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# ***W99702 Sensor DSP Engine Library API Reference Guide***

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## Introduction

In this document, it will describe two W99702 engines – Sensor DSP engine, and parts of video capture engine. And it will show you how to access these 2 engines through the following C library functions.

The library for these two engines :

- The library name is called “**libdsp.a**” and its header file is “**libdsp.h**”.

## Supported C Library Functions Listing

- Global Controls
  - dspEnableDSPinterrupt
  - dspSetIRQHandler
  - dspGetInterruptStatus
  - dspResetDSPengine
  - dspInitialization
  - dspEnableDSPfunc
  - dspDisableAllDSPfunc
  - dspGetDSPfuncStatus
  - dspSetSensorInterface
  - dspGetBayerRawData
  - dspSetSubsampling
  - dspSetCroppingWnd
  - dspSetTimingControl
  - dspSetSubWindow
- Black Level Compensation
  - dspSetBLCwnd
  - dspSetBLCMode
  - dspUpdateUserBlackLevels
  - dspGetDetectedBlackLevel
- False color suppression
  - dspFalseColorSupp
- High color suppression
  - dspHSS
- Auto white balance and Auto exposure
  - dspSetSceneMode
- White Balance Control
  - dspSetAWBcontrol
  - dspUpdateAutoWhiteBalance
  - dspUpdateWhiteBalance
  - dspGetColorGains
  - dspGetAWBstats
  - dspGetAWBstats\_sw
  - dspGetWCounts
- Exposure Control
  - dspSetExpControl
  - dspSetFlashLightControl
  - dspUpdateAutoExposure
  - dspUpdateExposure

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- dspSetEV
- dspGetFrameYAvg
- dspGetAECstats\_sw
- Edge Enhancement Control
  - dspSetEdgeGain
- Color Correction Matrix
  - dspSetColorMtx
- Gamma Control
  - dspSetGammaTables
  - dspGetGammaTables
- Histogram Reports
  - dspSetHistogramCtrl
  - dspGetHistogramStats
- Auto Focus Control
  - dspSetAFcontrol
  - dspGetAFstats
- Bad Pixel Compensation
  - dspSetBadPixelTables
  - dspGetBadPixelTables
- Lens Shading Compensation
  - dspFindLensShadingParam
    - This function will be supported in Windows AP
  - dspLensCorrection
- Video Quality Adjustment
  - dspSetBrightnessContrast
  - dspSetHueSaturation
- Noise Reduction Filter
  - dspNoiseReduction

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## ***Used structures in dsplib.a***

### ***The types of YUV formats***

```
typedef enum YUV_Data_Format
{
    YUYV=0,
    YVYU,
    UYVY,
    VYUY
} YUV_DATA_FORMAT_E;
```

### ***The types of RGB bayer format***

```
typedef enum RGB_bayer_Format
{
    GBRG=0,
    GRBG,
    BGGR,
    RGGG
} RGB_BAYER_FORMAT_E;
```

### ***The definitions of Sensor output formats***

```
typedef union Sensor_Output_Format
{
    YUV_DATA_FORMAT_E      eYUVformat;
    RGB_BAYER_FORMAT_E     eBayerFormat;
} SENSOR_OUTPUT_FORMAT;
```

### ***The definition of Sensor interface control***

```
typedef struct Sensor_Interface
{
    INT      nSensorOutputType;
    SENSOR_OUTPUT_FORMAT SensorOutputFormat;
    INT      nSensorInterfMode;
    INT      nPCLK_P;
    INT      nHsync_P;
    INT      nVsync_P;
    INT      nYUV_input_type;
} SENSOR_INTERFACE_T;
```

### ***The Settings of timing generators for Master mode sensors***

```
typedef struct Frame_Timing_Gen
{
    INT      nEnd_Hsync;
    INT      nTotal_Hsyncs;
    INT      nStart_PCLK;
    INT      nEnd_PCLK;
    INT      nTotal_PCLKs;
} FRAME_TIMING_GEN_T;
```

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### ***The definitions of cropping windows***

```
typedef struct Crop_Start_Addr
{
    UINT32    uStartX;
    UINT32    uStartY;
    UINT32    uCropWidth;
    UINT32    uCropHeight;
} CROP_START_ADDR_T;
```

### ***The definitions of subwindows***

```
typedef struct SubWindow_Ctrl
{
    INT        nStartX;
    INT        nStartY;
    INT        nSW_Width;
    INT        nSW_Height;
    INT        nSW_Xoff;
    INT        nSW_Yoff;
    INT        nAECSrc;
    INT        nAWBSrc;
} SUBWINDOW_CTRL_T;
```

### ***The structures of digital programmable multiplier gains***

```
typedef struct DPGM
{
    INT        nRgain;
    INT        nGrgain;
    INT        nGbgain;
    INT        nBgain;
} DPGM_T;
```

### ***The definitions of white object detections***

```
typedef struct White_Objects
{
    BOOL        blsSkipWhitePoint;
    UINT8        ucAWBSrc;
    BOOL        blsDetectWO;
    UINT8        ucWO_coord;
    INT        nWO_PA;
    INT        nWO_PB;
    INT        nWO_PC;
    INT        nWO_PD;
    INT        nWO_PE;
    INT        nWO_PF;
    INT        nWO_Ka;
    INT        nWO_Kb;
    INT        nWO_Kc;
    INT        nWO_Kd;
} WHITE_OBJECTS_T;
```

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### ***The structure of lens shading compensation***

```
typedef struct Shading_Compensate_Coefficients
{
    int      nSC_up;
    int      nSC_down;
    int      nSC_left;
    int      nSC_right;
} SHADING_COMP_COEFF_T;

typedef struct Shading_Comp_Control
{
    INT      nSC_Shift;
    RGB_BAYER_FORMAT_E eBayerFormat;
    INT      nCenterX;
    INT      nCenterY;
    SHADING_COMP_COEFF_T *tYRcoeff;
    SHADING_COMP_COEFF_T *tUGcoeff;
    SHADING_COMP_COEFF_T *tVBcoeff;
} SHADING_COMP_CTRL_T;
```



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## **Sensor DSP Library API**

### ***dspEnableDSPInterrupt***

- To enable Interrupt of Sensor DSP engine or not
- void dspEnableDSPInterrupt (BOOL bEnableINT)
  - Parameters :
    - bEnableINT :
      - (1) TRUE : Enable the interrupt issued by the sensor DSP engine
      - (2) FALSE : Disable the interrupt
  - Return value :
    - None

### ***dspSetIRQHandler***

- The callback subroutine for the application using when an interrupt occurs
- void dspSetIRQHandler (PVOID pvDspFuncPtr)
  - Parameters :
    - dspFuncPtr : The callback function pointer
  - Return :
    - None

### ***dspGetInterruptStatus***

- To retrieve the status of the DSP interrupt
- UINT32 dspGetInterruptStatus (void)
  - Parameters :
    - None
  - Return :
    - bit 1 : Sensor DSP interrupt signal's mask
      - (1) 0 : Disable the generation of the interrupt signal
      - (2) 1 : Enable the generation of the interrupt signal
    - bit 0 : Sensor DSP interrupt status
      - (1) 0 : No interrupt is generated
      - (2) 1 : An interrupt is generated

### ***dspResetDSPEngine***

- To reset Sensor DSP engine, but all registers' setting will be kept
- void dspResetDSPEngine (void)
  - Parameters :
    - None
  - Return :
    - None

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### ***dspInitialization***

- To enable DSP engine, set the sensor clock and initialize the sensor and related registers of W99702 Sensor DSP engine
- UINT64 dspInitialization (UINT32 uFrameRateCtrl, char \*pcSensorType)
  - Parameters :
    - uFrameRateCtrl :
      - (1) 0 : 30 fps
      - (2) 1 : 20 fps
      - (3) 2 : 15 fps
      - (4) 3 : 10 fps
    - pcSensorType :
 Which sensor is supported in this library. From the last 2 characters, you can also know the sensor type – YUV sensors or RGB bayer sensors.  
 The last 2 characters :
      - 00 : RGB bayer sensors
      - 01 : YUV422 data from YUV sensors or TV-decoder
  - Return :
    - None

### ***dspEnableDSPfunc***

- To enable DSP functions according to users' definitions
- void dspEnableDSPfunc (UINT32 uDspFuncCtrl)
  - Parameters :
    - dspFuncCtrl :
      - (1) 0 for Disable and 1 for Enable
      - (2) bit 14 : Digital programmable gain multiplier
      - (3) bit 13 : High saturation suppression
      - (4) bit 12 : Sub-Window Statistics
      - (5) bit 11 : Histogram Statistics
      - (6) bit 10-9 : Bad pixel Compensation
        - a. 00 : disable bad-pixel compensation
        - b. 01 :  $\mu$ C can write bad pixel registers, but the compensation is disabled (**Reserved**)
        - c. 10 :  $\mu$ C can read bad pixel registers, but the compensation is disabled (**Reserved**)
        - d. 11 : Enable bad-pixel compensation
      - (7) bit 8 : Black level clamping
      - (8) bit 7 : Auto Focus
      - (9) bit 6 : Peak valley filter
      - (10) bit 5 : Missing color generation (MCG)
      - (11) bit 4 : Color correction
      - (12) bit 3 : Gamma correction
      - (13) bit 2 : Color space conversion
      - (14) bit 1 : Edge enhancement
  - Return :
    - None

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### ***dspDisableAllDSPfunc***

- To disable all DSP functions. If all DSP functions are disabled, then the sensors' RGB 10-bit raw data can be retrieved from the Y and U buffers of the planar pipe through dspGetBayerRawData (...).
- void dspDisableAllDSPfunc (void)
  - Parameters :
    - None
  - Return :
    - None

### ***dspGetDSPfuncStatus***

- To get the status of all related DSP functions
- UINT32 dspGetDSPfuncStatus (void)
  - Parameters :
    - None
  - Return :
    - The bit representations are same as dspEnableDSPfunc ()

### ***dspSetSensorInterface***

- To set sensors' output format
- void dspSetSensorInterface (Sensor\_Interface \*tSensorInterf)
  - Parameters :
    - Ref. to the structure definition -- [Sensor Data Format](#)
    - SensorOutputType and SensorOutputFormat :
      - (1) nSensorOutputType and SensorOutputFormat :
        - a. nSensorOutputType = 0 → RGB bayer format data from RGB sensors  
There are 4 RGB bayer formats. Ref. to [SENSOR OUTPUT FORMAT](#) and [RGB BAYER FORMAT E](#)
        - b. nSensorOutputType = 1 → YUV data from YUV sensors  
There are 4 YUV packet formats. Ref. to [SENSOR OUTPUT FORMAT](#) and [YUV DATA FORMAT E](#)
      - (2) nSensorInterfMode : The interface between W99702 DSP engine and the sensors
        - a. 0 : Slave Mode
        - b. 1 : Master Mode.
      - (3) nPCLK\_P : the polarity of PCLK latch signal
        - a. 0 : Data will be latched by the negative edge
        - b. 1 : Data will be latched by the positive edge
      - (4) nHsync\_P : The polarity of Horizontal sync.
        - a. 0 : Singal is low during Hsync. period (i.e. When signal is at low level is active sync. period)
        - b. 1 : latched by the positive edge (i.e. When signal is at high level is active sync. period)
      - (5) nVsync\_P : The polarity of Vertical sync.  
Definitions are same as Hsync\_P
      - (6) nYUV\_input\_type
        - a. 0 : Full scalar input. That is, the ranges of Y, Cb, and Cr are all 0 ~ 255
        - b. 1 : Standard CCIR601. That is, the range of Y is 16 ~ 235 and the ranges of Cb and Cr are 16 ~ 240.
  - Return :
    - None

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### ***dspGetBayerRawData***

- To save 10-bit RGB bayer raw data if nSensorOutputType=0 of dspSetSensorInterface (...) and all DSP functions are disabled.
- void dspGetBayerRawData (UINT32 uRawBufAddr)
  - Parameters :
    - uRawBufAddr : The starting address to store raw data. The buffer size of uRawBufAddr should be reserved at least (cropping width x cropping height x 2) bytes.
  - Return :
    - None

### ***dspSetCroppingWnd***

- To set the starting address (x, y) and the size of the specified window
- void dspSetCroppingWnd (CROP\_START\_ADDR \*tCropWnd)
  - Parameters :
    - Ref. to the definition of the cropping windows - [CROP\\_START\\_ADDR](#).
    - uStartX : The starting address in X-axis. (Column)
    - uStartY : The starting address in Y-axis. (Line)
    - uCropWidth : The width of the image
    - uCropHeight : The height of the image
  - Return :
    - None
  - If VGA image size is captured, then uCropWidth=640 and uCropHeight=480 will be filled in this function.

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### ***dspSetSubsampling***

- To set subsample mode for changing sensor output image size
- void dspSetSubsampling (INT32 nSubsmpIMode)
  - Parameters :
    - nSubsmpIMode : The subsample settings. **It will depend on what kind of the sensor is used and what subsample modes that sensor will provide.** And it will be noted in the dsplib.h of the released library according to different sensors. For examples,
      - (1) OV2620 UXGA image sensor,
        - a. nSubsmpIMode = 0 : UXGA (1600x1200)
        - b. nSubsmpIMode = 1 : CIF (352x288)
        - c. nSubsmpIMode = 2 : SVGA (800x600)
      - (2) OV9640 SXGA image sensor,
        - a. nSubsmpIMode = 0 : 1280x960 (Normal)
        - b. nSubsmpIMode = 1 : QCIF (176x144)
        - c. nSubsmpIMode = 2 : QVGA (320x240)
        - d. nSubsmpIMode = 4 : CIF (352x288)
        - e. nSubsmpIMode = 8 : VGA (640x480)
      - (3) OV7640 VGA image sensors,
        - a. nSubsmpIMode = 0 : VGA (640x480)
        - b. nSubsmpIMode = 1 : QVGA (320x240)
      - (4) Micron MT9M111 YUV 1.3M image sensors,
        - a. nSubsmpIMode = 0 : SXGA (1280x960, Normal, default mode)
        - b. nSubsmpIMode = 1 : VGA (640x480)
        - c. nSubsmpIMode = 2 : QVGA (320x240)
        - d. nSubsmpIMode = 3 : QQVGA (160x120)
  - Return :
    - None

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### ***dspSetTimingControl***

- If a sensor is designed as the slave mode interface, this function needs to be enabled and W99702 Sensor DSP engine will produce Vsync, Hsync, and PCLKs to sensors.
- void dspSetTimingControl (FRAME\_TIMING\_GEN\_T \*tTG\_Control)
  - Parameters :
    - Ref. to the definition of the structure – [FRAME\\_TIMING\\_GEN\\_T](#)
    - nEnd\_Hsync : Each active Vsync period is always from the 0<sup>th</sup> line to the “end\_Hsync”<sup>th</sup> line
    - nTotal\_Hsyncs : The total lines (Hsync.) per frame (Including the whole sensing area)
    - nStart\_PCLK and nEnd\_PCLK : Each active Hsync period is always from the “start\_PCLK”<sup>th</sup> pixel to “end\_PCLK”<sup>th</sup> pixel
    - nTotal\_PCLKs : The total pixel (PCLK) per Hsync.
  - Return :
    - None

### ***dspSetSubWindow***

- To set the subwindows for AEC and AWB to calculate statistics for each subwindow
- void dspSetSubWindow (SUBWINDOW\_CTRL\_T \*tSubWndCtrl)
  - Parameters :
    - The subwindow control can be referenced to the definition of the structure – [SUBWINDOW\\_CTRL\\_T](#)
    - nStartX : The starting address in X-axis for the subwindow (0, 0)
    - nStartY : The starting address in Y-axis for the subwindow (0, 0)
    - nSW\_Width : The width of each subwindow
    - nSW\_Height : The height of each subwindow
    - nSW\_Xoff : The offset between two adjacent subwindows in X-axis
    - nSW\_Yoff : The offset between two adjacent subwindows in Y-axis
    - nAECsrc : The source of the AEC statistics for each subwindow will be calculated before DPGM or after DPGM
      - nAECsrc = 0 : Before DPGM
      - nAECsrc = 1 : After DPGM
    - nAWBsrc : The source of the AWB statistics for each subwindow will be calculated before DPGM or after DPGM
      - nAECsrc = 0 : Before DPGM
      - nAECsrc = 1 : After DPGM
  - Return :
    - None

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### ***dspSetBLCwnd***

- To define a sub window for black level compensation using
- void dspSetBLCwnd (CROP\_START\_ADDR\_T \*tBlcWnd)
  - Parameters :
    - The definition of the structure – [CROP START ADDR T](#)
    - uStartX : The starting address in X-axis
    - uStartY : The starting address in Y-axis
    - uCropWidth / uCropHeight : The width and height of the window for black level.  
 The usages of uCropWidth and uCropHeight are different from the usages in dspSetCroppingWnd(...). It is just an index in this functions.
      - (1) 0 : 8
      - (2) 1 : 16
      - (3) 2 : 32
      - (4) 3 : 64
      - (5) 4 : 128
      - (6) 5 : 256
      - (7) 6 : 512
      - (8) 7 : 1024
  - Return :
    - None

### ***dspSetBLCMode***

- To set the black level clamping mode
- void dspSetBLCMode (BOOL blsUserDefined, BOOL blsAutoBLC)
  - Parameters :
    - blsUserDefined :
      - (1) 0 : disable user-defined mode
      - (2) 1 : enable user-defined mode
    - blsAutoBLC :
      - (1) 0 : disable auto-detection black level clamping
      - (2) 1 : enable auto-detection black level clamping
  - Return :
    - None

### ***dspUpdateUserBlackLevels***

- To set the user-defined black level for each color filter. This function will be valid only when bUserDefined=1 in dspSetBLCMode ()
- void dspUpdateUserBlackLevels (INT nUDBL\_Gr, INT nUDBL\_Gb, INT nUDBL\_R, INT nUDBL\_B)
  - Parameters :
    - nUDBL\_Gr : The user-defined black level for Gr channel.
    - nUDBL\_Gb : The user-defined black level for Gb channel.
    - nUDBL\_R : The user-defined black level for R channel.
    - nUDBL\_B : The user-defined black level for B channel.
    - The limitation for these four variables is between -128 and 127.
  - Return :
    - None

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### ***dspGetDetectedBlackLevel***

- To get the average black level from the user-defined subwindow – defined in `dspSetBLCMode ()` with `bAutoBLC=TRUE`
- INT32 `dspGetDetectedBlackLevel (void)`
  - Parameters :
    - None
  - Return :
    - The detected black level in auto-detected mode

### ***dspFalseColorSupp***

- To do false color suppression to eliminate some false color
- void `dspFalseColorSupp (INT nFCS_factor)`
  - Parameters :
    - `nFCS_factor` :
      - (1) 0 : 1.0x. That is, there is no effect of the false color suppression
      - (2) 2 : 0.5x. That is, if this point (R, G, B) is regarded as false color, its color will be equal to the half of the original color.
      - (3) 3 : 0.25x. That is, if this point (R, G, B) is regarded as false color, its color will be equal to one-fourth of the original color.
  - Return :
    - None

### ***dspSetSceneMode***

- To set different scenes for AEC and AWB using
- void `dspSetSceneMode (INT32 nSceneMode)`
  - Parameters :
    - `nSceneMode` : ***(These definitions are temporary)***
      - (1) 0 : Normal condition 1
      - (2) 1 : Normal condition 2
      - (3) 2 : Portrait
      - (4) 3 : Indoor 60Hz
      - (5) 4 : Indoor 50Hz
      - (6) 5 : Night mode
      - (7) 6 : User-defined mode
  - Return :
    - None



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### ***dspSetAWBcontrol***

- To set the relative AWB controls for white object detection using.
- void dspSetAWBcontrol (CROP\_START\_ADDR\_T \*tCropWO, WHITE\_OBJECTS\_T \*tDefWO)
  - Parameters :
    - tCropWO : Ref. to the definition of the cropping window -- [CROP\\_START\\_ADDR\\_T](#)
    - tDefWO : Ref. to the definition of the structure -- [WHITE\\_OBJECTS\\_T](#)
      - blsSkipWhitePoint :
        - (1) FALSE : If at least one of R, G or B value is saturated, it still calculate these points.
        - (2) TRUE : If at least one of R, G or B value is saturated, then this pixel will not be calculated.
      - ucAWBSrc : The source data used for AWB calculation
        - (1) 0 : The statistical data will be calculated before DPGM
        - (2) 1 : The statistical data will be calculated after DPGM
      - blsDetectedWO :
        - (1) FALSE : The detection of white objects will not be done. That is, all pixels which exist in defined white object window will be calculated.
        - (2) TRUE : The pixels which only satisfy the definition of white objects will be calculated.
      - ucWO\_coord :
        - (1) 0 : B-Y and R-Y (i.e. Use Y as a referenced axis)
        - (2) 1 : B-G and R-G (i.e. Use G as a referenced axis)
      - nWO\_PA, nWO\_PB, nWO\_PC, nWO\_PD, nWO\_PE, nWO\_PF, nWO\_Ka, nWO\_Kb, nWO\_Kc, nWO\_Kd : The definitions of white objects for a specified sensor.
  - Return :
    - None

### ***dspUpdateAutoWhiteBalance***

- To do color balance automatically.
- void dspUpdateAutoWhiteBalance (void)
  - Parameters :
    - None
  - Return :
    - None

### ***dspUpdateWhiteBalance***

- To do adjust color balance manually
- void dspUpdateWhiteBalance (DPGM\_T \*tColorBalance)
  - Parameters :
    - The definition of the structure – [DPGM\\_T](#)
    - nRgain : The digital gain is applied on R channel
    - nGrgain : The digital gain is applied on Gr channel
    - nGbgain : The digital gain is applied on Gb channel
    - nBgain : The digital gain is applied on B channel
  - Return :
    - None

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### ***dspGetColorGains***

- To get the 4 color digital gains which are applied in Sensor DSP engine now.
- void dspGetColorGains (DPGM\_T \*tColorBalance)
  - Parameters :
    - Ref. to the definition of the strucutre – [DPGM\\_T](#) and the description in dspUpdateWhiteBalance (...)
  - Return :
    - None

### ***dspGetAWBstats***

- To report the R, G or B average of all pixels defined in the white object window.
- UINT32 dspGetAWBstats (void)
  - Parameters :
    - None
  - Return :
    - bit [31:24] : Reserved
    - bit [23:16] : The R average of pixels defined in the white object window
    - bit [15:8] : The G average of pixels defined in the white object window
    - bit [7:0] : The B average of pixels defined in the white object window

### ***dspGetAWBstats\_sw***

- To caculate the average on R channel, G channel or B channel of each subwindow
- void dspGetAWBstats\_sw (UINT8 \*pucAvgR, UINT8 \*pucAvgG, UINT8 \*pucAvgB)
  - Parameters :
    - The length of the average of each subwindow is 8-bit long and the total length of 16 subwindows for average R, average G or average B for 16 subwindows should be 8x16 = 128 bytes
    - pucAvgR : The pointer of the buffer for R averages of 16 subwindows
    - pucAvgG : The pointer of the buffer for G averages of 16 subwindows
    - pucAvgB : The pointer of the buffer for B averages of 16 subwindows
  - Return :
    - None

### ***dspGetWOCOUNTS***

- To report the number of pixels which will satisfy the definition of white objects.
- UINT32 dspGetWOCOUNTS (void)
  - Parameters :
    - None
  - Return :
    - bit[15:0] = The number of the white object points. ( = total\_WO\_Counts / 32)

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### ***dspSetExpControl***

- To set the target luminous.
- void dspSetExpControl (int nAE\_targetLum, int nForeGndRatio, CROP\_START\_ADDR\_T \*tForeWin, UINT8 ucAECsrc)
  - Parameters :
    - nAE\_targetLum : To set the target luminance for auto exposure using.
    - nForeGndRatio : To set the ratio of the foreground window and this value is valid from 0 ~ 16. And (16-ForeGndRatio) is the ratio of the background.
    - tForeWin : Ref. to the structure [CROP\\_START\\_ADDR\\_T](#) and [dspSetCroppingWnd \(...\)](#)
    - ucAECsrc : The source data used for AEC caculation.
      - (1) 0 : Before DPGM (The data will be caculated before DPGM is applied.)
      - (2) 1 : After DPGM (The data will be caculated after DPGM is applied.)
  - Return :
    - None

### ***dspSetFlashLightControl***

- To set the flash light control
- void dspSetFlashLightControl (UINT32 uFlashLightMode)
  - Parameters :
    - uFlashLightMode : the control of the flash light
      - (1) 0 : Automatically. It will depend on the report from dspUpdateAutoExposure (...) or dspUpdateExposure (...)
      - (2) 1 : The flash light will be enforced to be turned on
      - (3) 2 : The flash light will not be turned on.
  - Return :
    - None

### ***dspUpdateAutoExposure***

- To do auto exposure control
- UINT32 dspUpdateAutoExposure (void)
  - Parameters :
    - None
  - Return :
    - bit 0 : The report of AEC status
      - (1) 0 : AEC is still in the unstable status
      - (2) 1 : AEC is in the stable status
    - bit 1 : The status of the flash light control
      - (1) 0 : The flash light do not need to be turned on
      - (2) 1 : The flash light should be turned on

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### ***dspUpdateExposure***

- To update exposure control manually
- void dspUpdateExposure (UINT32 uExpTime, UINT32 uAGC)
  - Parameters :
    - uExpTime : To control sensors's exposure time
    - uAGC : To set auto gain control
  - Return :
    - bit 0 : The report of AEC status
      - (1) 0 : AEC still in the unstable status
      - (2) 1 : AEC in the stable status
    - bit 1 : The status of the flash light control
      - (1) 0 : The flash light do not need to be turned on
      - (2) 1 : The flash light should be turned on

### ***dspSetEV***

- To update EV control
- void dspSetEV (int nEV)
  - Parameters :
    - nEV : The EV value
  - Return :
    - None

### ***dspGetFrameYAvg***

- To get the Y averages of the foreground and whole window
- UINT32 dspGetFrameYAvg (void)
  - Parameters :
    - None
  - Return :
    - bit [31:16] : Reserved
    - bit [15:8] : The average luminance of the whole window
    - bit [7:0] : The average luminance of the foreground window

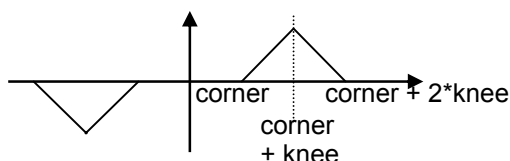
### ***dspGetAECstats\_sw***

- To get the Y averages of 16 subwindows
- void dspGetAECstats\_sw (UINT8 \*pucAvgY)
  - Parameters :
    - pucAvg : The Y averages of 16 subwindows. The length of each subwindow for average Y is 8-bit long.
  - Return :
    - None

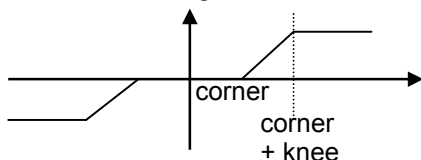
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### ***dspSetEdgeGain***

- To set the the strength of the edge enhancement
- void dspSetEdgeGain (int nKneeMode, int nKneePoint, int nCornerPoint, int nEdgeGain)
  - Parameters :
    - nKneeMode : Which kind of the edge enhancement will be done
      - (1) 0 : The enhanced strength after the corner point will be decreased



- (2) 1 : The enhanced strength after the corner point will be the same as the corner point



- nKneePoint : Edge knee point
  - nCornerPoint : Edge corner point
  - nEdgeGain : The strength of the edge enhancement ( 0 ~ 31 → 0.0x ~ 7.75x)
- Return :
  - None

### ***dspHSS***

- To enable high saturation suppression to eliminate some over-saturated color.
- void dspHSS (int nHSS\_Fa2, int nHSS\_Fa1, int nHSS\_Point)
  - Parameters :
    - nHSS\_Fa2 : Tuning of HSS\_Fa1 (Smaller HSS\_Fa2 results in more saturated colors)
    - nHSS\_Fa1 : HSS\_Fa1 – 255/HSS\_Point
    - nHSS\_Point : High saturation suppression will be active from the gray level = HSS\_Point
  - Return
    - None

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### **dspSetColorMtx**

- To set the color correction matrix
- void dspSetColorMtx (INT32 nCCMtx[3][3])
  - Parameters :
    - nCCMtx : The 3x3 color corrected matrix. The representation is shown as following :

$$\begin{bmatrix} CCMtx[0][0] & CCMtx[0][1] & CCMtx[0][2] \\ CCMtx[1][0] & CCMtx[1][1] & CCMtx[1][2] \\ CCMtx[2][0] & CCMtx[2][1] & CCMtx[2][2] \end{bmatrix}$$

The relations of Color Correction matrix :

$$\begin{bmatrix} R' \\ G' \\ B' \end{bmatrix} = \begin{bmatrix} CCMtx[0][0] & CCMtx[0][1] & CCMtx[0][2] \\ CCMtx[1][0] & CCMtx[1][1] & CCMtx[1][2] \\ CCMtx[2][0] & CCMtx[2][1] & CCMtx[2][2] \end{bmatrix} \times \begin{bmatrix} R \\ G \\ B \end{bmatrix}$$

- Return :
  - None

### **dspSetGammaTables**

- To set the gamma correction type and 16/32 gamma entries
- void dspSetGammaTables (UINT32 nGamType, UINT16 usGamTbl[64])
  - Parameters :
    - nGamType : The gamma correction type
      - (1) 0 : Table mapping for R, G, B. Same W99682's gamma correction
      - (2) 1 : Reserved
      - (3) 2 : Multiplication for R, G, B. And use Y as the referenced point.
      - (4) 3 : Multiplication for R, G, B. And use ((Y+MAX(R,G,B)/2) as the referenced point
    - usGamTbl
      - (1) if gamType = 0, there are 64 gamma entries used in the gamma correction. Each gamma entry is 8-bit unsigned integer.
      - (2) if gamType=2 or 3, there are only 32 gamma entries used in the gamma correction. Each gamma entry (multiplication factor) consists of 3-bit integer and 7-bit decimal fraction.
  - Return :
    - None

### **dspGetGammaTables**

- To get the gamma correction type and 32/64 gamma entries
- UINT32 GetGammaTables (UINT32 \*puGamTbl)
  - Parameters :
    - puGamTbl :
      - (1) 32 entries for gamma correction type is set 2 or 3. That is, the length of the GamTbl should be (16\*32) bytes
      - (2) 64 entries for gamma correction type is set 0. That is, the length of each gamma entry is 8-bit long and the length of GamTbl is = (16\*32) bytes
  - Return :
    - The returned value is the gamma type. The definition is referenced to the dspSetGammsTables ()

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### ***dspSetHistogramCtrl***

- To enable the gray level statistics of the image and control its related settings
- void dspSetHistogramCtrl (int nHistoSrc, int nHistoScalar, int nHistoSrcChannel)
  - Parameters :
    - nHistoSrc :
      - (1) 0 : Before DPGM
      - (2) 1 : After DPGM
    - nHistoScalar :
      - (1) 0 : the factor of reported values = 2
      - (2) 1 : the factor of reported values = 4
    - nHistoSrcChannel :
      - (1) 0 : R channel
      - (2) 1 : G channel
      - (3) 2 : B channel
      - (4) 3 : Y=(5R+9G+2B)/16
      - (5) 4 : MAX (R, G, B)
  - Return :
    - None

### ***dspGetHistogramStats***

- To get the statistics of 12-step histogram
- void dspGetHistoStats (UINT16 \*pucHistoPtr)
  - Parameters :
    - pucHistoPtr : The 12-step histogram. The length of pHisto should be at least (12\*16) bytes.
    - Each step is 16-bit long.
  - Return :
    - None

### ***dspSetAFcontrol***

- Set Target value and the effective window
- void dspSetAFcontrol (CROP\_START\_ADDR\_T \*tAFcontrol)
  - Parameters :
    - tAFcontrol : The definition of the structure – [CROP\\_START\\_ADDR\\_T](#)
  - Return :
    - None

### ***dspGetAFstats***

- To return the statistics of the high-pass frequency domain in the specified window
- UINT32 dspGetAFreports (void)
  - Parameters :
    - None
  - Return value :
    - The format of 32-bit return values : the LSB 24 bits (bit 23 ~ bit 0) of the high-pass frequency

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### ***dspSetBadPixelTables***

- To set the bad pixels and the maximum number of bad pixels is 32.
- void dspSetBadPixelTables (int nBadPixCnt, UINT32 \*puBPtblAddr)
  - Parameters :
    - nBadPixCnt : The total number of bad pixels and BadPixCnt should be at most 32.
    - puBPtblAddr : The tables for bad pixels. And its address format (x, y) is :
      - (1) bit [27:16] : X position of a bad pixel
      - (2) bit [11:0] : Y position of a bad pixel
  - Return :
    - None

### ***dspGetBadPixelTables***

- To retrieve the number of the bad pixel and its position.
- void dspGetBadPixelTables (UINT32 \*puBPtblAddr)
  - Parameters :
    - puBPtblAddr : The address of the buffer for storing bad pixels' table
      - (1) The 1<sup>st</sup> word : the number of the bad pixels.
      - (2) The words after the 1<sup>st</sup> word are positions of bad pixels. And one word representation (x, y) :
        - bit [27:16] : the X position of a bad pixel
        - bit[11:0] : the Y position of a bad pixel
  - Return :
    - None

### ***dspLensCorrection***

- To compensate the lens shading
- void dspLensCorrection (SHADING\_COMP\_CTRL\_T \*tSCctrl)
  - Parameters :
    - tSCctrl : Ref. to the definition of the structure -- [SHADING\\_COMP\\_CTRL\\_T](#)
      - (1) nSC\_shift : The shift value for all coefficients
        - a. 0 : SC\_Shift = 17
        - b. 1 : SC\_Shift = 18
        - c. 2 : SC\_Shift = 19
        - d. 3 : SC\_Shift = 20
      - (2) eBayerFormat : The color filter array (bayer format). And this setting will be a little different from the color filter array in dspSetSensorInterface (...). Ref. to the defined emulator – [RGB\\_BAYER\\_FORMAT\\_E](#)
      - (3) nCenterX : The address of the referenced center point in X-axis
      - (4) nCenterY : The address of the referenced center point in Y-axis
      - (5) tYRcoeff, tUGcoeff, tVBcoeff : The compensated parabola coefficients for YUV output format or RGB output format individually. Ref. to the definition of the structure – [SHADING\\_COMP\\_COEFF\\_T](#)
        - a. nSC\_up : Parabola coefficient at the position < Y0
        - b. nSC\_down : Parabola coefficient at the position > Y0
        - c. nSC\_left : Parabola coefficient at the position < X0
        - d. nSC\_right : Parabola coefficient at the position > X0
  - Return :
    - None



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### ***dspFindLensCorrectionParam***

- To dump a raw data picture or YUV data (packet or planar) and let AP on PC find related parameters of the lens shading compensation.

### ***dspSetBrightnessContrast***

- To make adjustments to the tonal range of an image
- void dspSetBrightnessContrast (int nYscale, int nYoffset)
  - Parameters :
    - nYscale : The contrast adjustment. Its range is 0 ~ 63 and the default value is 16.
    - nYoffset : The adjustment of the brightness. Range : -128 ~ 127
    - $Y' = Y \times nYoffset + nYoffset$
  - Return :
    - None

### ***dspSetHueSaturation***

- To adjust the hue and saturation of the entire image
- void dspSetHueSaturation (int nHS1, in nHS2)
  - Parameters :
    - nHS1 and nHS2:
      - (1) nHS1 will influence the saturation. Its range is 127 ~ -128 and the default value is 32.
      - (2) nHS2 will influence the hue. Its range is 127 ~ -128 and the default value is 0.
      - (3)  $Cb' = Cb \times nHS1 - Cr \times nHS2$
      - (4)  $Cr' = Cb \times nHS2 - Cr \times nHS1$
  - Return :
    - None

### ***dspNoiseReduction***

- To reduce the noise reduction or not
- void dspNoiseReduction (BOOL bEnableNR)
  - Parameters :
    - bEnableNR :
      - (1) TRUE : Enable the noise reduction
      - (2) FALSE : Disable the noise reduction
  - Return :
    - None

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## Sample Code

- **For General Users**

- **For RGB sensors,**  
extern void dspInitHandler ();  
  
dspResetDSPengine ();  
dspInitialization (0);  
dspSetIRQHandler ((PVOID)dspInitHandler);  
dspEnableDSPinterrupt (TRUE);  
  
while (1)  
{     dspUpdateAutoExposure ();  
      dspUpdateAutoWhiteBalance ();  
}
- **For YUV sensors,**  
dspInitialization (0);     //Only this function is needed

- **For Advanced users,**

- **For RGB sensors,**  
extern void dspInitHandler ();  
  
dspResetDSPengine ();  
dspInitialization ();  
dspSetIRQHandler ((PVOID)dspInitHandler);  
dspEnableDSPinterrupt ();  
  
**//You can control related DSP functions and settings anytime**  
//e.g. dspSetEdgeGain ()     -- to set different  
//       dspSetGammaTables () – you can specify it  
//       dspUpdateUserBlackLevels ()  
//       .....  
  
while (1)  
{     dspUpdateExposure ();  
      dspUpdateWhiteBalance ();  
}

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```

○ For YUV sensors,
  int nConstrast = 10;    //For example
  int nBrightness = 20;   //For example
  int nHue = 0x20;        //For example
  int nSaturation = 0x20; //For example

  dspInitialization (0);

  while (1)
  {
    dspSetBrightnessContrast (nConstrast, nBrightness);
    dspSetHueSaturation (nHue, nSaturation);
    dspLensCorrection (...);    //Should depend the lens shading compensation parameters
  }

```

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## Special Programming Notes.

- Bad Pixels :
  - When writing bad pixels' address (x, y) and index into DSP control registers, it should use HCLK to write.
  - When reading bad pixels' address (x, y) and index into DSP control registers, it should use ECLK to read.
  - Bad pixels' real position should be (x+3, y+2) as compared with captured image after cropping.
- Cache Issue,
  - With cache on,
    - Fast Serial bus (H/W I2C) : Prefer to do I2C initialization before WB\_EnableCache (CACHE\_WRITE\_THOUGH) or WB\_EnableCache(CAHCH\_WRITE\_BACK)
    - Software I2C : The delay between some signals should be longer
- For slave mode sensors, the polarities of PCLK, Hsync., and Vsync. are all defined in Video capture engine.
- **All related DSP initializations should be called before the initialization of video capture engine.**
  - For example, dspInitialization (0, SensorMdl);
-