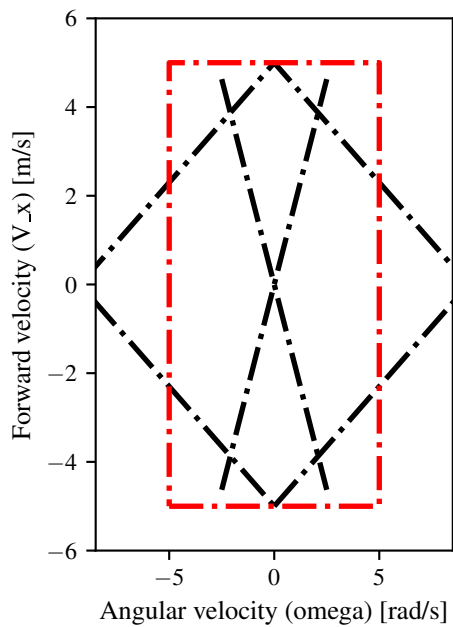
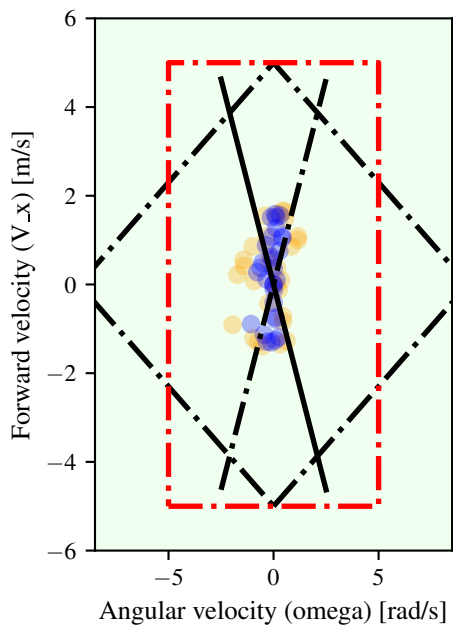


All roboticist with a maximum linear sampling speed of 2.0 m/s  
Cmd vs steady-state results for all\_types\_of\_terrain

Body vel on grass



Command

Mean of body steady-state speed

Mean of wheel steady-state speed

— vehicle limits

- - -  $r = \inf$  :straight line

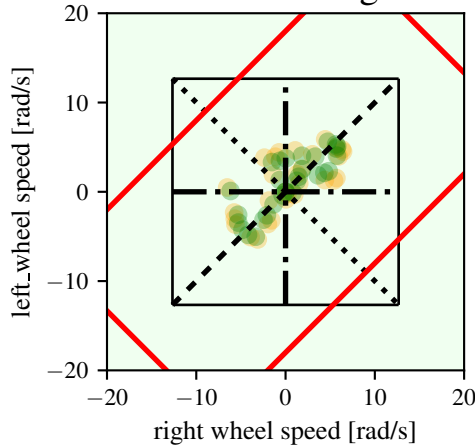
.....  $r = 0$  : Turning on spot

$\frac{b}{2} < r < \infty$

$-\frac{b}{2} < r < \frac{b}{2}$

$-\infty < r < -\frac{b}{2}$

Wheels vel on grass



Graph analyzer helper

