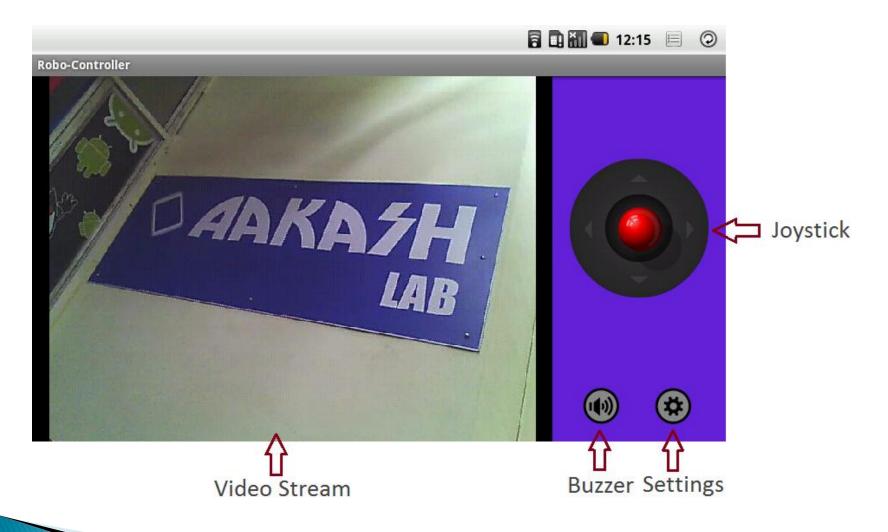


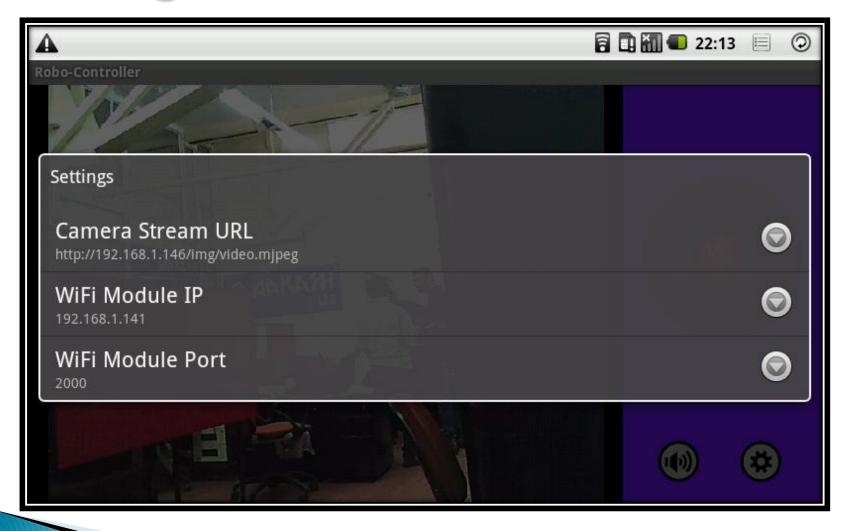
ROBO

A Robot's motion controller App with video streaming

Robo-Controller



Settings



Requirements

Hardware

- Fire Bird V (robot, programmer, charger)
- WiFly-EZX module for Fire Bird V
- USB to serial converter board (for configuring WiFly module)
- ▶ IP Camera
- Wi-Fi Router
- Tablet
- Windows Laptop with Wi-Fi capability

Requirements

Software

- ► For Fire Bird V AVR Studio 4.17, NEX AVR STK500V2
- For WiFly Module WiFly Driver, USB to Serial COM driver, Bray Terminal
- For IP Camera Installation CD (provided with camera)

Configurations

Wi-Fly EZX Module

Following specifications are used for configuring the Wi-Fi module

- Authentication type Open
- Connection type UDP
- Joining policy Connect to the access point matching the stored SSID

Configurations

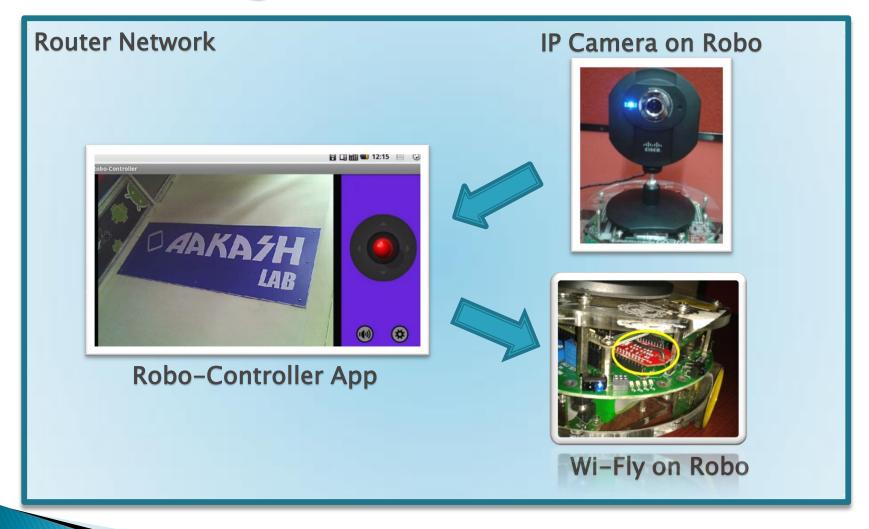
IP Camera

The IP Camera is configured with the Router and it supports following stream formats-

- RTSP Real Time Streaming Protocol
- MJPEG Motion JPEG

The present application uses MJPEG stream to show the video.

Flow Diagram



Working-Motion Control

 A virtual joystick is used in the Application to control the Robo's motion.

- 6 Different types of turns along with forward and backward motion are provided.
- Unique data is sent to the Wi-Fi module from the application on the tablet corresponding to the area in which the joystick has moved.
- The Wi-Fi module transfers that data to the microcontroller on Robo which controls its motion accordingly.

Working-IP Camera

- ▶ The IP camera streams its video over Wi-Fi in MJPEG format using its built-in Wi-Fi server.
- The application captures and decodes this stream using a predefined URL in Settings of the app.

Applications

- Surveillance
- Hostage situations

Any Questions ??

