#### Vectors

### 1 Geometry of Linear Equations

Given a system of linear equations, what is the solution set?

Let us work in equations of three variables x, y, z. We will consider a solution to be a vector in  $\mathbb{R}^3$ . We assume that each individual linear equation is consistent.

With 0 equations our solution set is  $\mathbb{R}^3$ .

With 1 equation our solution set is a plane.

With 2 equations our solution set is either

- 1. a line
- 2. the empty set
- 3. a plane

The first case is the most common, while the second occurs if the planes are parallel; this corresponds to an inconsistent set of equations. The third occurs if the two equations are "the same".

With 3 equations our solution set is

- 1. a point
- 2. a line
- 3. the empty set
- 4. a plane

notice that there is now a greater variety in how it can be inconsistent. Also, it appears that the only way to have a point as a solution is to have the number of equations greater or equal to the number of unknowns.

## 2 Gauss Algorithm

Now we develop an algebraic way to solve this.

Gauss's Algorithm. If a linear system is changed to another by one of these operations

1. an equation is swapped with another  $(\rho_i \leftrightarrow \rho_j)$ 

- 2. an equation has both sides multiplied by a nonzero constant  $(n\rho_i)$
- 3. an equation is replaced by the sum of itself and a multiple of another  $(n\rho_i + \rho_j)$

then the two systems have the same set of solutions.

There is an algorithm (gaussian elimination) that uses these operations to write the equation in reduced row-echelon form

#### 3 Algebraic proofs

solution sets are  $\mathbb{R}^n$ 

**Theorem.** For any linear system there are vectors  $\vec{p}, \vec{\beta_1}...\vec{\beta_k}$  such that the solution set can be described as a  $\vec{p}$  and a linear combination of  $\beta$ .

RREF

A homogeneous system of m linear equations in n un-knowns always has a nontrivial solution if m; n.

 $m \geq n$  for unique solution

# 4 General = Particular + Homogenous

Such a split occurs in ordinary differential equations, linear diophantine equations, and many more (vector space!)