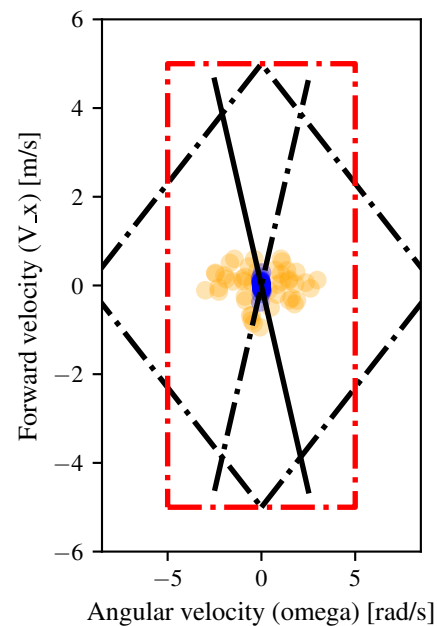
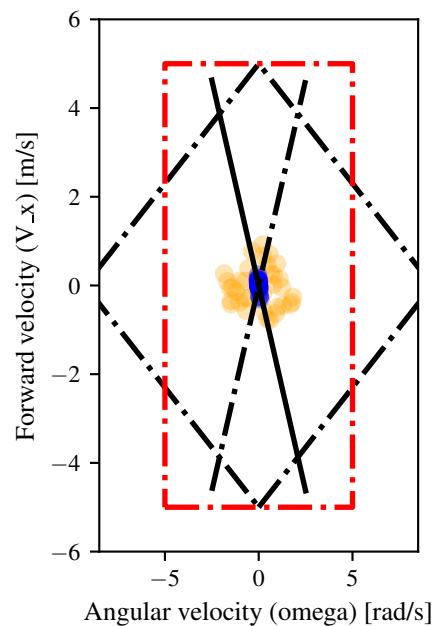


Robotist nicolassamson with a maximum linear sampling speed of 1.0 m/s  
 Cmd vs steady-state results for all\_types\_of\_terrain

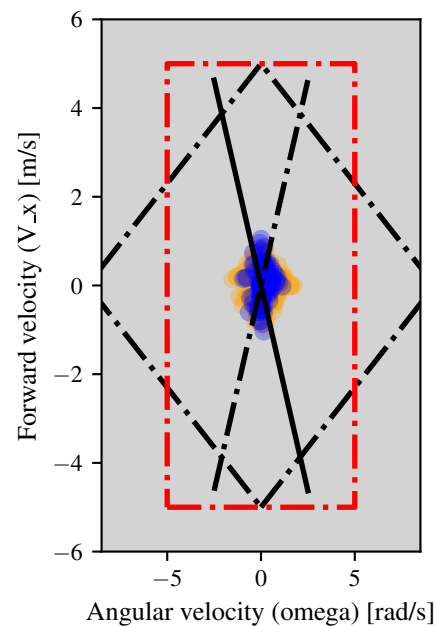
Body vel on avide



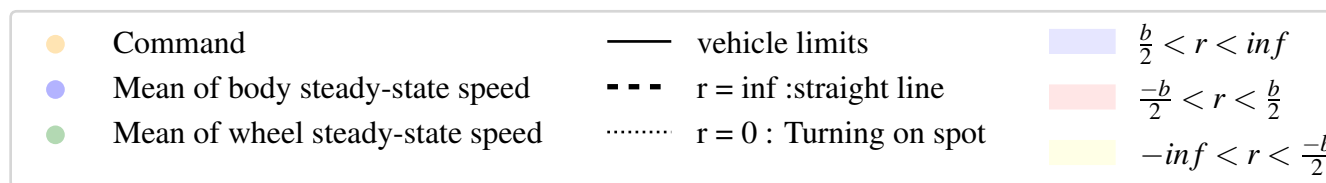
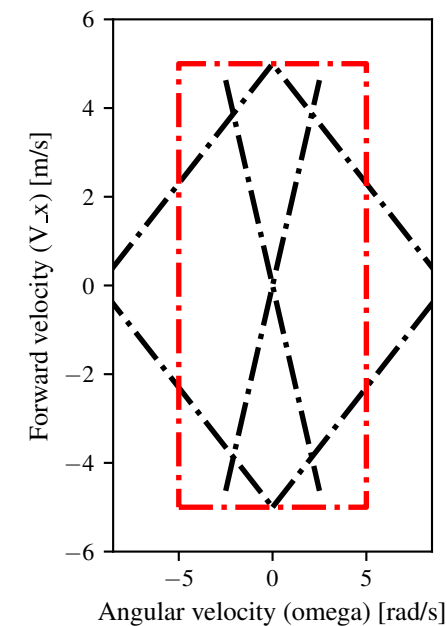
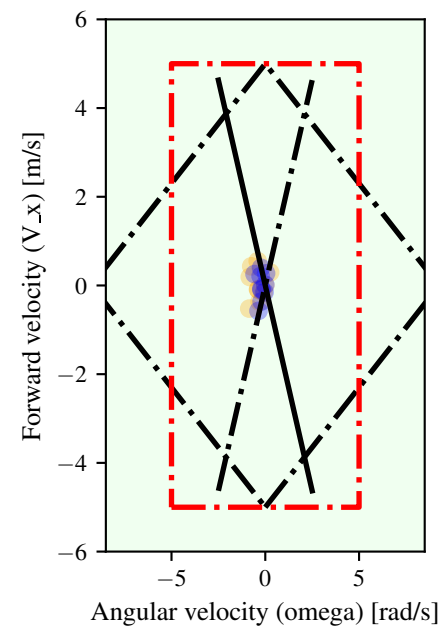
Body vel on avide2



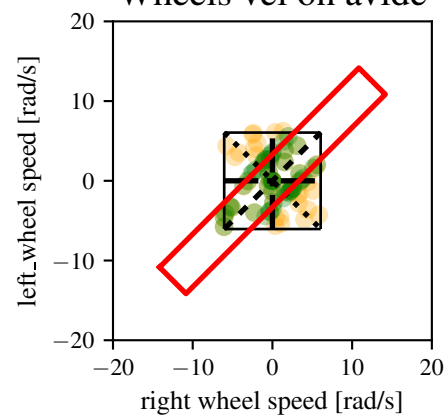
Body vel on asphalt



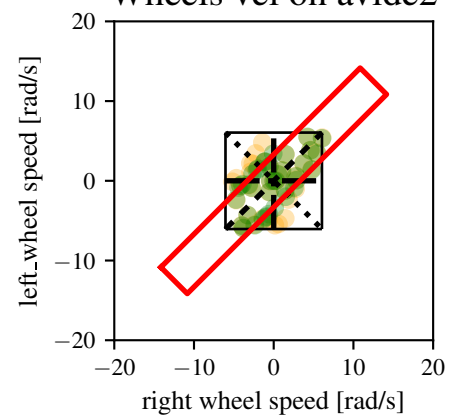
Body vel on grass



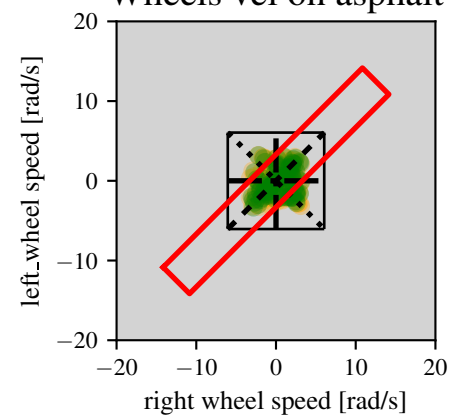
Wheels vel on avide



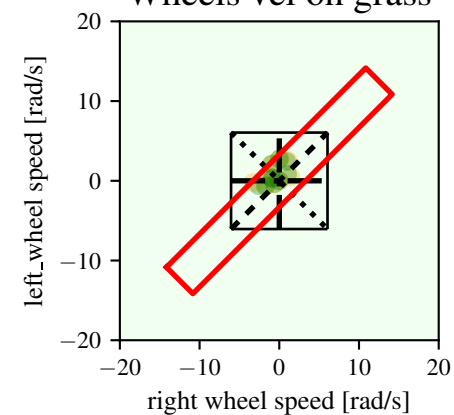
Wheels vel on avide2



Wheels vel on asphalt



Wheels vel on grass



Graph analyzer helper

