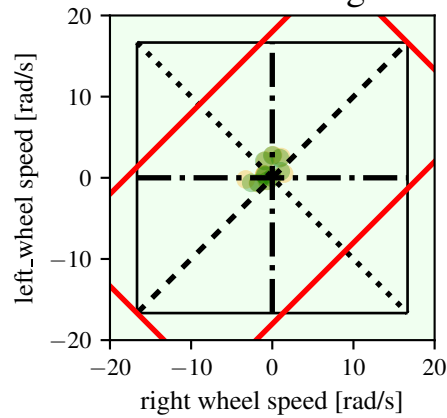
Wheels vel on avide



Wheels vel on asphalt



Wheels vel on grass



Graph analyzer helper

