## **IETF-109 Hackathon**

# **IPWAVE Basic Protocols Project**

November 9-13, 2020 Online Champion: Jaehoon Paul Jeong (SKKU)
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### IP Wireless Access in Vehicular Environments (IPWAVE) Basic Protocols

Champion: Jaehoon (Paul) Jeong (SKKU)

**Environment Setup** 



### **Professors:**

- Jaehoon (Paul) Jeong (SKKU)
- · Younghan Kim (SSU)

### Students:

- Yiwen (Chris) Shen (SKKU)
- Bien Aime Mugabarigira (SKKU)
- Xiaohong (Dawn) Yu (SKKU)
- Jae Won Lee (SKKU)
- Kyoungjae Sun (SSU)
- Jinho Park (KNU)

**Enabling OCB Mode** 





#### **WAVE Protocol Stack**



### Objectives:

- Demonstrate IPWAVE Basic Protocols
- IPv6 packet transmission by two OCB-enabled wifi modules
- Discover technology gaps for IPWAVE

### Where to get source code:

Git-hub open source:

https://github.com/ipwave-hackathon-ietf

### How to set up an environment:

#### Hardware

- Two laptops with AR94XX wifi modules (ath9k)
- Webcam: embedded or USB type

#### Software

- OS: OCB-enabled Linux kernel (version 4.4) in Ubuntu 18.04
- Tools: iw > v4.0

#### Implementation Contents:

- Develop a Vehicular Communication System for safe and secure driving using IETF IPWAVE protocols
- Transmission of IPv6 over IEEE 802.11-OCB
- Linux Kernel Compiling for OCB mode (Kernel version 4.4)
- Vehicular Mobility Information (VMI) option in IP-based vehicular network
- IPv6 packet transmission by two OCB-enabled WiFi modules
  - UDP Packets transmission by Python script
  - Video streaming by GStreamer







## Previous Hackathon Work

- IETF-106 Hackathon Project
  - IPv6 Packet Transmission over two OCB-enabled WiFi modules in vehicular networks

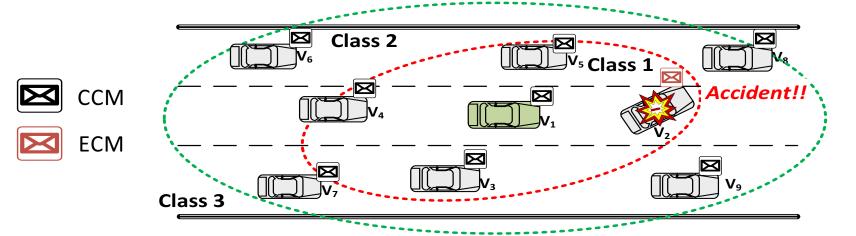
- IETF-108 Hackathon Project
  - Simulation of Context-Aware Navigation Protocol for road crash avoidance

## Hackathon Plan

- Support of Context-Aware Navigation Protocol over IPWAVE
  - draft-jeong-ipwave-context-aware-navigator-02
- To implement the enhanced IPv6 ND in Ubuntu Linux Kernel to enable the proposed a new ND option for vehicle driving safety.
- To test the modified Linux Kernel for a robot car (i.e., Aion Robotics R1) to verify the CNP for crash avoidance.
  - https://www.aionrobotics.com/products



## Context-Aware Navigation Protocol over IPWAVE

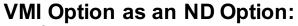


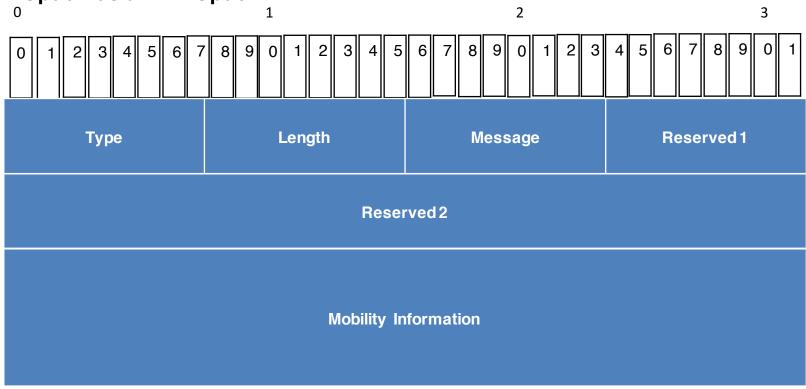
- \* Road-Context Awareness through Light-weight Message Exchange
  - Cooperation Context Message (CCM) and Emergency Context Message (ECM) Options

**Reference 1:** "Context-Aware Navigation Protocol for IP-Based Vehicular Networks", <a href="https://tools.ietf.org/html/draft-jeong-ipwave-context-aware-navigator-02">https://tools.ietf.org/html/draft-jeong-ipwave-context-aware-navigator-02</a>

Reference 2: "Context-Aware Navigator for Road Safety in Vehicular Cyber-Physical Systems", ICCE-Asia, June 2018. <a href="http://iotlab.skku.edu/publications/international-conference/ICCE-ASIA-CAN.pdf">http://iotlab.skku.edu/publications/international-conference/ICCE-ASIA-CAN.pdf</a>
IPWAVE Hackathon Project

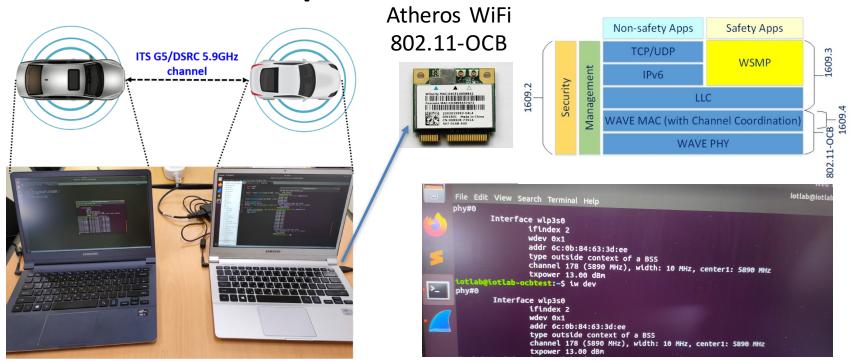
# Vehicle Mobility Information (VMI)





**Type: CCM or ECM Options** 

# Setup Environment



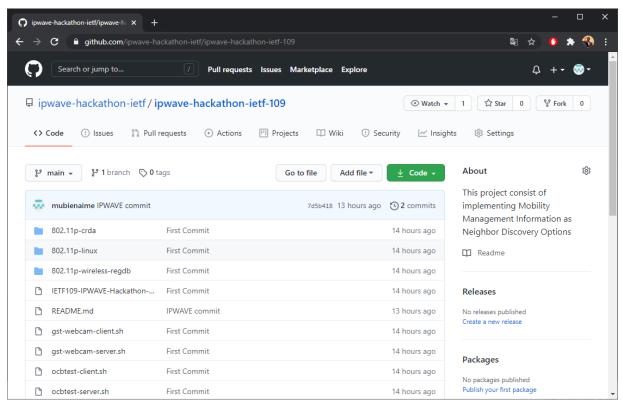
**Environment Setup** 

# What got done

- Extending the neighbor discovery options regenerates the kernel compilation errors.
  - It requires to make modifications to kernel kbuild (i.e., kernel configuration file).
- We got the feasibility to extend the Linux kernel's IPv6 neighbor discovery implementation and add the Vehicle Mobility Information (VMI) option for driving safety purpose.
- Next Steps
  - To fix the compilation errors for such VMI option.
  - To extend the IPv6 ND of Ubuntu Linux Kernel in a Robot Car to support Context-Aware Navigator Protocol over IPWAVE.

## Open Source Project at Github

https://github.com/ipwave-hackathon-ietf/ipwave-hackathon-ietf-109



# Wrap Up

### **Hackathon Team**

## Champion:

Jaehoon Paul Jeong (SKKU)

### Professor:

Younghan Kim (SSU)

### Students:

- Yiwen Chris Shen (SKKU)
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- Kyoungjae Sun (SSU)
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IPWAVE hackathon team worked in collaboration with I2NSF and BMWG teams.