
System Requirements Specification Index

For

Ecosystem Simulation System

Version 1.0

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Ecosystem Simulation System

System Requirements Specification

1 PROJECT ABSTRACT

EcoLearn Foundation, a non-profit dedicated to environmental education, requires an interactive Ecosystem Simulation program to promote ecological awareness among students and the general public. The simulation will model interactions between different organisms in a virtual environment, demonstrating key ecological concepts such as food chains and environmental adaptation. By visualizing these relationships, EcoLearn aims to foster a deeper understanding of ecosystem dynamics and the importance of biodiversity conservation.

2 BUSINESS REQUIREMENTS:

Screen Name	Console input screen
Problem Statement	<ol style="list-style-type: none">1. System needs to simulate different types of organisms (plants, herbivores, carnivores)2. System must support basic ecosystem operations such as organism creation and interaction3. Console implementation must demonstrate object-oriented programming concepts like Classes and objects, Inheritance and polymorphism

3 CONSTRAINTS

3.1 CLASS REQUIREMENTS

1. `Organism` Class (Base Class):
 - o Attributes: id, species_name, energy, is_alive

- Class Variables: `organism_count`
 - Methods: `display_info()`, `consume_energy()`, `interact()`
 - Example: Cannot be instantiated directly
2. ``Plant` Class (inherits from `Organism`):`
- Additional attributes: `growth_rate`
 - Override methods: `display_info()`, `interact()`
 - New methods: `photosynthesize()`
 - Example: ``Plant`("P001", "Oak Tree", 100, True, 0.2)``
3. ``Animal` Class (inherits from `Organism`):`
- Additional attributes: `speed`, `diet_type`, `food_eaten`
 - Override methods: `display_info()`
 - New methods: `hunt()`
 - Example: Cannot be instantiated directly
4. ``Herbivore` Class (inherits from `Animal`):`
- Additional attributes: `plant_preference`
 - Override methods: `hunt()`, `interact()`, `display_info()`
 - Example: ``Herbivore`("H001", "Rabbit", 70, True, 3, "herbivore", "grass")``
5. ``Carnivore` Class (inherits from `Animal`):`
- Additional attributes: `hunting_efficiency`
 - Override methods: `hunt()`, `interact()`, `display_info()`
 - Example: ``Carnivore`("C001", "Wolf", 80, True, 5, "carnivore", 0.7)``
6. ``Environment` Class:`
- Attributes: `name`, `weather_condition`, `organisms`, `day_count`, `next_id`
 - Methods: `add_organism()`, `remove_organism()`, `get_organisms_by_type()`, `find_organism_by_id()`, `get_population_count()`, `simulate_day()`, `get_next_id()`
 - Example: ``Environment`("Forest Ecosystem", "sunny")``

3.2 OPERATION CONSTRAINTS

1. Basic Interactions:

- Plants generate energy through photosynthesis based on weather
 - Implement in ``photosynthesize(weather_condition)`` method

- Weather impacts: sunny (1.0), cloudy (0.6), rainy (0.3)
- Herbivores hunt plants with preference for specific species
 - Implement in `hunt(pre_yorganisms)`` method
 - Should filter available plants by preference
- Carnivores hunt herbivores with success based on `hunting_efficiency`
 - Implement in `hunt(pre_yorganisms)`` method
 - $\text{Success chance} = \text{hunting_efficiency} * (\text{predator_speed} / \text{prey_speed})$
- Animals interact with prey through `interact(other_organism)`` method
- All organisms consume energy daily using `consume_energy(amount)`` method
- Organisms die when energy reaches zero (handled in energy setter)

2. Input Validation:

- All organism IDs must be unique
- Energy must be positive (10-100)
- Growth rates must be between 0.1 and 0.5
- Speed must be positive integer
- Hunting efficiency must be between 0.3 and 0.7

3. Exception Handling:

- Must handle `OrganismNotFoundException` when organism not found
- Must handle `InvalidInputException` for invalid user inputs

4. Object-Oriented Requirements:

- Must use protected attributes (single underscore prefix)
- Must use private attributes for Environment (double underscore prefix)
- Must implement inheritance hierarchy as specified
- Must use polymorphism with method overriding

3.3 OUTPUT CONSTRAINTS

1. Display Format:

- Organism info must show: ID, species name, energy, status, type-specific attributes
- Environment info must show: name, weather, day count, organism counts by type

2. Output Format:

- Must show in this order:
 - Show "== ECOSYSTEM SIMULATION =="
 - Show "Environment: {name}"
 - Show "Weather: {weather_condition}"
 - Show "Total Organisms: {count}"
 - Show "Population Breakdown:" followed by counts by type
 - Show "Simulation Day: {day_count}"

3.4 PROPERTY IMPLEMENTATION CONSTRAINTS

1. Each class must implement proper property getters/setters:
 - Organism class: id, species_name, energy (with setter), is_alive
 - Plant class: growth_rate
 - Animal class: speed, diet_type, food_eaten
 - Herbivore class: plant_preference
 - Carnivore class: hunting_efficiency
 - Environment class: name, weather_condition (with setter), organisms, day_count

3.5 CONSTRUCTOR/DESTRUCTOR CONSTRAINTS

1. All classes must implement appropriate constructors that initialize attributes
2. The Organism class must increment organism_count in its constructor
3. The Organism class must decrement organism_count in its destructor
4. Environment class constructor must initialize private collections

4. TEMPLATE CODE STRUCTURE:

1. Organism Classes:

- `Organism` (base class)
- `Plant` (derived from Organism)
- `Animal` (derived from Organism)
- `Herbivore` (derived from Animal)
- `Carnivore` (derived from Animal)

2. Environment Class:

- `Environment`

3. Exception Classes:

- `OrganismNotFoundException`
- `InvalidInputException`

4. Program Control:

- `main()` - main program function

5. EXECUTION STEPS TO FOLLOW:

1. Run the program
2. View the main menu
3. Select operations:
 - Option 1: Add Organism to Environment (numeric selection)
 - Option 2: Simulate One Day
 - Option 3: Simulate Multiple Days
 - Option 4: Display All Organisms
 - Option 0: Exit
4. Perform operations on the ecosystem simulation
5. View results after each operation
6. Exit program when finished