

Cross-Domain Self-supervised Learning

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A Story about **Cake** (in Yann LeCun's Turing Talk)

- ▶ **“Pure” Reinforcement Learning (cherry)**

- ▶ The machine predicts a scalar reward given once in a while.

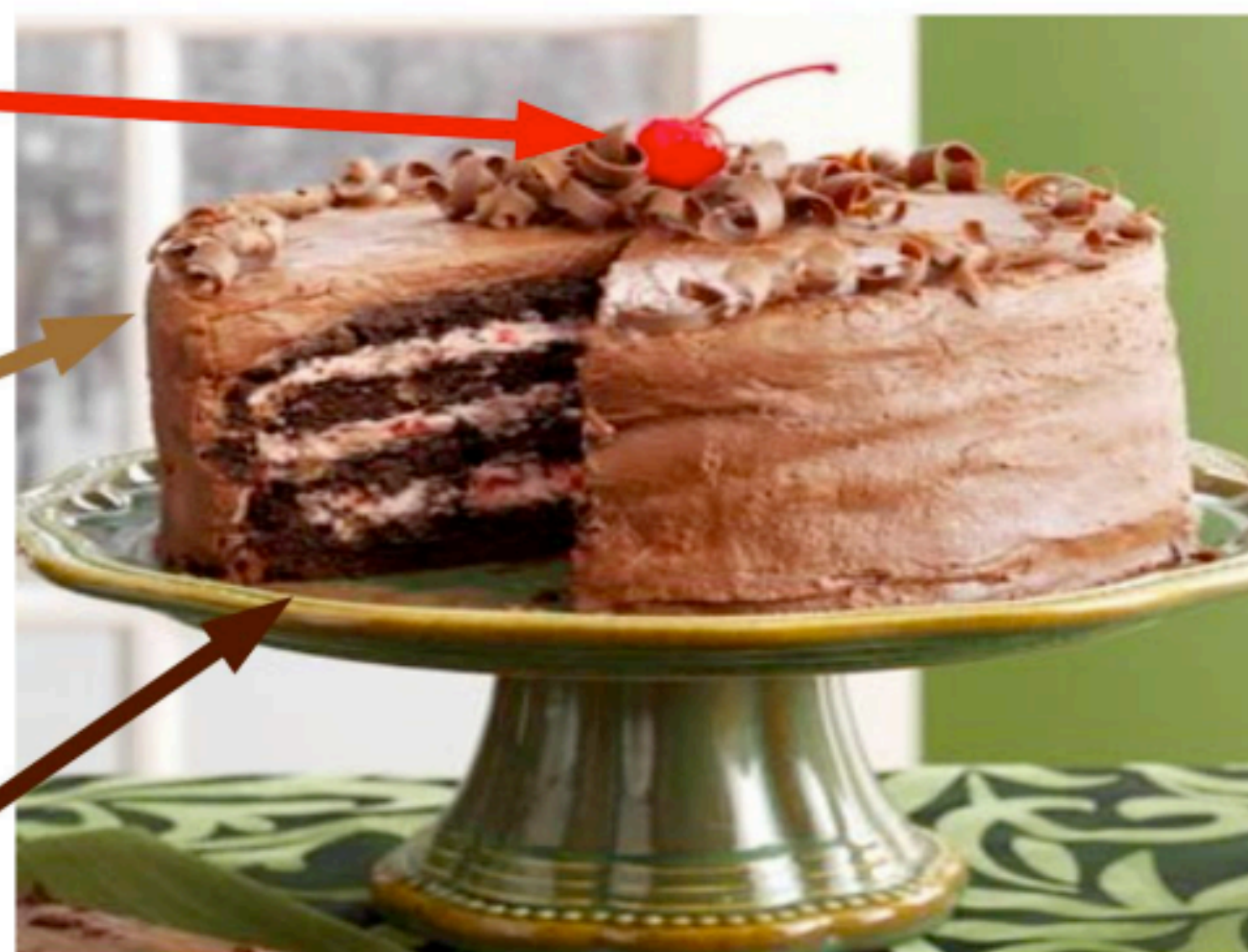
- ▶ **A few bits for some samples**

- ▶ **Supervised Learning (icing)**

- ▶ The machine predicts a category or a few numbers for each input
- ▶ Predicting human-supplied data
- ▶ **10→10,000 bits per sample**

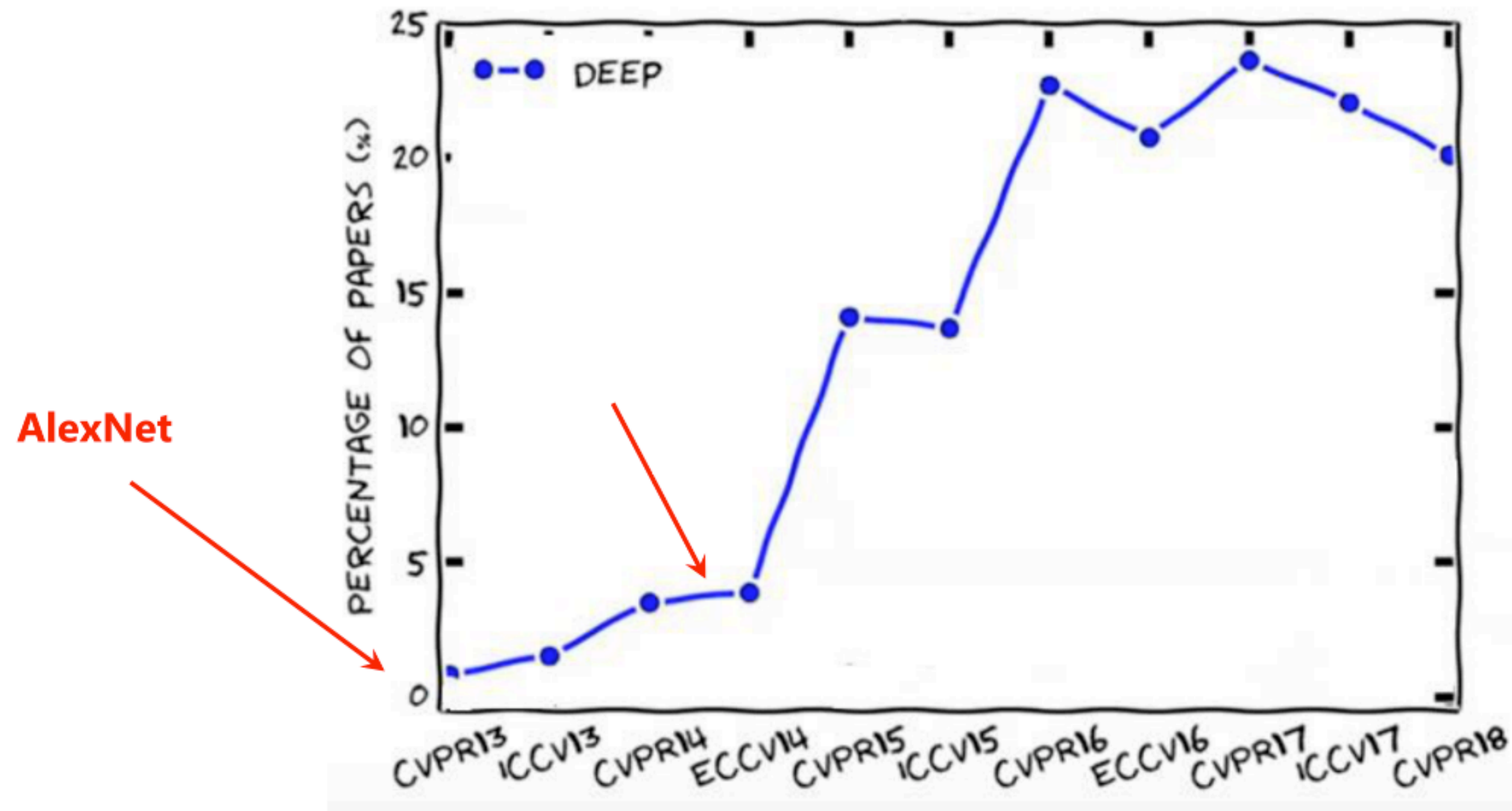
- ▶ **Self-Supervised Learning (cake génoise)**

- ▶ The machine predicts any part of its input for any observed part.
- ▶ Predicts future frames in videos
- ▶ **Millions of bits per sample**



Credit by Yann LeCun

A Story about ImageNet



Supervised Pretraining + Finetuning (2014)

- A kind of **transfer learning** paradigm



Pretraining on ImageNet Classification

Finetuning



Semantic Segmentation



Object Detection



Fine-grained Classification

Two Stories Meet Each Other

- **Unsupervised** Pretraining + Finetuning

Momentum Contrast for Unsupervised Visual Representation Learning

Kaiming He Haoqi Fan Yuxin Wu Saining Xie Ross Girshick

Facebook AI Research (FAIR)

Code: <https://github.com/facebookresearch/moco>



2019.11

MoCo

FAIR

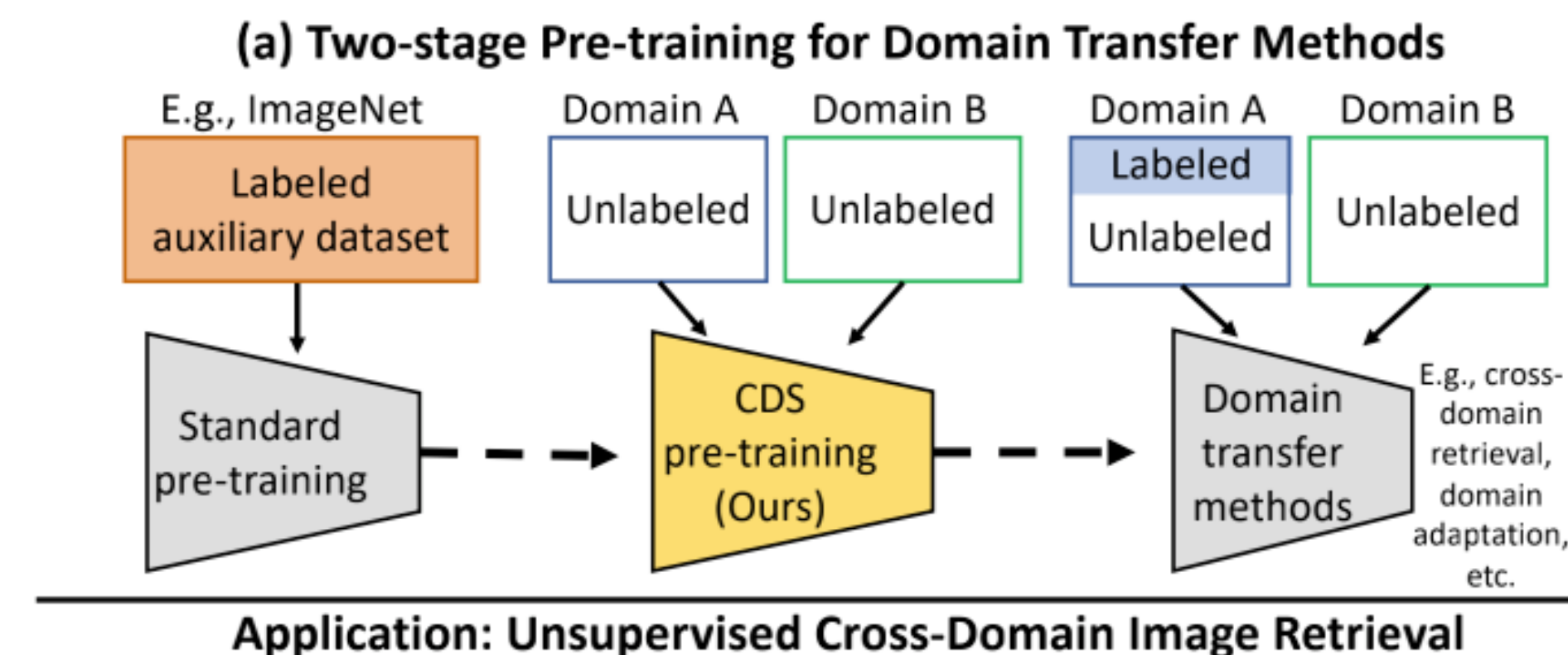
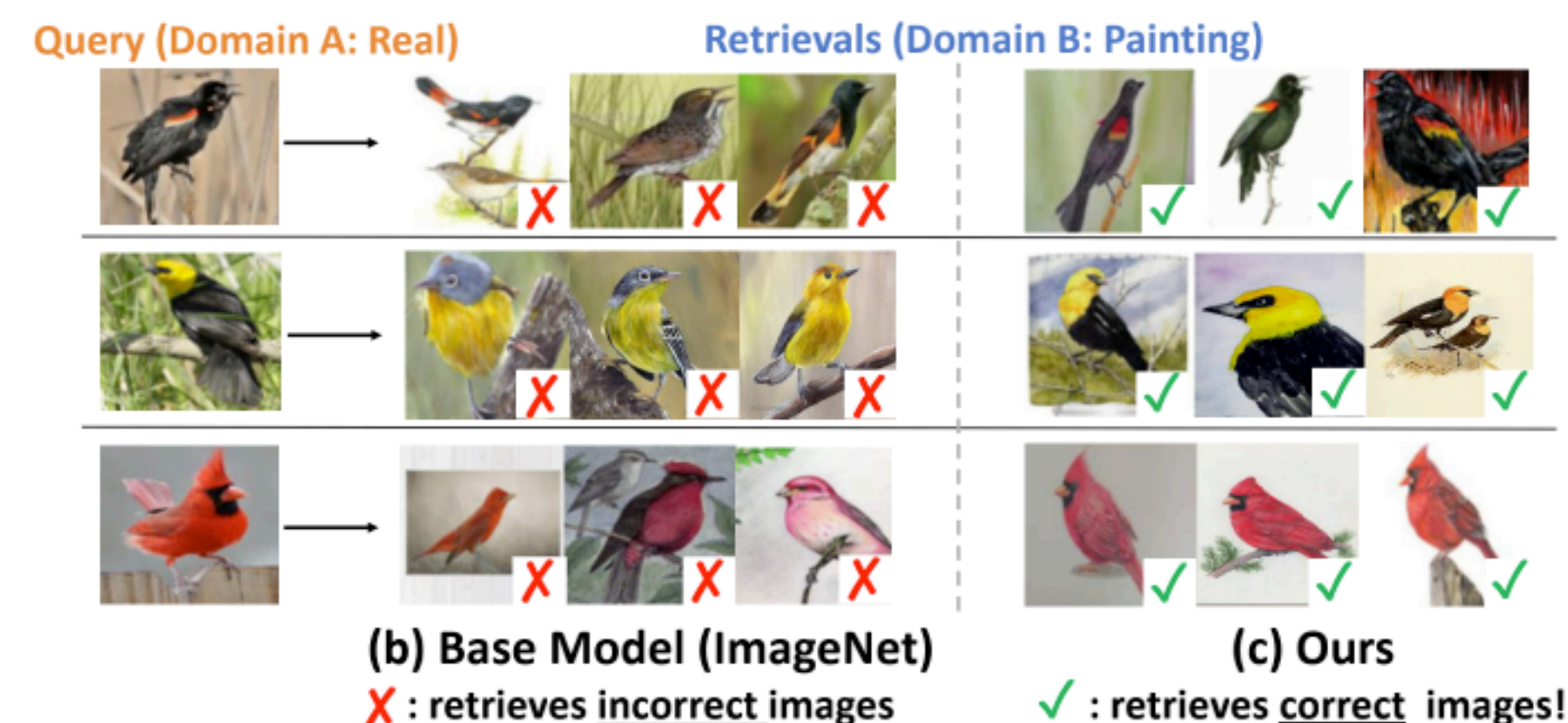
- For the first time, unsupervised pretraining outperform supervised pretraining on 7 down-stream tasks

ICCV 2021: CDS: Cross-Domain Self-supervised Pre-training

Donghyun Kim, Kuniaki Saito, Tar-Hyun Oh, Bryan A. Plummer, Stan Sclaroff, Kate Sarnko
Boston University, POSTECH, MIT-IBM Watson AI Lab

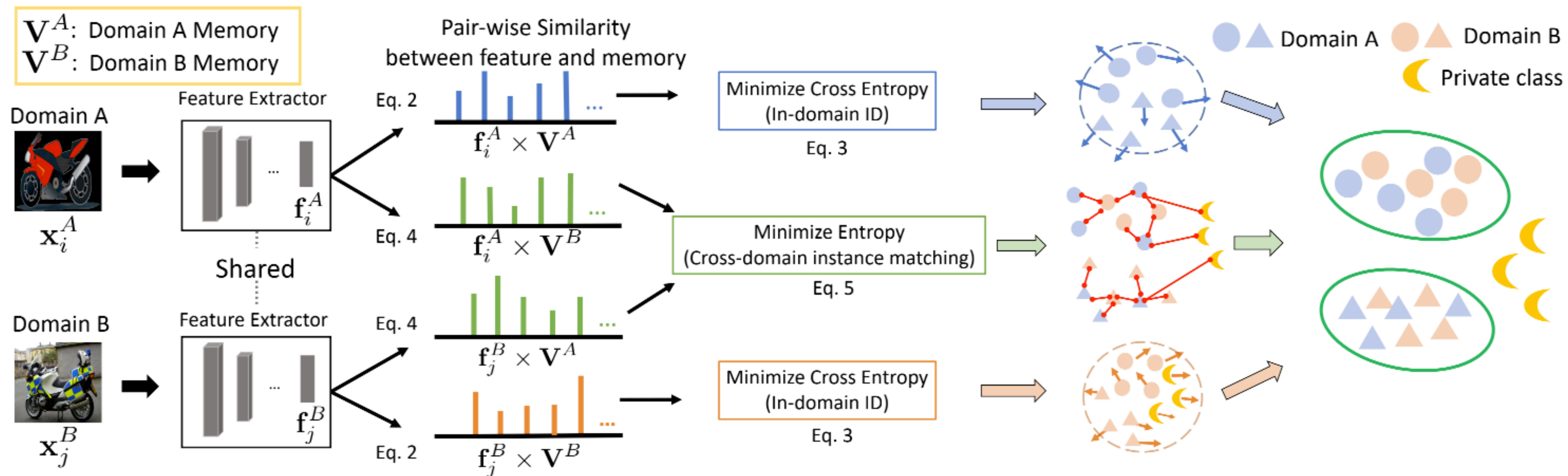
- Motivation:
- ImageNet上的预训练模型在表示学习上具有偏向性
 - SSL在单域无监督表示学习上具有很好的效果

- Method:
- 在预训练模型迁移到下游跨域任务的过程中，额外增加SSL Pre-Training作为过渡



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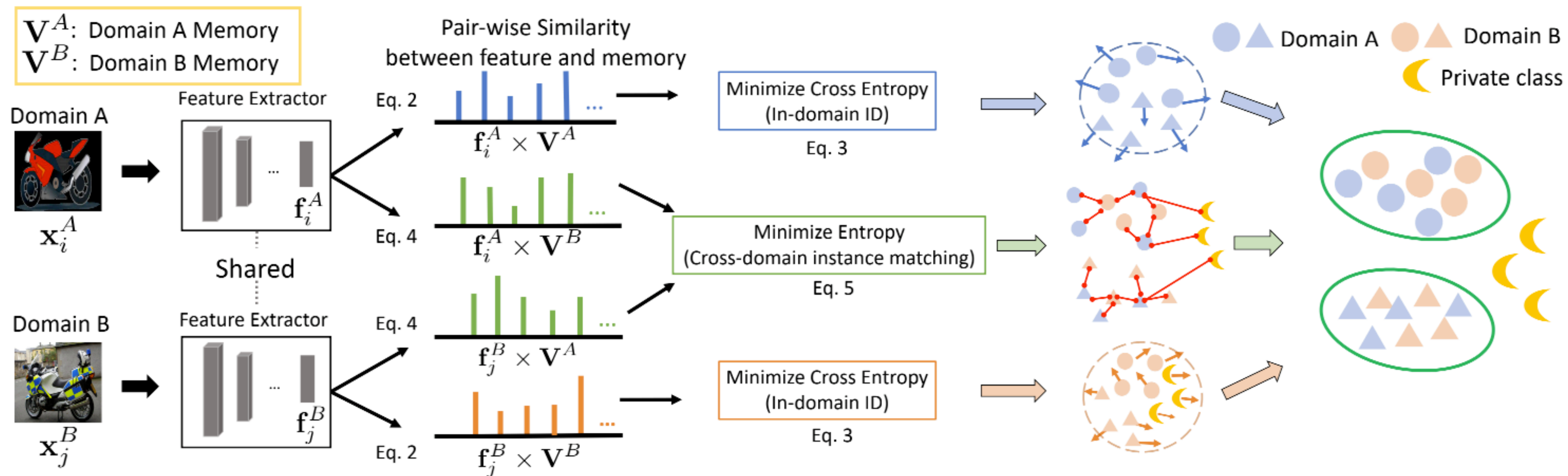


Step1:

$$P_i^A = \frac{\exp((\mathbf{v}_i^A)^\top \mathbf{f}_i^A / \tau)}{\sum_{k=1}^{N_A} \exp((\mathbf{v}_k^A)^\top \mathbf{f}_i^A / \tau)}, P_j^B = \frac{\exp((\mathbf{v}_j^B)^\top \mathbf{f}_j^B / \tau)}{\sum_{k=1}^{N_B} \exp((\mathbf{v}_k^B)^\top \mathbf{f}_j^B / \tau)}, \quad \mathcal{L}_{I-ID} = -\frac{1}{|\mathbb{B}|} (\sum_{i \in \mathbb{B}} \log P_i^A + \sum_{j \in \mathbb{B}} \log P_j^B),$$

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Step2:

$$P_{j',i}^{A \rightarrow B} = \frac{\exp((\mathbf{v}_{j'}^B)^\top \mathbf{f}_i^A / \tau)}{\sum_{k=1}^{N_B} \exp((\mathbf{v}_k^B)^\top \mathbf{f}_i^A / \tau)}, P_{i',j}^{B \rightarrow A} = \frac{\exp((\mathbf{v}_{i'}^A)^\top \mathbf{f}_j^B / \tau)}{\sum_{k=1}^{N_A} \exp((\mathbf{v}_k^A)^\top \mathbf{f}_j^B / \tau)}$$

$$\mathcal{L}_{CDM} = \frac{1}{|\mathbb{B}|} (\sum_{i \in \mathbb{B}} H(P_i^{A \rightarrow B}) + \sum_{j \in \mathbb{B}} H(P_j^{B \rightarrow A})),$$

$$H(P_i^{A \rightarrow B}) = - \sum_{j'}^{N_A} P_{j',i}^{A \rightarrow B} \log P_{j',i}^{A \rightarrow B},$$

$$H(P_j^{B \rightarrow A}) = - \sum_{i'}^{N_B} P_{i',j}^{B \rightarrow A} \log P_{i',j}^{B \rightarrow A},$$

CVPR 2021: Prototypical Cross-domain Self-supervised Learning for Few shot Unsupervised Domain Adaptation

Xiangyu Yue, Zangwei Zheng, Shanghang Zhang, Yang Gao
Trevor Darrell, Kurt Keutzer, Alberto Sangiovanni Vincentelli
UC Berkeley, Nanjing University, Tsinghua University

Motivation:

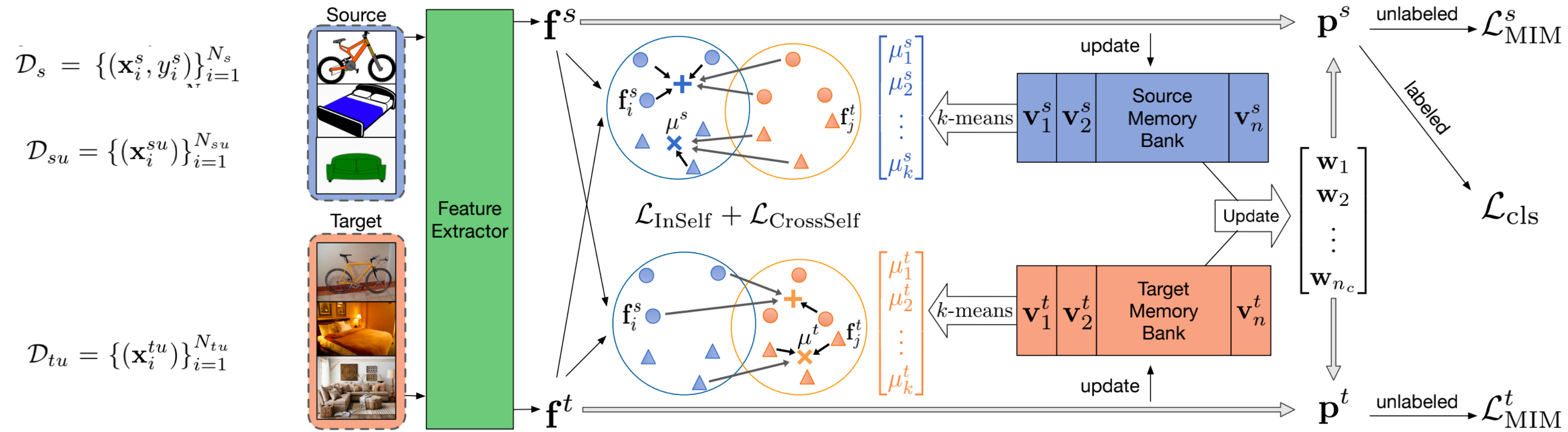
- CDS的域内损失减弱了数据的语义信息；域间损失在某些场景下受abnormal样本的影响
- two-stage pre-training在下游任务上的表现与DA方法有关

Method:

- 引入类原型思想，加强语义表示
- 设置自适应原型分类器，实现端到端训练

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In domain

Cross domain

$$P_{i,j}^s = \frac{\exp(\mu_j^s \cdot \mathbf{f}_i^s / \phi)}{\sum_{r=1}^k \exp(\mu_r^s \cdot \mathbf{f}_i^s / \phi)},$$

$$\mathcal{L}_{\text{PC}} = \sum_{i=1}^{N_s + N_{su}} \mathcal{L}_{\text{CE}}(P_i^s, c_s(i)) + \sum_{i=1}^{N_{tu}} \mathcal{L}_{\text{CE}}(P_i^t, c_t(i))$$

$$\mathcal{L}_{\text{InSelf}} = \frac{1}{M} \sum_{m=1}^M \mathcal{L}_{\text{PC}}^{(m)}$$

$$P_{i,j}^{s \rightarrow t} = \frac{\exp(\mu_j^t \cdot \mathbf{f}_i^s / \tau)}{\sum_{r=1}^k \exp(\mu_r^t \cdot \mathbf{f}_i^s / \tau)}.$$

$$H(P_i^{s \rightarrow t}) = - \sum_{j=1}^k P_{i,j}^{s \rightarrow t} \log P_{i,j}^{s \rightarrow t}.$$

$$\mathcal{L}_{\text{CrossSelf}} = \sum_{i=1}^{N_s + N_{su}} H(P_i^{s \rightarrow t}) + \sum_{i=1}^{N_{tu}} H(P_i^{t \rightarrow s})$$

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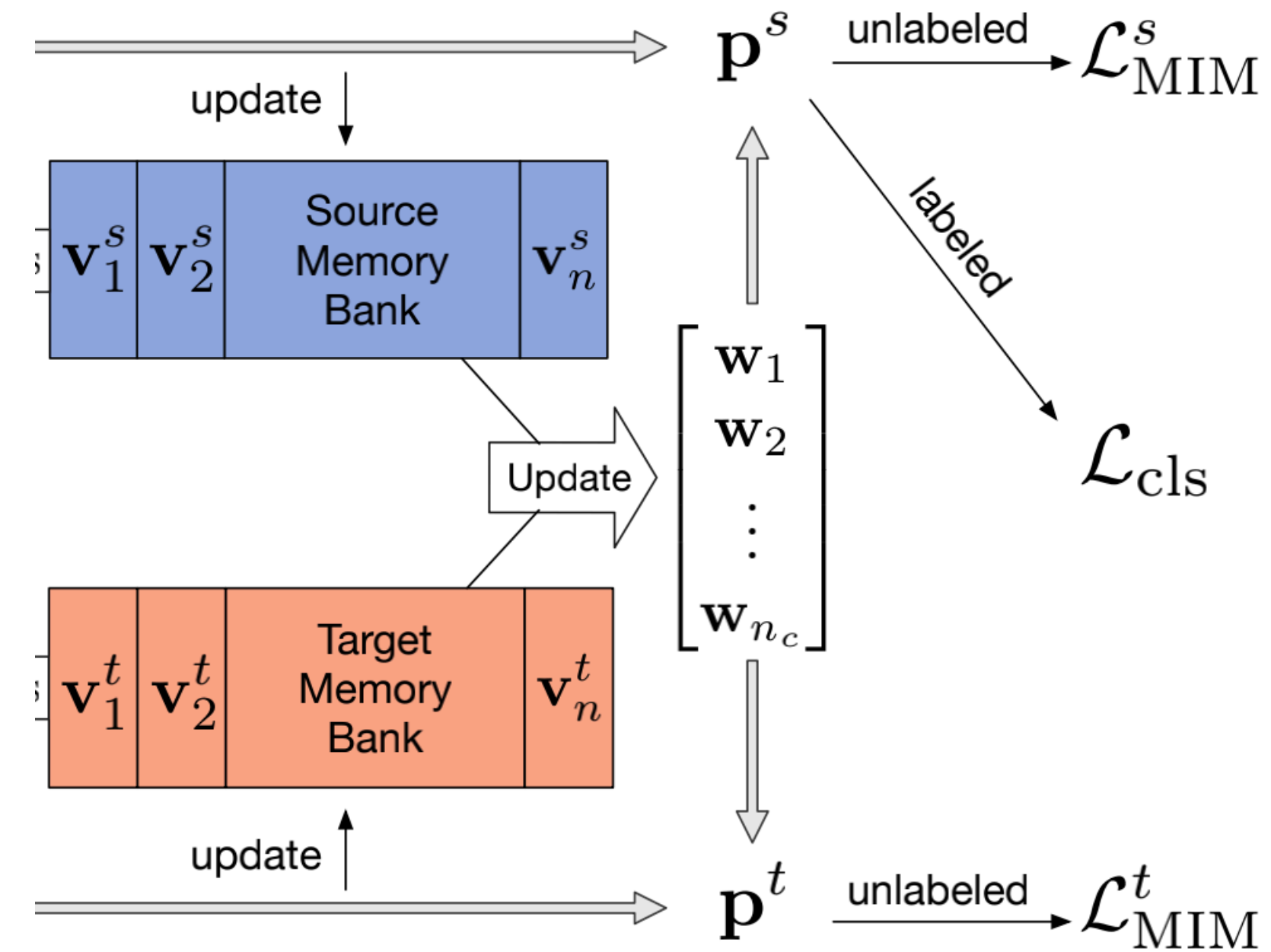
Adaptive Prototype-Classifier Learning

$$\mathbf{p}(\mathbf{x}) = \sigma\left(\frac{1}{T} \dot{\mathbf{W}}^T \mathbf{f}\right).$$

$$\mathcal{L}_{\text{cls}} = \mathbb{E}_{(\mathbf{x}, y) \in \mathcal{D}_s} \mathcal{L}_{CE}(\mathbf{p}(\mathbf{x}), y)$$

$$\hat{\mathbf{w}}_i^s = \frac{1}{|\mathcal{D}_{s+}^{(i)}|} \sum_{\mathbf{x} \in \mathcal{D}_{s+}^{(i)}} \mathbf{V}^s(\mathbf{x}); \hat{\mathbf{w}}_i^t = \frac{1}{|\mathcal{D}_{tu}^{(i)}|} \sum_{\mathbf{x} \in \mathcal{D}_{tu}^{(i)}} \mathbf{V}^t(\mathbf{x})$$

$$\mathbf{w}_i = \begin{cases} \text{unit}(\hat{\mathbf{w}}_i^s) & \text{if } |\mathcal{D}_{tu}^{(i)}| < t_w \\ \text{unit}(\hat{\mathbf{w}}_i^t) & \text{otherwise} \end{cases}$$



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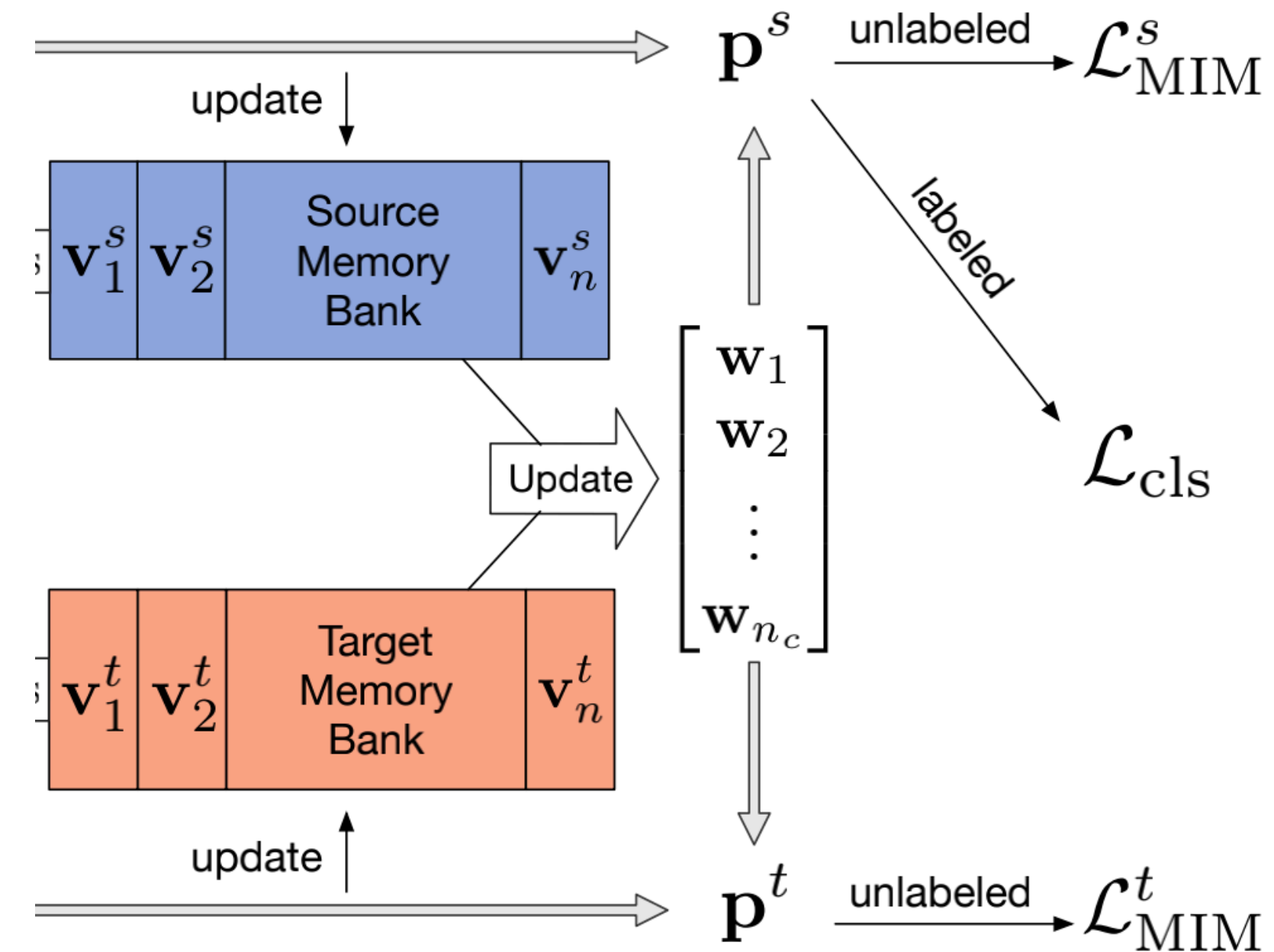
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Adaptive Prototype-Classifier Learning

$$\mathcal{I}(y; \mathbf{x}) = \mathcal{H}(\mathbf{p}_0) - \mathbb{E}_{\mathbf{x}}[\mathcal{H}(p(y|\mathbf{x}; \theta))],$$

$$\mathcal{L}_{\text{MIM}} = -\mathcal{I}(y; \mathbf{x})$$

$$\begin{aligned} \mathcal{L}_{PCS} = & \mathcal{L}_{\text{cls}} + \lambda_{\text{in}} \cdot \mathcal{L}_{\text{InSelf}} \\ & + \lambda_{\text{cross}} \cdot \mathcal{L}_{\text{CrossSelf}} + \lambda_{\text{mim}} \cdot \mathcal{L}_{\text{MIM}} \end{aligned}$$



总结

- Cross-domain Self-supervised Learning将SSL扩展到了跨域场景下
- 用Prototype思想代替传统分类器在OOD场景下有更多发挥的空间