

# Shadow - Bot

(IEDatron)

Group 32

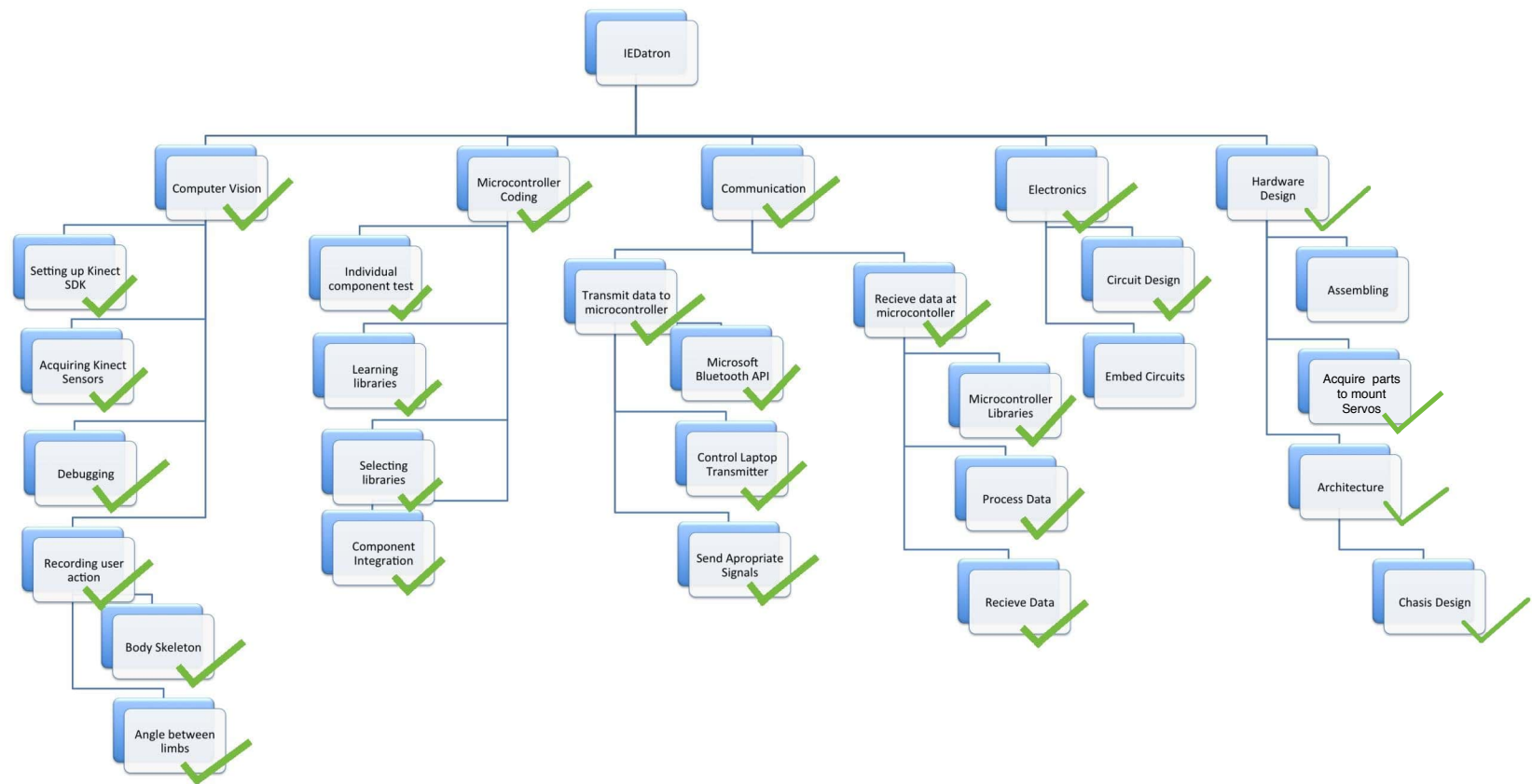
**Anant Sharma (2016129)**

**Aditya Chetan (2016217)**

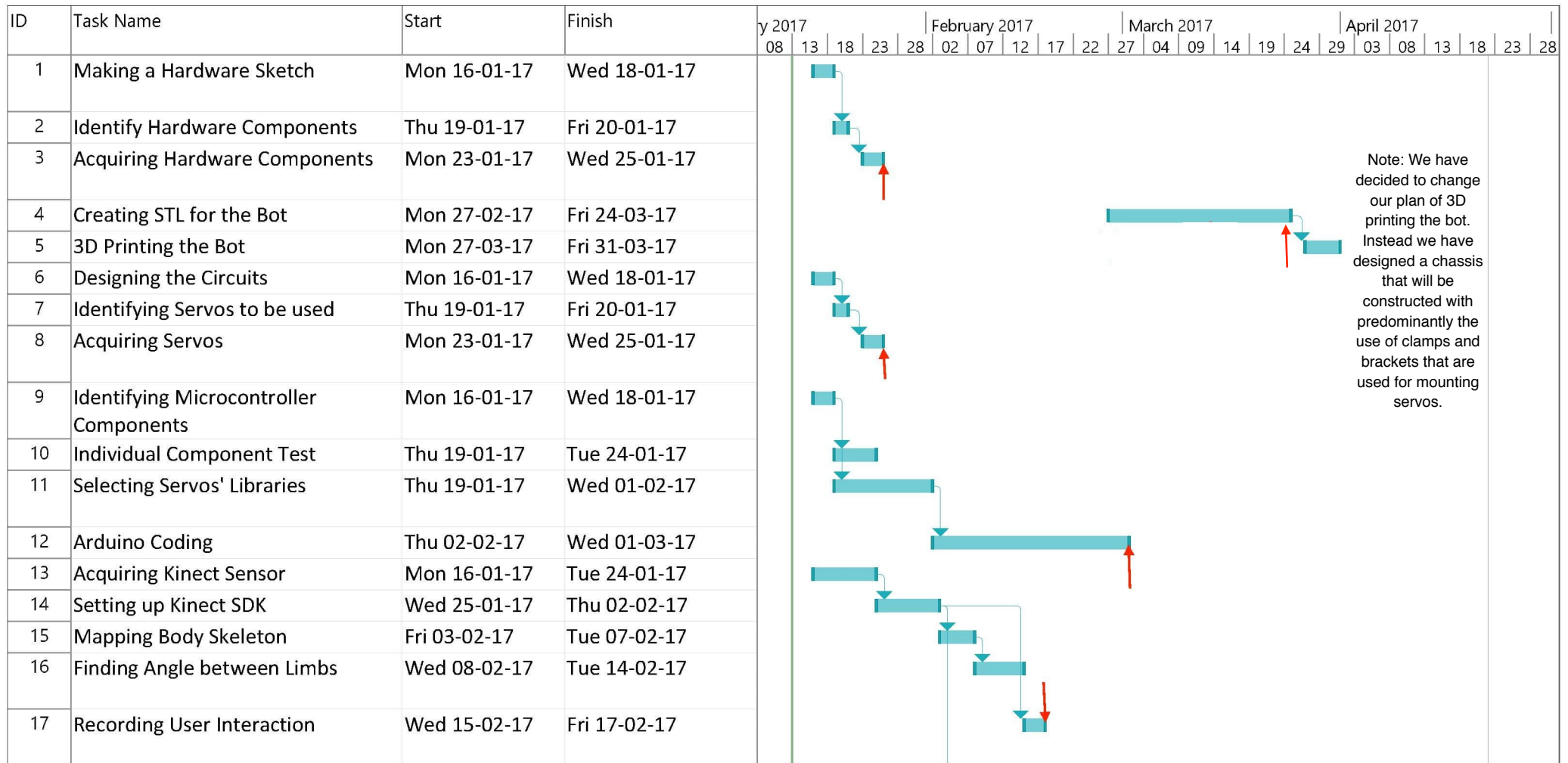
**Siddharth Yadav (2016268)**

**Shwetank Shrey (2016095)**




















# Work Breakdown Structure (WBS)

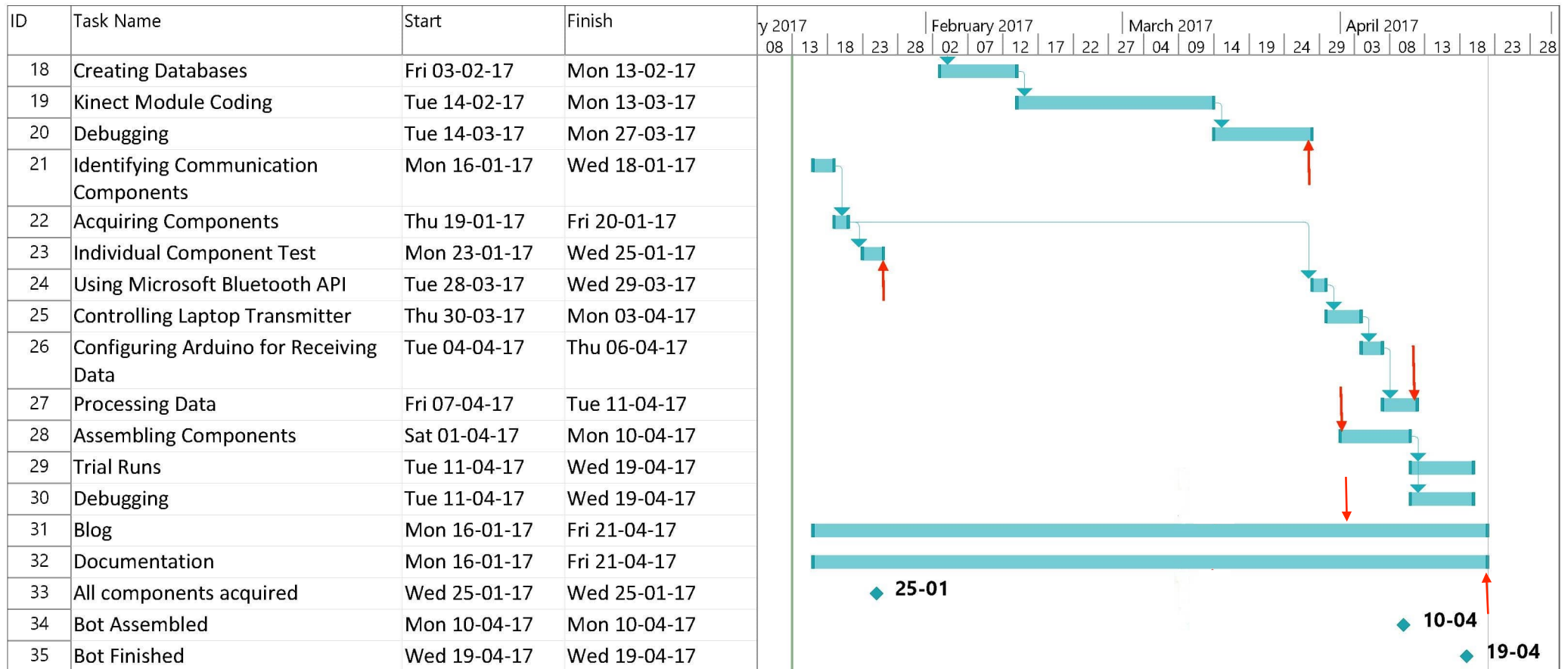


# Gantt Diagram






















Project: Project1  
Date: Fri 13-01-17

Task		Inactive Summary		External Tasks	
Split		Manual Task		External Milestone	
Milestone		Duration-only		Deadline	
Summary		Manual Summary Rollup		Progress	
Project Summary		Manual Summary		Manual Progress	
Inactive Task		Start-only			
Inactive Milestone		Finish-only			

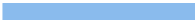




















Project: Project1 Date: Fri 13-01-17	Task		Inactive Summary		External Tasks	
	Split		Manual Task		External Milestone	
	Milestone		Duration-only		Deadline	
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	Split		Manual Task		External Milestone	
	Milestone		Duration-only		Deadline	
	Summary		Manual Summary Rollup		Progress	
	Project Summary		Manual Summary		Manual Progress	
	Inactive Task		Start-only			
	Inactive Milestone		Finish-only			



## **Note regarding changes:**

We have finally decided to do away with 3D printing entirely. Instead, we are going to construct the chassis out of brackets and clamps used for mounting servos, wooden parts, etc. This was done because we felt that 3D printing the chassis might complicate things for us as once printed, it would be difficult to make changes to the design if at all the need arises. Also, it was comparatively easier for us to obtain the parts that we feel necessary for our design.