

Differential Equations and $\exp(At)$

Consider $\frac{du}{dt} = Au$

$$A = \begin{bmatrix} -1 & 1 \\ 1 & -2 \end{bmatrix}$$

$$\lambda = 0, -3$$

so for certain eigenvectors the equation becomes $\frac{du}{dt} = 0u$ and $\frac{du}{dt} = -3u$. The 0 solution is the steady state, the -3 one dies out.

$$u(t) = c_1 e^{\lambda_1 t} x_1 + c_2 e^{\lambda_2 t} x_2$$

compare to the formula for difference equations

1 Cases

Stability, $u(\infty) = 0$ when all $\operatorname{Re} \lambda < 0$

Steady state, $\lambda_1 = 0$ and other eigenvectors have $\operatorname{Re} \lambda < 0$

Blowup if any $\operatorname{Re} \lambda > 0$

2 Special case

For 2×2 matrix:

$$\operatorname{Tr} = a + d = \lambda_1 + \lambda_2 < 0$$

$$\operatorname{Det} = ad - bc = \lambda_1 \lambda_2 > 0$$

positive determinant, negative trace.

3 S

Let's write the solution down in terms of S and Λ . Eigenvalues uncouple them.

$$\frac{du}{dt} = Au$$

set $u = Av$

$$S \frac{dv}{dt} = ASv$$

$$\frac{dv}{dt} = \Lambda v$$

no coupling! Just a diagonal matrix.

$$v(t) = e^{\Lambda t v(0)}$$

$$u(t) = S e^{\Lambda t} S^{-1} u(0) = e^{At} u(0)$$

what do the matrix exponentials mean?

4 Power series

$$e^{At} = I + At + \frac{(At)^2}{2!} + \dots$$

$$(I - At)^{-1} = I + At + (At)^2 + \dots$$

the exponential always converges but if A is too big (eigenvalue > 1) the second series will blow up.

now just write $A = S \Lambda S^{-1}$, we get $e^{At} = S e^{\Lambda t} S^{-1}$

5 Exponential of a diagonal matrix

$$e^{\Lambda t} = \begin{bmatrix} e^{\lambda_1 t} & & \\ & e^{\lambda_2 t} & \\ & & \dots \end{bmatrix}$$

this goes to zero when all $\operatorname{Re} \lambda < 0$

stability for differential equation: λ in left half plane. Powers of the matrix go to zero if λ is contained in the unit disc.

6 Cheapskate trick

$$y'' + by' + ky = 0 \quad u = [y' y], u' = \begin{bmatrix} -b & -k \\ 1 & 0 \end{bmatrix} u$$

in general, coefficients in the first row, and other rows have just one 1 among 0's.