

## PHY 101 : Worksheet-1

*Bold faced objects are vectors*

The position vector  $\mathbf{x}(t)$  of a particle in a co-ordinate system is given as a function of time  $t$  as

$$\mathbf{x}(t) = \alpha t^2 \hat{\mathbf{i}} + \beta t^3 \hat{\mathbf{j}},$$

where  $\alpha, \beta$  are constants. Find out

1. The velocity of the particle  $\mathbf{v}(t) = d\mathbf{x}(t)/dt$  and the acceleration  $\mathbf{a}(t) = d\mathbf{v}(t)/dt$ .
2. Angle between the position vector and the velocity vector at  $t = 2$ .
3. Angle between the velocity vector and the acceleration vector at  $t = 5$ .
4. The angular momentum vector  $\mathbf{L}(t)$  if the mass of the particle is  $m$  units.

A unit mass particle with a charge  $q$  enters a region of magnetic field  $\mathbf{B}$  and starts experiencing a force  $\mathbf{F}(t) = -2q\omega \sin(\omega t) \hat{\mathbf{i}} - 2q\omega \cos(\omega t) \hat{\mathbf{j}}$ , where  $\omega$  is a constant. Its location at any time  $t$  is given as the position vector  $\mathbf{r}(t) = 2 \sin(\omega t) \hat{\mathbf{i}} + 2 \cos(\omega t) \hat{\mathbf{j}}$

1. Find out the magnetic field in this set-up.
2. Find out the angular momentum  $\mathbf{L}$  of the particle w.r.t. the origin.
3. What is the relation between the angular momentum and the magnetic field?
4. Find out  $\mathbf{r} \times \mathbf{L}$  and  $\mathbf{v} \times \mathbf{L}$  in this set-up.

[Hint :  $d \sin(y)/dy = \cos(y)$  and  $d \cos(y)/dy = -\sin(y)$  ]

## Worksheet - 1

Q.1

$$\vec{x}(t) = \alpha t^2 \hat{i} + \beta t^3 \hat{j}$$

$$(i) \quad \vec{v}(t) = \frac{d\vec{x}}{dt} = \frac{d}{dt} (\alpha t^2 \hat{i} + \beta t^3 \hat{j})$$
$$= \alpha \hat{i} \frac{d}{dt} t^2 + \beta \hat{j} \frac{d}{dt} t^3$$

Since  $\alpha, \beta, \hat{i}, \hat{j}$  do not change with  $t$

$$= 2\alpha t \hat{i} + 3\beta t^2 \hat{j}$$

$$\text{Acceleration} \quad \vec{a}(t) = \frac{d\vec{v}}{dt} = \frac{d}{dt} (2\alpha t \hat{i} + 3\beta t^2 \hat{j})$$

$$= 2\alpha \hat{i} + 6\beta t \hat{j}$$

(ii) Let the angle between  $\vec{x}$  and  $\vec{v}$  be  $\theta(t)$

$$\Rightarrow \vec{x} \cdot \vec{v} = |\vec{x}| |\vec{v}| \cos \theta(t)$$

$$|\vec{x}| = \sqrt{\alpha^2 t^4 + \beta^2 t^6}$$

$$|\vec{v}| = \sqrt{4\alpha^2 t^2 + 9\beta^2 t^4}$$

$$(\alpha t^2 \hat{i} + \beta t^3 \hat{j}) \cdot (2\alpha t \hat{i} + 3\beta t^2 \hat{j})$$
$$2\alpha^2 t^3 + 3\beta^2 t^5 = \sqrt{\alpha^2 t^4 + \beta^2 t^6} \sqrt{4\alpha^2 t^2 + 9\beta^2 t^4} \cos \theta(t)$$

$$\therefore \cos \theta(t) = \frac{2\alpha^2 t^3 + 3\beta^2 t^5}{\sqrt{\alpha^2 t^4 + \beta^2 t^6} \sqrt{4\alpha^2 t^2 + 9\beta^2 t^4}}$$

At  $t = 2$

$$\cos \theta(2) = \frac{8\alpha^2 + 106\beta^2}{\sqrt{16\alpha^2 + 64\beta^2} \sqrt{16\alpha^2 + 144\beta^2}}$$

(iii) Let the angle between  $\vec{a}$  and  $\vec{v}$  be  $\tilde{\theta}(t)$

$$|\vec{a}| = \sqrt{4\alpha^2 + 36\beta^2 t^2}$$

$$\vec{a} \cdot \vec{v} = |\vec{a}| |\vec{v}| \cos \tilde{\theta}(t)$$

$$(2\alpha \hat{i} + 6\beta t \hat{j}) \cdot (2\alpha t \hat{i} + 3\beta t^2 \hat{j})$$

$$= 4\alpha^2 t + 18\beta^2 t^3 = \sqrt{4\alpha^2 + 36\beta^2 t^2} \sqrt{4\alpha^2 t^2 + 9\beta^2 t^4} \cos \tilde{\theta}(t)$$

$$\Rightarrow \cos \tilde{\theta}(t) = \frac{4\alpha^2 t + 18\beta^2 t^3}{\sqrt{4\alpha^2 + 36\beta^2 t^2} \sqrt{4\alpha^2 t^2 + 9\beta^2 t^4}}$$

(iv) Angular momentum

$$\begin{aligned}\vec{L} &= \vec{r} \times \vec{p} = \vec{r} \times m \vec{v} \\&= m (\alpha t^2 \hat{i} + \beta t^3 \hat{j}) \times (2\alpha t \hat{i} + 3\beta t^2 \hat{j}) \\&= m [\alpha \beta t^4 \hat{k} - 2\alpha \beta t^4 \hat{k}] \\&= \alpha \beta t^4 \hat{k}\end{aligned}$$

Q.2 In the magnetic field a charged particle experiences a force

$$\begin{aligned}\vec{F} &= q (\vec{v} \times \vec{B}) \\-2qw(\sin \omega t \hat{i} + \cos \omega t \hat{j}) &= q \left( \frac{d\vec{r}}{dt} \times \vec{B} \right)\end{aligned}$$

$$\begin{aligned}\vec{r} &= 2 \sin \omega t \hat{i} + 2 \cos \omega t \hat{j} \\ \vec{v} = \frac{d\vec{r}}{dt} &= 2 \hat{i} \frac{d}{dt} \sin \omega t + 2 \hat{j} \frac{d}{dt} \cos \omega t\end{aligned}$$

because  $2, \hat{i}, \hat{j}$  are constants

$$\frac{d}{dt} \sin \omega t = \frac{d(\omega t)}{dt} \frac{d}{d(\omega t)} \sin \omega t = \omega \cos \omega t$$

since  $\omega$  is constant

$$\frac{d}{dt} \cos \omega t = \frac{d(\omega t)}{dt} \frac{d}{d(\omega t)} \cos \omega t = -\omega \sin \omega t$$

$$\begin{aligned}
 \vec{v} &= 2\omega \cos \omega t \hat{i} - 2\omega \sin \omega t \hat{j} \\
 &- 2q\omega (\sin \omega t \hat{i} + \cos \omega t \hat{j}) \\
 &= 2q\omega (\cos \omega t \hat{i} - \sin \omega t \hat{j}) \times \vec{B}
 \end{aligned}$$

If  $\vec{B} = B_0 \hat{k}$ , the RHS is

$$\begin{aligned}
 &2q\omega B_0 (\cos \omega t (-\hat{j}) - \sin \omega t \hat{i}) \\
 &= -2q\omega B_0 (\sin \omega t \hat{i} + \cos \omega t \hat{j})
 \end{aligned}$$

Comparing it to LHS,  $B_0 = 1$  unit

$$\therefore \vec{B} = \hat{k}$$

$$\begin{aligned}
 \vec{L} &= \vec{r} \times m \vec{v} = (2 \sin \omega t \hat{i} + 2 \cos \omega t \hat{j}) \\
 &\quad \times (2\omega \cos \omega t \hat{i} - 2\omega \sin \omega t \hat{j}) \\
 &= -4\omega \sin^2 \omega t \hat{k} - 4\omega \cos^2 \omega t \hat{k} \\
 &= -4\omega \hat{k}
 \end{aligned}$$

$$(iii) \quad \vec{L} = -\frac{\vec{B}}{4\omega}$$

$$(iv) \quad \vec{r} \times \vec{L}$$

$$\Rightarrow (2\sin\omega t \hat{i} + 2\cos\omega t \hat{j}) \times (-4\omega \hat{k}) \\ = 8\omega \sin\omega t \hat{j} - 8\omega \cos\omega t \hat{i}$$

$$\vec{v} \times \vec{L}$$

$$(2\omega \sin\omega t \hat{i} - 2\omega \cos\omega t \hat{j}) \times (-4\omega \hat{k}) \\ = 8\omega^2 \sin\omega t \hat{j} + 8\omega^2 \cos\omega t \hat{i}$$