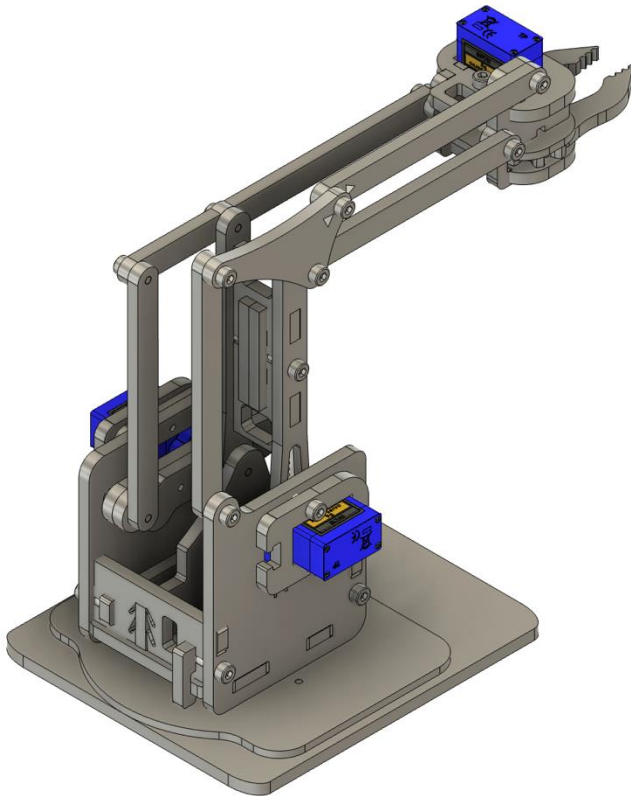


# CYBER PHYSICAL SYSTEMS



## DE Arm 25 Assembly Instructions

Dyson School of  
Design Engineering

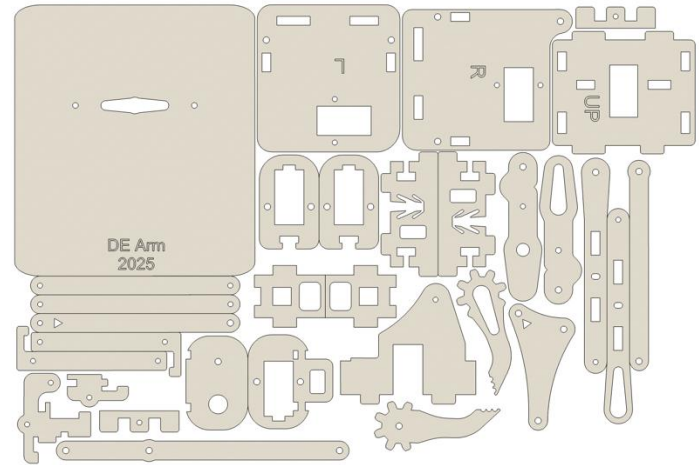
# Important Notes:

- Joints should move freely, do not overtighten the screws. The arm should be like a marionette without the servo motors.
- Before assembly you **have to** test and calibrate your servo motors to the positions shown in page 5.
- Take it easy, parts should sit in place with little force, if you find yourself using excessive force, check the manual and orientation again.

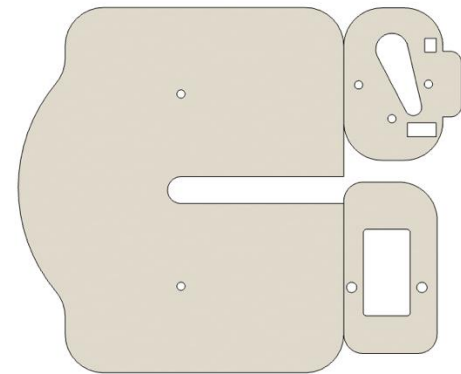


# List of Parts

- 4mm Plywood Parts: 31 pcs



- 2.5mm MDF Parts: 3 pcs



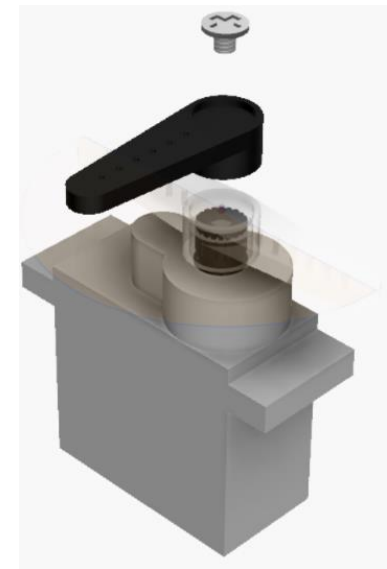
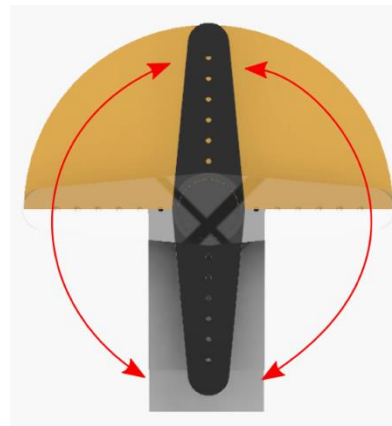
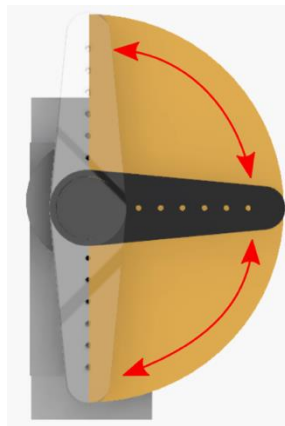
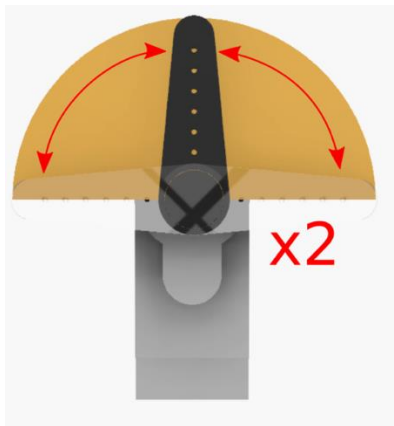
# List of Parts

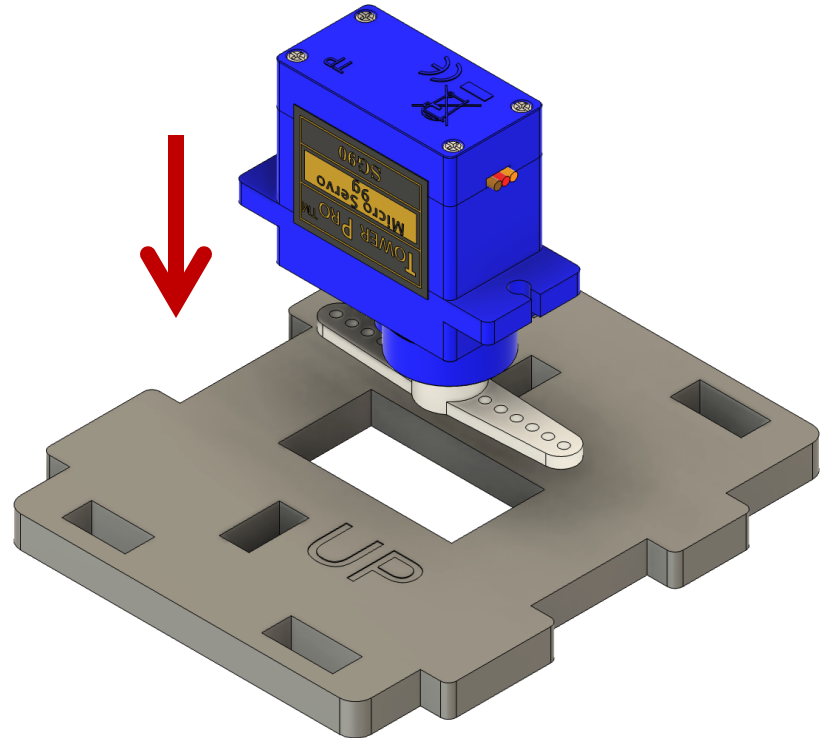
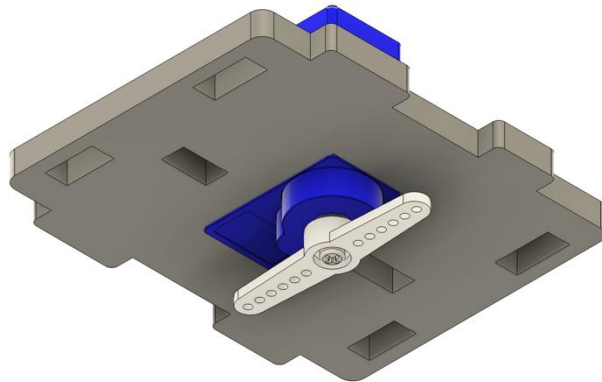
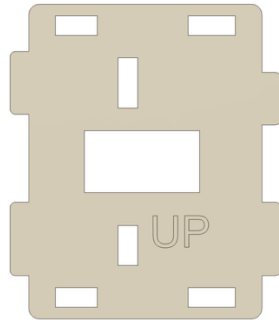
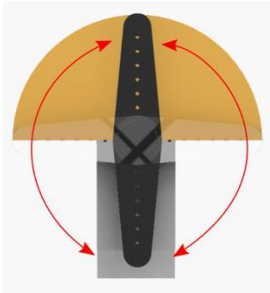
- M3 x 6mm Screw: 2 pcs
- M3 x 8mm Screw: 10 pcs
- M3 x 12mm Screw: 13 pcs
- M3 x 20mm Screw: 2 pcs
- SG90 Servo Motor: 4 pcs
- Stick-on Silicon Feet: 4 pcs

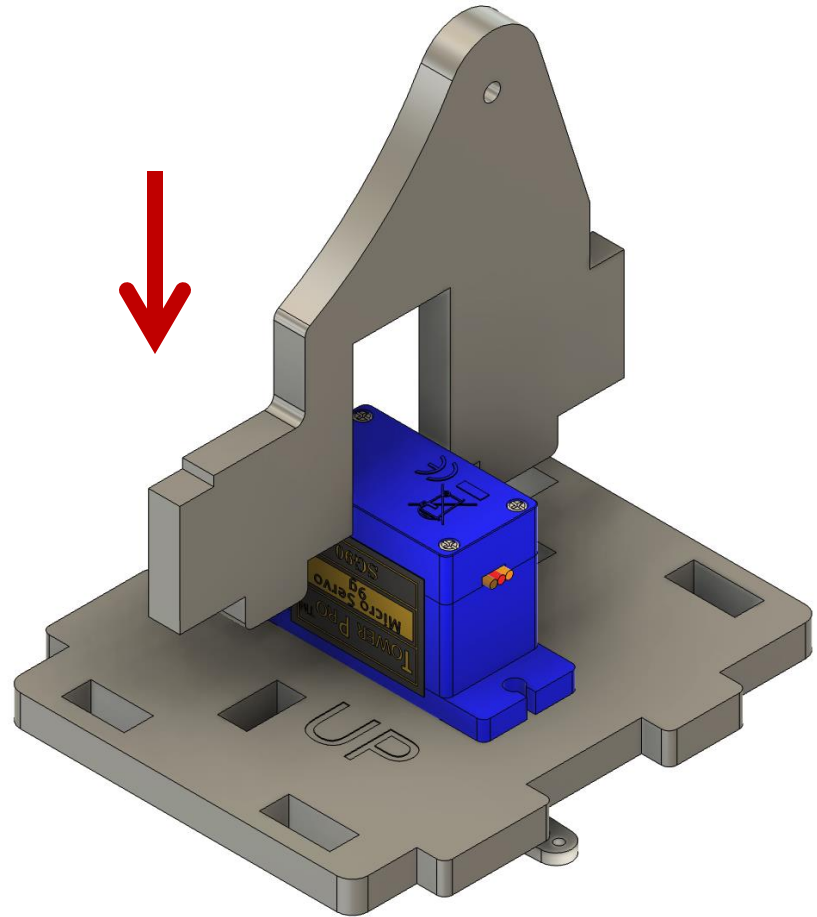
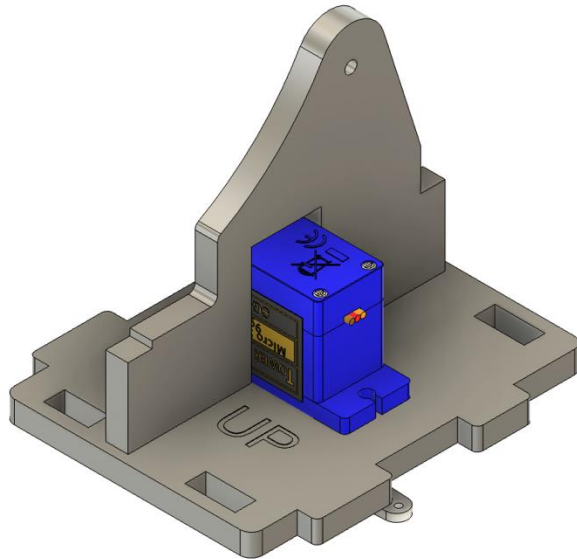
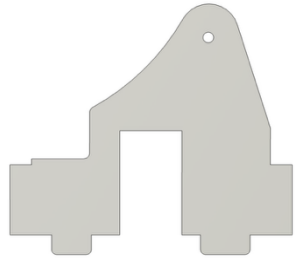


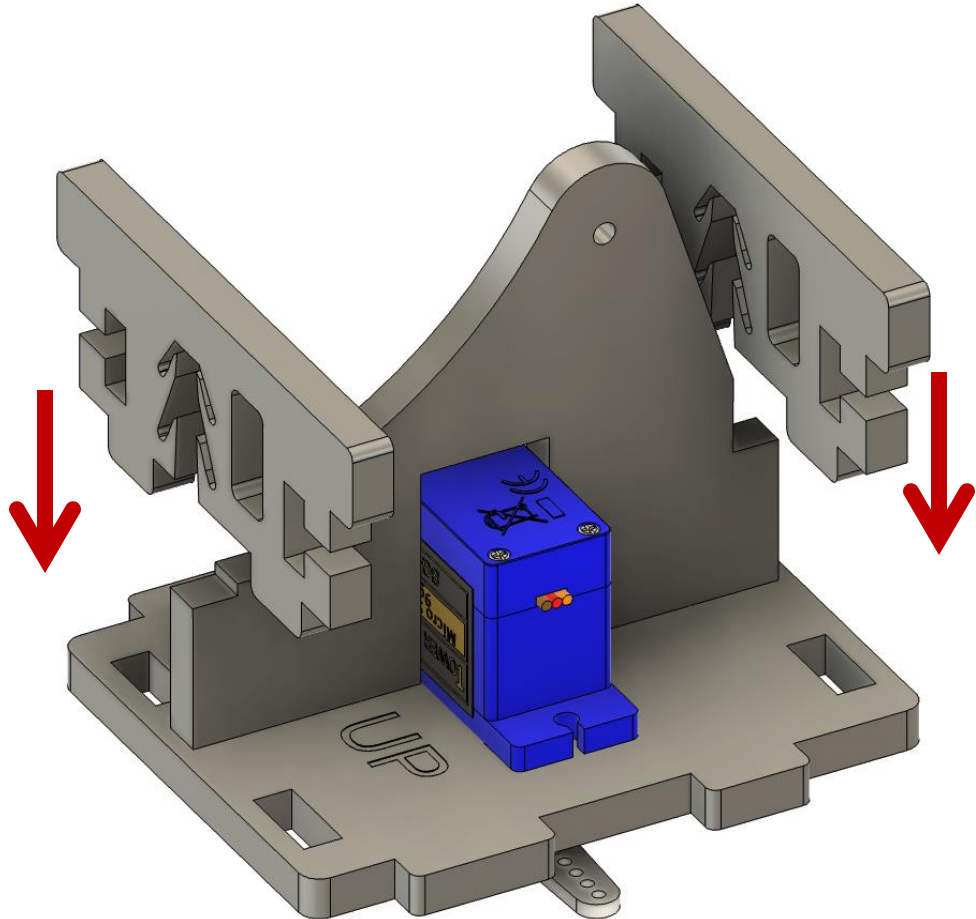
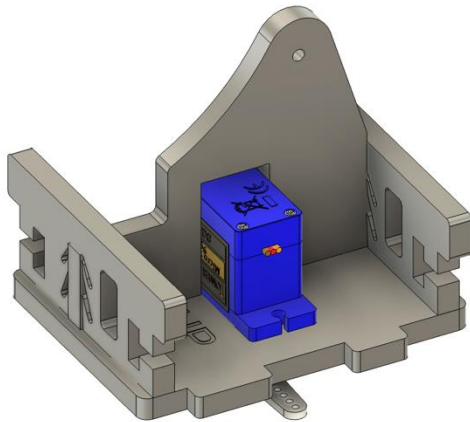
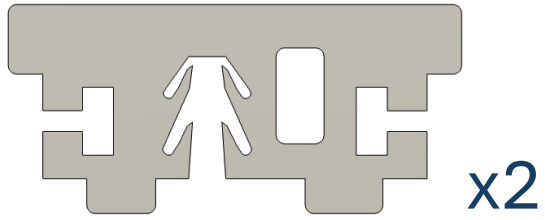
# Servo Calibration

\*You should have a total of 4 servos, calibrated as followed, They will be identified and used in the assembly.

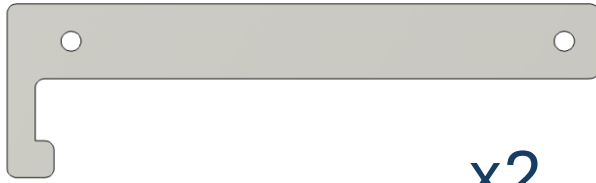




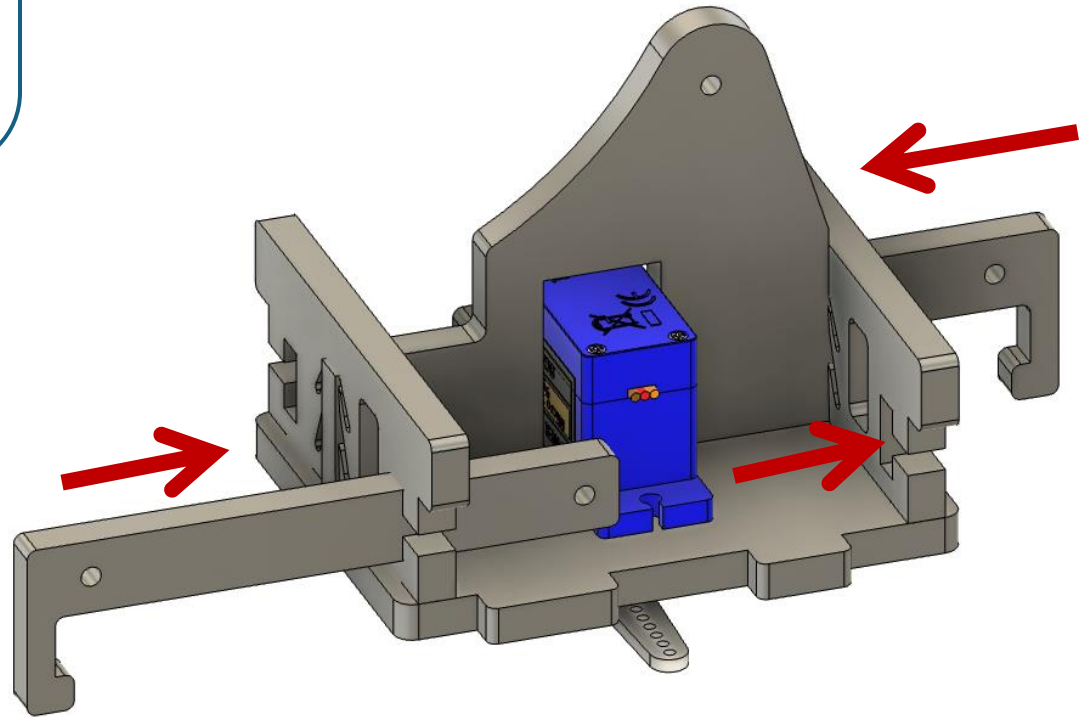
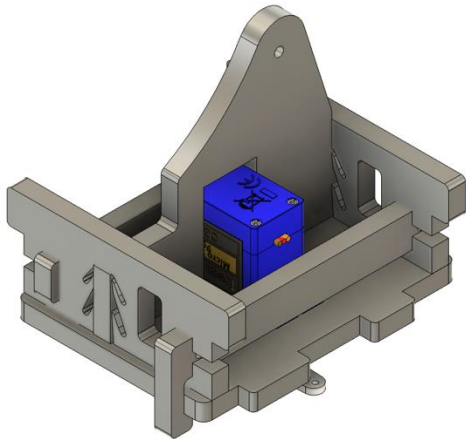


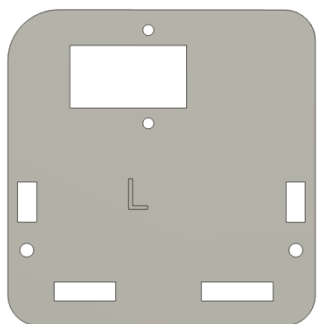






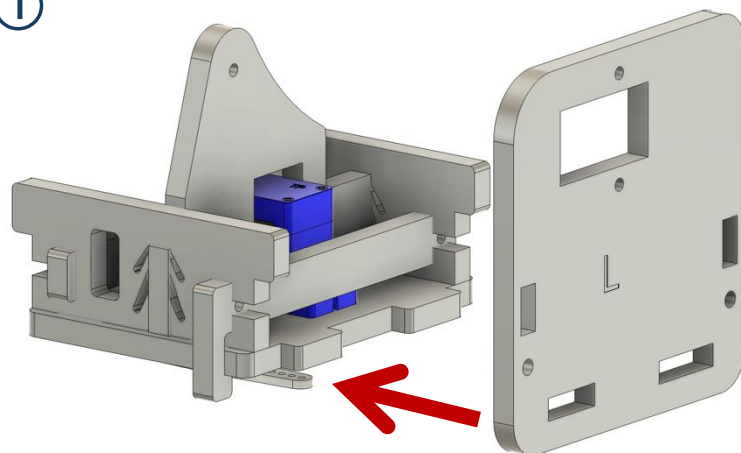
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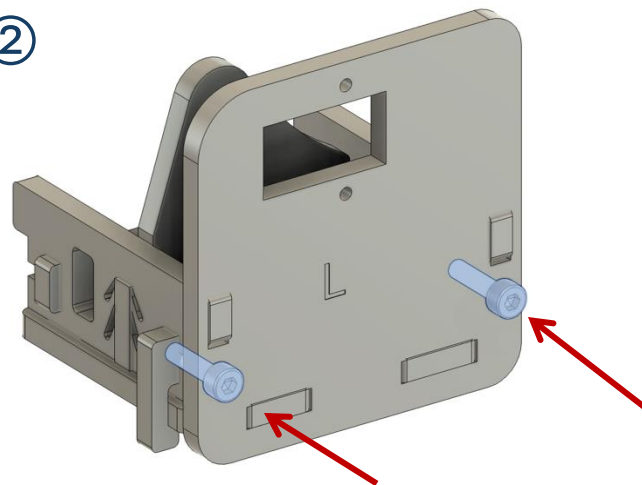


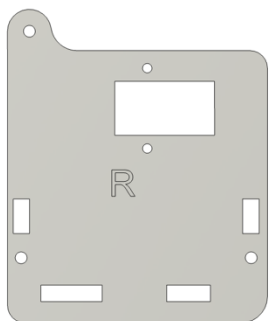
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①



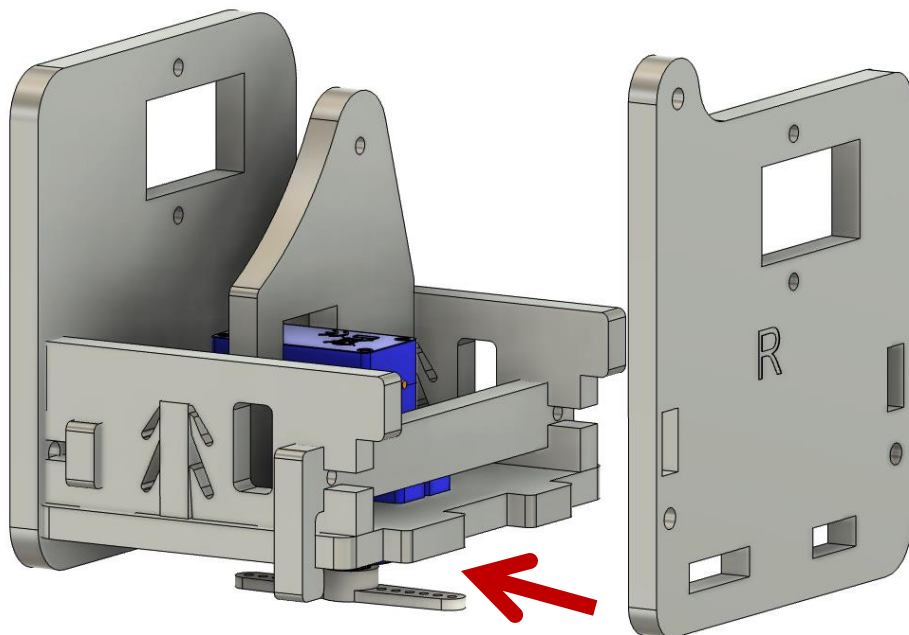
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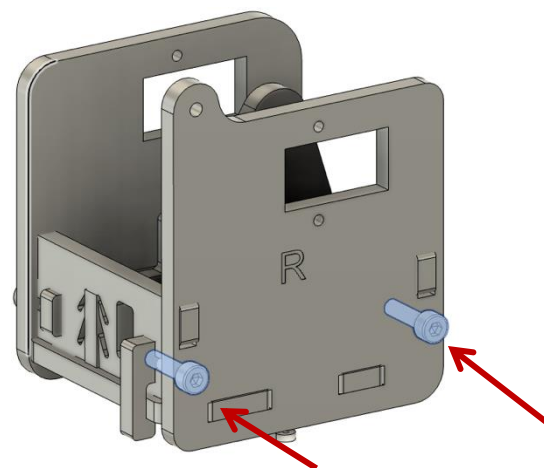


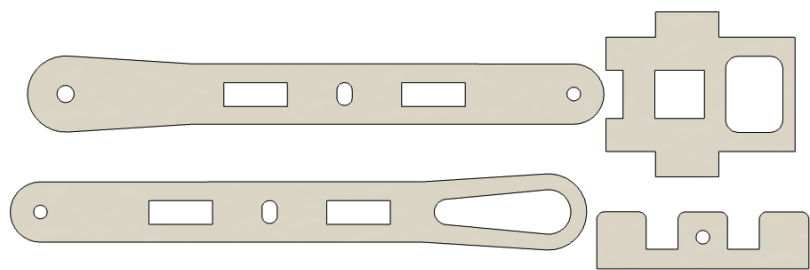
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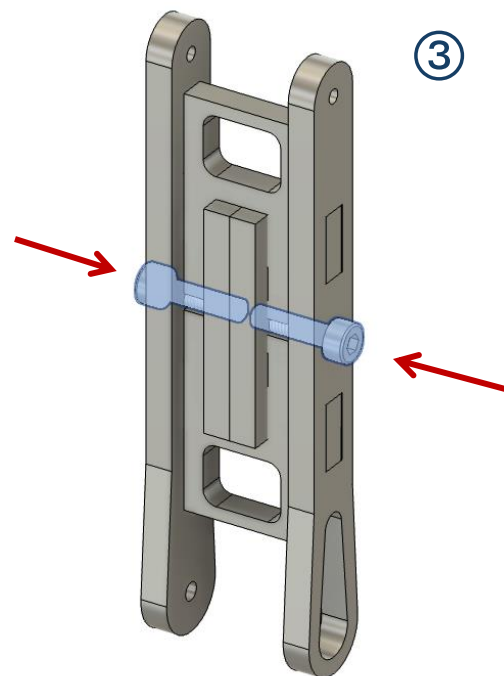
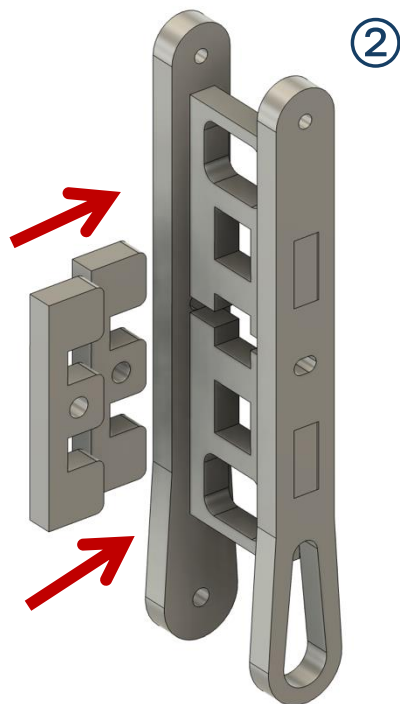
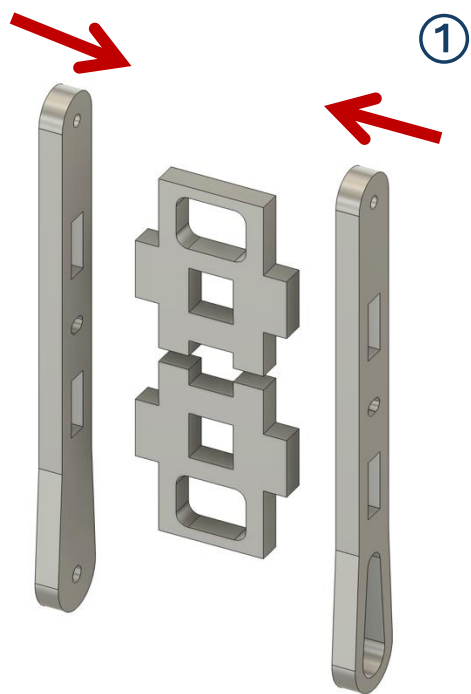
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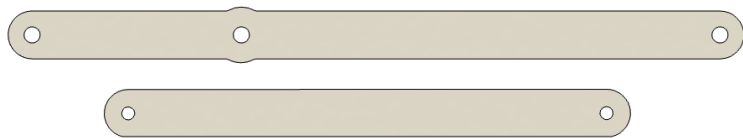




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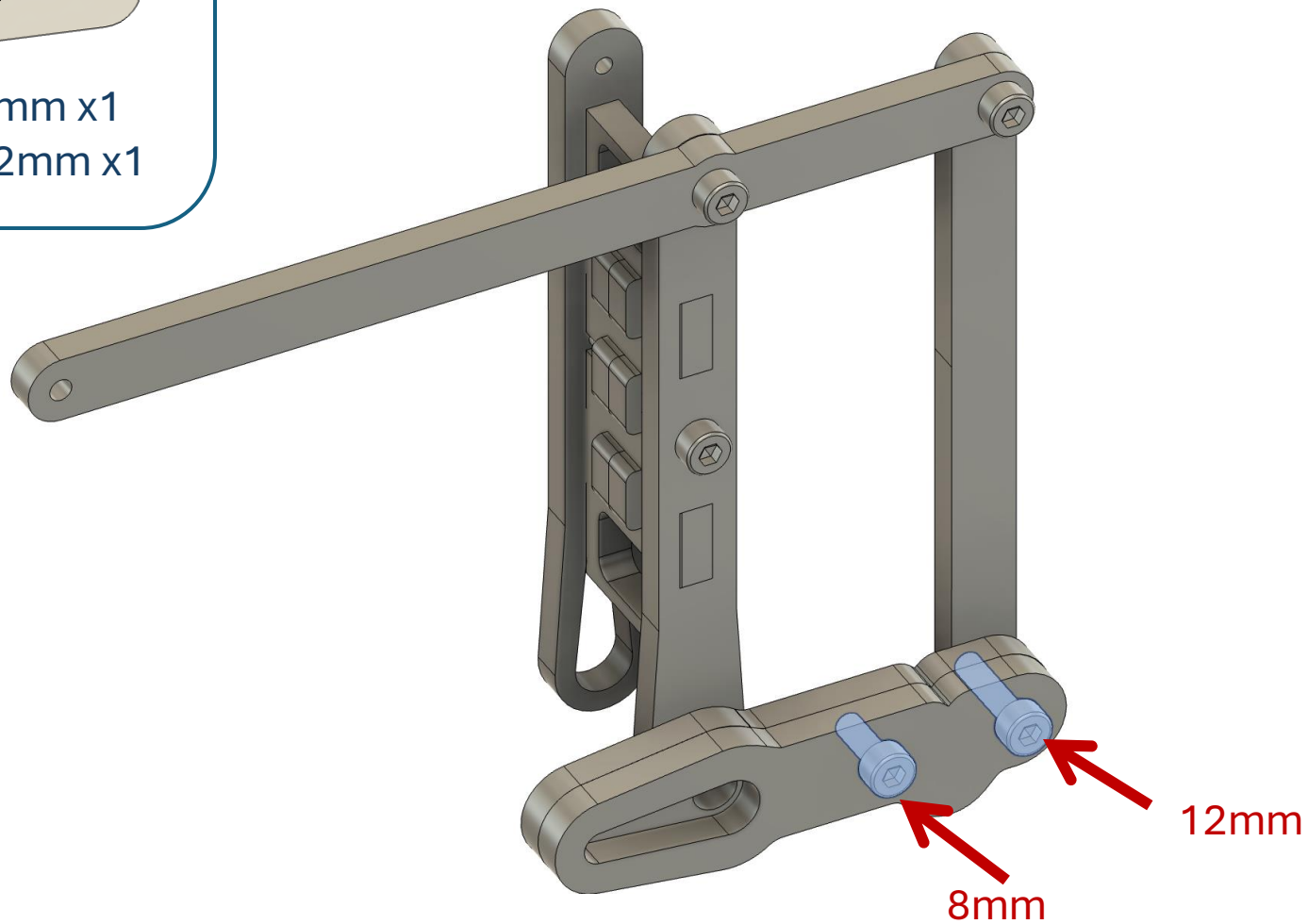
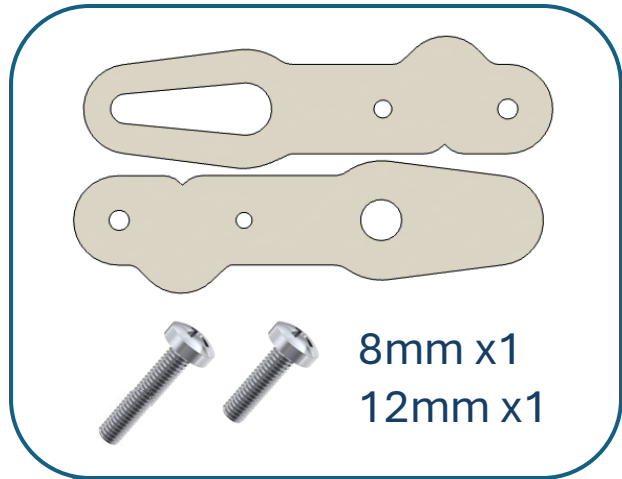
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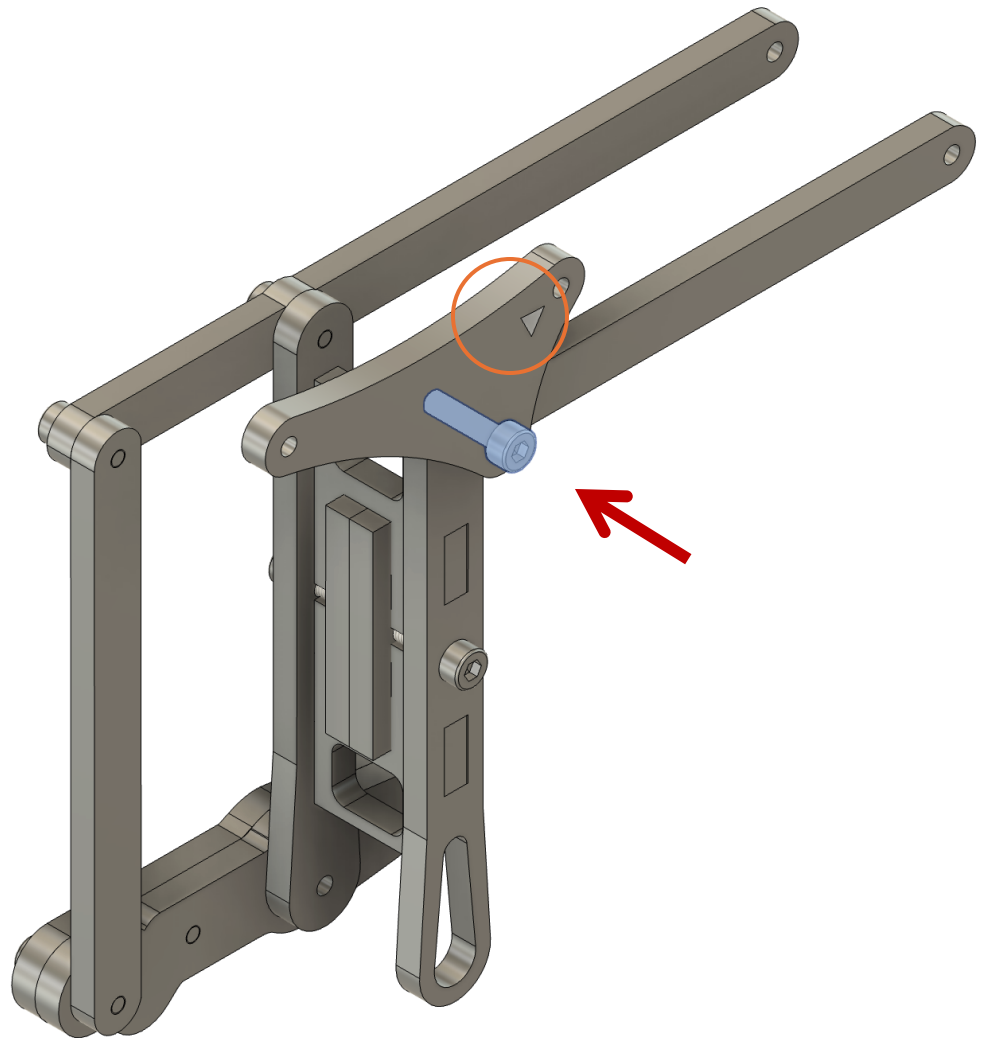
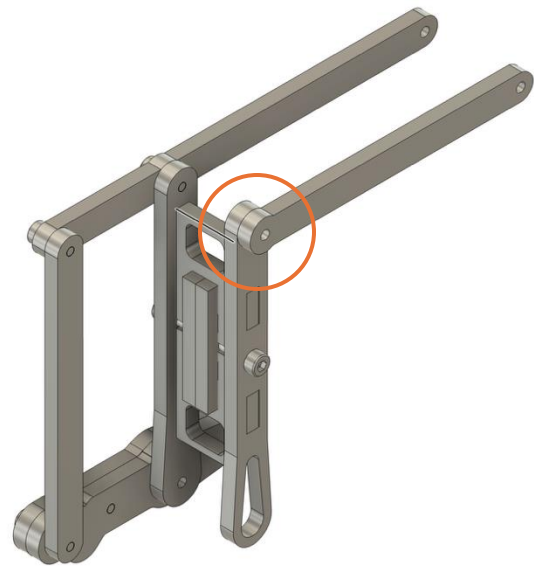
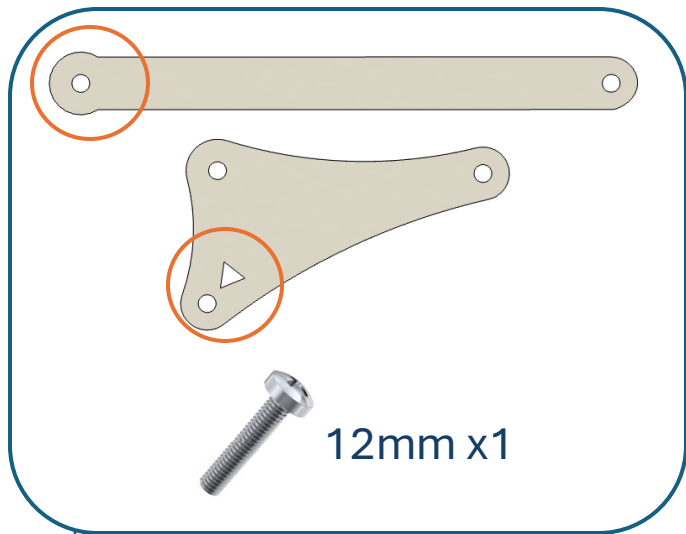


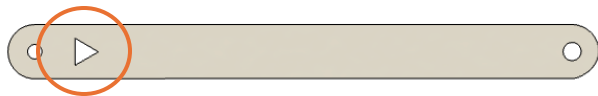


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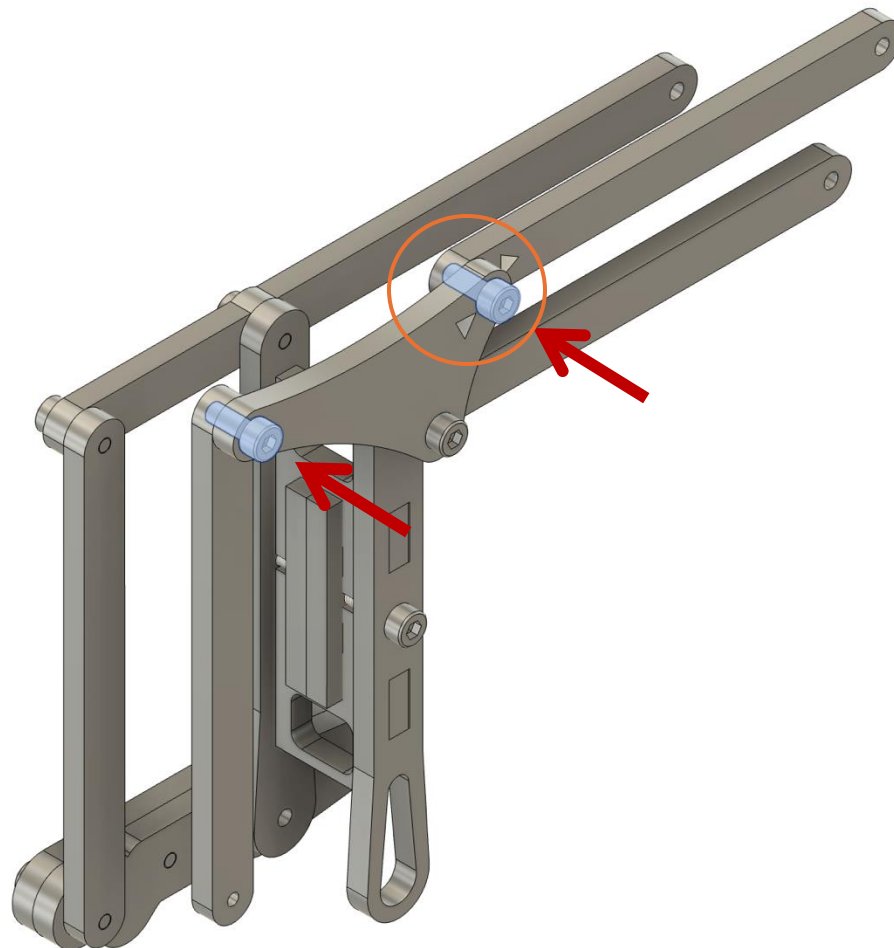




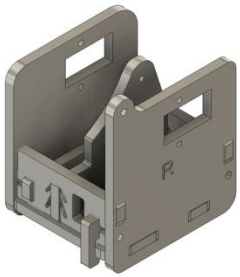




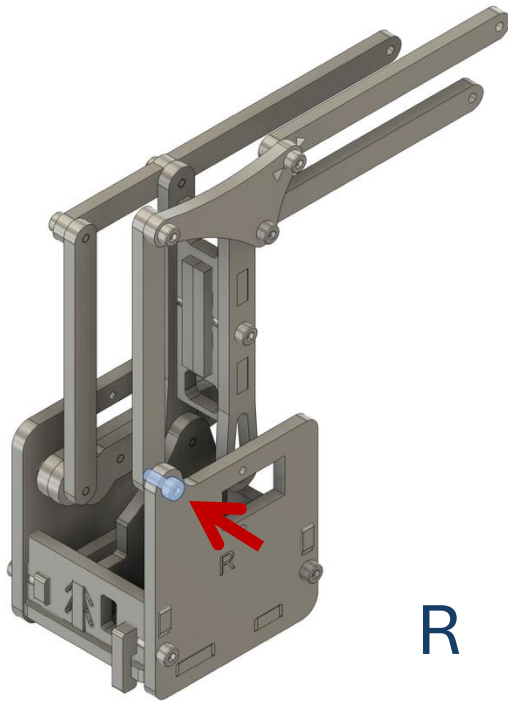
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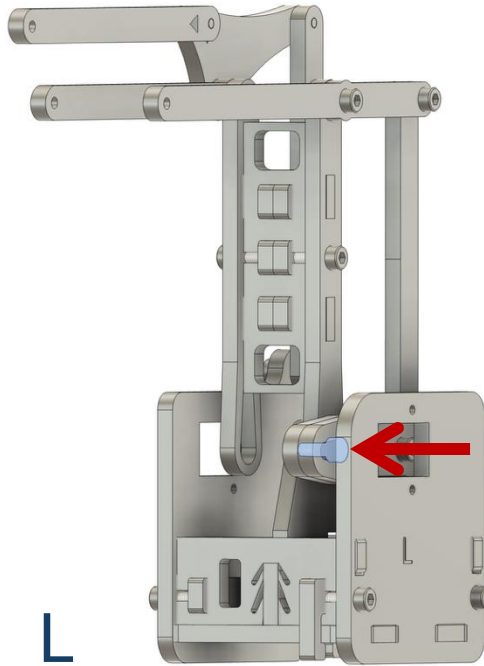




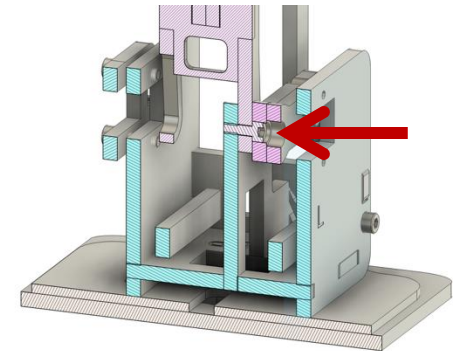
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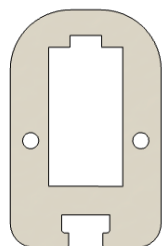
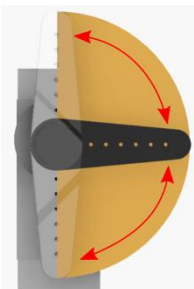


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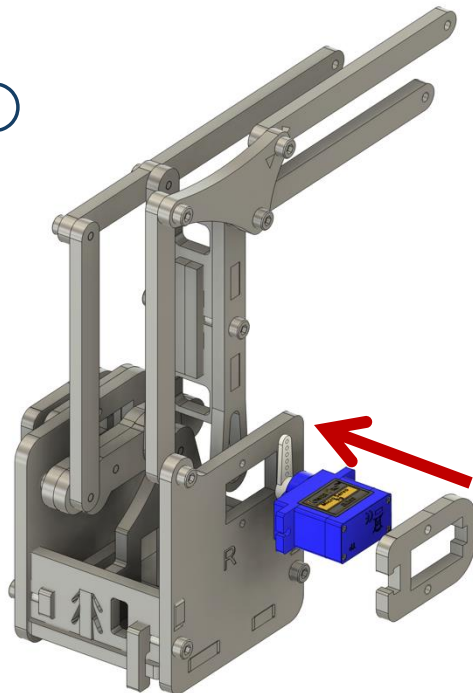
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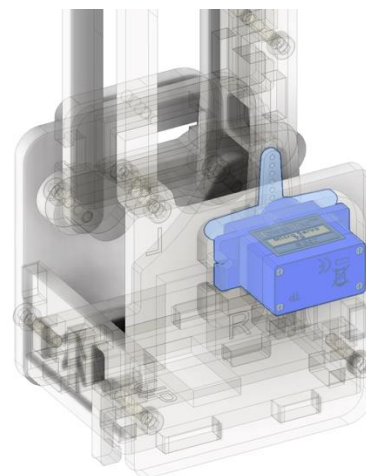
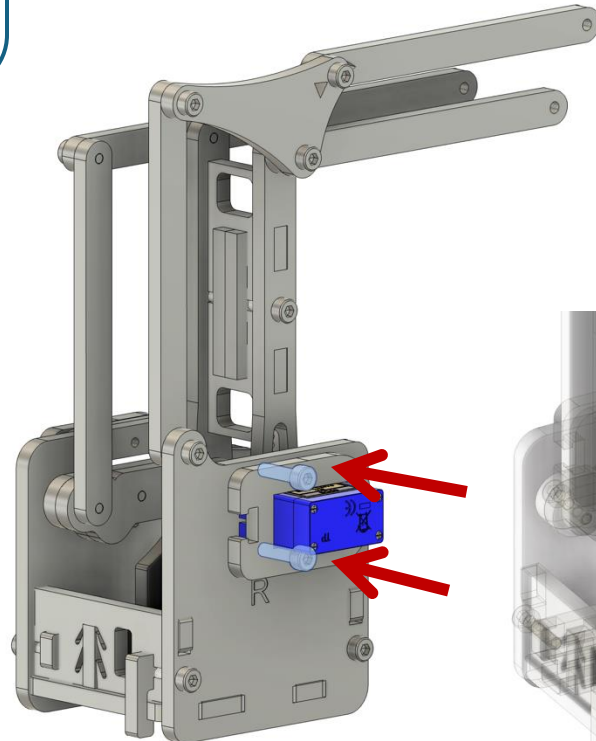


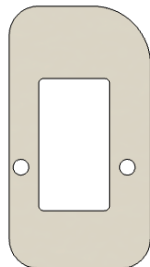
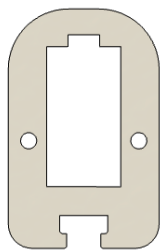
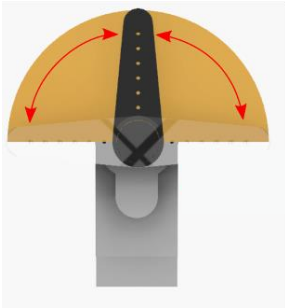
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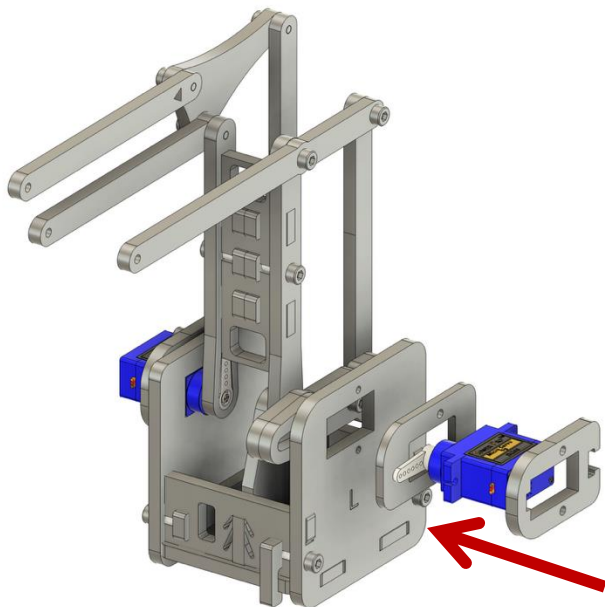
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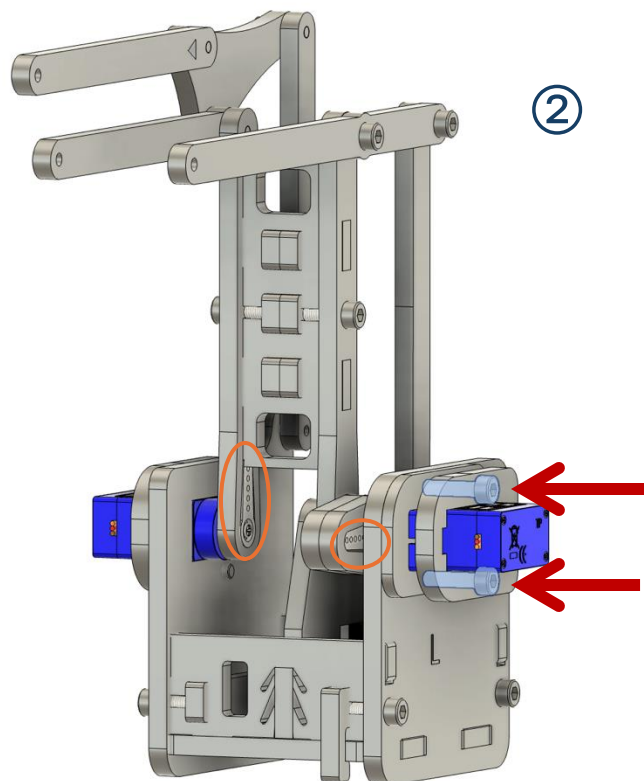


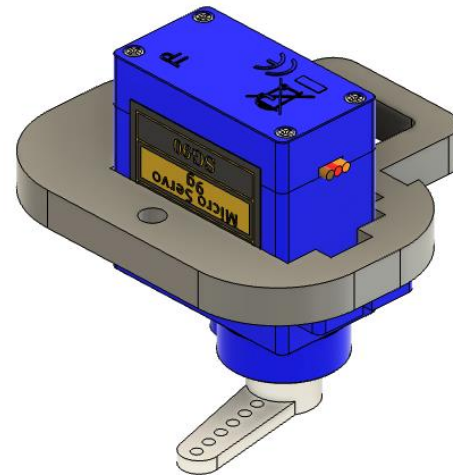
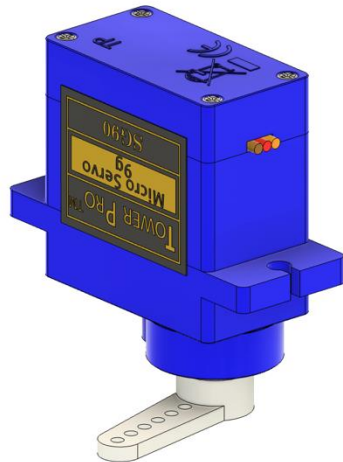
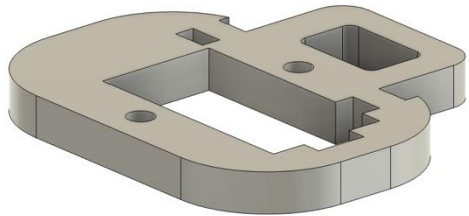
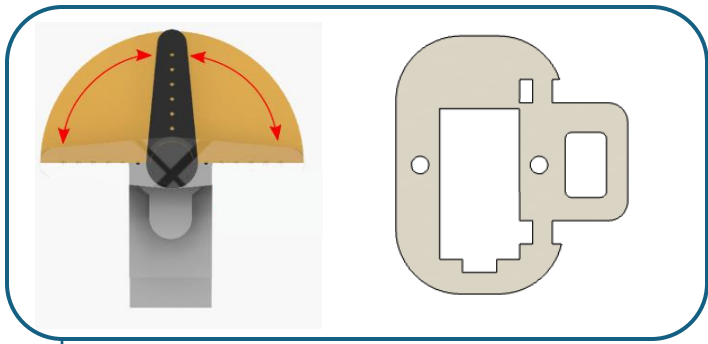
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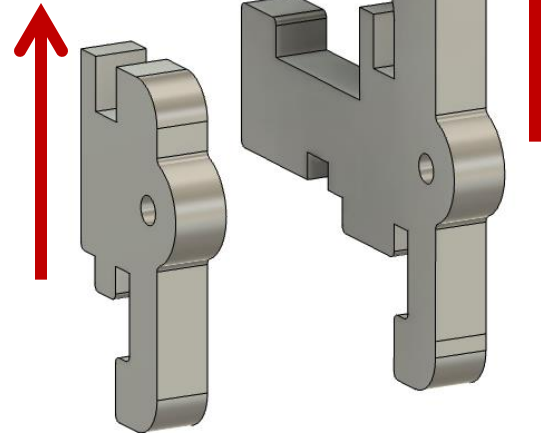
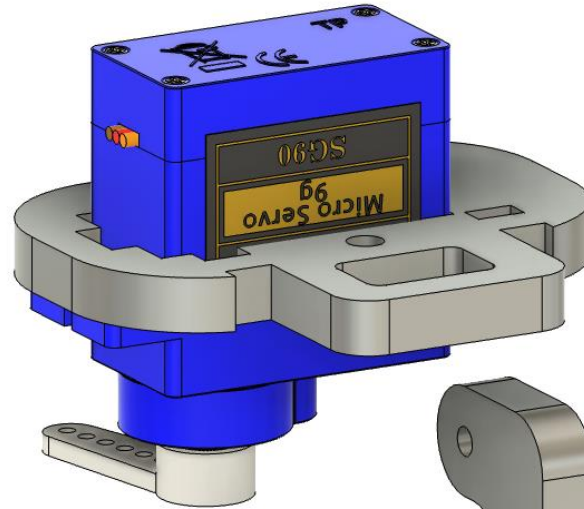
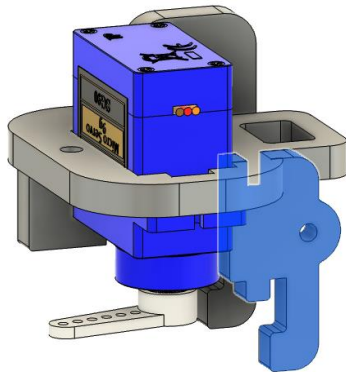
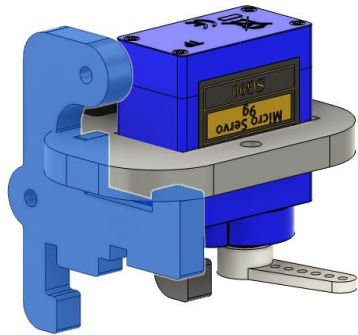
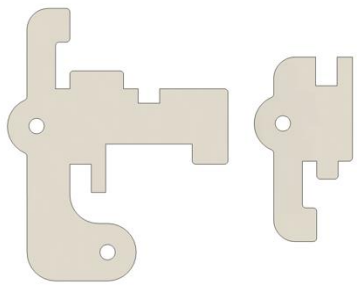
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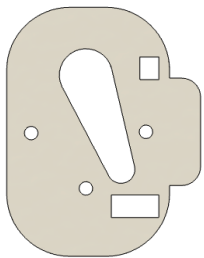


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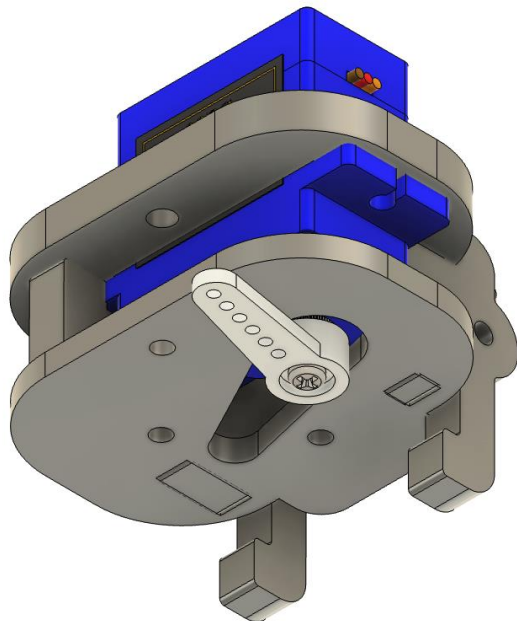




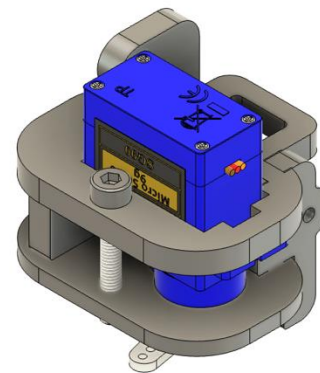
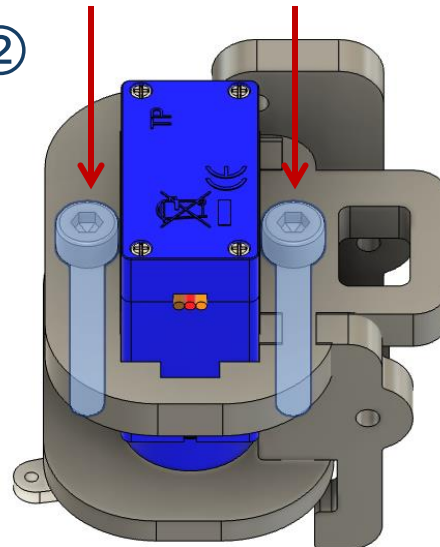


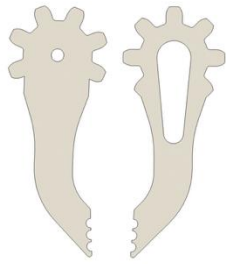
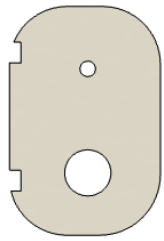
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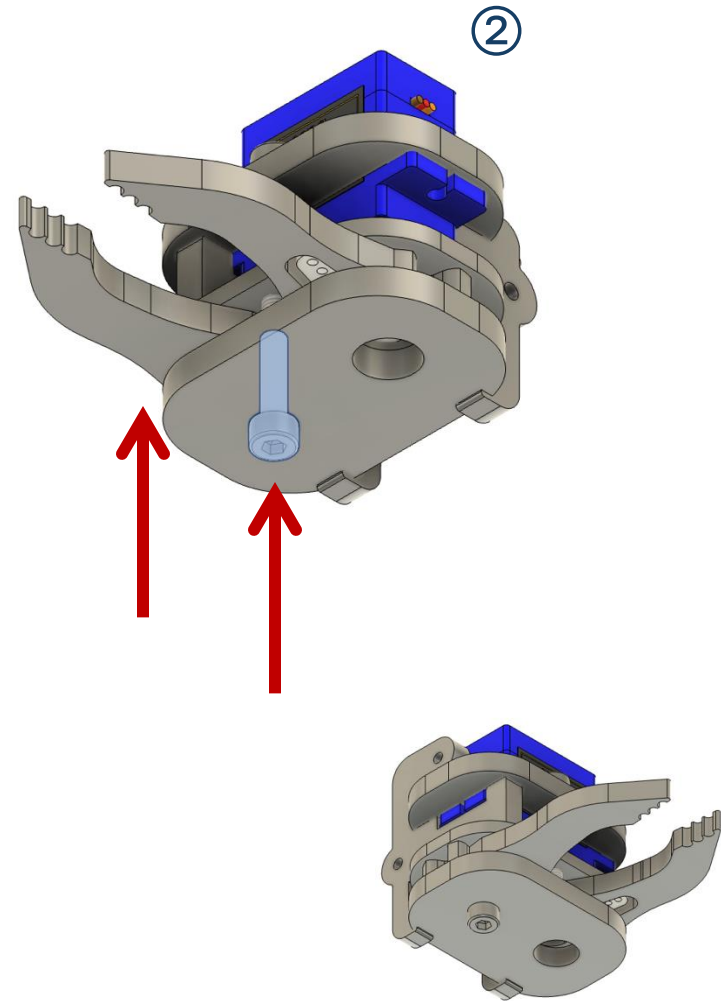
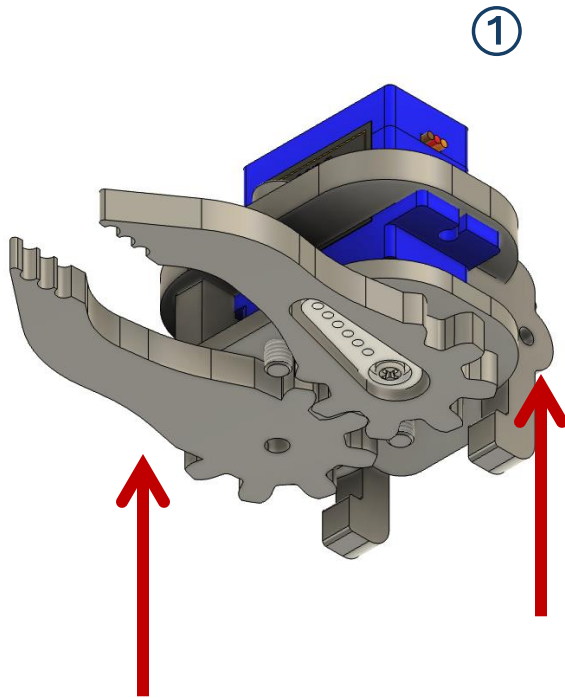


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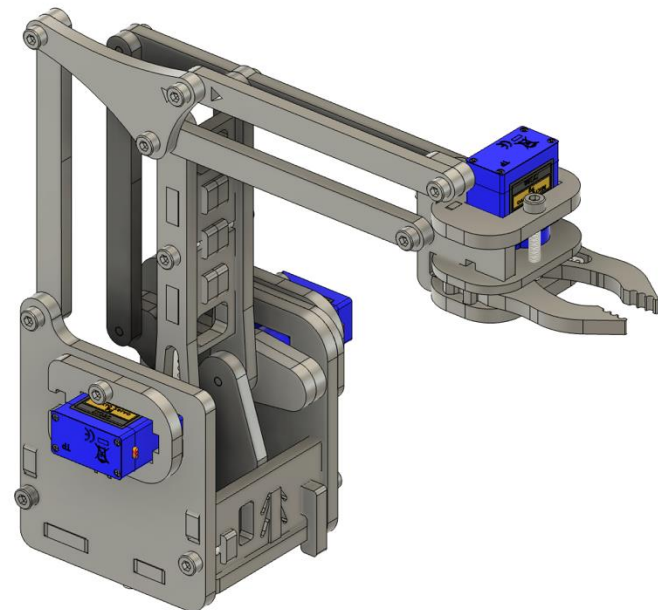
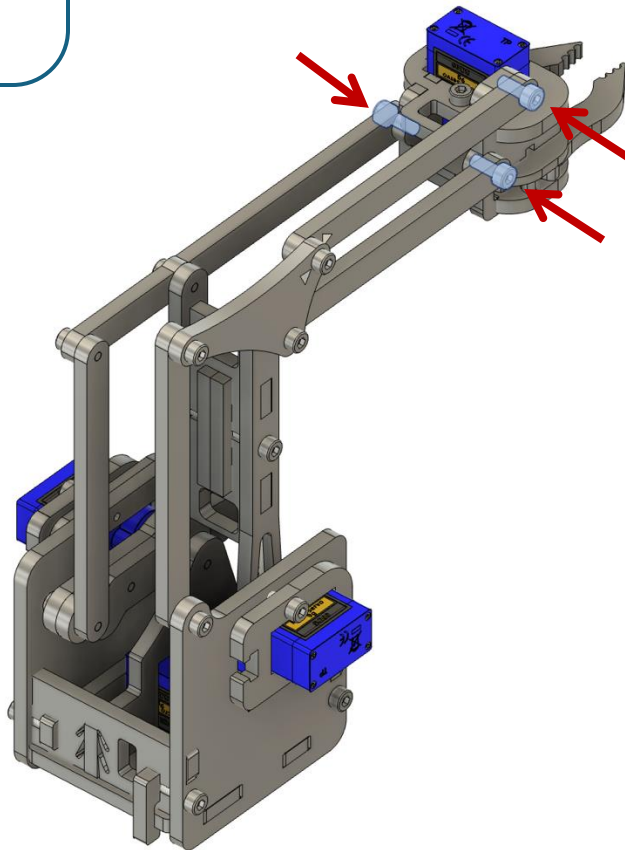
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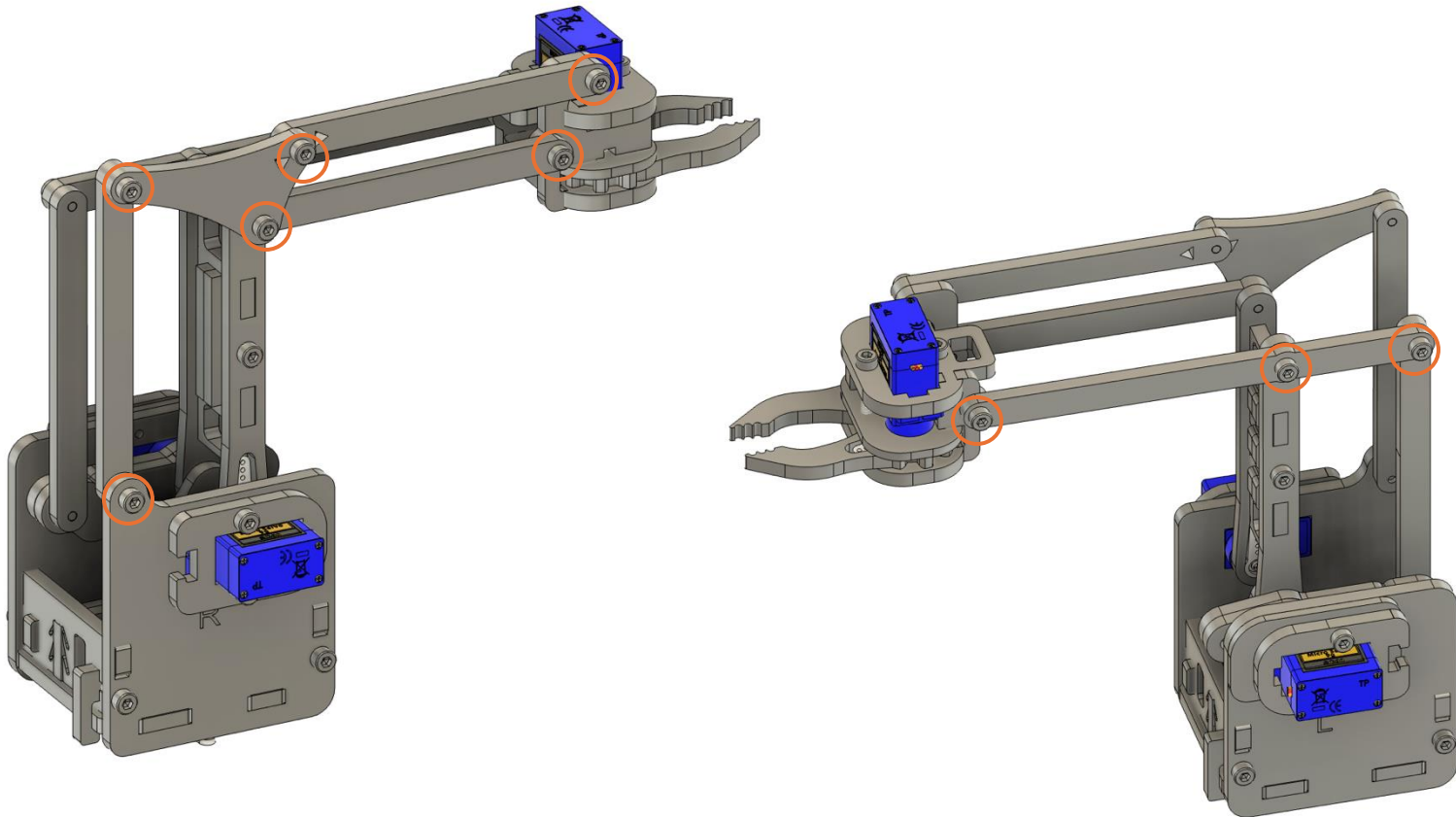


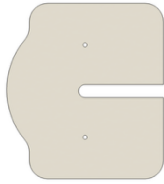
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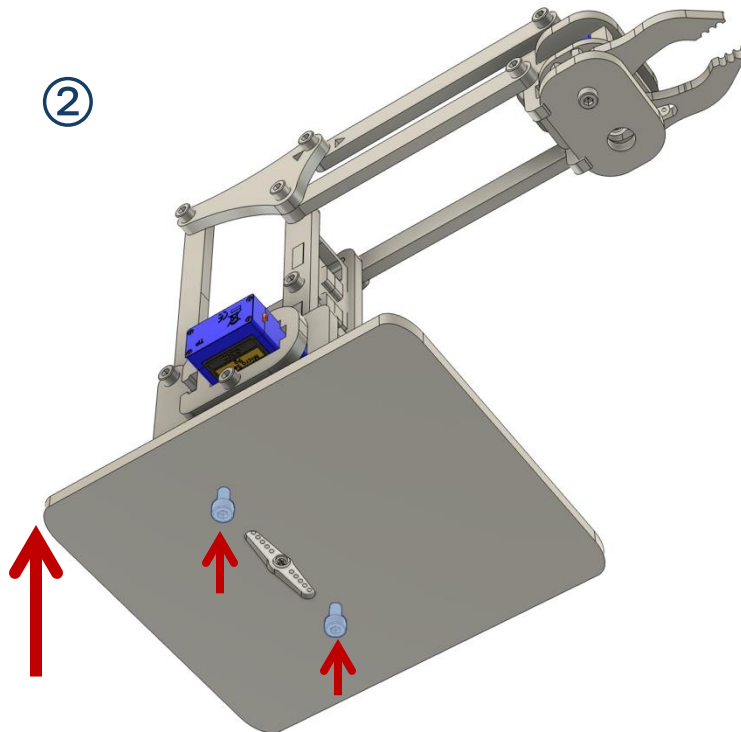
\*Check if all joints move with little friction, if not, loosen the screw a few turns.



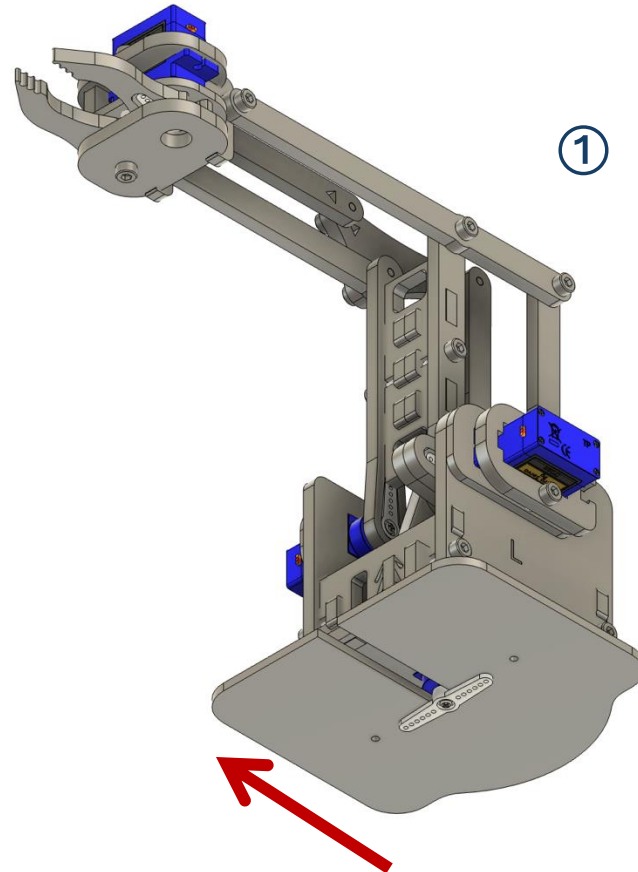


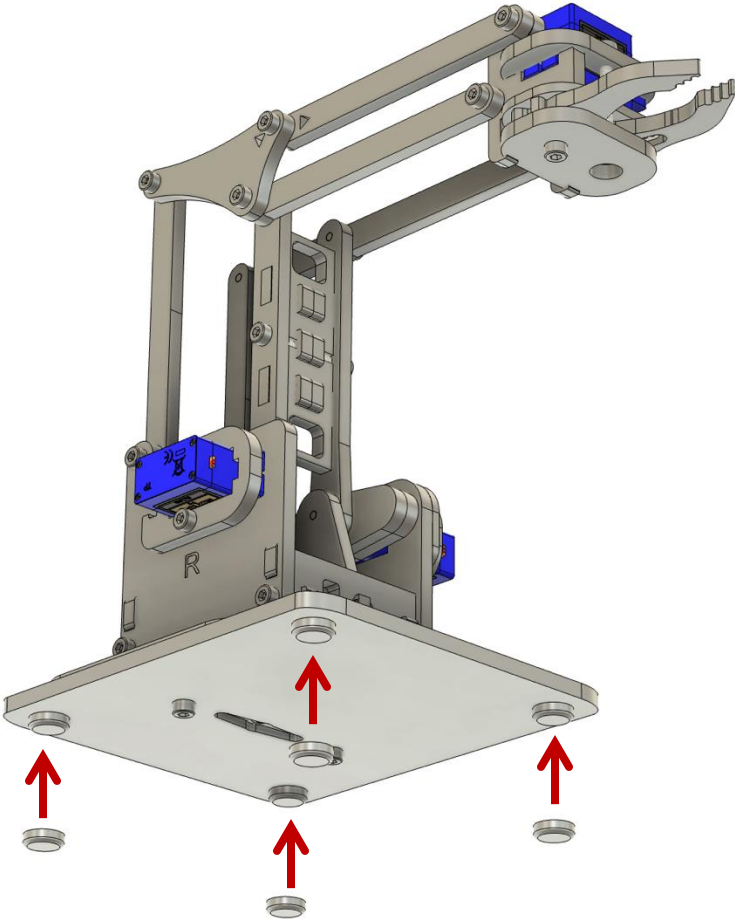
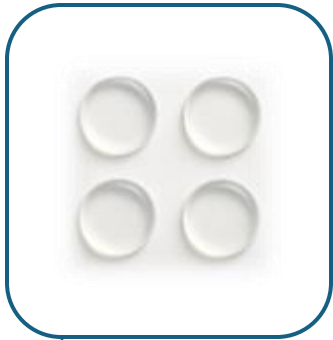
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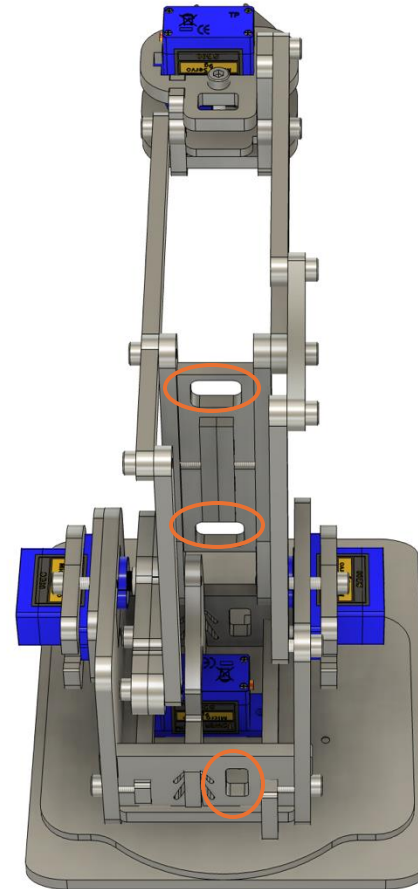
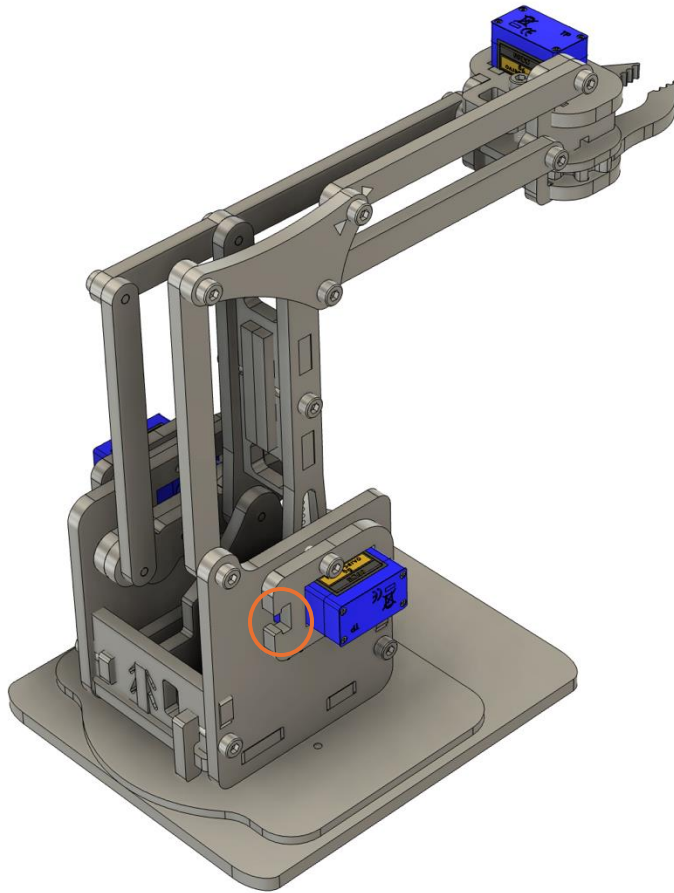


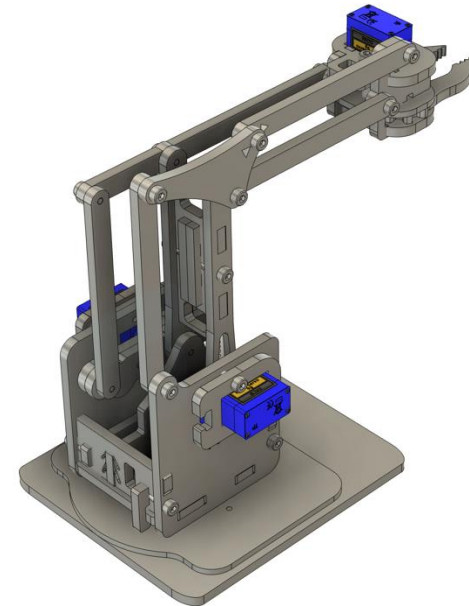
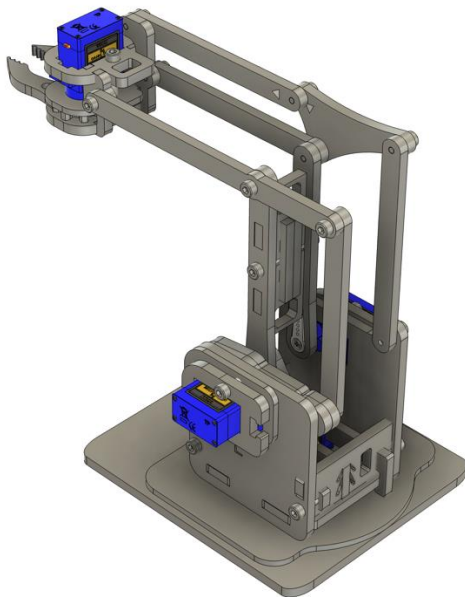
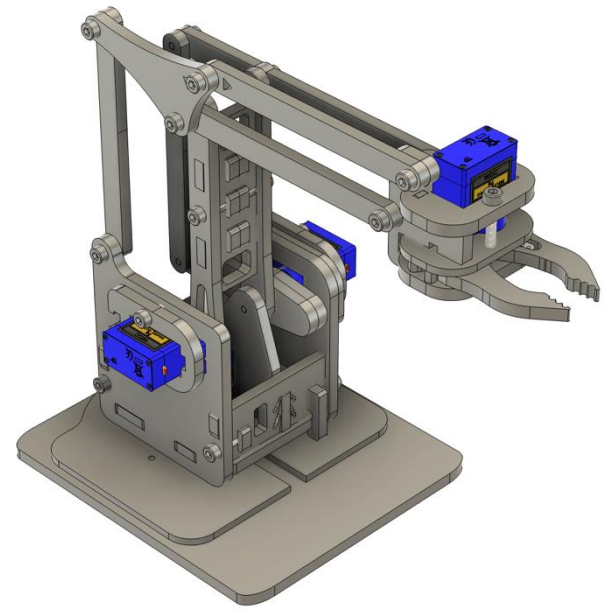
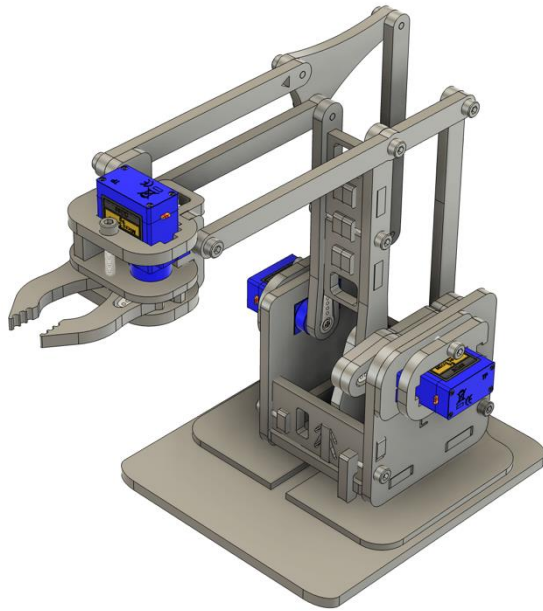
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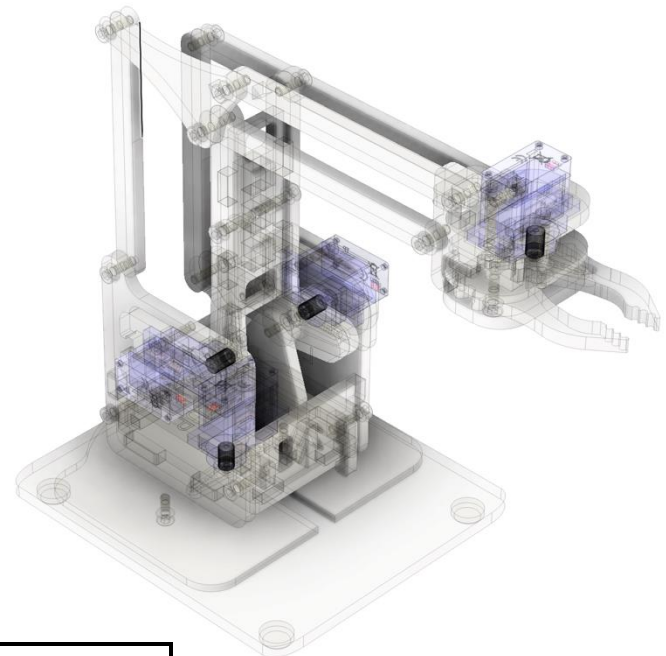
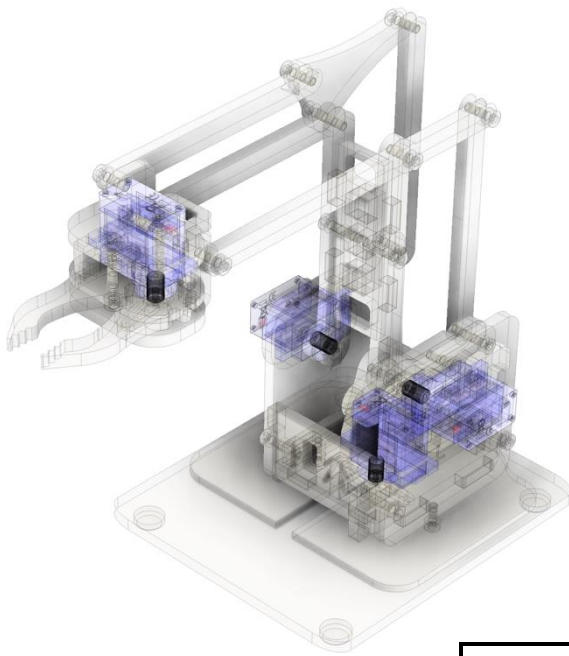




\*Use the holes to manage the servo cables.







Congratulations!

