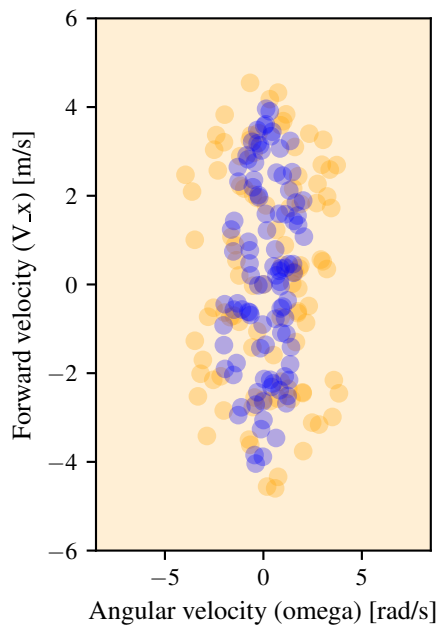
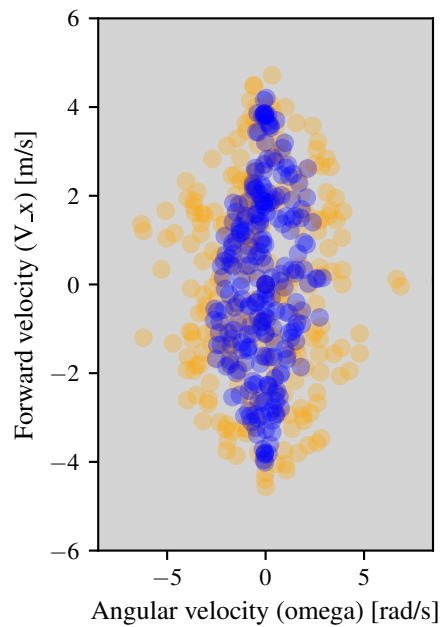


Robotist nicolassamson with a maximum linear sampling speed of 5.0 m/s
Cmd vs steady-state results for all_types_of_terrain

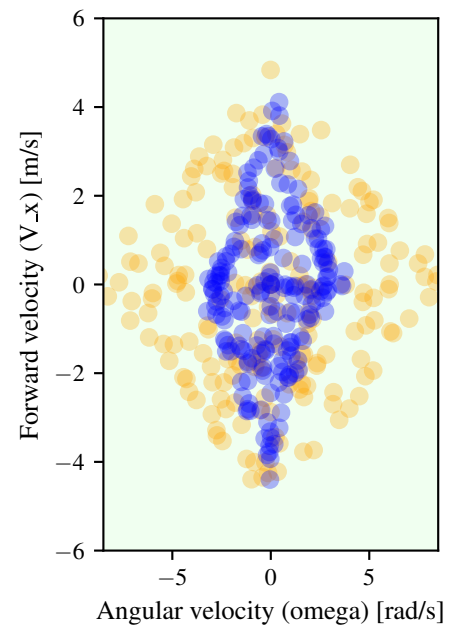
Body vel on gravel



Body vel on asphalt



Body vel on grass

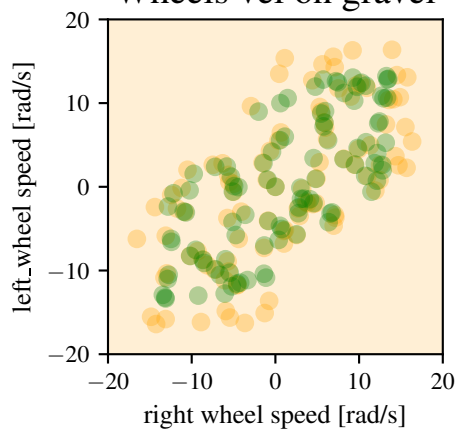


Command

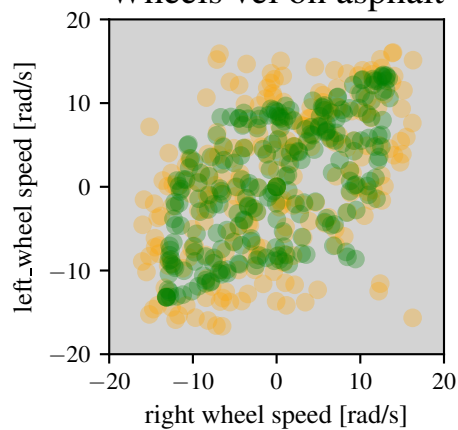
Mean of body steady-state speed

Mean of wheel steady-state speed

Wheels vel on gravel



Wheels vel on asphalt



Wheels vel on grass

