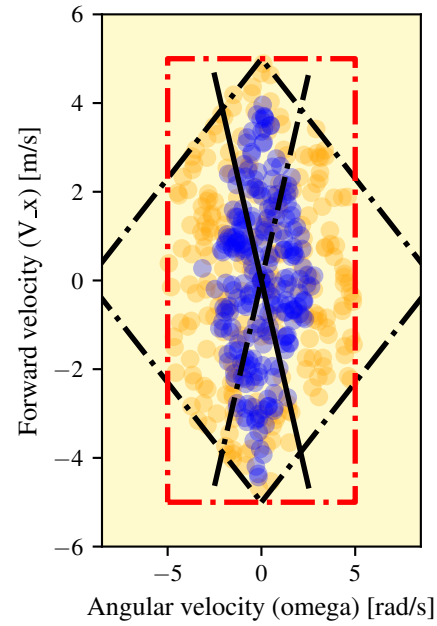
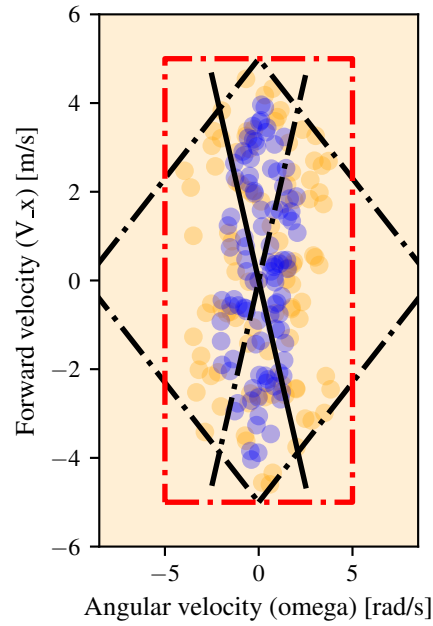


Robotist nicolassamson with a maximum linear sampling speed of 5.0 m/s
 Cmd vs steady-state results for all_types_of_terrain

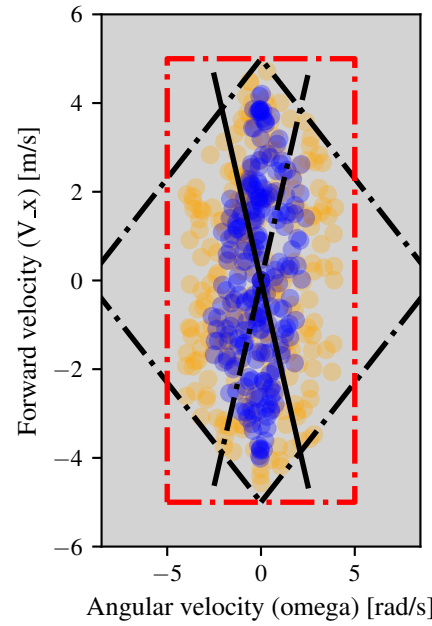
Body vel on sand



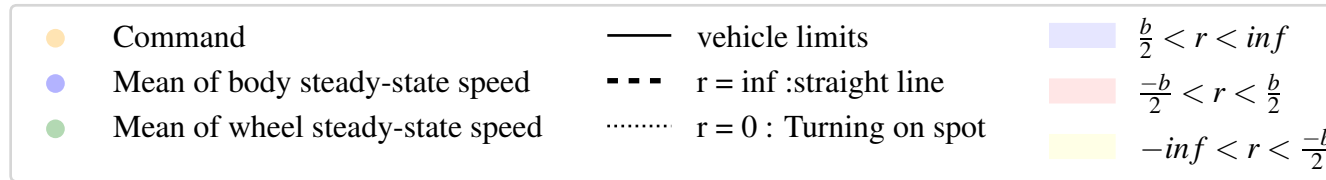
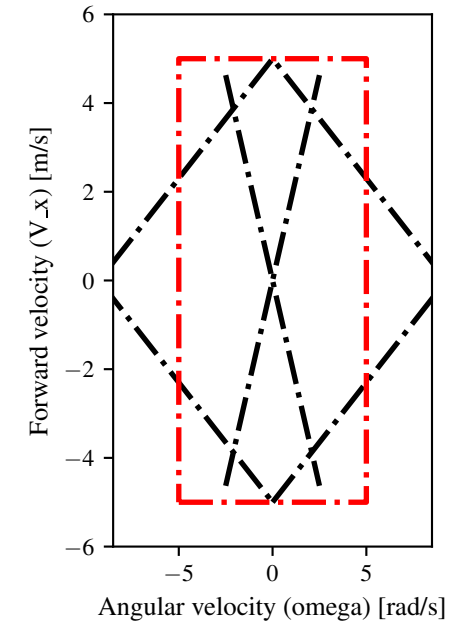
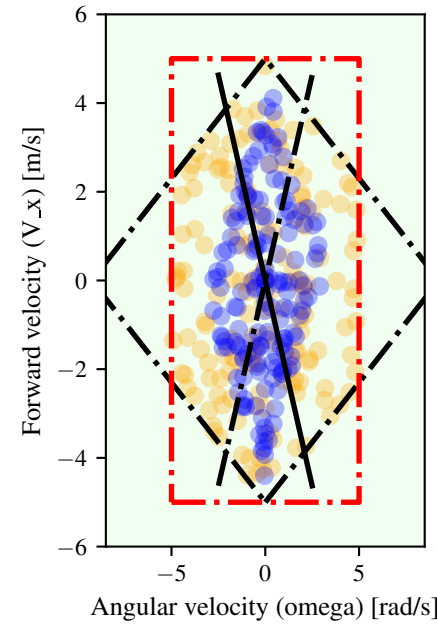
Body vel on gravel



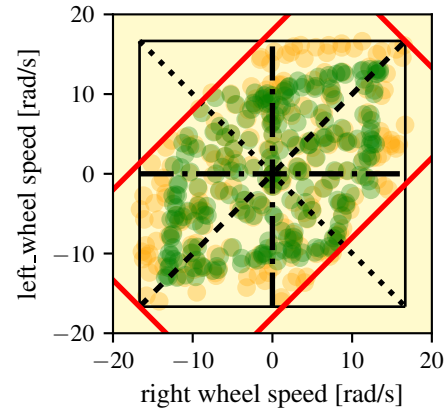
Body vel on asphalt



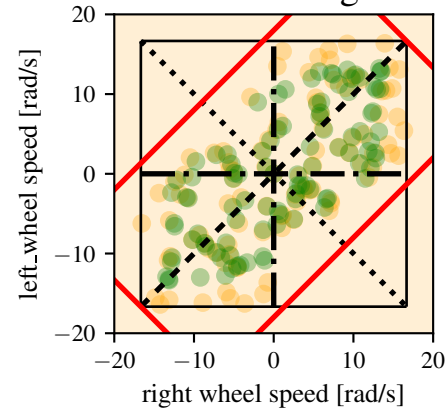
Body vel on grass



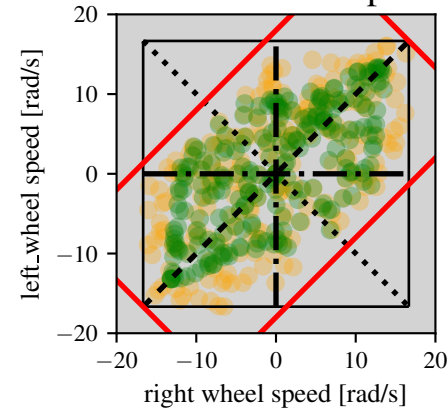
Wheels vel on sand



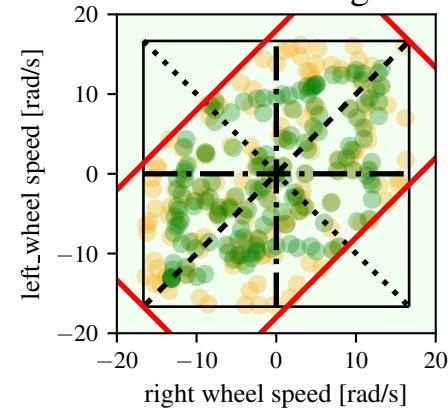
Wheels vel on gravel



Wheels vel on asphalt



Wheels vel on grass



Graph analyzer helper

