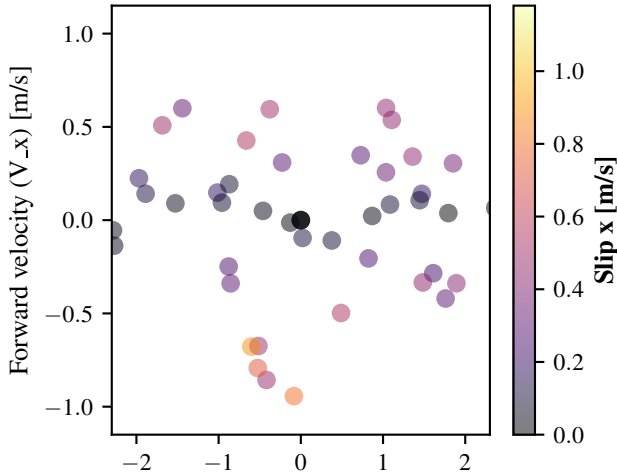


Robotist nicolassamson with the robot husky m/s  
Absolute Steady-state slip (x,y,yaw) for all\_types\_of\_terrain

Steady-state slip for avide



Steady-state slip for avide2

