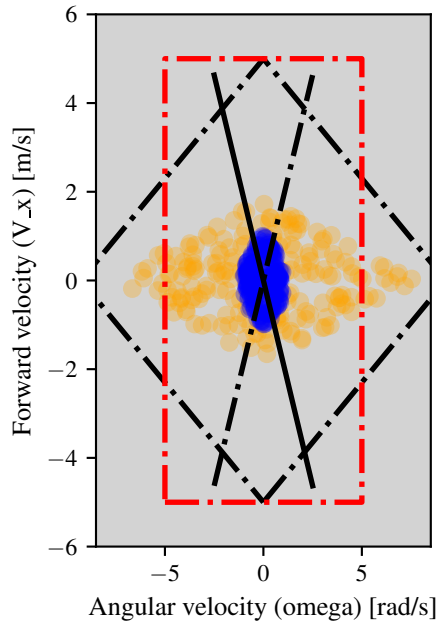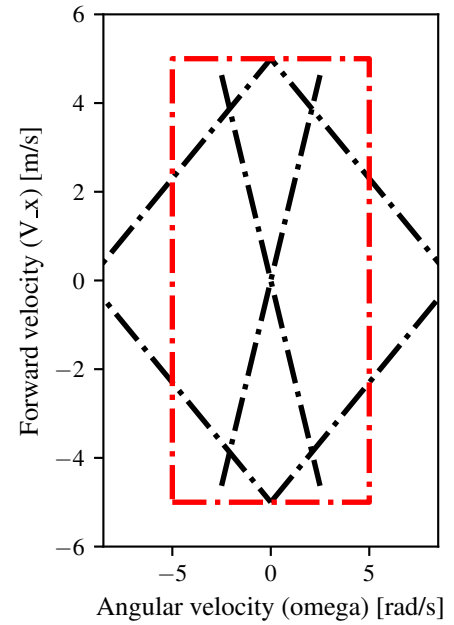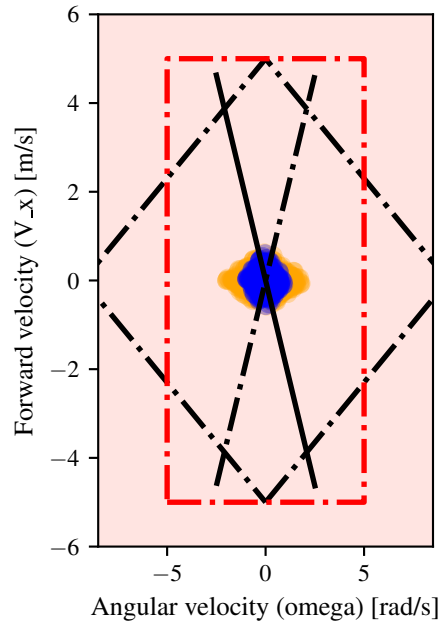All roboticist with a maximum linear sampling speed of 1.5 m/s
Cmd vs steady-state results for all_types_of_terrain

Body vel on boreal

Body vel on tile
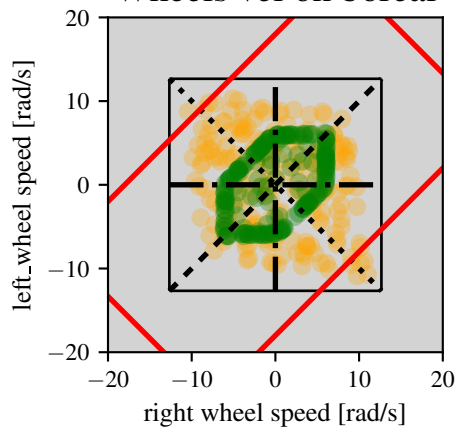
Wheels vel on boreal

Wheels vel on tile

Graph analyzer helper
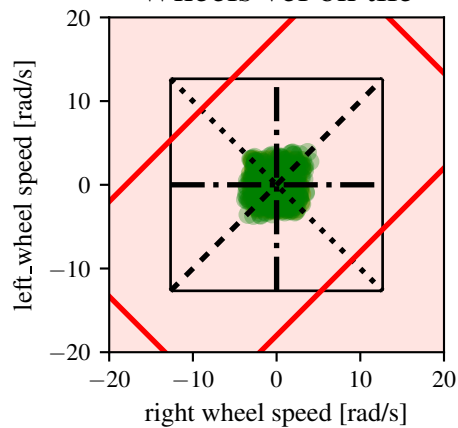
Command
Mean of body steady-state speed
Mean of wheel steady-state speed

vehicle limits
r = inf :straight line
r = 0 : Turning on spot

$\frac{b}{2} < r < inf$
$\frac{-b}{2} < r < \frac{b}{2}$
$-inf < r < \frac{-b}{2}$