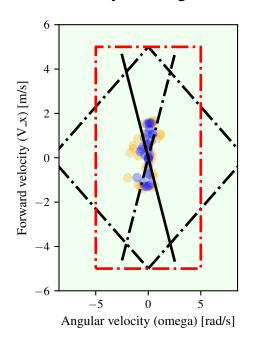
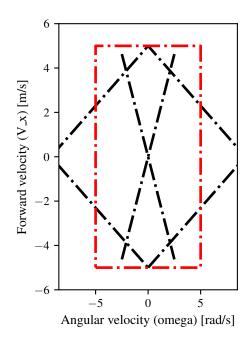
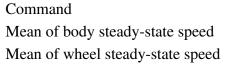
All roboticist with a maximum linear sampling speed of 2.0 m/s Cmd vs steady-state results for all_types_of_terrain

Body vel on grass







vehicle limitsr = inf :straight line

- - - r = inf :straight line ------ r = 0 : Turning on spot



