

1 Introduction

1.1 Purpose

The purpose of this document is to describe the operating steps, description theory, and fault isolation procedures of the microdroplet impact analysis software.

1.2 Document Conventions

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1.3 Intended Audience

MATLAB Microdroplet Impact Analysis Application is designed for students, professors, professionals, and anyone interested in analyzing microdroplet impacts. This application was initially designed for Interfacial Fluid Dynamics Lab at Washington State University Vancouver. However, this is an open source program and can be used by anyone.

1.4 Product Scope

This applet is to be used for automated processing of microfluid droplet videos. This applet takes an input of .avi video files and provides a table of parameters for instantaneous primary droplet velocity, primary droplet spread radius, satellite droplet velocity, number of satellite droplets per frame, jet velocity, jet diameter, jet tip position, primary droplet contact angle, maximum primary droplet spread radius, and maximum primary droplet velocity. This data is intended for use in aiding research in microfluid behavior. This applet is not intended to replace logical reasoning, so data taken from this applet should be checked before use in academic research in case errors have occurred in processing.

2 Overall Description

2.1 Product Perspective

This applet reduces the need for extensive image processing training and coding for researchers, as it provides much of the basic parameters that are necessary for microfluid droplet analysis. However, this applet is a living code that needs continuous updates to be compatible with a wide range of droplet videos. At its current iteration, this applet can be used on droplets with high contrast against their environment that move vertically from the perspective of the camera.

2.2 Product Functions

The applet can be used to output:

- Basic microdroplet parameters, such as:
 - primary and satellite droplet velocity
 - primary droplet spread radius
 - primary droplet contact angle
 - jet speed
 - jet diameter
 - jet tip position
 - number of satellite droplets
- Individual processed frames with either droplet outlines or contact angle lines.

2.3 User Classes and Characteristics

The user classes for this applet include undergraduate, graduate, and postgraduate researchers as well as university instructors and researchers. Undergraduate researchers are likely to be using laptops or other computers with limited memory resources. These users will also be performing introductory levels of analysis of microfluid droplet behavior. Graduate, postgraduate, and university researchers are likely to have access to high performing computing, such as that provided by computing clusters. These users are likely to be performing higher level analysis of microfluid droplet behavior and are more likely to be able to spot processing errors if they arise. For all user classes, this applet provides many of the key parameters necessary for conducting microfluid droplet analysis without the need to learn image processing algorithms or extensive MATLAB coding tools.

2.4 Operating Environment

This applet was created in MATLAB, which has been tested on Mac, Windows, and Ubuntu operating systems. This applet was created and tested using Windows.

2.5 Design and Implementation Constraints

This applet is constrained to use on microfluid droplet videos in the .avi format. Future iterations may be implemented for use with a wider range of video formats. The applet is also unable to process droplets that are clear or provide little contrast to the background. Input videos must be converted to grayscale prior to use in the applet. The user is expected to provide high quality input videos for optimal processing.

2.6 User Documentation

Any user of this applet is the target audience of this user documentation. For users that may be altering the code of the GUI or image processing functions, additional documentation found on the MathWorks website is suggested as a supplemental resource.

2.7 Assumptions and Dependencies

It is assumed that all users of this applet have at least a basic understanding of microfluid analysis and an ability to understand MATLAB error messages.

3 GUI User Guide

In this chapter, a step-by-step guide for the use of the GUI is provided, with images.

3.1 Installation

Step 1. Double left-click on GUI_Design.mlappinstall.

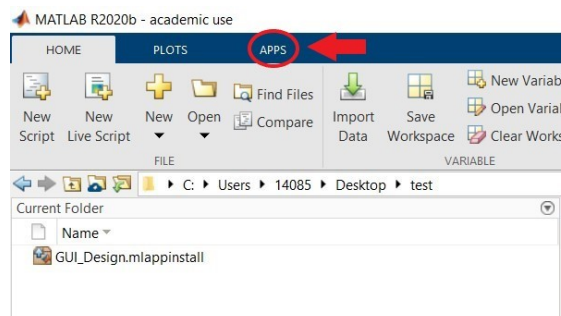
Step 2. Left-click on "Install" on pop-up window.



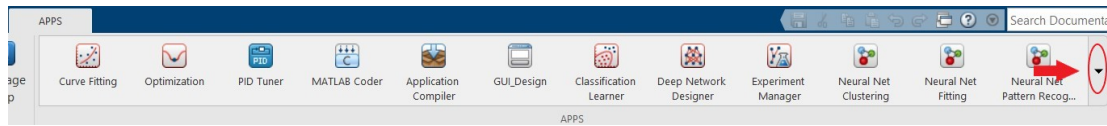
3.2 Opening the Applet

Step 1. Open MATLAB.

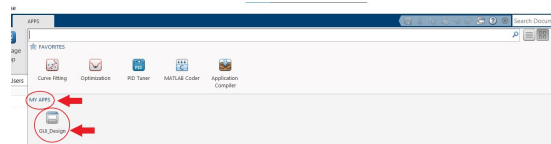
Step 2. Left-click on the "APPS" tab in the top left corner of the MATLAB environment



Step 3. Left-click on the dropdown menu in the APPS bar.



Step 4. From the dropdown menu, left-click GUI_Design from the "MY APPS" section.



3.3 Using the Applet

3.3.1 Uploading a Video

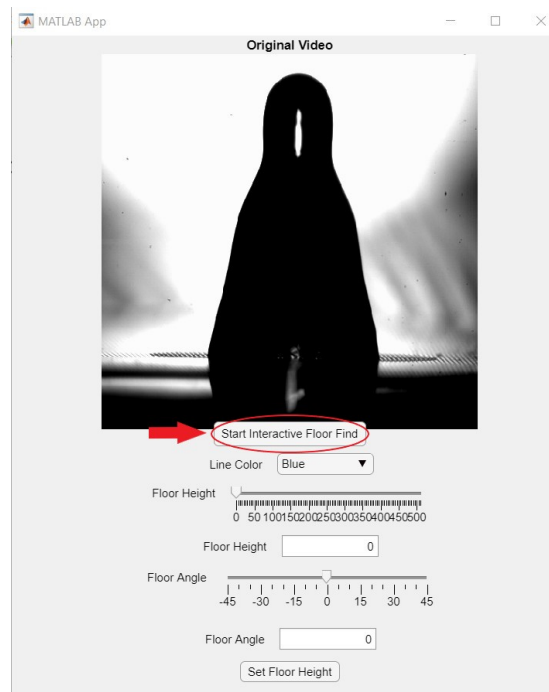
Step 1. Left-click on the "Upload Video" button.



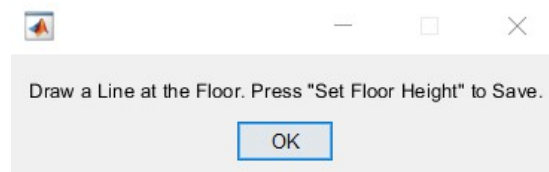
Step 2. Select the video you would like to upload from the File Explorer window. Select "Open" to open that video file in the applet. The applet will open a secondary window for floor selection. You can either use the interactive floor finding or input the floor height in pixels and the floor angle.

Interactive Floor Finding

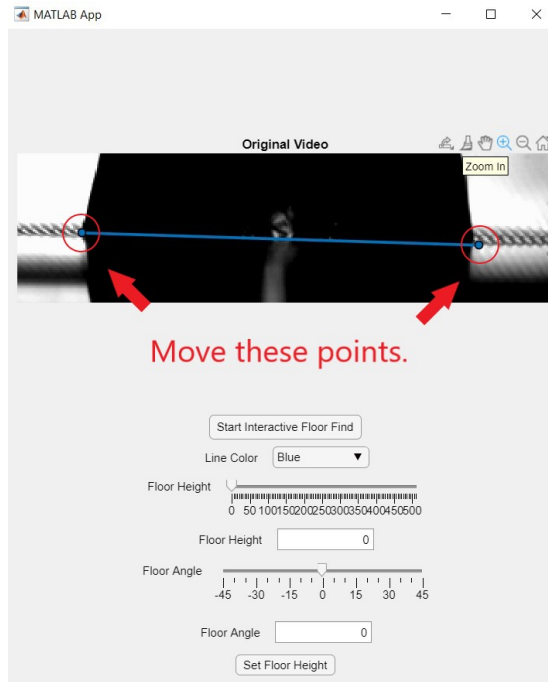
Step 1. Left-click the "Start Interactive Floor Find" button.



Step 2. An instructional message will appear, informing the user that they can now draw a line at the floor on the video frame. Press the "OK" button to proceed with the interactive floor finding.



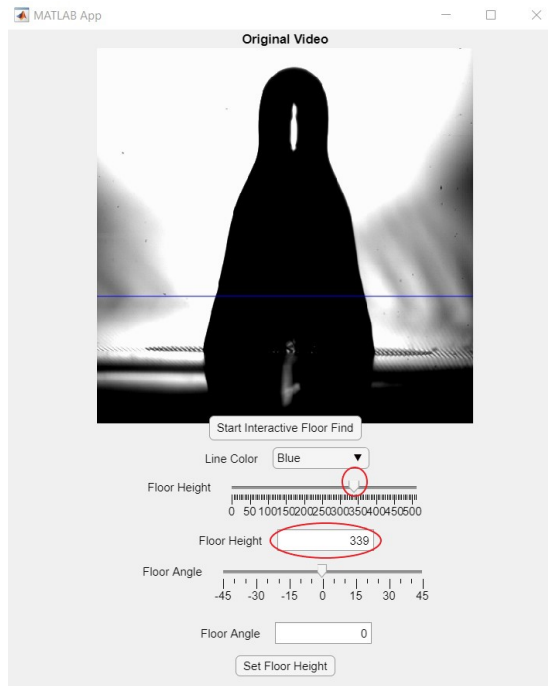
Step 3. Left-click and drag on the image to draw a line for the floor. To move this line, left-click and drag either blue dot at the ends of the line. Use the "Zoom-In" feature in the upper right-hand corner of the image to get a better look at where the floor line is located on the image. Continue manipulating the line by moving the blue dots until the interactive floor line matches the line of the floor in the original image. Press "Set Floor Height" Button once the interactive line is aligned.



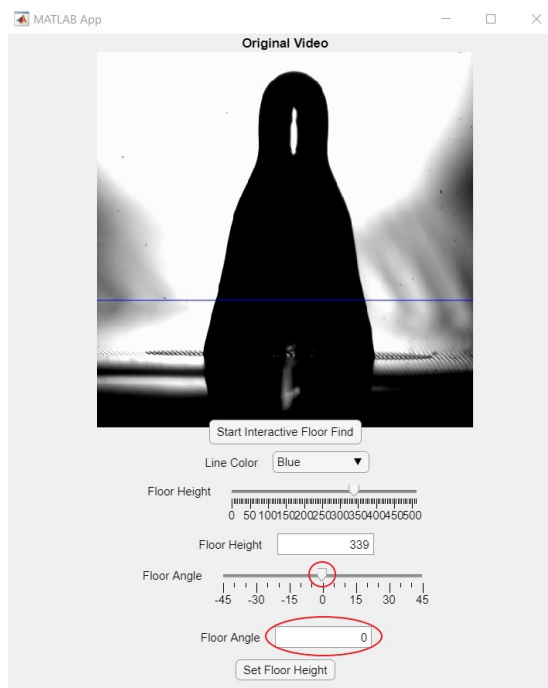
Manual Floor Height and Angle Entry

During the manual floor height and angle entry process, if the line is difficult to see, the user can select a different line option from the "Line Color" dropdown menu. This feature is **ONLY** available for the line printed by manual floor height and angle entry.

- Step 4. Move the slider next to "Floor Height" or manually enter floor height value into the textbox below to set a floor height. Note: "Floor Height" is measured in pixels, counting the number of pixels from the top of the image to the centermost pixel of the floor line.



Step 5. Move the slider next to "Floor Angle" or manually enter floor angle value into the textbox below to set a floor angle.



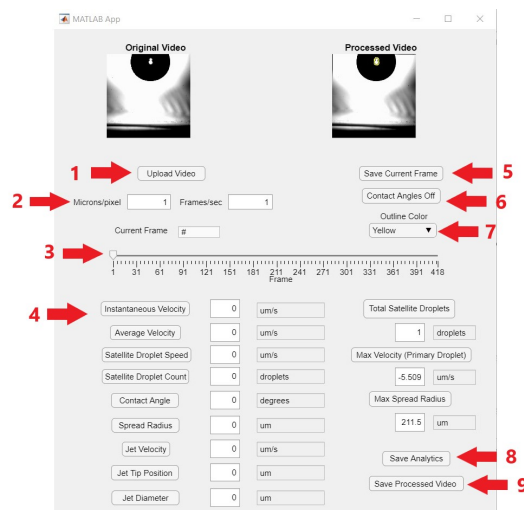
Step 6. Once both floor height and floor angle are at the correct values, left-click the "Set Floor Height" button to input the floor values.

Step 7. Once the floor height and angle has been set, the applet will process the entire video, then display the processed video. Please note, this process takes a lot of computation and will take time, especially on computers with limited processing power.



3.3.2 Applet Features

The following section describes the function and interactivity of each feature, listed in order as marked in the figure below.



Feature 1. Upload Video Button.

Function: The upload video button allows the user to select a video file from the

file explorer window to upload to the applet for processing.

Interactivity: The user can press the button to activate the button-down callback.

Feature 2. Micron/pixel and Frame/sec text boxes.

Function: These text boxes are used to change the micron/pixel ratio and frame/second ratio for the parameters found by the applet. The applet automatically converts all values using the user's input.

Interactivity: The user can type a decimal value into the text boxes to activate the value changed callback.

Feature 3. Frame Slider.

Function: The frame slider is used to change the current frame displayed in the original and processed video image boxes. This also changes the displays of all of the parameter text boxes to show the value of each parameter at the newly selected frame. The frames and values change in realtime as the user interacts with the slider.

Interactivity: The user can right-click on any point along the line to activate the value changed callback. The user can right-click and drag the indicator along the line to activate the value changing callback.

Feature 4. Parameter Text Boxes.

Function: The parameter text boxes display the various calculated parameters that the applet obtains from the video. Some values displayed are calculated per frame, while others are calculated for the entire video (i.e. max spread radius is the maximum for the whole video).

Interactivity: The user cannot interact directly with these text boxes.

Feature 5. Save Current Frame Button.

Function: The save current frame button allows the user to save the image displayed in the processed video image box as an image in the directory of their choice from the file explorer window. This image is named by the user through the file explorer window.

Interactivity: The user can press the button to activate the button-down callback.

Feature 6. Contact Angles On/Off.

Function: The contact angles on/off button allows the user to switch between displaying the border line around the processed image, indicating the edge detected by the applet, and the contact angle lines, indicating the angle of the point of contact of the droplet with the floor. When the button displays "Contact Angles Off", the processed video image box will show the bordered image. When the

button displays "Contact Angles On", the processed video image box will show the contact angle image.

Interactivity: The user can press the button to activate the button-down callback.

Feature 7. Outline Color Dropdown Menu.

Function: This menu allows the user to select the color of the lines drawn over the processed video image within the processed video image box. The user can select yellow, red, green, or blue.

Interactivity: The user can press the arrow to open the menu, then select a color to activate the value changed callback.

Feature 8. Save Analytics Button.

Function: The save analytics button allows the user to save the processed data for the entire video to a single file. The data is organized into a table with columns that correspond to each parameter and rows that correspond to each frame. This table is named by the user through the file explorer window.

Interactivity: The user can press the button to activate the button-down callback.

Feature 9. Save Processed Video Button.

Function: The save processed video button allows the user to save the processed video in the directory of their choice from the file explorer window. This video is named by the user through the file explorer window.

Interactivity: The user can press the button to activate the button-down callback.

4 System Functions

In this chapter each of the image processing and droplet analysis functions are described. A paragraph of the system theory is given and describes the overall operation of the function and the variables in it. A fault isolation section is also provided which gives solutions and fixes to possible issues that may arise.

4.1 borders

4.1.1 Theory and Description

The borders function is the second video processing function applied to the source video.

4.1.2 Fault Isolation

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4.2 fallVelocity

See also: [video2frame](#), [floorremove](#), [borders](#)

4.2.1 Theory and Description

The function fallVelocity finds and tracks the centroids and velocities of all objects in an input four-dimensional borders matrix of data type uint8. This function finds the speed and frame of impact of the main droplet, records the centroids and velocities of all tracked objects per frame, and tracks the total number of satellite objects found in the video. The function can be called as follows:

```
[dropletVelocity, impactData, numberOfSatellites] =  
fallVelocity(videoFloorRemoved, floorHeight)
```

Where numberOfSatellites is an integer number of satellite droplets in the video, impactData is a two-element array where the first element is the downwards velocity of the first droplet at impact as a double and the second element is the frame at which the droplet made impact, and dropletVelocity is a three-dimensional array of the size [4,numberOfSatellites+1,Frames]. dropletVelocity is formatted as follows:

```
[Centroid1_X, Centroid2_X, Centroid3_X, Centroid4_X;...
Centroid1_Y, Centroid2_Y, Centroid3_Y, Centroid4_Y;...
Velocity1_X, Velocity2_X, Velocity3_X, Velocity4_X;...
Velocity1_Y, Velocity2_Y, Velocity3_Y, Velocity4_Y...]
```

videoFloorRemoved is the four-dimensional matrix output from the floorremove function. floorHeight is the value tracking the height of the floor; it is used to find the frame of impact.

4.2.2 Fault Isolation

This functions currently does not have fault isolation. This function needs to be able to reliably identify and track droplets even when they pass off screen. This has not been implemented and may cause errors. In addition, the floor impact data relies heavily on the floorremove function. If there are errors, check floorremove and floor GUI.

4.3 contactAngles

See also: [video2frame](#), [floorremove](#), [borders](#), [drawContactAngles](#)

4.3.1 Theory and Description

The function contactAngles finds the angles of the contact the droplet has with the floor and the locations of contact. This function can be called as follows:

```
[contactAngle, contactPoints] =
contactAngles(imageFloorRemoved, floorHeight, numberOfPoints, polyOrder)
```

The inputs are the following: imageFloorRemoved, the four-dimensional matrix from the floorremoved function; floorHeight, the floor pixel height used in the floorremoved function; numberOfPoints, the number of sample points along the edge of the droplet to calculate the contact angles. Default: 10; polyOrder, the polynomial order used to calculate the contact angles. Default: 2. numberOfPoints must always be greater than polyOrder. The outputs are as follows: contactAngle is a two-dimensional matrix of the size [2,Frames]. The first value of contactAngles is the right contact angle, while the second value is the left contact angle. contactPoints is a three-dimensional of the size [2,2,frames]. contactPoints is formatted as follows:

```
contact[1, :, :] is the right contact point.
contact[2, :, :] is the left contact point.
contact[:, 1, :] is the x value.
contact[:, 2, :] is the y value.
```

The contactAngles function works by collecting a series of points on either side of the droplet once it has contacted the floor. Those points are then used to create a polyfit estimation of the curve of the droplet. Once the derivative of the polyfit is found the slope at each contact point, found using the floorHeight input, is calculated. The slopes are converted into degrees and saved.

4.3.2 Fault Isolation

contactAngles as two optional inputs. If numberOfPoints and polyOrder are not entered, that is:

```
[contactAngle, contactPoints] =contactAngles(imageFloorRemoved, floorHeight)
```

then default values for those inputs are used. There is no error checking to ensure that the found contact angles make sense. Instead, those additional options were created to allow for more refined configurations. contactAngles relies heavily on floorremove. If the user input floorremove settings are inaccurate, this function will be prone to create errors.

4.4 convertSource

See also: [video2frame](#), [floorremove](#), [maskOverlay](#)

4.4.1 Theory and Description

The function convertSource converts an input video frame matrix, referred to as videoSource, to an RGB video frame matrix of data type of uint8. This function also rotates videoSource to match the rotation of the analyzed frames. The function can be called as follows:

```
convertedVideoSource = convertSource(videoSource, floorAngle)
```

Where convertedVideoSource is a four-dimensional matrix of data type uint8 and the form [Height, Width, 3, Frame]. convertedVideoSource is the same size as videoSource but has a video mode of 3. floorAngle is given in degrees.

4.4.2 Fault Isolation

This function is compatible with RGB24 and greyscale videoSource matrices for future compatibility. If videoSource is off the wrong format, not a four-dimensional matrix or videoMode is not either 1 or 3, this function will halt and report the following error:

'Unexpected Source Matrix format. Please provide a grayscale image, an RGB image, or a binary image.'

If you receive this error, videoSource may have been changed after video2frame, or video2frame encountered an uncaught error importing the video.

4.5 drawContactAngles

See also: [maskOverlay](#), [outlineMask](#), [contactAngles](#),

4.5.1 Theory and Description

The function `drawContactAngles` creates a post-processing video frame matrix mask showing the contact angles with a predefined line length. The returned video mask is Boolean black-and-white 4D video matrix of the height, width, and length defined by the `videoSize` input. The function can be called as follows:

```
maskAngle = drawContactAngles(videoSize, contactAngle, contactPoints, lineLength)
```

Where `videoSize` is a four-element integer array of the form [Height, Width, videoMode, Frames], `contactAngle` is the contact angle matrix from the `contactAngles` function, `contactPoints` is the contact position matrix from the `contactAngles` function, and `lineLength` is an integer line length.

`drawContactAngles` creates this contact angle video mask by first creating a four-dimensional Boolean matrix of the size [videoHeight, videoWidth, 1, videoLength] set to false. Each contact angle in each frame is defined by the variables `lineX` and `lineY`, where `lineX` is an array of linearly spaced integer x-axis values between $(contactPointInX \pm LineLength * Cos[contactAngle])$

`lineY` is a similar array in the vertical direction with the same number of elements. Together `lineX` and `lineY` make up linearly spaced integer coordinate pairs. If either value in each coordinate pair is outside the height or width range of the video, that pair is removed from the set [lineX,lineY]. The [lineX,lineY] coordinate pairs are then used to set the corresponding pixels in each frame to true. This process is repeated for each contact point in each frame of the video.

4.5.2 Fault Isolation

By removing any points that are outside of the given range, the video mask matrix will always match the `videoSize` dimensions provided. This function can handle non-integer `lineLength` values, but it will be rounded down to the nearest odd number. This function skips drawing contact angles for frames where either the contact point or the contact angle is undefined, meaning this function works when there are no contact angles to draw. There is no error checking for the `videoSize` inputs.

4.6 calculateVelocity

4.6.1 Theory and Description

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4.6.2 Fault Isolation

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4.7 floorremove

4.7.1 Theory and Description

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4.7.2 Fault Isolation

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4.8 frame2file

See also: [floorremove](#), [video2frame](#), [convertSource](#), [maskOverlay](#)

4.8.1 Theory and Description

frame2file takes a frame from a video frame matrix and saves it as an image file at a chosen location. This function is compatible with RGB24 and greyscale video frame matrices. The file may be saved as .bmp, .gif, .hdf, .jpg, .jpeg, .jp2, .jpx, .pbm, .pcx, .png, .pnm, .ppm, .ras, .tif, .tiff, or .xwd. This function can be called as follows:

```
frame2file(videoToBeSaved, your_file_name.ext, 'C:\your_file_Path', frameToBeSaved.)
```

Where videoToBeSaved is a four-dimensional video frame matrix of your choice, and frameToBeSaved is the desired frame number. Place a valid file extension at the end of the file name to save as that format.

4.8.2 Fault Isolation

If no file extension is provided, then this function returns the following error:

'No file extension provided!'

This function does not currently check for a valid file extension.

4.9 jetVelocity

4.9.1 Theory and Description

The function `jetVelocity` finds the position, velocity, and diameter of the "jet" of the droplet. Because this function cannot identify a jet, this function is applied to the top of the droplet on every frame. This function can be used as follows:

```
[jetVel, jetPos, jetDia = jetVelocity(videoFloorRemoved)
```

The input `videoFloorRemoved` is the four-dimensional video frame matrix output of the function `floorremove`. The output `jetVel` is an array of length `frames-1` containing the instantaneous velocity of the top of the droplet in pixels as an integer. The output `jetPos` is an array of length `frames` that contains the vertical pixel location of the top of the droplet. The top of the frame is vertical position 0, while the bottom of the frame is vertical position `Height`. The output `jetDia` is an array of length `frames` containing the calculated diameter of the jet in pixels.

`jetVelocity` works by first converting the boundary of the primary droplet into coordinate points. The topmost point of the droplet is saved for each frame in `jetPos`. For each pixel row starting from the top of the droplet and ending at the bottom, the width between the most left and most right points are collected. The first local maximum width starting from the top of droplet is used for the output `jetDia`. If no local maximum is found, the average width of the first ten percent of the droplet is used instead. Local maximum jet diameter values will be integer numbers, while averaged jet diameter data will be a decimal pixel number. Finally, `jetVel` is calculated by finding the difference between `jetPos(frame)` and `jetPos(frame+1)`.

4.9.2 Fault Isolation

This function uses NaN values to indicate frames where no value could be calculated. This function uses the first local maximum width of the droplet to calculate the diameter of the jet. If there is no local maximum, then the first ten percent of the droplet is used to find the jet diameter. Because of these two modes, the jet diameter data will sometimes instantaneously jump from one value from to another. Consider adjusting 0.1 on line 48 of the function to adjust the percentage of the second mode, or manually check decimal values that seem to be outliers.

4.10 maskOverlay

See also: [outlineMask](#), [drawContactAngles](#), [convertSource](#),

4.10.1 Theory and Description

The function `maskOverlay` overlays a mask over a selected video input using a selected line weight and color. This function can be called as follows:

```
videoOverlay = maskOverlay(convertedSourceVideo, videoMask, lineThickness, lineColor)
```

Where `convertedVideoSource` is the four-dimensional matrix of data type `uint8` and the form `[Height, Width, 3, Frame]` from the function `convertSource`. `videoMask` is a Boolean black-and-white 4D video matrix of the height, width, and length of the `convertedVideoSource`. `videoMask` may either be the output matrix from the function `outlineMask` or the function `drawContactAngles`. `lineThickness` is an odd integer value. `lineThickness` determines how thick the lines in the `videoMask` matrix will be in the final video in number of pixels. The input `lineColor` is a RGB color defined by a three-element `uint8` array of the form `[R,G,B]`. The output `videoOverlay` is a four-dimensional matrix of data type `uint8` and the form `[Height, Width, 3, Frame]`, the same format as `convertedVideoSource`. First, each frame of the mask is dilated by the amount given by the `lineThickness`. For each of the RGB color components, accessed by `[:, :, 1, :]`, `[:, :, 2, :]`, `[:, :, 3, :]`, the mask is applied over the `convertedSourceVideo` matrix with the corresponding value of the `lineColor` input.

4.10.2 Fault Isolation

This function checks if the `convertedSourceVideo` and `videoMask` are of the same size in height, width, and the number of frames. If the sizes do not match, then the following error occurs:

'Source and Overlay matrix sizes do not match!'

If this is the case, please ensure that the `convertedSourceVideo` matrix was not altered after being created by the function `convertSource`, and check that the function `drawContactAngles`, one of the mask functions, has the correct size input array. If no input is given for the `lineThickness` of the `lineColor`, 1 and red (`[255,0,0]`) are used respectively. If the `lineColor` is of the wrong format, the following error called:

'lineColor is in incorrect format. Please use an RGB value in the form [R,G,B]'

Check to make sure that the line color input is a three-element `uint8` array of the format `[R,G,B]`.

4.11 maxSpread

4.11.1 Theory and Description

The droplet radius spreading feature determines the radius of the droplet on the left and right side and provide the maximum radius the droplet in the video. Radii is only calculated after the droplet has made contact with the floor.

This function begins by determining the number of frames in dataset ('d'). Once the length is determined, it finds the last frame that is completely black (no droplet appears)

and saves it as 'frame'. A new dataset is created from the original, this time eliminating the frames without any droplet.

4.11.2 Fault Isolation

4.12 outlineMask

See also: [maskOverlay](#), [drawContactAngles](#), [floorremove](#),

4.12.1 Theory and Description

The function `outlineMask` creates a post-processing video frame matrix mask showing the borders of all objects in the processed video matrix `videoFloorRemoved`, the output of `floorremoved`. The returned video mask is Boolean black-and-white 4D video matrix of the height, width, and length of the `videoFloorRemoved` input. This function can be called as follows:

```
maskOutline = outlineMask(videoFloorRemoved)
```

Where `videoFloorRemoved` is a four-dimensional matrix of data type `uint8` and the form [Height, Width, 1, Frame].

4.12.2 Fault Isolation

This function has no fault isolation. This function relies solely on `videoFloorRemoved` and uses the MATLAB function `bwperim` to generate the mask. If there are errors with this mask highlighting incorrect elements, check the 4D video matrix `videoFloorRemoved` and ensure no noise is present.

4.13 removePartialDroplet

4.13.1 Theory and Description

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4.13.2 Fault Isolation

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4.14 video2frame

See also: [borders](#), [convertSource](#), [frame2file](#), [drawContactAngles](#)

4.14.1 Theory and Description

The function `video2frame` imports a greyscale .AVI video file and converts it into MATLAB video frame data. The function takes in a video file and returns the video frame matrix and its dimensions. This function can be called as follows:

```
[videoSource, videoSize] = video2frame('C:\video_file_path\video.avi')
```

Where `videoSource` is a four-dimensional matrix of data type `uint8` and the form `[Height, Width, videoMode, Frame]`, and `videoSize` is a four-element array of the form `[Height, Width, videoMode, Frames]`.

4.14.2 Fault Isolation

Currently, this function does not have fault isolation. This function should return an error if the read .AVI video has a `videoMode` not equal to 1, which would indicate a color video.

5 Other Nonfunctional Requirements

5.1 Performance Requirements

Matlab requirements are needed. Found at <https://www.mathworks.com/support/requirements/matlab-system-requirements.html>

5.2 Safety Requirements

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5.3 Security Requirements

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5.4 Software Quality Attributes

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5.5 Business Rules

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6 Other Requirements

7 Appendix A: Glossary

Dataset: Any video file that has been uploaded to MATLAB.

Floor: (Variable) The horizontal reference in which the droplet impacts and begins spreading.

8 Appendix B: Analysis Models

9 Appendix C: TBD