

**Present Scenario**

Achintya and Vineeth are working on implementation of stereo vision with the dataset mentioned earlier.

Bhaskar and Rahul are analysing different fusion algorithm's efficiency and will start implementing those.

Expected (by the end of Dec)

Python implementation of both stereo vision and tof.

Finalizing 2/3 fusion algo based on their performance in python (as we'll also need to check hardware implementation)

Maybe starting to design fusion ip blocks.