

User Guide

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Let us explain how to use SSSS algorithm for Sentinel-2 super-resolution. *Notations:* \mathbf{K}_j is a $j \times j$ zero matrix with the (1,1)th entry replaced by 1; \otimes is Kronecker product.

1. Given a real Sentinel-2 image with the dimension of 10m band being $C \times D$, remove the band that records only the cirrus information (usually, B10), resulting in a 12-band image:
 - For those 20m bands \mathbf{Y}_i , insert zeros to get $\mathbf{Y}_i \otimes \mathbf{K}_2$, whose dimension becomes $C \times D$.
 - For those 60m bands \mathbf{Y}_i , insert zeros to get $\mathbf{Y}_i \otimes \mathbf{K}_6$, whose dimension becomes $C \times D$.
 - Note that both C and D should be multiples of 6.

So, the Sentinel-2 data are formalized as a tensor of dimension $C \times D \times 12$.

2. If the spatial dimension $C \times D$ is very large, we explain how to divide it into *overlapping* subimages, and how to merge the super-resolved subimages.
 - If a blurring kernel with 13×13 support is considered, border pixels in the first/last $6 = \frac{13-1}{2}$ columns/rows (of the super-resolved subimage) should be removed, as the blurring is BCCB.
 - Therefore, the dimension C and D should also satisfy

$$C - 12 = (n_r - 12)A, \tag{1}$$

$$D - 12 = (n_c - 12)B, \tag{2}$$

for some positive integers A, B ; in other words, the $C \times D$ image are divided into $A \times B$ *overlapping* blocks/subimages (each subimage is of size $n_r \times n_c$.)

- (Remark) n_r, n_c should also be multiples of 6.
- In our demo, $(C, D) = (432, 108)$, so we choose (n_r, n_c) as $(n_r, n_c) = (72, 108)$, which satisfies Equation (1)-(2) with $(A, B) = (7, 1)$.
- In other words, the vertical dimension is divided into 7 *overlapping* blocks/subimages in our demo, while the horizontal dimension is not divided. As mentioned above, border pixels of the super-resolved subimages are removed before they are merged.

Implementation of the dividing/merging processes are demonstrated in the “demo.m” file.

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