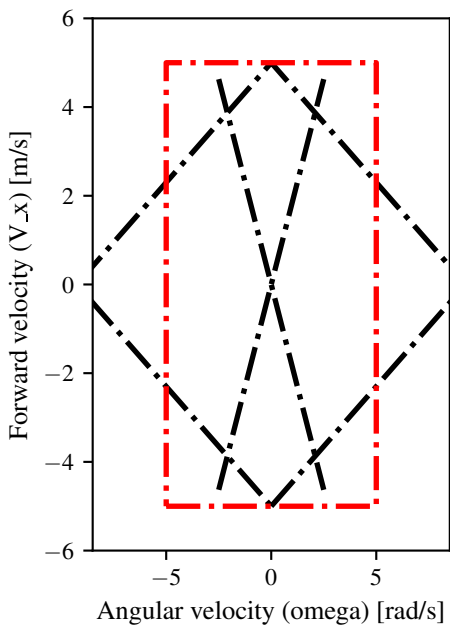
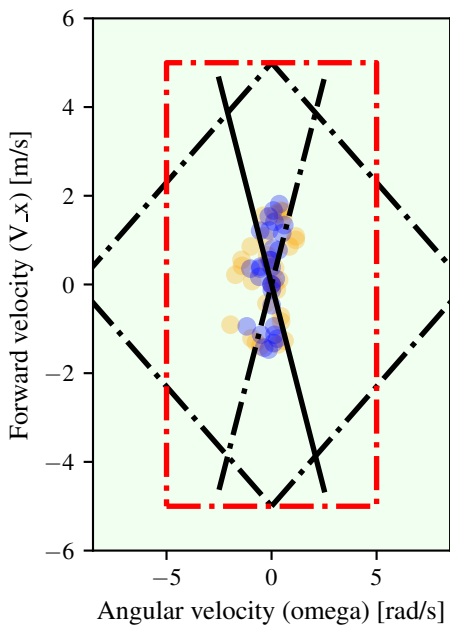


Robotist nicolassamson with a maximum linear sampling speed of 2.0 m/s
Cmd vs steady-state results for all_types_of_terrain

Body vel on grass



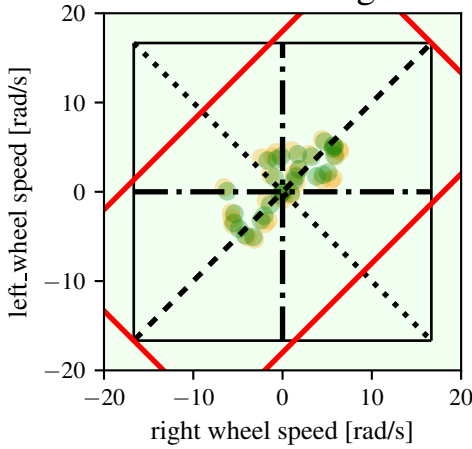
Command

Mean of body steady-state speed

Mean of wheel steady-state speed

- vehicle limits
- - - $r = \inf$: straight line
- $r = 0$: Turning on spot
- $\frac{b}{2} < r < \frac{b}{2}$
- $-\frac{b}{2} < r < \frac{b}{2}$
- $-\inf < r < \frac{b}{2}$

Wheels vel on grass



Graph analyzer helper

