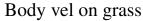
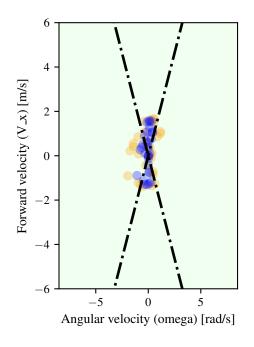
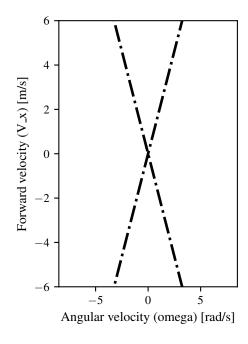
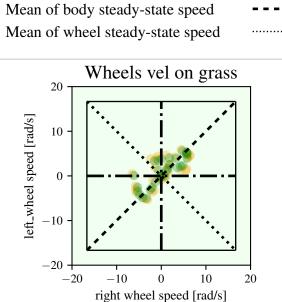
All roboticist with a maximum linear sampling speed of 2.0 m/s Cmd vs steady-state results for all_types_of_terrain

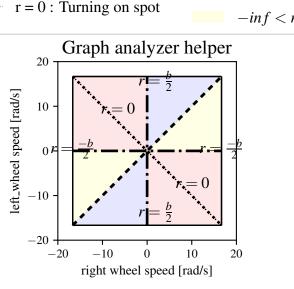








Command



vehicle limits

 $r = \inf$:straight line

r = 0: Turning on spot