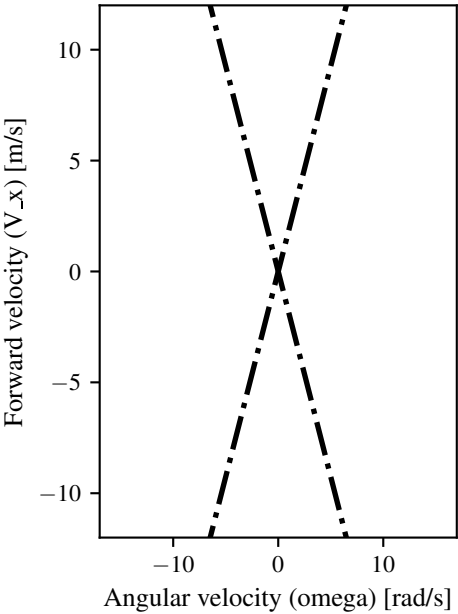
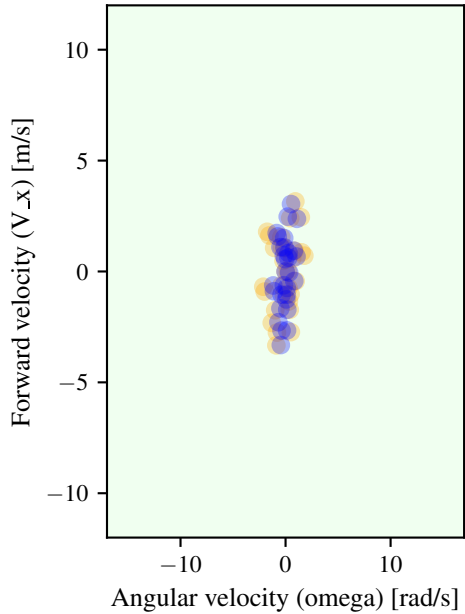


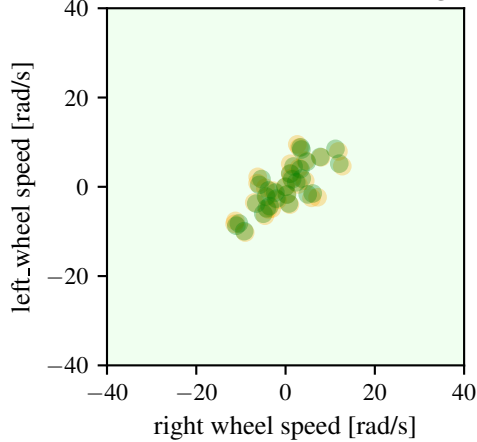
All roboticist with a maximum linear sampling speed of 2.0 m/s
Cmd vs steady-state results for all_types_of_terrain

Body vel on grass



Command	— vehicle limits	$\frac{b}{2} < r < \frac{b}{2}$
Mean of body steady-state speed	- - - $r = \inf$:straight line	$-\frac{b}{2} < r < \frac{b}{2}$
Mean of wheel steady-state speed $r = 0$: Turning on spot	$-\inf < r < \inf$

Centered Wheels vel on grass



Graph analyzer helper

