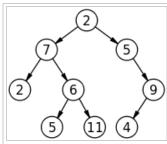
# Binary tree

From Wikipedia, the free encyclopedia

In computer science, a **binary tree** is a tree data structure in which each node has at most two child nodes, usually distinguished as "left" and "right". Nodes with children are parent nodes, and child nodes may contain references to their parents. Outside the tree, there is often a reference to the "root" node (the ancestor of all nodes), if it exists. Any node in the data structure can be reached by starting at root node and repeatedly following references to either the left or right child. A tree which does not have any node other than root node is called a null tree. In a binary tree, a degree of every node is maximum two. A tree with *n* nodes has exactly *n*–1 branches or degree.

Binary trees are used to implement binary search trees and binary heaps, finding applications in efficient searching and sorting algorithms.



A simple binary tree of size 9 and height 3, with a root node whose value is 2. The above tree is unbalanced and not sorted.

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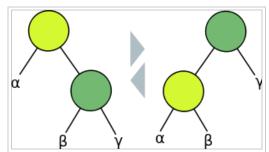
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## **Definitions for rooted trees**

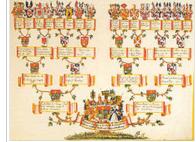
- A directed edge refers to the link from the parent to the child (the arrows in the picture of the tree).
- The root node of a tree is the node with no parents. There is at most one root node in a rooted tree.
- A leaf node has no children.
- The **depth** of a node is the length of the path from the root to the node. The set of all nodes at a given depth is sometimes called a **level** of the tree. The root node is at depth zero.
- The **depth** (or *height*) of a tree is the length of the path from the root to the deepest node in the tree. A (rooted) tree with only one node (the root) has a depth of zero.
- **Siblings** are nodes that share the same parent node.
- A node p is an **ancestor** of a node q if it exists on the path from the root to node q. The node q is then termed as a **descendant** of p.
- The **size** of a node is the number of descendants it has including itself.
- **In-degree** of a node is the number of edges arriving at that node.
- Out-degree of a node is the number of edges leaving that node.
- The root is the only node in the tree with In-degree = 0.
- All the leaf nodes have Out-degree = 0.

# Types of binary trees

- A **rooted binary tree** is a tree with a root node in which every node has at most two children.
- A full binary tree (sometimes proper binary tree or 2-tree or strictly binary tree) is a tree in which every node other than the leaves has two children. Or, perhaps more clearly, every node in a binary tree has exactly (strictly) 0 or 2 children. Sometimes a full tree is ambiguously defined as a perfect tree (see next). Physicists define a binary tree to mean a full binary tree. [1]
- A **perfect binary tree** is a *full binary tree* in which all *leaves* are at the same *depth* or same *level*, and in which every parent has two children.<sup>[2]</sup> (This is ambiguously also called a *complete binary tree* (see next).) An example of a perfect binary tree is the ancestry chart of a person to a given depth, as each person has exactly two biological parents (one mother and one father); note that this reverses the usual parent/child tree convention, and these trees go in the opposite direction from usual (root at bottom).
- A **complete binary tree** is a binary tree in which every level, *except possibly the last*, is completely filled, and all nodes are as far left as possible. [3] A tree is called an almost complete binary tree or nearly complete binary tree if the exception holds, i.e. the last level is not completely filled. This type of tree is used as a specialized data structure called a heap.
- An **infinite complete binary tree** is a tree with a countably infinite number of levels, in which every node has two children, so that there are  $2^d$  nodes at level d. The set of



Tree rotations are very common internal operations on self-balancing binary trees



An ancestry chart which maps to a perfect depth 4 binary tree

all nodes is countably infinite, but the set of all infinite paths from the root is uncountable: it has the cardinality of the continuum. These paths correspond by an order preserving bijection to the points of the Cantor set, or (through the example of the Stern–Brocot tree) to the set of positive irrational numbers

- A balanced binary tree is commonly defined as a binary tree in which the depth of the left and right subtrees of every node differ by 1 or less, [4] although in general it is a binary tree where no leaf is much farther away from the root than any other leaf. (Different balancing schemes allow different definitions of "much farther". [5]) Binary trees that are balanced according to this definition have a predictable depth (how many nodes are traversed from the root to a leaf, root counting as node 0 and subsequent as 1, 2, ..., depth). This depth is equal to the integer part of  $\log_2(n)$  where n is the number of nodes on the balanced tree. Example 1: balanced tree with 1 node,  $\log_2(1) = 0$  (depth = 0). Example 2: balanced tree with 3 nodes,  $\log_2(3) = 1.59$  (depth=1). Example 3: balanced tree with 5 nodes,  $\log_2(5) = 2.32$  (depth of tree is 2 nodes).
- A **degenerate tree** is a tree where for each parent node, there is only one associated child node. This means that in a performance measurement, the tree will behave like a linked list data structure.

Note that this terminology often varies in the literature, especially with respect to the meaning of "complete" and "full".

# **Properties of binary trees**

- The number n of nodes in a perfect binary tree can be found using this formula:  $n = 2^{h+1} 1$  where h is the depth of the tree.
- The number n of nodes in a binary tree of height h is at least n = h + 1 and at most  $n = 2^{h+1} 1$  where h is the depth of the tree.
- The number L of leaf nodes in a perfect binary tree can be found using this formula:  $L = 2^h$  where h is the depth of the tree.
- The number n of nodes in a perfect binary tree can also be found using this formula: n = 2L 1 where L is the number of leaf nodes in the tree.
- The number of null links (absent children of nodes) in a complete binary tree of n nodes is (n + 1).
- The number n = L of internal nodes (non-leaf nodes) in a Complete Binary Tree of n nodes is  $\lfloor n/2 \rfloor$ .
- For any non-empty binary tree with  $n_0$  leaf nodes and  $n_2$  nodes of degree 2,  $n_0 = n_2 + 1$ . [6]

#### Proof:

Let n = the total number of nodes

B = number of branches

 $n_0$ ,  $n_1$ ,  $n_2$  represent the number of nodes with no children, a single child, and two children respectively.

B = n - 1 (since all nodes except the root node come from a single branch)  $B = n_1 + 2*n_2$   $n = n_1 + 2*n_2 + 1$   $n = n_0 + n_1 + n_2$  $n_1 + 2*n_2 + 1 = n_0 + n_1 + n_2 \Longrightarrow n_0 = n_2 + 1$ 

# **Common operations**

There are a variety of different operations that can be performed on binary trees. Some are mutator operations, while others simply return useful information about the tree.

#### Insertion

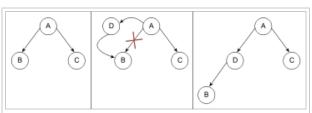
Nodes can be inserted into binary trees in between two other nodes or added after an external node. In binary trees, a node that is inserted is specified as to which child it is.

#### **External nodes**

Say that the external node being added on to is node A. To add a new node after node A, A assigns the new node as one of its children and the new node assigns node A as its parent.

#### **Internal nodes**

Insertion on internal nodes is slightly more complex than on external nodes. Say that the internal node is node A and that node B is the child of A. (If the insertion is to insert a right child, then B is the right child of A, and similarly with a left child insertion.) A assigns its child to the new node and the new node assigns its parent to A. Then the new node assigns its child to B and B assigns its parent as the new node.



The process of inserting a node into a binary tree

#### **Deletion**

Deletion is the process whereby a node is removed from the tree. Only certain nodes in a binary tree can be removed unambiguously.<sup>[7]</sup>

#### Node with zero or one children

Say that the node to delete is node A. If a node has no children (external node), deletion is accomplished by setting the child of A's parent to null. If it has one child, set the parent of A's child to A's parent and set the child of A's parent to A's child.

# B B C

The process of deleting an internal node in a binary tree

#### Node with two children

In a binary tree, a node with two children cannot be deleted unambiguously.<sup>[7]</sup> However, in certain binary trees these nodes *can* be deleted, including binary search trees.

#### Iteration

Often, one wishes to visit each of the nodes in a tree and examine the value there, a process called iteration or enumeration. There are several common orders in which the nodes can be visited, and each has useful properties that are exploited in algorithms based on binary trees:

Pre-Order: Root, Left child, Right child
In-Order: Left child, Root, Right child.
Post-Order: Left Child, Right child, Root

#### Pre-order, in-order, and post-order traversal

Main article: Tree traversal

Pre-order, in-order, and post-order traversal visit each node in a tree by recursively visiting each node in the left and right subtrees of the root.

#### Depth-first order

In depth-first order, we always attempt to visit the node farthest from the root that we can, but with the caveat that it must be a child of a node we have already visited. Unlike a depth-first search on graphs, there is no need to remember all the nodes we have visited, because a tree cannot contain cycles. Pre-order is a special case of this. See depth-first search for more information.

#### **Breadth-first order**

Contrasting with depth-first order is breadth-first order, which always attempts to visit the node closest to the root that it has not already visited. See breadth-first search for more information. Also called a *level-order traversal*.

# Type theory

In type theory, a binary tree with nodes of type A is defined inductively as  $T_A = \mu \alpha$ .  $1 + A \times \alpha \times \alpha$ .

# **Definition in graph theory**

For each binary tree data structure, there is equivalent rooted binary tree in graph theory.

Graph theorists use the following definition: A binary tree is a connected acyclic graph such that the degree of each vertex is no more than three. It can be shown that in any binary tree of two or more nodes, there are exactly two more nodes of degree one than there are of degree three, but there can be any number of nodes of degree two. A **rooted binary tree** is such a graph that has one of its vertices of degree no more than two singled out as the root.

With the root thus chosen, each vertex will have a uniquely defined parent, and up to two children; however, so far there is insufficient information to distinguish a left or right child. If we drop the connectedness requirement, allowing multiple connected components in the graph, we call such a structure a forest.

Another way of defining binary trees is a recursive definition on directed graphs. A binary tree is either:

- A single vertex.
- A graph formed by taking two binary trees, adding a vertex, and adding an edge directed from the new vertex to the root of each binary tree.

This also does not establish the order of children, but does fix a specific root node.

## **Combinatorics**

$$((X*X)*X)*X, (X*(X*X))*X, (X*X)*(X*X), X*((X*X)*X), X*(X*(X*X)).$$

The correspondence to binary trees should be obvious, and the addition of redundant parentheses (around an already parenthesized expression or around the full expression) is disallowed (or at least not counted as producing a new possibility).

There is a unique binary tree of size 0 (consisting of a single leaf), and any other binary tree is characterized by the pair of its left and right children; if these have sizes i and j respectively, the full tree has size i + j + 1. Therefore the number  $C_n$  of binary trees of size n has the following recursive description  $C_0 = 1$ , and  $C_n = \sum_{i=0}^{n-1} C_i C_{n-1-i}$  for any positive integer n. It follows that  $C_n$  is the Catalan number of index n.

The above parenthesized strings should not be confused with the set of words of length 2n in the Dyck language, which consist only of parentheses in such a way that they are properly balanced. The number of such strings satisfies the same recursive description (each Dyck word of length 2n is determined by the Dyck subword enclosed by the initial '(' and its matching ')' together with the Dyck subword remaining after that closing parenthesis, whose lengths 2i and 2j satisfy i + j + 1 = n); this number is therefore also the Catalan number  $C_n$ . So there are also five Dyck words of length 10:

$$()()(), ()(()), (())(), (()()), ((()()).$$

These Dyck words do not correspond in an obvious way to binary trees. A bijective correspondence can nevertheless be defined as follows: enclose the Dyck word in an extra pair of parentheses, so that the result can be interpreted as a Lisp list expression (with the empty list () as only occurring atom); then the dotted-pair expression for that proper list is a fully parenthesized expression (with NIL as symbol and '.' as operator) describing the corresponding binary tree (which is in fact the internal representation of the proper list).

The ability to represent binary trees as strings of symbols and parentheses implies that binary trees can represent the elements of a free magma on a singleton set.

# Methods for storing binary trees

Binary trees can be constructed from programming language primitives in several ways.

#### Nodes and references

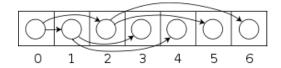
In a language with records and references, binary trees are typically constructed by having a tree node structure which contains some data and references to its left child and its right child. Sometimes it also contains a reference to its unique parent. If a node has fewer than two children, some of the child pointers may be set to a special null value, or to a special sentinel node.

In languages with tagged unions such as ML, a tree node is often a tagged union of two types of nodes, one of which is a 3-tuple of data, left child, and right child, and the other of which is a "leaf" node, which contains no data and functions much like the null value in a language with pointers.

### **Arrays**

Binary trees can also be stored in breadth-first order as an implicit data structure in arrays, and if the tree is a complete binary tree, this method wastes no space. In this compact arrangement, if a node has an index i, its children are found at indices 2i + 1 (for the left child) and 2i + 2 (for the right), while its parent (if any) is found at index  $\left\lfloor \frac{i-1}{2} \right\rfloor$  (assuming the root has index zero). This method benefits from more compact storage and better locality of reference, particularly during a preorder traversal. However, it is expensive to grow and wastes space proportional to  $2^h$  - n for a tree of depth n with n nodes.

This method of storage is often used for binary heaps. No space is wasted because nodes are added in breadth-first order.



# **Encodings**

# **Succinct encodings**

A succinct data structure is one which occupies close to minimum possible space, as established by information theoretical lower bounds. The number of different binary trees on n nodes is  $C_n$ , the nth Catalan number (assuming we view trees with identical *structure* as identical). For large n, this is about  $4^n$ ; thus we need at least about  $\log_2 4^n = 2n$  bits to encode it. A succinct binary tree therefore would occupy 2n + o(n) bits.

One simple representation which meets this bound is to visit the nodes of the tree in preorder, outputting "1" for an internal node and "0" for a leaf. [1]

(http://theory.csail.mit.edu/classes/6.897/spring03/scribe\_notes/L12/lecture12.pdf) If the tree contains data, we can simply simultaneously store it in a consecutive array in preorder. This function accomplishes this:

```
function EncodeSuccinct(node n, bitstring structure, array data) {
   if n = nil then
      append 0 to structure;
   else
      append 1 to structure;
      append n.data to data;
      EncodeSuccinct(n.left, structure, data);
      EncodeSuccinct(n.right, structure, data);
}
```

The string *structure* has only 2n + 1 bits in the end, where n is the number of (internal) nodes; we don't even have to store its length. To show that no information is lost, we can convert the output back to the original tree like this:

```
function DecodeSuccinct(bitstring structure, array data) {
   remove first bit of structure and put it in b
   if b = 1 then
        create a new node n
        remove first element of data and put it in n.data
        n.left = DecodeSuccinct(structure, data)
        n.right = DecodeSuccinct(structure, data)
        return n
   else
        return nil
}
```

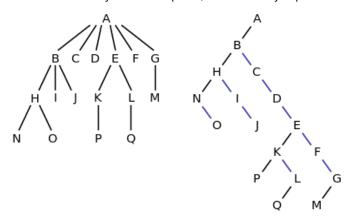
More sophisticated succinct representations allow not only compact storage of trees but even useful operations on those trees directly while they're still in their succinct form.

## **Encoding general trees as binary trees**

There is a one-to-one mapping between general ordered trees and binary trees, which in particular is used by Lisp to represent general ordered trees as binary trees. To convert a general ordered tree to binary tree, we only need to represent the general tree in left child-sibling way. The result of this representation will be automatically binary tree, if viewed from a different perspective. Each node N in the ordered tree corresponds to a node N' in the binary tree; the *left* child of N' is the node corresponding to the first child of N', and the *right* child of N' is the node corresponding to N' is next sibling --- that is, the next node in order among the children of the parent of N. This binary tree representation of a general order tree is sometimes also referred to as a left child-right sibling binary tree (LCRS tree), or a doubly chained tree, or a Filial-Heir chain.

One way of thinking about this is that each node's children are in a linked list, chained together with their *right* fields, and the node only has a pointer to the beginning or head of this list, through its *left* field.

For example, in the tree on the left, A has the 6 children {B,C,D,E,F,G}. It can be converted into the binary tree on the right.



The binary tree can be thought of as the original tree tilted sideways, with the black left edges representing *first child* and the blue right edges representing *next sibling*. The leaves of the tree on the left would be written in Lisp as:

which would be implemented in memory as the binary tree on the right, without any letters on those nodes that have a left child.

## See also

- **2-3** tree
- **2-3-4** tree
- AA tree
- AVL tree
- B-tree
- Binary space partitioning
- Huffman tree
- Kraft's inequality
- Random binary tree
- Recursion (computer science)
- Red-black tree
- Rope (computer science)
- Self-balancing binary search tree
- Splay tree
- Strahler number
- Tree of primitive Pythagorean triples#Alternative methods of generating the tree
- Unrooted binary tree

## **Notes**

- 1. ^ Unitary Symmetry, James D. Louck, World Scientific Pub., 2008
- 2. ^ "perfect binary tree" (http://www.nist.gov/dads/HTML/perfectBinaryTree.html). NIST.
- 3. ^ "complete binary tree" (http://www.nist.gov/dads/HTML/completeBinaryTree.html). NIST.
- 4. ^ Aaron M. Tenenbaum, et. al Data Structures Using C, Prentice Hall, 1990 ISBN 0-13-199746-7
- 5. ^ Paul E. Black (ed.), entry for data structure in Dictionary of Algorithms and Data Structures. U.S. National

- Institute of Standards and Technology. 15 December 2004. Online version (http://xw2k.nist.gov/dads//HTML/balancedtree.html) Accessed 2010-12-19.
- 6. ^ Mehta, Dinesh; Sartaj Sahni (2004). *Handbook of Data Structures and Applications*. Chapman and Hall. ISBN 1-58488-435-5.
- 7. ^ *a b* Dung X. Nguyen (2003). "Binary Tree Structure" (http://www.clear.rice.edu/comp212/03-spring/lectures/22/). rice.edu. Retrieved December 28, 2010.

## References

- Donald Knuth. The art of computer programming vol 1. Fundamental Algorithms, Third Edition.
   Addison-Wesley, 1997. ISBN 0-201-89683-4. Section 2.3, especially subsections 2.3.1–2.3.2 (pp. 318–348).
- Kenneth A Berman, Jerome L Paul. *Algorithms: Parallel, Sequential and Distributed*. Course Technology, 2005. ISBN 0-534-42057-5. Chapter 4. (pp. 113–166).

## **External links**

- Gamedev.net introduction on binary trees (http://www.gamedev.net/page/resources/\_/technical/general-programming/trees-part-2-binary-trees-r1433)
- Binary Tree Proof by Induction (http://www.brpreiss.com/books/opus4/html/page355.html)
- Balanced binary search tree on array How to create bottom-up an Ahnentafel list, or a balanced binary search tree on array (http://piergiu.wordpress.com/2010/02/21/balanced-binary-search-tree-on-array/)

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