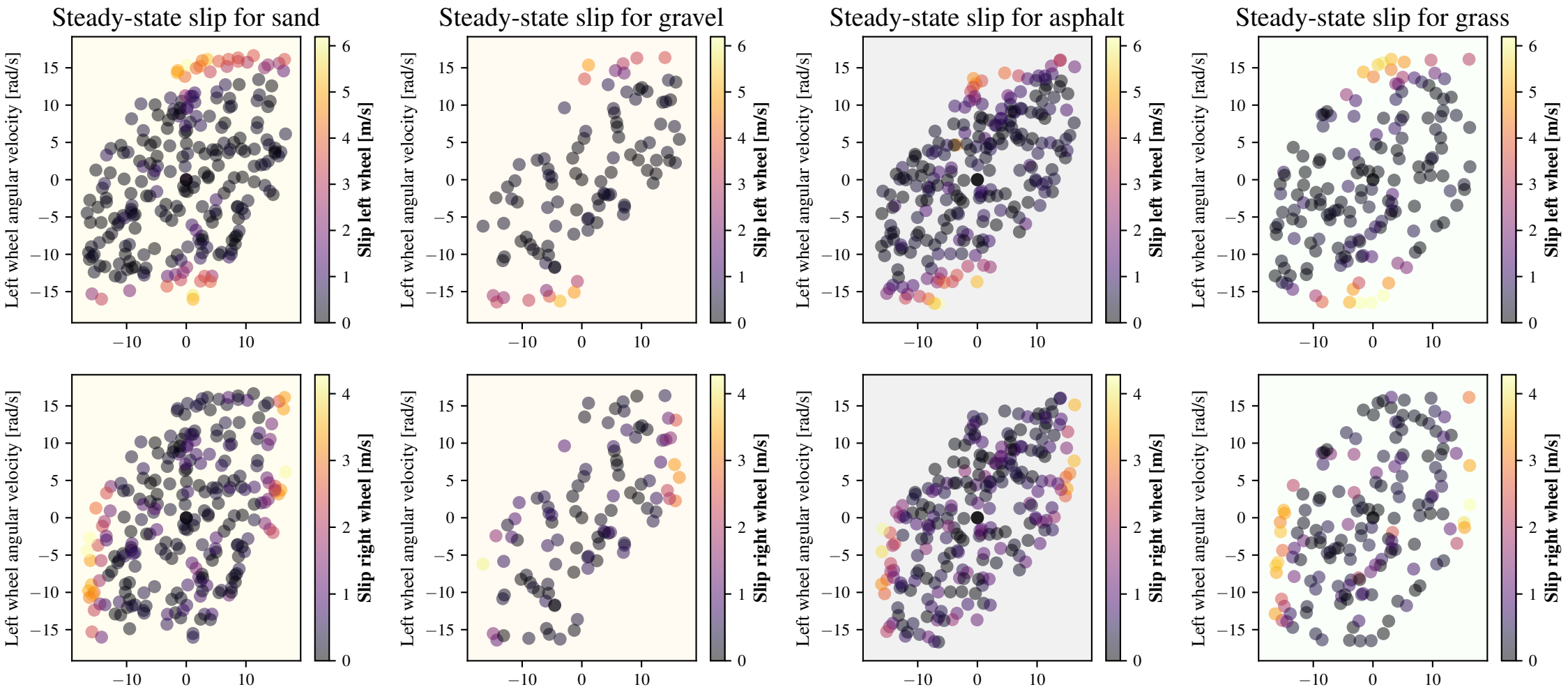Roboticist nicolassamson with the robot warthog m/s
Absolute Steady-state slip (x,y,yaw) for all_types_of_terrain