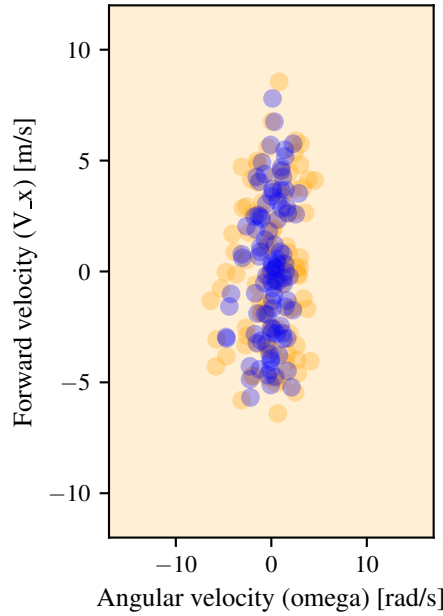
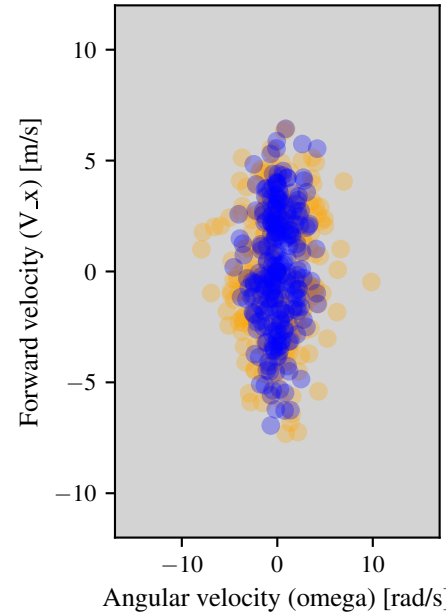


Robotist nicolassamson with a maximum linear sampling speed of 5.0 m/s
Cmd vs steady-state results for all_types_of_terrain

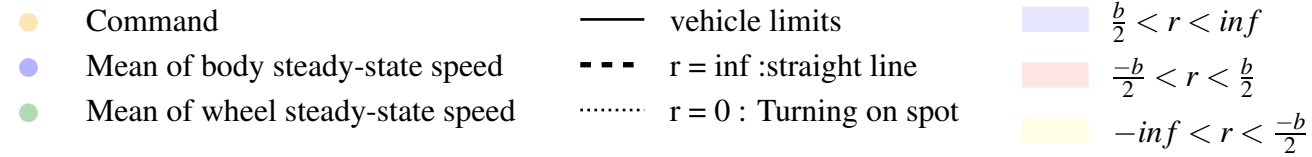
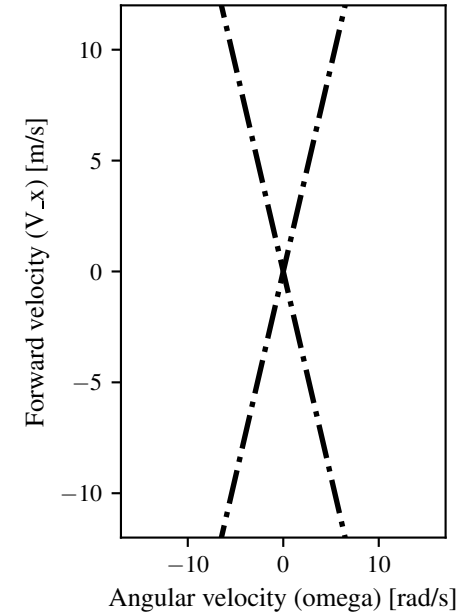
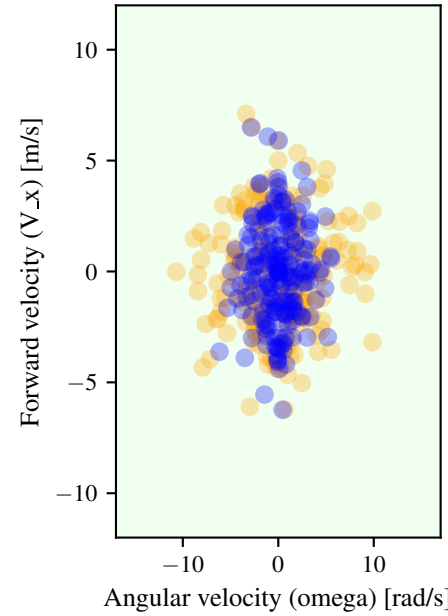
Body vel on gravel



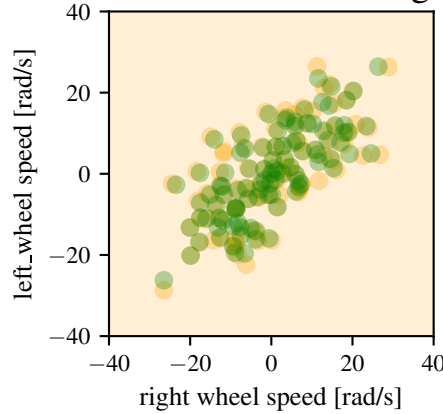
Body vel on asphalt



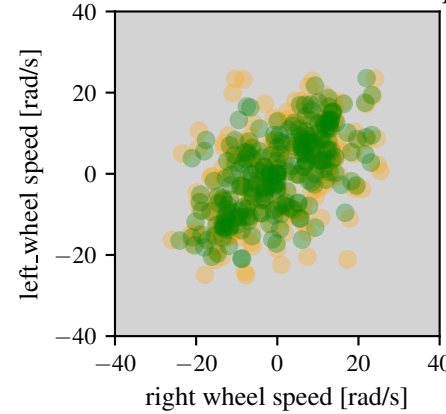
Body vel on grass



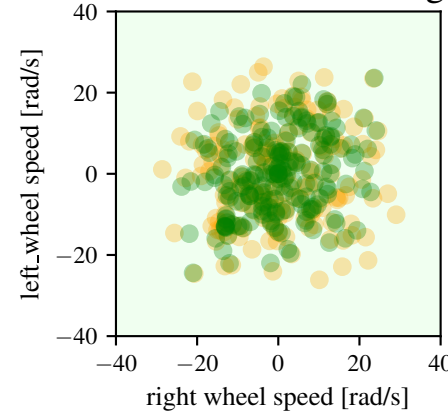
Centered Wheels vel on gravel



Centered Wheels vel on asphalt



Centered Wheels vel on grass



Graph analyzer helper

