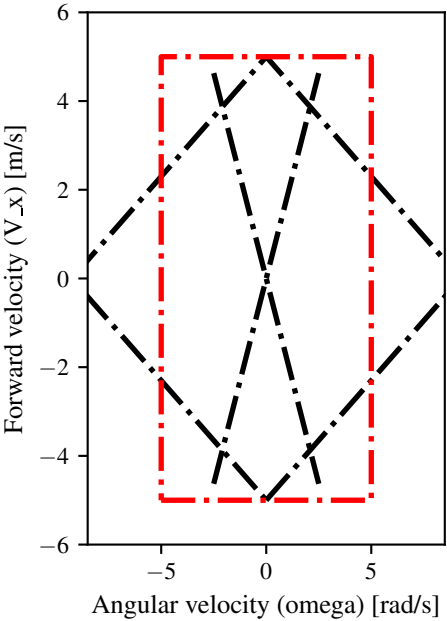
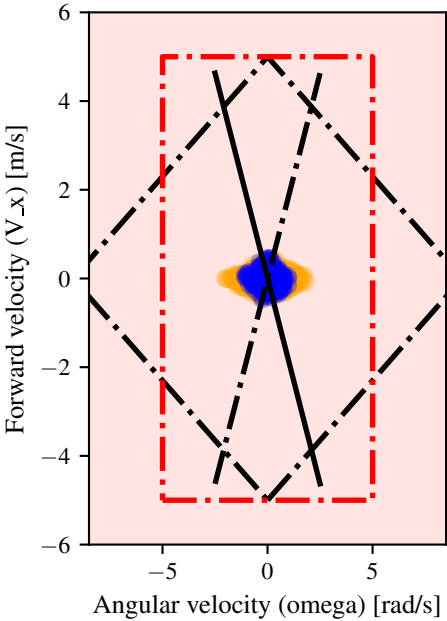


Robotist dominicbaril with a maximum linear sampling speed of 1.5 m/s
Cmd vs steady-state results for all_types_of_terrain

Body vel on tile



Command

Mean of body steady-state speed

Mean of wheel steady-state speed

— vehicle limits

- - - $r = \text{inf}$: straight line

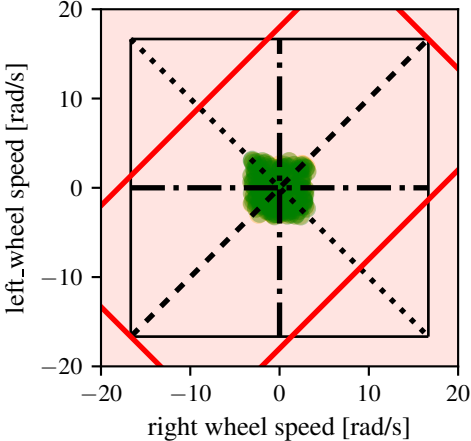
..... $r = 0$: Turning on spot

$\frac{b}{2} < r < \text{inf}$

$-\frac{b}{2} < r < \frac{b}{2}$

$-\text{inf} < r < -\frac{b}{2}$

Wheels vel on tile



Graph analyzer helper

