



Assuming cylindrical tanks, of identical section areas, we have this model, in state space,

$$\frac{dh_1}{dt} = A^{-1} \cdot \left( q(t) - c_{12} \cdot (h_1 - h_2) - c_{13} \cdot (h_1 - h_3) \right)$$

$$\frac{dh_2}{dt} = A^{-1} \cdot \left( c_{12} \cdot (h_1 - h_2) - c_{23} \cdot (h_2 - h_3) \right)$$

$$\frac{dh_3}{dt} = A^{-1} \cdot \left( c_{13} \cdot (h_1 - h_3) + c_{23} \cdot (h_2 - h_3) - c_{3A} \cdot h_3 \right)$$

We implement this model, in the S-Function, via a discrete time model.

