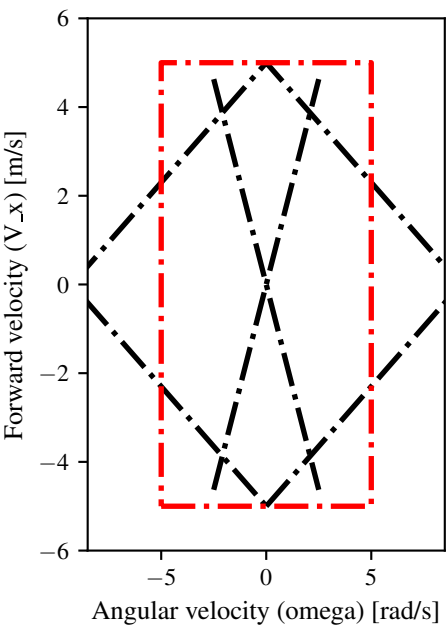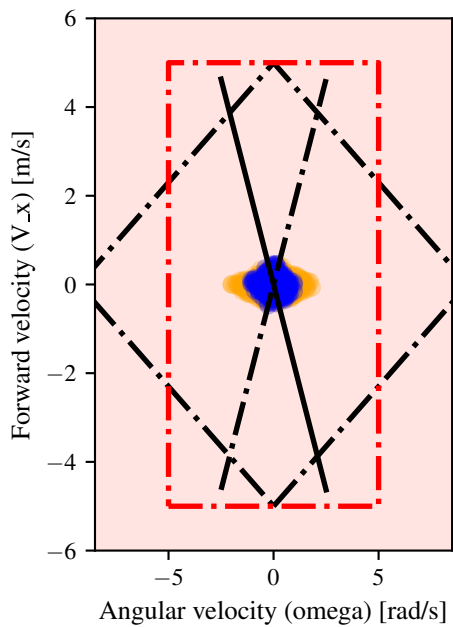# All roboticist with a maximum linear sampling speed of 1.5 m/s
Cmd vs steady-state results for all_types_of_terrain

Body vel on tile

Command
Mean of body steady-state speed
Mean of wheel steady-state speed
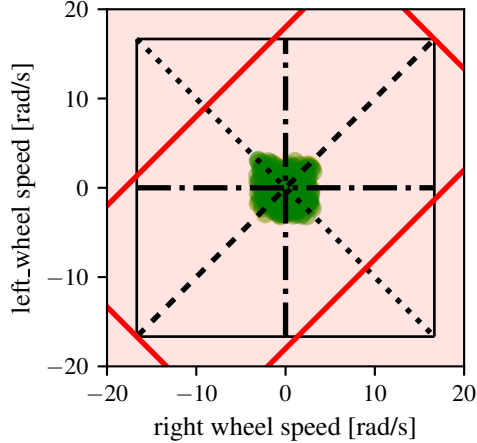
—— vehicle limits
- - - r = inf :straight line
········ r = 0 : Turning on spot

$\frac{b}{2} < r < i$
$\frac{-b}{2} < r <$
$-inf < r$

Wheels vel on tile

Graph analyzer helper