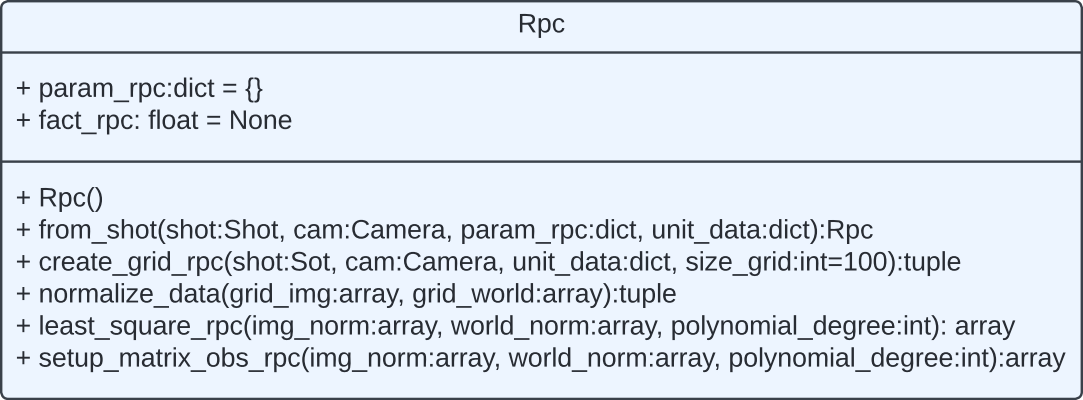
Rpc
+ param_rpc:dict = {}
+ fact_rpc: float = None
+ Rpc()
+ from_shot(shot:Shot, cam:Camera, param_rpc:dict, unit_data:dict):Rpc
+ create_grid_rpc(shot:Sot, cam:Camera, unit_data:dict, size_grid:int=100):tuple
+ normalize_data(grid_img:array, grid_world:array):tuple
+ least_square_rpc(img_norm:array, world_norm:array, polynomial_degree:int): array
+ setup_matrix_obs_rpc(img_norm:array, world_norm:array, polynomial_degree:int):array