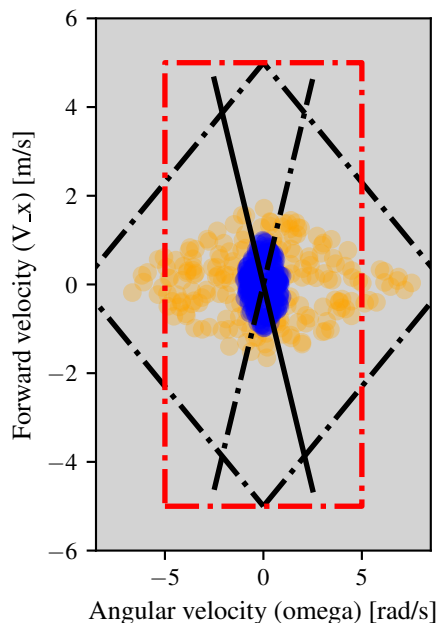
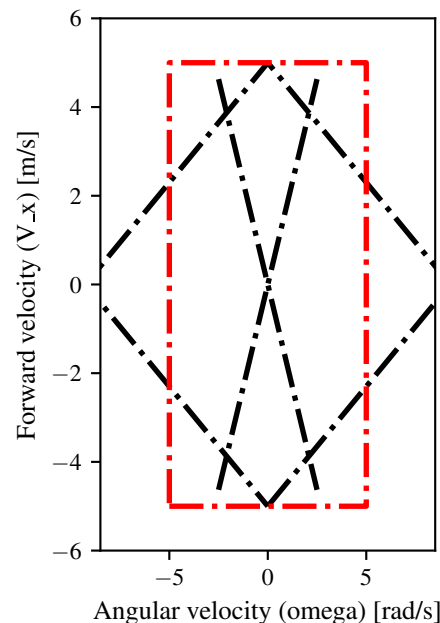
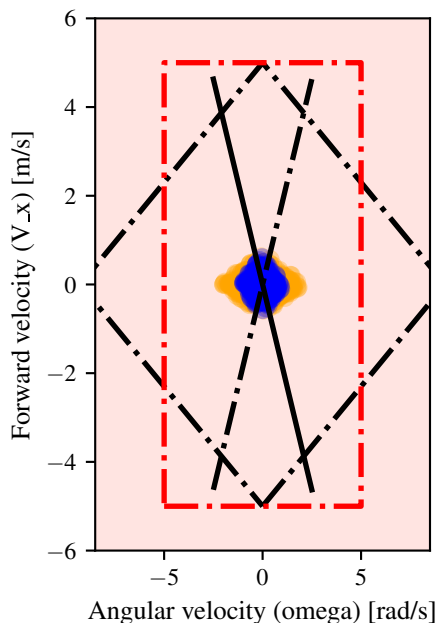


Robotist dominicbaril with a maximum linear sampling speed of 1.5 m/s
 Cmd vs steady-state results for all_types_of_terrain

Body vel on boreal



Body vel on tile

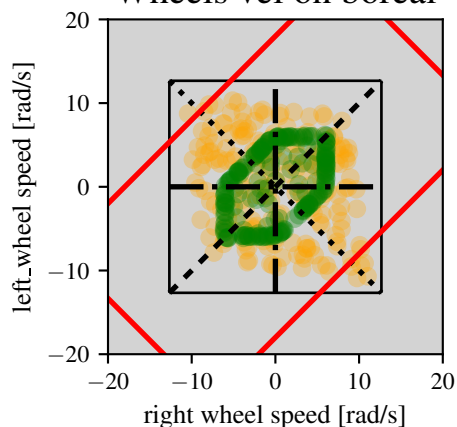


- Command
- Mean of body steady-state speed
- Mean of wheel steady-state speed

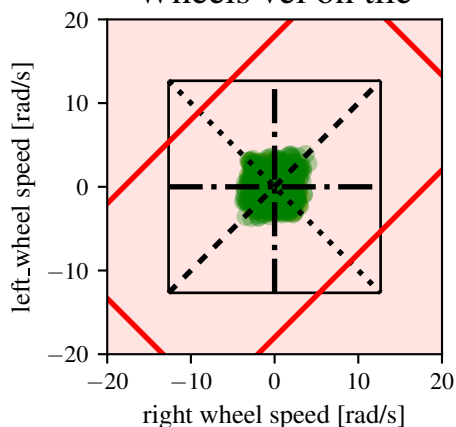
- vehicle limits
- - - $r = \inf$: straight line
- $r = 0$: Turning on spot

- $\frac{b}{2} < r < \inf$
- $-\frac{b}{2} < r < \frac{b}{2}$
- $-\inf < r < -\frac{b}{2}$

Wheels vel on boreal



Wheels vel on tile



Graph analyzer helper

