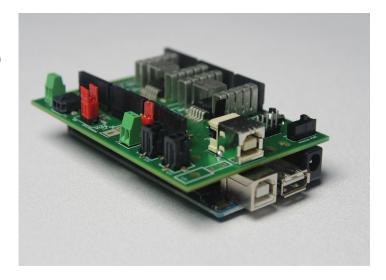


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# TurtleBot Power Interface Shield

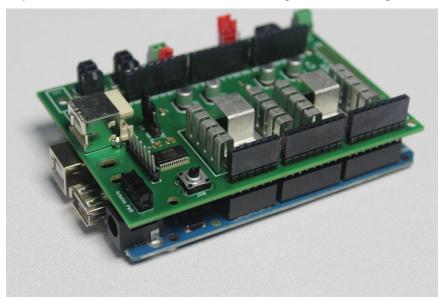
#### Includes

- 1x Mini-Din 7 to MTA100 Cable
- 1x Turtlebot Power Interface Shield
- Stacking Headers sold separately





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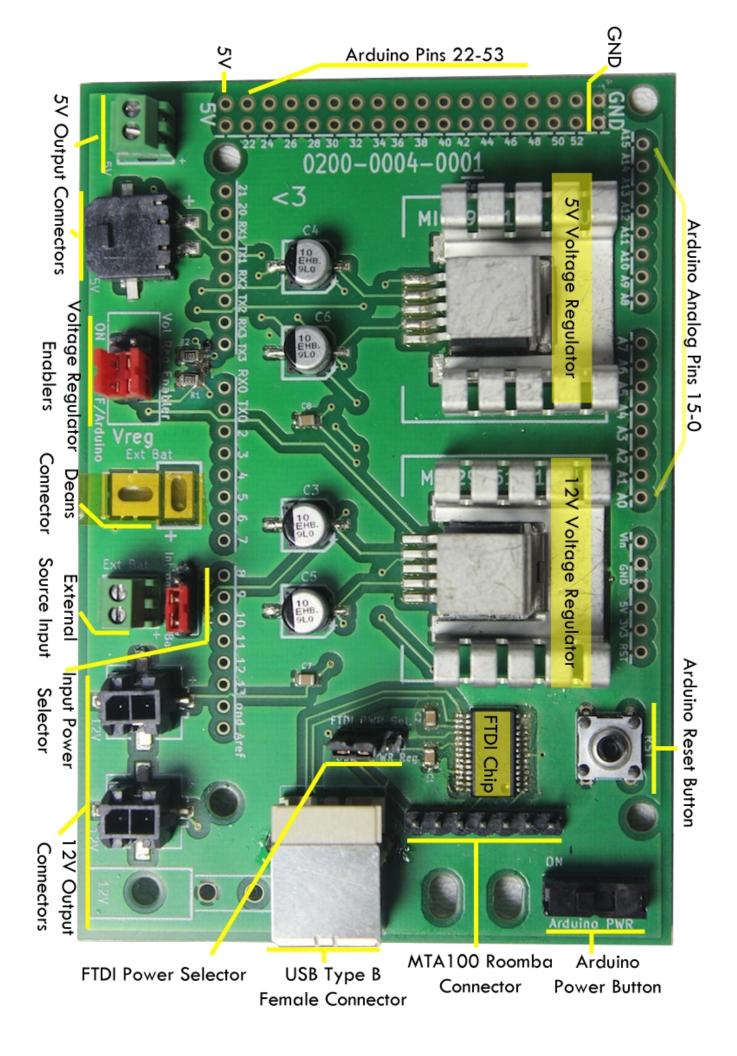


# Description

The Power Interface Shield is a board made for PC to Roomba (or iCreate) communication using an integrated FTDI chip and power regulator for Turtlebot devices.

The Arduino board RX and TX pins are tied to the Roomba's TX and RX respectively when the shield is stacked to an Arduino Uno or Mega board.

The board has two voltage regulators, 5V and 12V, that can be controlled by an Arduino board. If no Arduino board is present, the voltage regulators can be enabled and disabled with shunts.





# Power Supply Input

Select between using the Roomba's internal battery or an external battery to supply power to the 5V and 12V voltage regulators. There are two different external battery connector: a Deans connector and a 2-pin Screw Terminal block.

WARNING: Not using the proper power supply to turn on the Arduino board may cause damage to the Arduino Board. Use a power supply within the recommended input voltage range (recommended input voltage for the Arduino Uno is between 7V and 12V).

#### Voltage Regulator Enabler

Enable the 5V and 12V voltage regulators independently with a shunt. There are two positions on the jumpers: always on, and off or Arduino-controlled if an Arduino board is present. The Arduino board digital pin 6 enables the 5V regulator and pin 7 enables the 12V regulator. Pins 6 and 7 are tied to ground through a 1k-Ohm pull down resistor.

# Power Supply Output

The TurtleBot Power Interface Shield Rev. 01 has three 12V output connectors and two 5V output connectors. Rev. 02 has only two of each voltage output.

#### FTDI Power Select

Using a shunt select how to power the FTDI chip; using the USB 5V power supply or the output 5V from the shield's 5V regulator. Both supplies have a common ground.



#### Arduino Power Switch

A slide switch turns on or off the Arduino board. The input power (Internal or External battery depending on the selector) is connected to the Arduino board's Vin pin.

WARNING: Not using the proper power supply to turn on the Arduino board may cause damage to the Arduino Board. Use a power supply within the recommended input voltage range (recommended input voltage for the Arduino Uno is between 7V and 12V).

#### LED Indicators \*for Rev. 02 and above

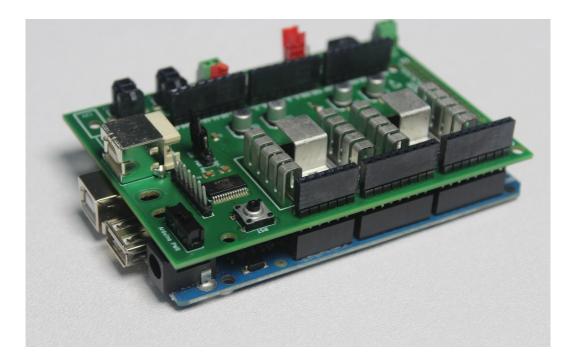
Two LEDs attached to the FTDI chip indicate data transmission. They are properly labeled RX and TX. There is a LED that turns on when the Arduino Power Switch is turned on. Two LEDs light up individually when the 5V and 12V regulators are enabled.

# **Mating Connectors**

The 12V output power connector soldered on the board is a female two-pin connector with Digikey Part Number: WM1801-ND (or its right-angle, surface mount version). It requires a male two-pin connector with Digikey Part Number: WM1783-ND.

The 5V output power connector soldered on the board is a female two-pin connector with Digikey Part Number: WM1890TR-ND. It requires a male two-pin connector with Digikey Part Number: WM1845-ND





# **Shield Stacking**

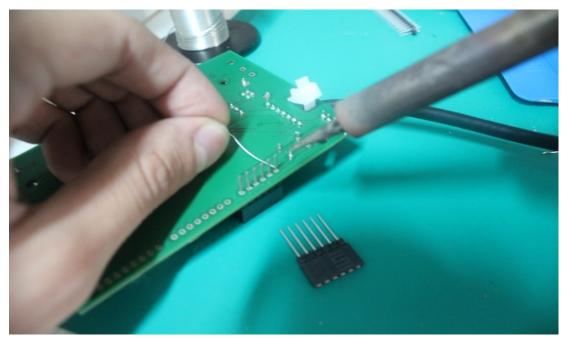
The TurtleBot Power Interface Shield can be stacked on the Arduino Uno, Arduino Mega, Arduino Duemilanove, and other Arduino boards with similar specifications.



# Soldering

Solder stacking headers to stack the shield to an Arduino board. Place the stacking headers from top to bottom and turn the shield upside down as seen on the picture. Solder one pin at a time applying enough heat and solder. Repeat process for Deans connector (not supplied).

If using regular header pins (non-stacking), place the pins on the Arduino Board, stack the shield on top and solder from the top side. That way the pins remain aligned with the Arduino Board.





#### **USB** Cable

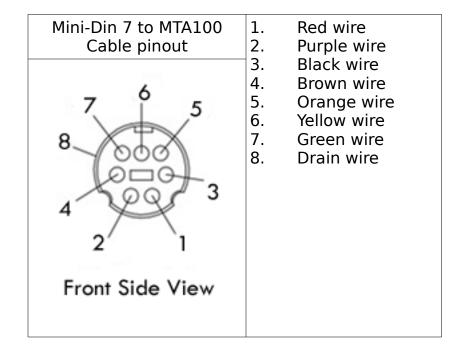
The TurltleBot Power Interface Shield Rev. 01 board uses a Type B USB connector. The TurltleBot Power Interface Shield Rev. 02 board uses a Micro B USB connector. Use a zip tie to securely attach the cable to the board.





#### Mini-Din 7 Cable Pinout

A Mini-Din 7 to MTA 100 cable (provided) connects the Roomba with the board.

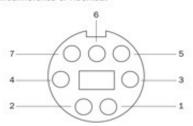




# Roomba Mini-Din 7 pinout

#### ROOMBA'S EXTERNAL SERIAL PORT MINI-DIN CONNECTOR PINOUT

This diagram shows the pin-out of the top view of the female connector in Roomba. Note that pins 5, 6, and 7 are towards the outside circumference of Roomba.



Name	Description
Vpwr	Roomba battery + (unregulated)
Vpwr	Roomba battery + (unregulated)
RXD	0 - 5V Serial input to Roomba
TXD	0 – 5V Serial output from Roomba
DD	Device Detect input (active low) – used to wake up Roomba from sleep
GND	Roomba battery ground
GND	Roomba battery ground
	Vpwr Vpwr RXD TXD DD

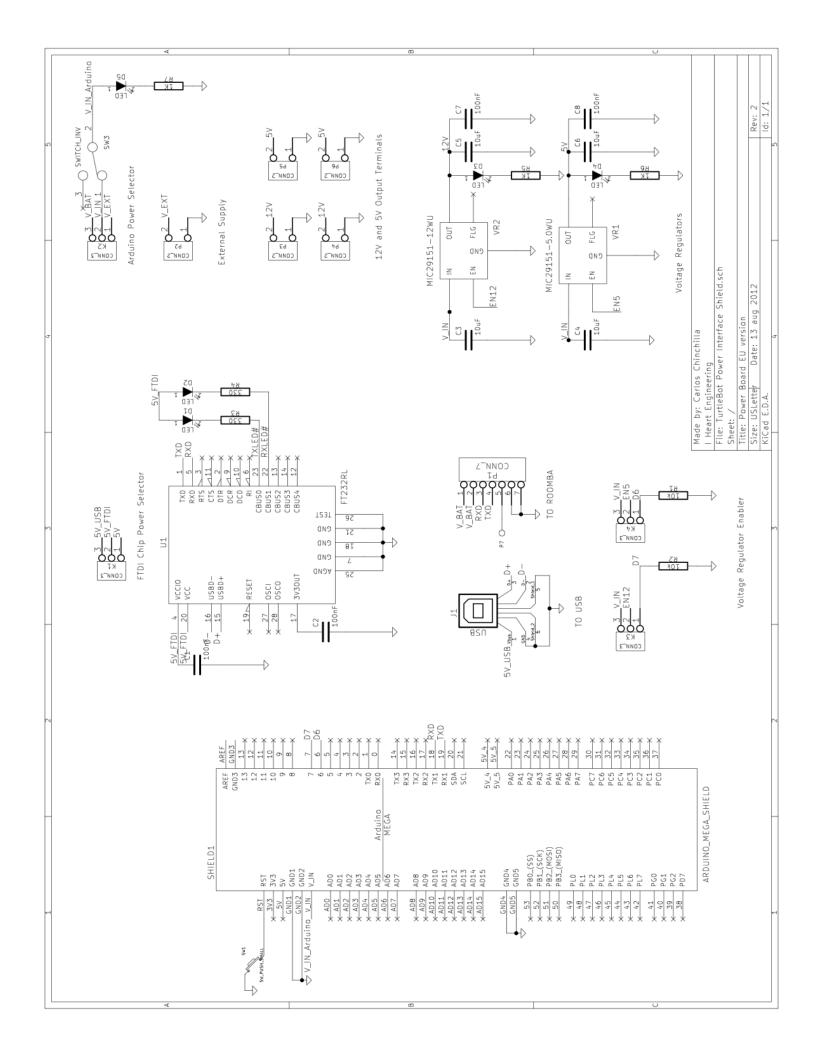
NOTE: pin 5, used for the baud rate selector on the iCreate, is broken out in the TurltleBot Power Interface Shield Rev. 02 board.



#### Resetting Roomba

To reset the Roomba and bring it to default values, press and hold the SPOT and DOCK buttons for 12 seconds. When reset, the Roomba plays a melody about a second after releasing the buttons. The Roomba 500 Series default baud rate is 115200 bps.







#### Serial Communication Test

To test for PC-Roomba communication, use the C-Kermit terminal or any preferred terminal. Turn off the Roomba, connect it to the shield and the shield to the computer, and type the following in kermit.

SET LINE /dev/ttyUSB0 # or respective location

SET PARITY NONE

SET FLOW NONE

SET CARRIER-WATCHDOG OFF

**SET SPEED 115200** 

CONNECT

Turn on the Roomba. If there is a proper connection, the terminal will print information about the Roomba on screen. If there is no readable text or no text is printed on screen, try changing the baud rate, checking the cable connections, and battery status of the Roomba. If the problem persists, reset the Roomba and use the default baud rate (115200 bsp) or contact tech support.

# **Tech Support**

For any problems, questions, or comments feel free to contact an I Heart Engineering representative via email at <a href="mailto:support@iheartengineering.com">support@iheartengineering.com</a> or phone.



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