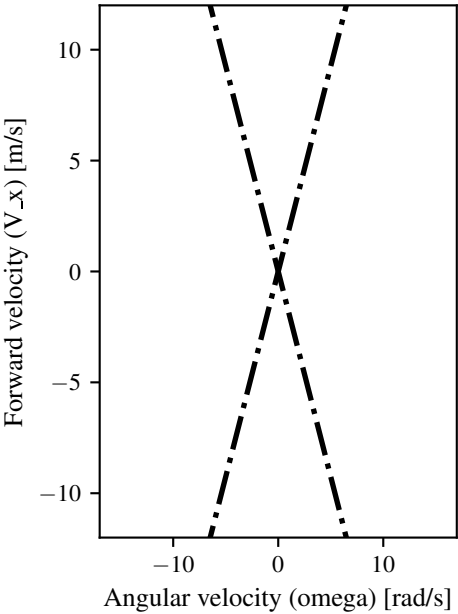
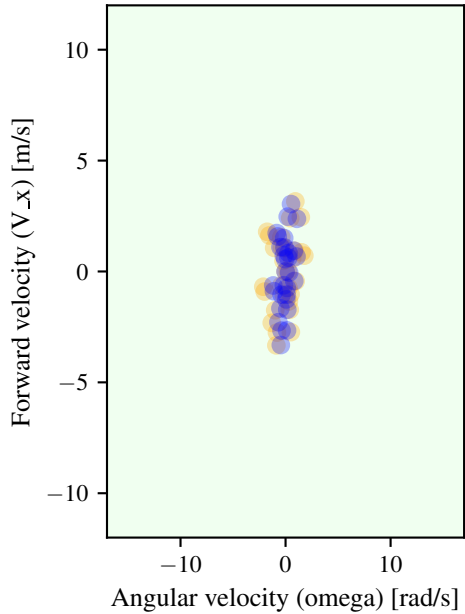


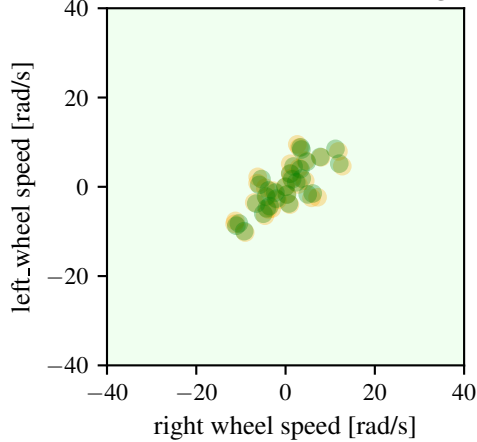
All roboticist with a maximum linear sampling speed of 2.0 m/s
Cmd vs steady-state results for all_types_of_terrain

Body vel on grass



| | | |
|----------------------------------|---------------------------------|----------------------------------|
| Command | — vehicle limits | $\frac{b}{2} < r < \frac{b}{2}$ |
| Mean of body steady-state speed | - - - $r = \inf$:straight line | $-\frac{b}{2} < r < \frac{b}{2}$ |
| Mean of wheel steady-state speed | $r = 0$: Turning on spot | $-\inf < r < \inf$ |

Centered Wheels vel on grass



Graph analyzer helper

