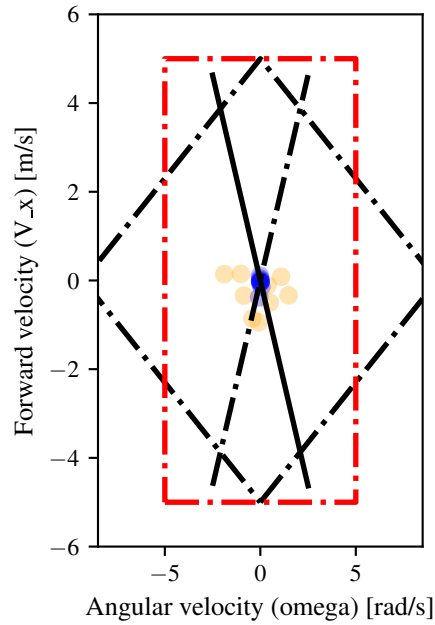
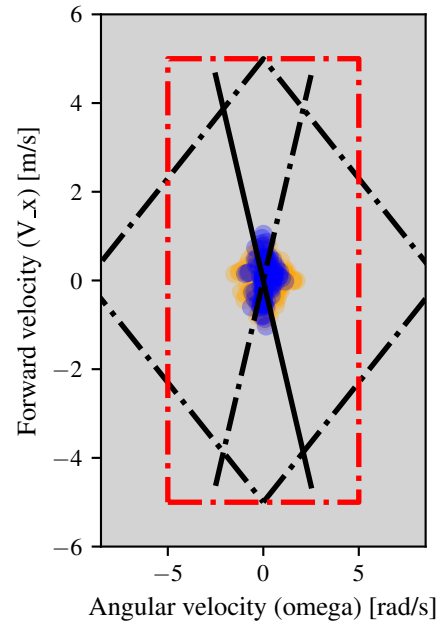


Robotist nicolassamson with a maximum linear sampling speed of 1.0 m/s
Cmd vs steady-state results for all_types_of_terrain

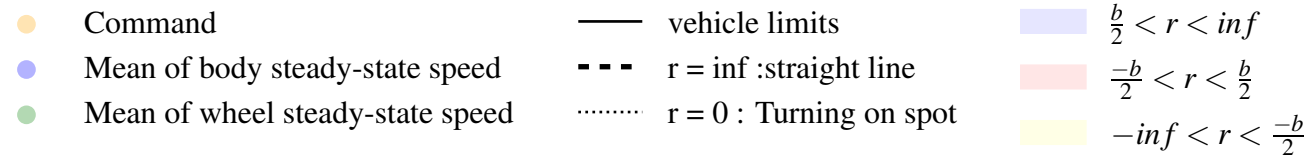
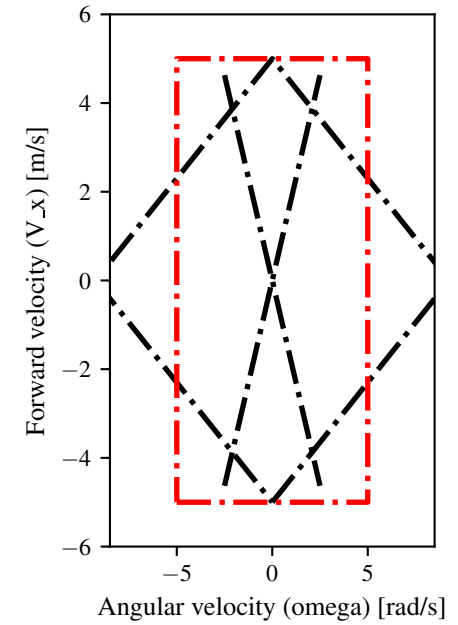
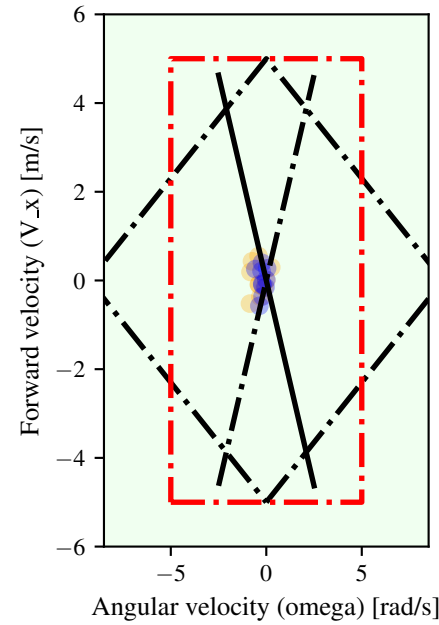
Body vel on avide



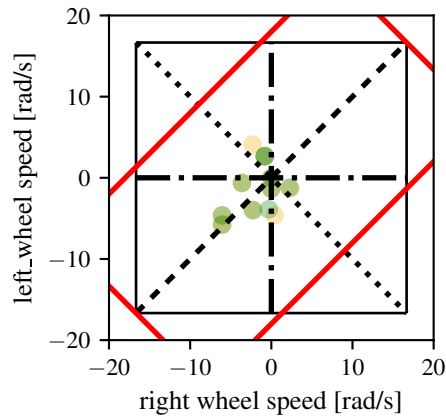
Body vel on asphalt



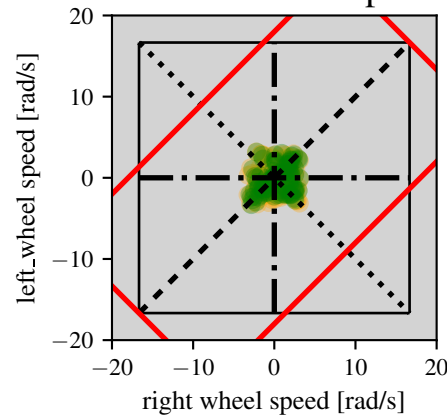
Body vel on grass



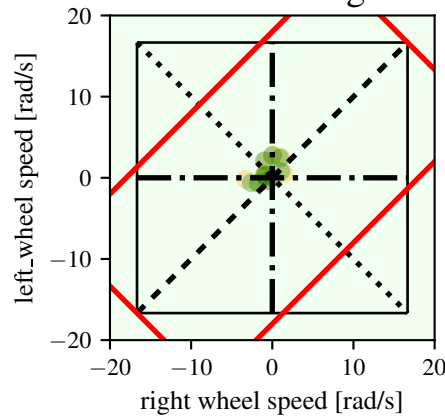
Wheels vel on avide



Wheels vel on asphalt



Wheels vel on grass



Graph analyzer helper

