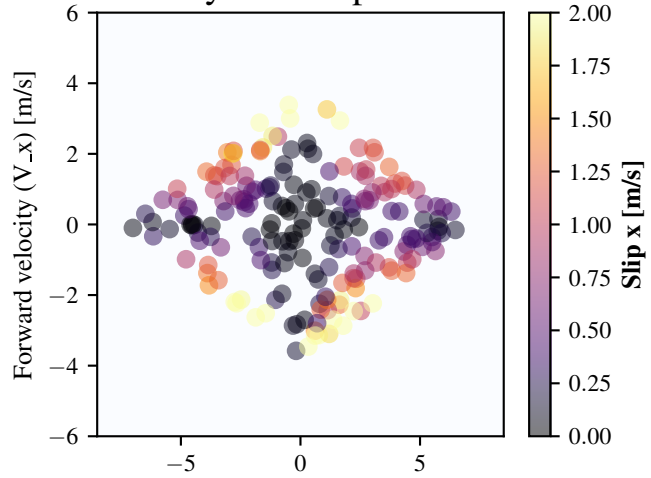
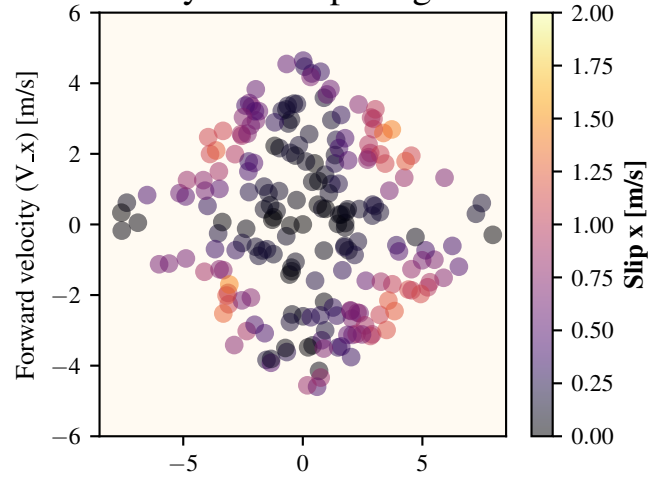


All roboticist with a maximum linear sampling speed of 5.0 m/s  
Absolute Steady-state slip (x,y,yaw) for all\_types\_of\_terrain

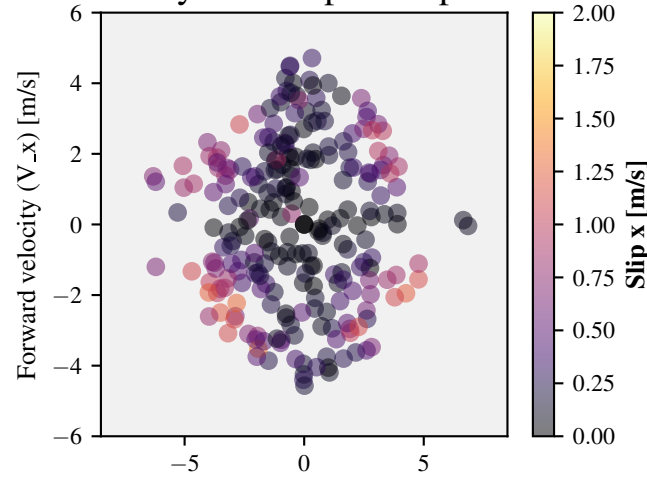
Steady-state slip for ice



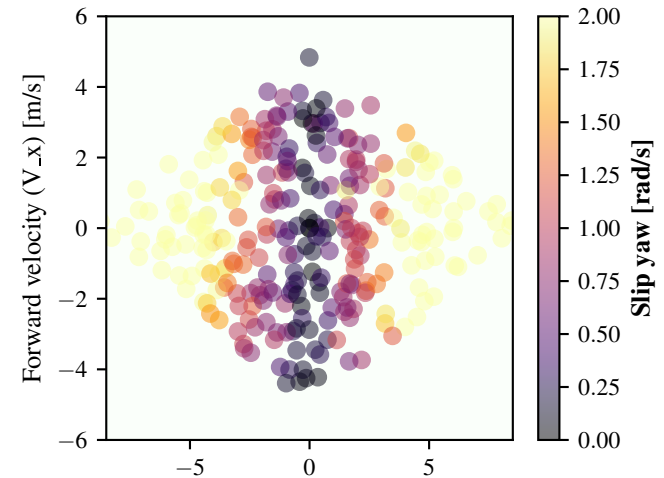
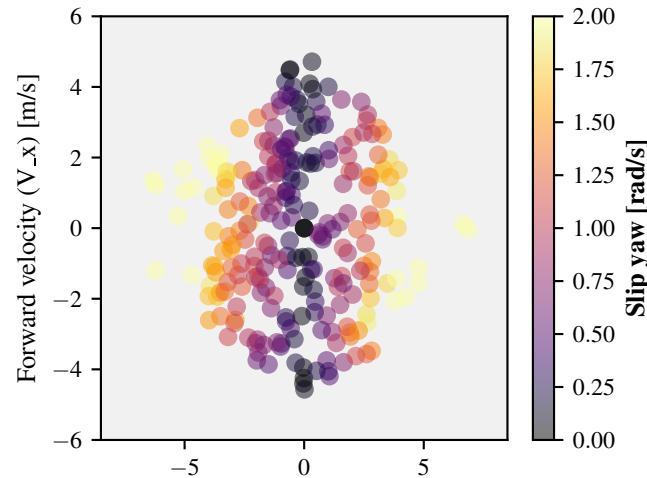
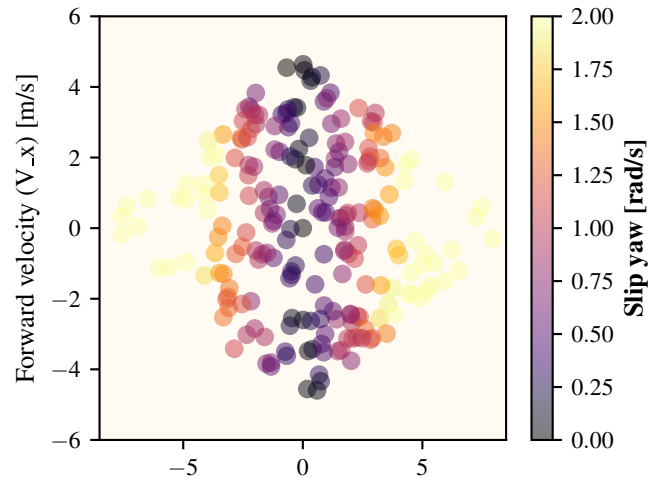
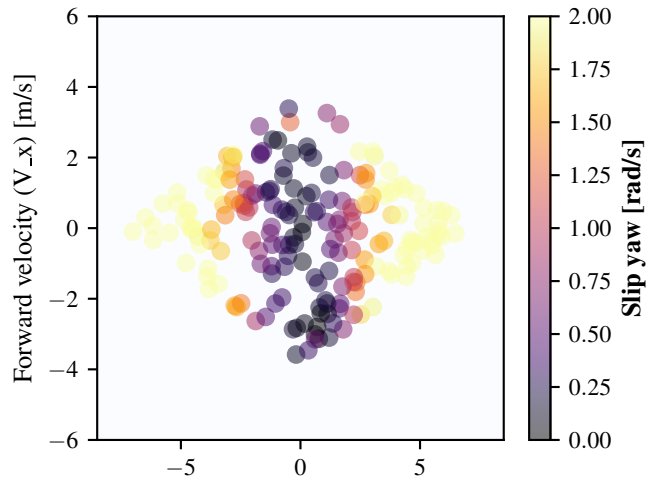
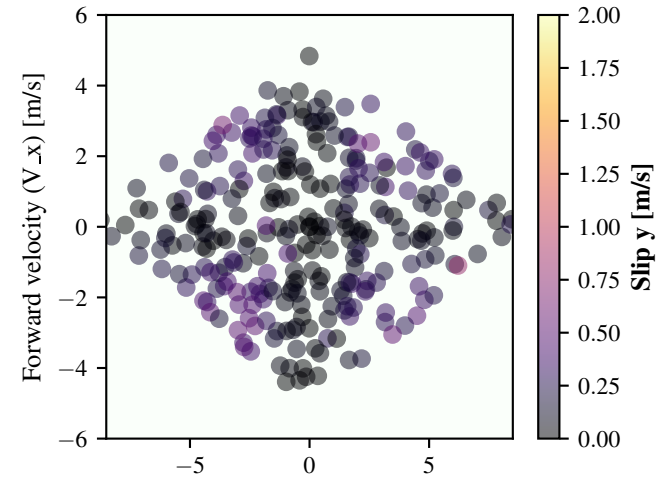
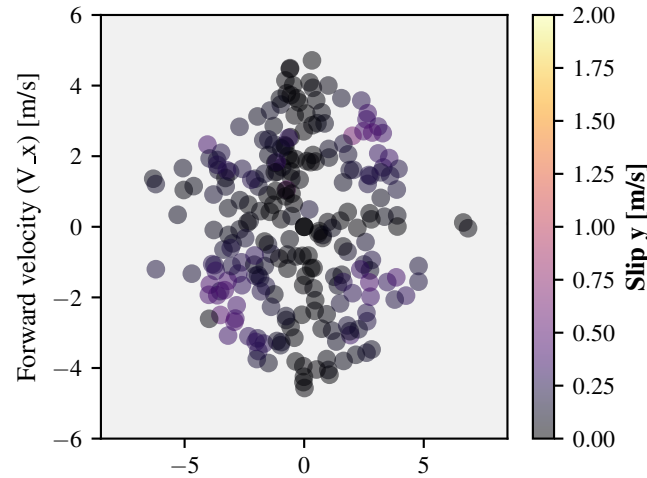
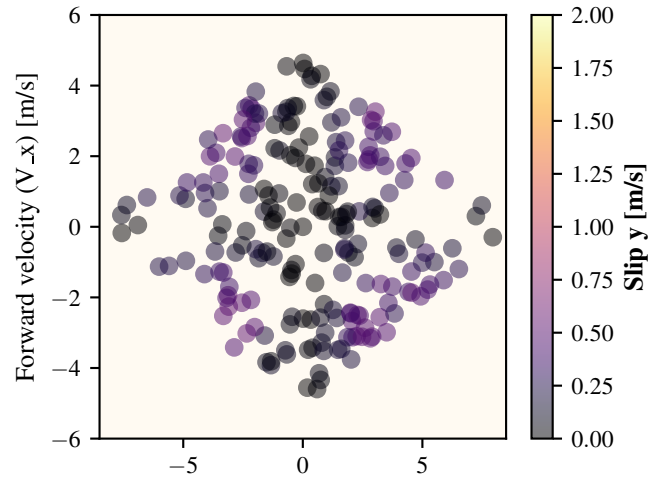
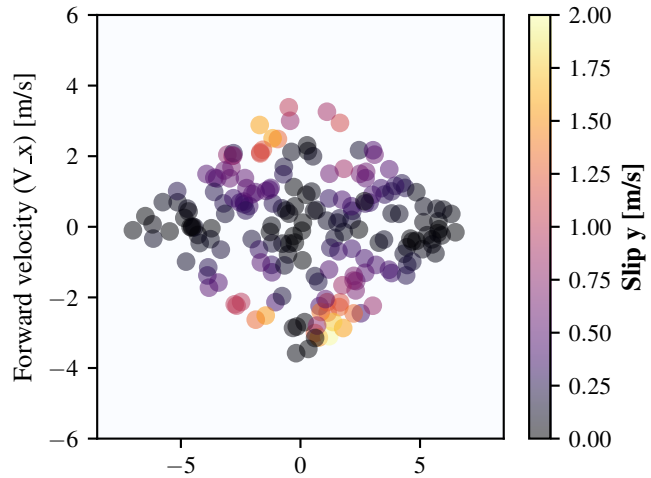
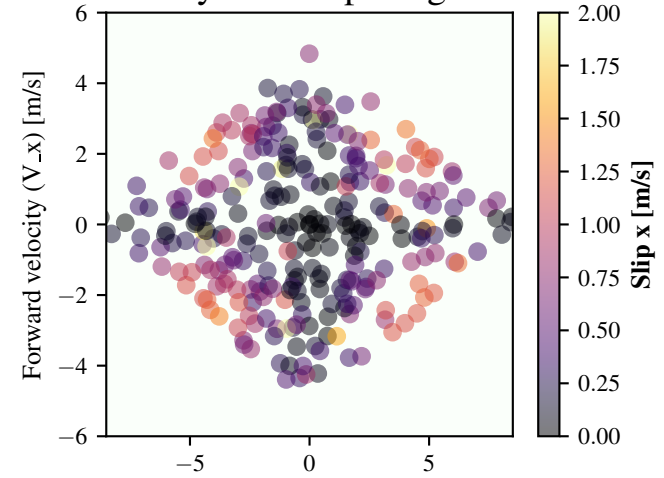
Steady-state slip for gravel



Steady-state slip for asphalt



Steady-state slip for grass



Angular velocity ( $\omega$ ) [rad/s]

Angular velocity ( $\omega$ ) [rad/s]

Angular velocity ( $\omega$ ) [rad/s]

Angular velocity ( $\omega$ ) [rad/s]