Nyan Mouse Readme

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26th April 2014

Abstract

Nyan Mouse is made to display Nyan Cat like blinking and audio. From a hardware perspective, Nyan Mouse will offer an FPGA with a Nios II processor implemented on it along with some peripherals for quaterature decoding (including count and inter-step delay for speed). Everything should be capable of parallel-execution including maze solving. Maze solving, due to time constraints, will not be implemented in a hardware accelerated form. This will be Brandon's micromouse entry for 2014 if it is completed. Otherwise, Overvolt will be the micromouse of choice for racing.

1 Introduction

Micromouse as a competition creates an environment that requires the harmonious marriage between hardware and software. There are many arguments that feature software or hardware as the superior micromouse success determiner, but in the end a micromouse simulator that is beautifully coded exists only in the computer and a hardware implementation with the best hardware imaginable including support for wall decoding and time delayed illumination is only a brainless device that goes forward nonstop at an unimaginable speed (probably to crash into the wall ahead of it). Micromouse is not a simple thing to do in any sense unless one decides to make it simple (and ignore the fine detail present in any of the advanced topics which it can cover). The most important thing to have during micromouse is probably time management; humans – especially college humans – are only given a finite amount of time on micromouse. It is possible to extract time from other things, but that can end in disaster quite easily.

2 Implementing the Cat

2.1 Hardware

The hardware on this micromouse is fairly complex and a full explanation of the hardware cannot be achieved easily.

In short, the main board contains the non-controller parts of nyan mouse. This includes parts such as the motors, drive train, encoders, speakers, LEDs, and other rather important parts that have absolutely nothing to do with making a functional micromouse but instead add quirky features to a micromouse.

2.2 Software

The software on this mouse will be my old software that ran on Overvolt. The software is actually quite craptastinc in that it does not support full encoder guidance or mapping. In fact, only one encoder was

used because of circuit design errors encountered while not considering the therevin equivalence models of the quaterature encoders inside the Faulhaber motors.

3 Nyaning and Catting (Methods)

Nyanning and catting is achieved with the use of CAD software and implementation of the *Cyclone IV Handbook* along with various application notes such as those from Spansion (which creates the flash ROM).

Autodesk Inventor 2013 is used to do the 3D design of the micromouse (and will hopefully do the printed circuit board stacks as well).

Altera Quartus is used to instantiate the FPGA internals including the Nios II cores.

Altera Nios II developer (based on eclipse) is used to program the Nios II processor and generate the programming files.

KiCAD is used to generate the actual printed circuit boards (this makes a significant portion of available PDF documentation because of the ease in exporting KiCAD to schematic).

4 Is there any win to this game?

Nyan Cat as a game itself (if one can consider it a game), has no end but a definite beginning. By default, the counter on the nyan cat webpage will keep incrementing (perhaps until it overflows at some very large number). The purpose of this document was to explain what one would find in the micromouse folder and how it's supposed to work, but I forgot to do that and instead went on about the philosophy of micromouse.