# **Dataflow Analysis**

(Reaching Definitions, Live Variable Analysis)

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#### Content

- Recap (with LLVM examples):
  - Generating CFG
  - Printing Dominators
  - Visualizing Domtree
  - Printing Domfrontier of a basic block
  - SSA construction in mem2reg pass

Dataflow Analysis

## SSA

Converting from unrestricted form to SSA form

- Where should we insert phi nodes?

  Dominance frontiers
- What do we need to do after inserting phi nodes?
  Rename variables so that every assignment gets a unique name

# Flow Graphs - Representation

```
entry:
opt -passes=dot-cfg
                                                                            %retval = alloca i32, align 4
                                                                            %x = alloca i32, align 4
                                                                            %i = alloca i32, align 4
-cfg-dot-filename-prefix=example2
                                                                            store i32 0, ptr %retval, align 4
                                                                             store i32 5, ptr %x, align 4
                                                                             store i32 0, ptr %i, align 4
example2.11
                                                                            br label %for.cond
                                                                       for.cond:
        int main() {
                                                                        %0 = load i32, ptr %i, align 4
                                                                        %cmp = icmp slt i32 %0, 10
              int x, i;
                                                                        br il %cmp, label %for.body, label %for.end
              x = 5;
              for(i=0;i<10;i=i+1
                                                 for.body:
                                                                                              for end:
                     if (i < 5)
                                                 %1 = load i32, ptr %i, align 4
                                                                                              %5 = load i32, ptr %x, align 4
                                                  %cmp1 = icmp slt i32 %1. 5
                                                                                               %call = call i32 (ptr, ...) @printf(ptr noundef 0.str, i32 noundef %5)
                                                  br il %cmpl, label %if.then, label %if.end
                       x = x+1;
                                                                                               ret i32 0
                     x = x*2:
10
                                             if.then:
                                             %2 = load i32, ptr %x, align 4
               printf("%d",x);
11
                                             %add = add nsw i32 %2, 1
                                             store i32 %add, ptr %x, align 4
12
              return 0;
                                             br label %if.end
13
                                                           if.end:
                                                           %3 = load i32, ptr %x, align 4
                                                           %mul = mul nsw i32 %3, 2
                                                           store i32 %mul, ptr %x, align 4
                                                           br label %for.inc
                                                                   for inc:
                                                                   %4 = load i32, ptr %i, align 4
                                                                   %add2 = add nsw i32 %4, 1
                                                                   store i32 %add2, ptr %i, align 4
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                                                                   br label %for.cond, !llvm.loop !6
                                                                                            CFG for 'main' function
```

#### **Dominators**

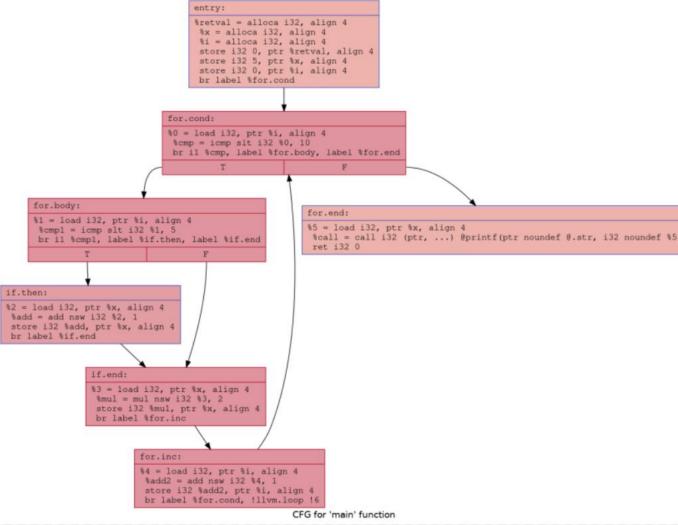
- Describe relationship between basic blocks
  - A block dominates other if it is guaranteed to execute before the other
  - Formally:
    - if all paths from entry of CFG to node B pass through node A then we say that A dominates B
  - The relationship is reflexive i.e. node B dominates itself

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#### **Dominators**

opt-load-pass-plugin=./fnmodpass/build/MyPass.so -passes="my-modulepass" -disable-output example2.bc

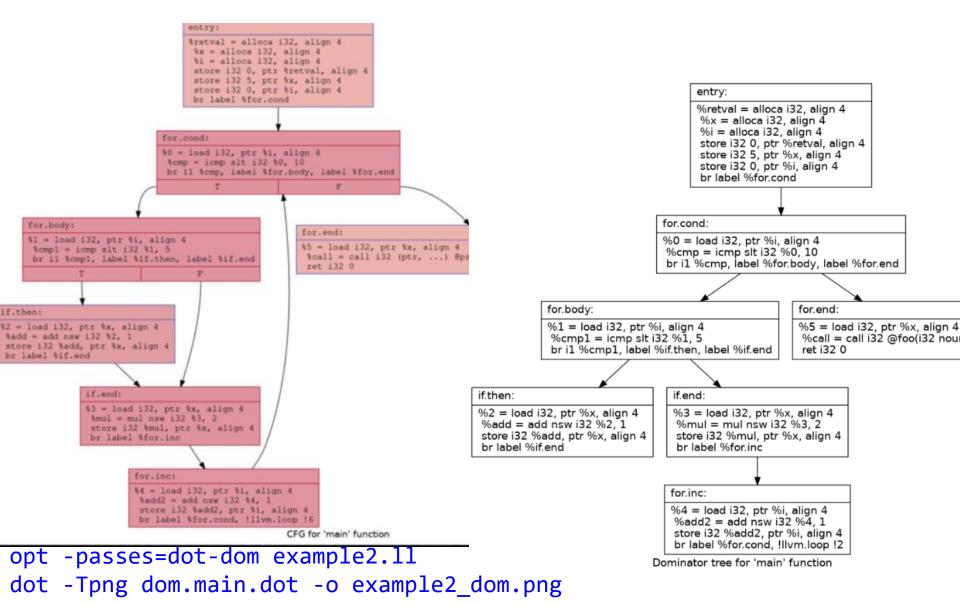
[ModulePass] Function: mai entry dominates entry entry dominates for.cond entry dominates for body entry dominates if then entry dominates if.end entry dominates for.inc entry dominates for.end for cond dominates for cond for.cond dominates for.body for .cond dominates if .then for.cond dominates if.end for .cond dominates for .inc for cond dominates for end for.body dominates for.body for.body dominates if.then for.body dominates if.end for.body dominates for.inc if then dominates if then if.end dominates if.end if.end dominates for inc for inc dominates for inc for end dominates for end



#### **Dominator Tree**

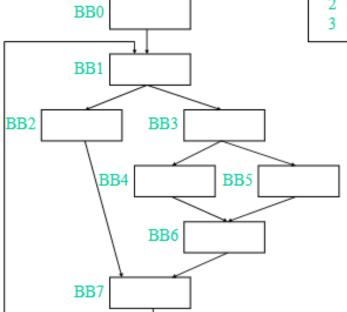
- A data structure for tracking dominator relation
- A node in the tree dominates all the nodes of the subtree, for which the node is the root
- Terminology:
  - Strict domination: A strictly dominates B if it dominates B and A ≠ B
  - Immediate domination: A dominates B and does not strictly dominate any other node that strictly dominates B (e.g. A is B's parent in the dominator tree)
  - Domination frontier (DF): B is in the DF of A if
    - A does not dominate B but
    - dominates a predecessor of B
  - Post domination: A post-dominates B if on *all* paths from B to the exit node, A appears.

## **Dominator Tree**

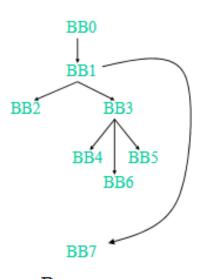


#### **Dominator Tree**

First BB is the root node, each node dominates all of its descendants



BB	DOM	BB	DOM
0	0	4	0,1,3,4
1	0,1	5	0,1,3,5
2	0,1,2	6	0,1,3,6
3	0,1,3	7	0,1,7



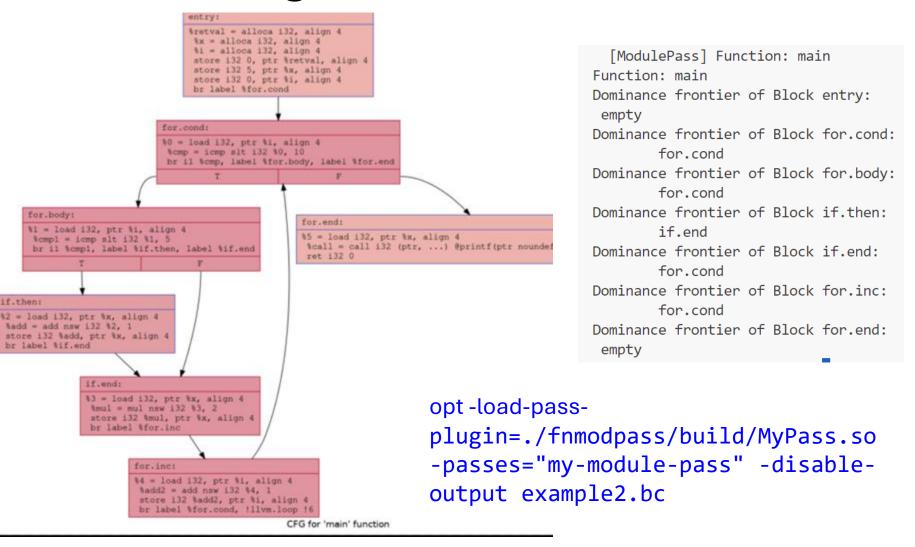
Dom tree

# Finding Dominance Frontiers

#### Recall:

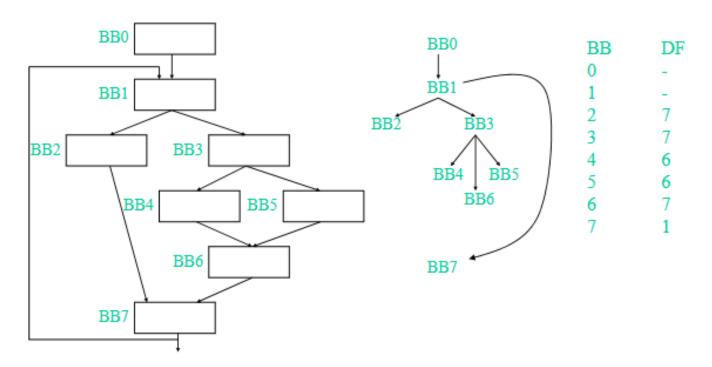
- Dominance frontier of a node X is the set of nodes Y such that
  - X dominates a predecessor of Y
  - X does not strictly dominate Y

# **Finding Dominance Frontiers**



Note: opt -passes=domtree ... does not work as domtree is an internal pass

#### **Computing Dominance Frontiers**



For each join point X in the CFG

For each predecessor of X in the CFG

Run up to the IDOM(X) in the dominator tree,

adding X to DF(N) for each N between X and IDOM(X)

8

COS 598C - Advanced Compilers

**Prof. David August** 

# Converting to SSA form

Where do we insert phi nodes?

```
for v in vars {
    for d in defs[v] {
        for block in DF[d] {
            if (block does not have a phi node)
                add phi node to block
            if (block is not part of defs[v])
                 add block to defs[v]
        }
    }
}
```

```
clang -00 -emit-llvm -S ex3.c -o ex3.ll
                                                       int test(int a, int b, _Bool c) {
                                                            int res;
                                                            if (c)
2
    entry:
                                                  4
                                                                 res = a;
      %x = alloca i32
3
      br i1 %cond, label %then, label %else
4
                                                            else
5
                                                  6
                                                                 res = b:
6
    then:
7
      store i32 %a, i32* %x
                                                            return res;
8
      br label %merge
                                                 8
9
10
    else:
      store i32 %b, i32* %x
11
      br label %merge
12
13
14
    merge:
      %val = load i32, i32* %x
15
      ret i32 %val
16
17
                     , after mem2reg pass: opt -passes=mem2reg ex3.ll -S -o
 5
     entrv:
                                                 ex3_mem2reg.ll
       br i1 %cond, label %then, label %else
 6
 7
     then:
                                                        ; preds = %entry
 8
 9
       br label %merge
10
11
     else:
                                                        ; preds = %entry
12
       br label %merge
13
14
                                                        ; preds = %else, %then
     merge:
15
       %x.0 = phi i32 [ %a, %then ], [ %b, %else ]
16
       ret i32 %x.0
                                                                                             14
17
```

# Try it yourself

- Generate CFG (in png format)
- Use the code provided and modify to print immediate dominators for each basic block
- Generate domtree (in png format)
- Print dominance frontier of each block

Do your observations coincide with those presented in slides?

# Dataflow Analysis – Motivation

# Optimize Loops -Factoring Invariant Expressions

Expressions cannot always be moved out!

Case I: We can move t = a op b if the statement <u>dominates</u> all loop exits where t is live

A node bb1 dominates node bb2 if all paths to bb2 must go

through bb1

```
for (...) {
    if(*)
    a = 100
}
c=a
```

# Optimize Loops -Factoring Invariant Expressions

Expressions cannot always be moved out!

Case II: We can move t = a op b if there is only one definition of t in the loop

```
for (...) {
   if(*)
      a = 100
   else
      a = 200
}
```

# Optimize Loops -Factoring Invariant Expressions

Expressions cannot always be moved out!

**Case III:** We can move t = a op b if t is not defined before the loop, where the definition reaches t's use after the loop

```
a=5
for (...) {
    a = 4+b
}
c=a
```

# Dataflow Analysis – More motivation

# Useful optimizations

- Common subexpression elimination (global)
  - Need to know which expressions are available at a point
- Dead code elimination
  - Need to know if the effects of a piece of code are never needed, or if code cannot be reached
- Constant folding
  - Need to know if variable has a constant value
- So how do we get this information?

# Dataflow analysis

- Framework for doing compiler analyses to drive optimization
- Works across basic blocks
- Examples
  - Constant propagation: determine which variables are constant
  - Liveness analysis: determine which variables are live
  - Available expressions: determine which expressions have valid computed values
  - Reaching definitions: determine which definitions could "reach" a use

# Dataflow Analysis - Common Traits

#### Common requirement among global optimizations:

- Know a particular property X at a program point
   (There is a program point one before a statement and one after a statement)
  - Say that property X definitely holds.

OR

Don't know if property X holds or not (okay to be conservative)

This requires the knowledge of entire program

# Dataflow analysis

- Framework for doing compiler analyses to drive optimization
- Works across basic blocks
- Examples
  - Constant propagation: determine which variables are constant
  - Liveness analysis: determine which variables are live
  - Available expressions: determine which expressions have valid computed values
  - Reaching definitions: determine which definitions could "reach" a use

# Liveness – Recap...

- A variable X is live at statement S if:
  - There is a statement S' that uses X
  - There is a path from S to S'
  - There are no intervening definitions of X

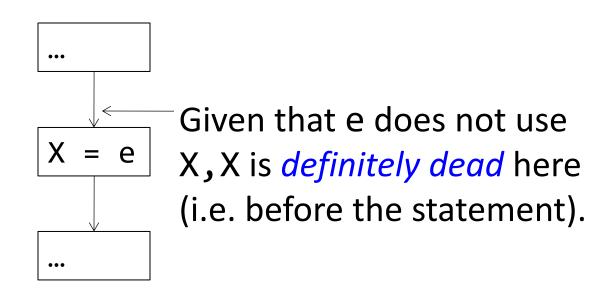
# Liveness – Recap...

- A variable X is dead at statement S if it is not live at S
  - What about  $\dots$ ; X = X + 1?

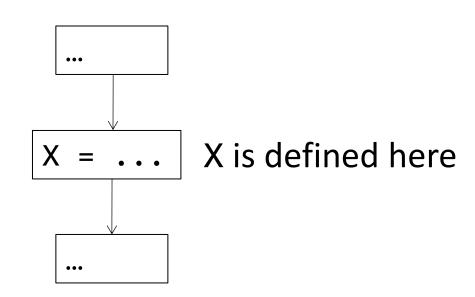
Choose the statements that are true with reference to the code snippet shown. Assume that this is a basic block (a sequence of statements) and this basic block is a part of a CFG.

- 1. X:=1
- 2. X:=4
- 3. Y:=X

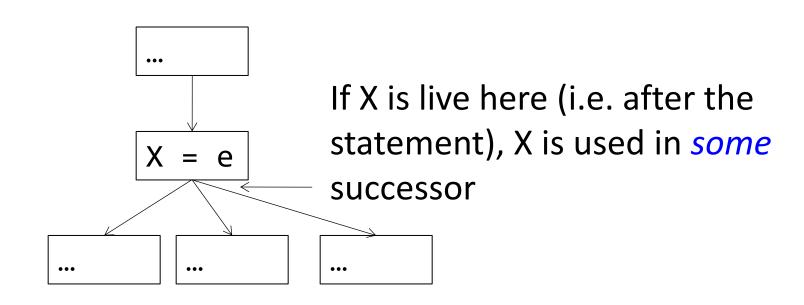
- a X is definitely dead at statement 1 (value of X is never used again)
- b X is definitely dead at statement 2
- C X is live at statement 2
- d Y must be live at statement 3
- e None



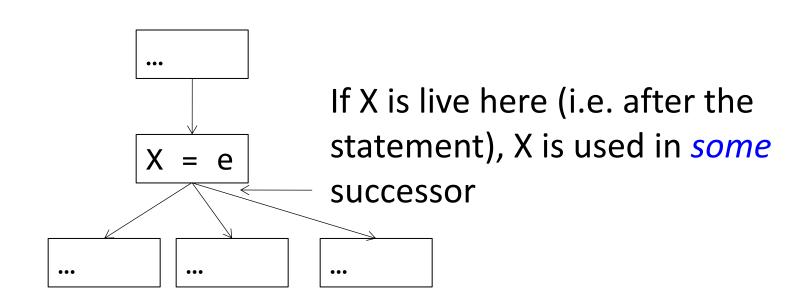
• Define a set LiveIn(b), where b is a basic block, as: the set of all variables live at the entrance of a basic block



Define a set Def(b), where b is a basic block,
 as: the set of all variables that are defined in b

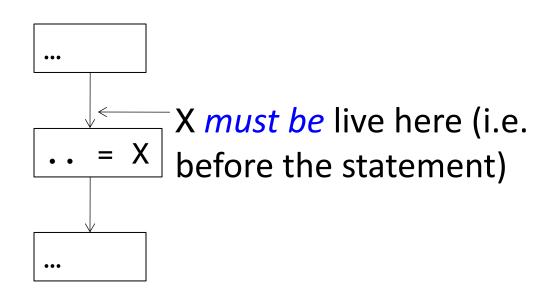


• Define a set LiveOut(b), where b is a basic block, as: the set of all variables live at the exit of a basic block



• If S(b) is the set of all successors of b, then

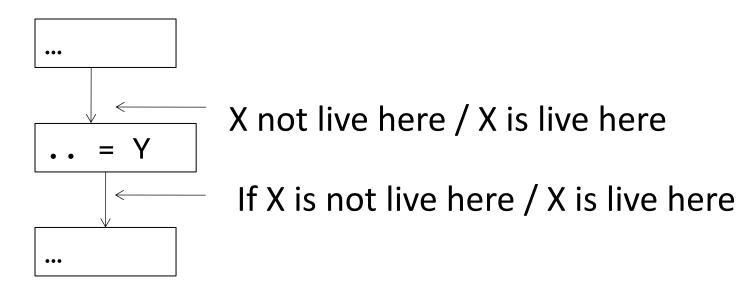
LiveOut(b) = 
$$\bigcup_{i \in S(b)}$$
 LiveIn(i)



• Define a set LiveUse(b), where b is a basic block, as the set of all variables that are used before they are defined within block b. LiveIn(b) ⊇ LiveUse(b)

## Liveness in a CFG - Observation

•If a node neither uses nor defines X, the liveness property remains the same before and after executing the node



• If a variable is live on exit from b, it is either defined in b or live on entrance to b

•Under what scenarios can a variable be live at the entrance of a basic block?

• If a variable is live on exit from b, it is either defined in b or live on entrance to b

- •Under what scenarios can a variable be live at the entrance of a basic block?
  - •Either the variable is used in the basic block

• If a variable is live on exit from b, it is either defined in b or live on entrance to b

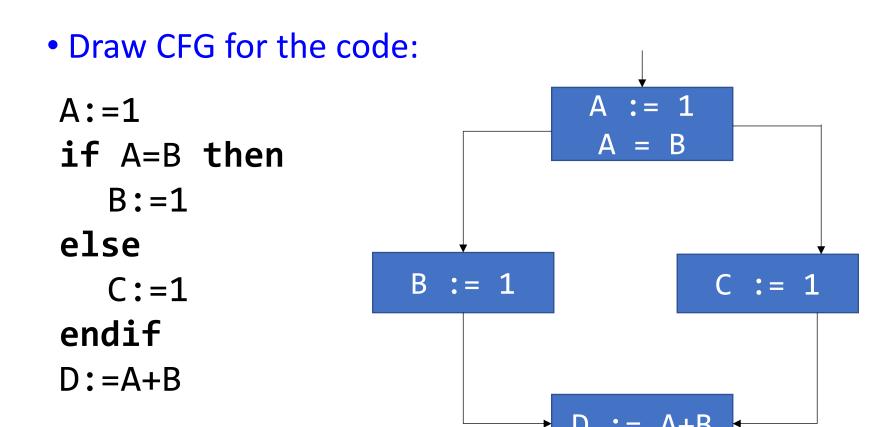
- •Under what scenarios can a variable be live at the entrance of a basic block?
  - •Either the variable is used in the basic block
  - •OR the variable is live at exit and not defined within the block

#### Liveness in a CFG

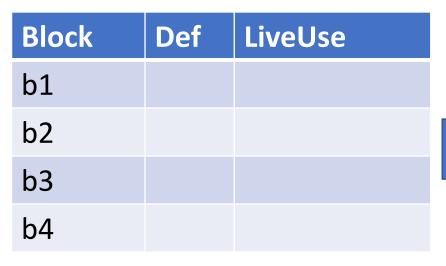
- •Under what scenarios can a variable be live at the entrance of a basic block?
  - Either the variable is used in the basic block
  - •OR the variable is live at exit and not defined within the block

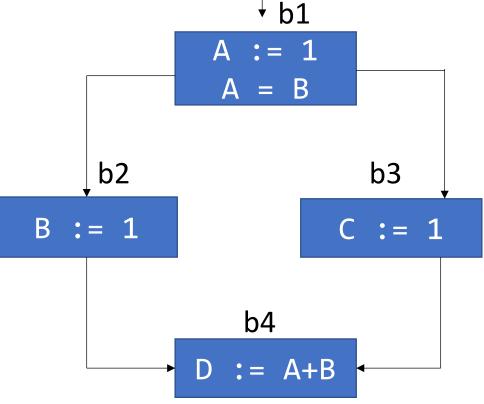
```
LiveIn(b) = LiveUse(b) U (LiveOut(b) -
Def(b))
```

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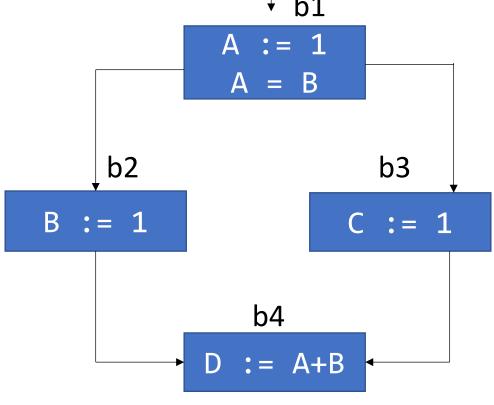




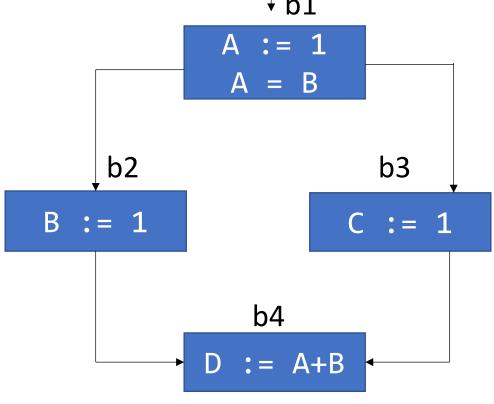




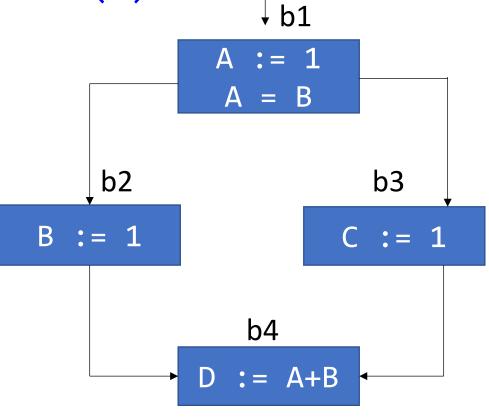
Block	Def	LiveUse
b1	{A}	{B}
b2		
b3		
b4		



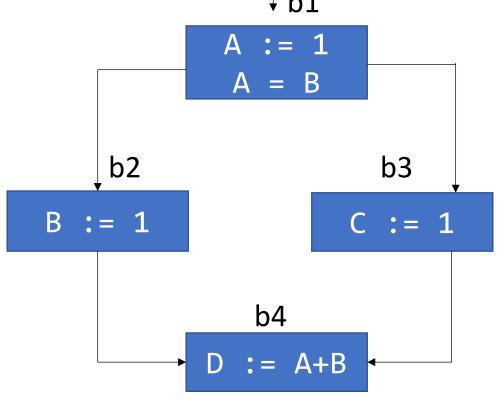
Block	Def	LiveUse
b1	{A}	{B}
b2	{B}	{}
b3		
b4		



Block	Def	LiveUse
b1	{A}	{B}
b2	{B}	{}
b3	{C}	{}
b4		



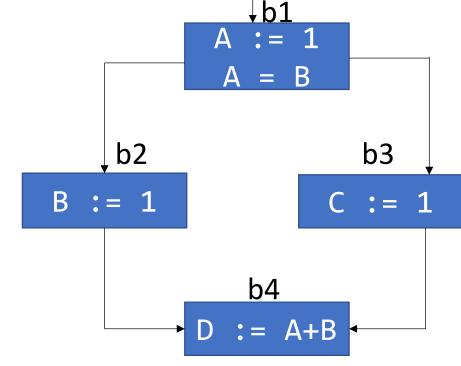
Block	Def	LiveUse
b1	{A}	{B}
b2	{B}	{}
b3	{C}	{}
b4	{D}	{A,B}



start from use of a variable to its definition.

Is this analysis going backward or forward w.r.t. control flow?

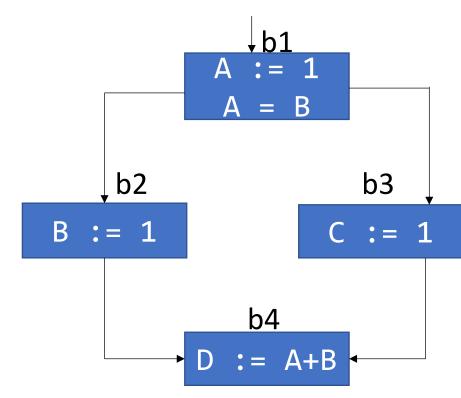
Block	Def	LiveUse
b1	{A}	{B}
b2	{B}	{}
b3	{C}	{}
b4	{D}	{A,B}



start from use of a variable to its definition.

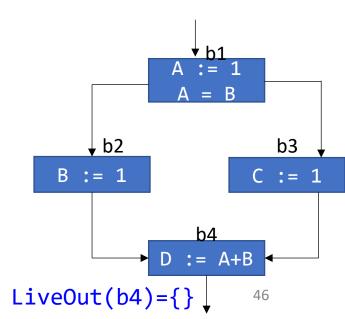
Backward-flow problem

Block	Def	LiveUse
b1	{A}	{B}
b2	{B}	{}
b3	{C}	{}
b4	{D}	{A,B}



- Start from use of a variable to its definition.
- Compute LiveOut and LiveIn sets:

Block	Def	LiveUse
b1	{A}	{B}
b2	{B}	{}
b3	{C}	{}
b4	{D}	{A,B}



```
LiveIn(b4) = LiveUse(b4) U (LiveOut(b4) - Def(b4))

= {A,B} U ({} - {D})

Program point

D := A+B
```

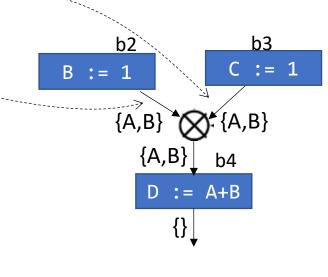
Block	Def	LiveUse
b1	{A}	{B}
b2	{B}	{}
b3	{C}	{}
b4	{D}	{A,B}

```
LiveOut(b) = U_{i \in S(b)} LiveIn(i)

LiveOut(b3) = LiveIn(b4) = {A,B}

LiveOut(b2) = LiveIn(b4) = {A,B}
```

Block	Def	LiveUse
b1	{A}	{B}
b2	{B}	{}
b3	{C}	{}
b4	{D}	{A,B}



```
LiveIn(b3) = LiveUse(b3) U (LiveOut(b3) - Def(b3))

= {} U ({A,B} - {C}) = {A,B}

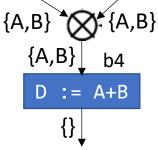
LiveIn(b2) = LiveUse(b2) U (LiveOut(b2) - Def(b2))

= {} U ({A,B} - {B}) = {A}

B := 1

C := 1
```

Block	Def	LiveUse
b1	{A}	{B}
b2	{B}	{}
b3	{C}	{}
b4	{D}	{A,B}

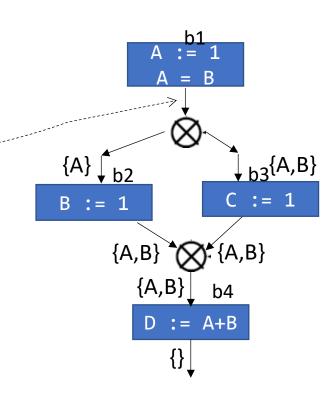


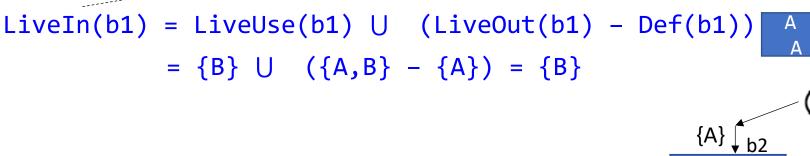
```
LiveOut(b) = \bigcup_{i \in S(b)} LiveIn(i)

LiveOut(b1) = LiveIn(b2) \bigcup LiveIn(b3)

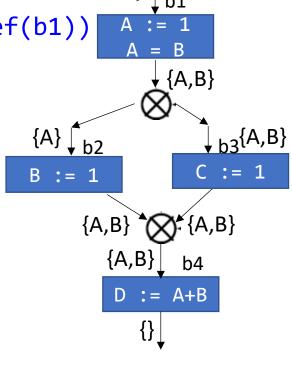
= \{A\} \bigcup \{A,B\} = \{A,B\}
```

Block	Def	LiveUse
b1	{A}	{B}
b2	{B}	{}
b3	{C}	{}
b4	{D}	{A,B}





Block	Def	LiveUse
b1	{A}	{B}
b2	{B}	{}
b3	{C}	{}
b4	{D}	{A,B}



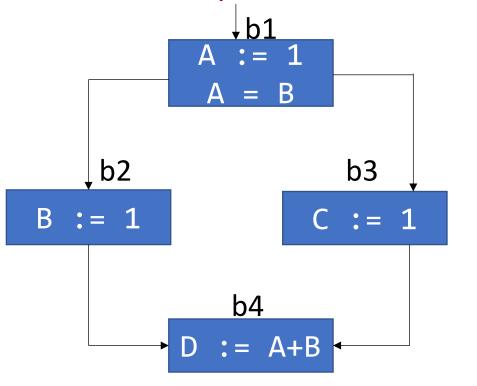
Summary: Compute LiveIn(b) and LiveOut(b)

Block	Def	LiveUse
b1	{A}	{B}
b2	{B}	{}
b3	{C}	{}
b4	{D}	{A,B}

Block	Liveln	LiveOut
b1	{B}	{A,B}
b2	{A}	{A,B}
b3	{A,B}	{A,B}
b4	{A,B}	{}

### Liveness in a CFG – Use Case

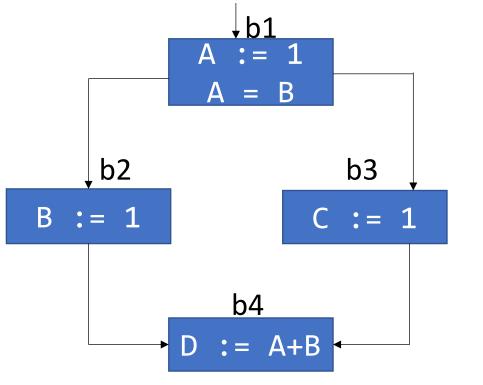
- Assume that the CFG below represents *your entire program* (b1 is the entry to program and b4 is the exit)
  - •What can you infer from the table?



Block	Liveln	LiveOut
b1	{B}	{A,B}
b2	{A}	{A,B}
b3	{A,B}	{A,B}
b4	{A,B}	{}

### Liveness in a CFG – Use Case

- Assume that the CFG below represents your entire program
  - •Variable B is live at the entrance of b1, the entry basic block of CFG. This implies that B is used before it is defined. An error!



Block	Liveln	LiveOut
b1	{B}	{A,B}
b2	{A}	{A,B}
b3	{A,B}	{A,B}
b4	{A,B}	{}

#### Liveness in a CFG – Use Case

 Liveness information tells us what variable is dead. Can remove statements that assign to dead variables.

$$X = 1$$
 $Y = X + 2$ 
 $Z = Y + A$ 
 $X = 1$ 
 $X = 1$ 
 $Y = 1 + 2$ 
 $Z = Y + A$ 
 $X = 1 + 2$ 
 $Z = Y + A$ 

**Constant Propagation** 

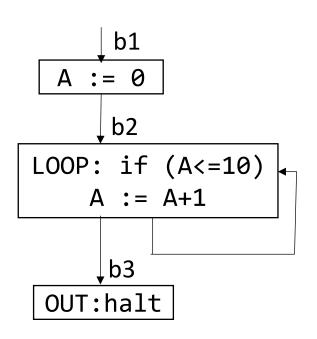
**Dead Code Elimination** 

X is dead here implies that we can

remove this statement.

# Liveness in a CFG – Example (Loop)

How do we compute liveness information when a loop is present?



Block	Def	LiveUse
b1	{A}	{}
b2	{A}	{A}
b3	{}	{}

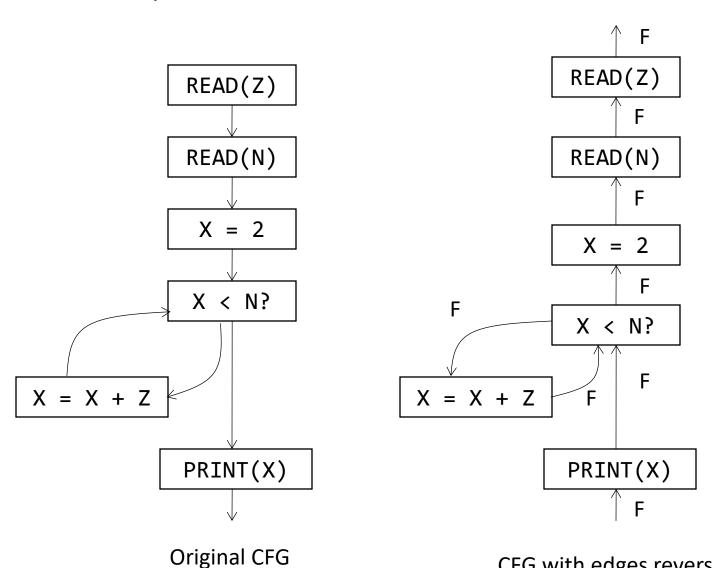
Block	Liveln	LiveOut
b1	{}	{A}
b2	{A}	{A}
В3	{}	{}

#### Liveness in a CFG - Observations

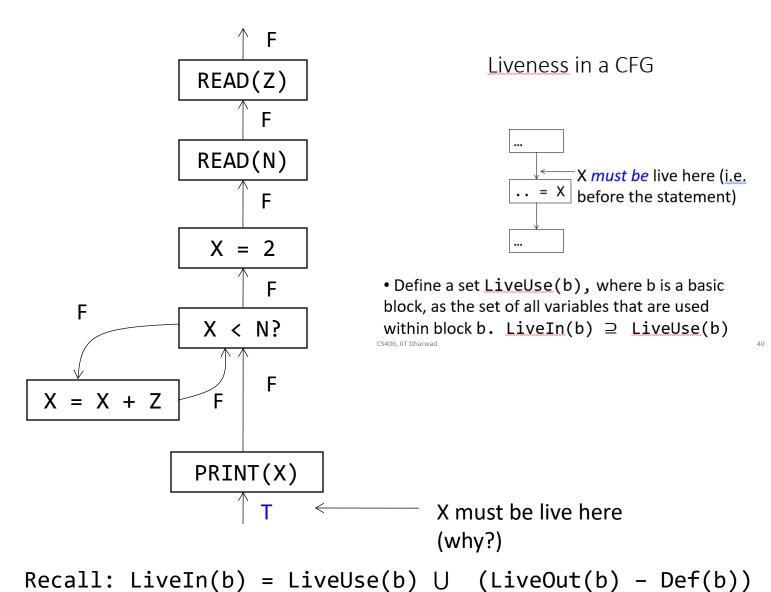
- Liveness is computed as information is transferred between adjacent statements
- At a program point, a variable can be live or not live (property: true or false)
  - To begin with we did not have any information=property is false

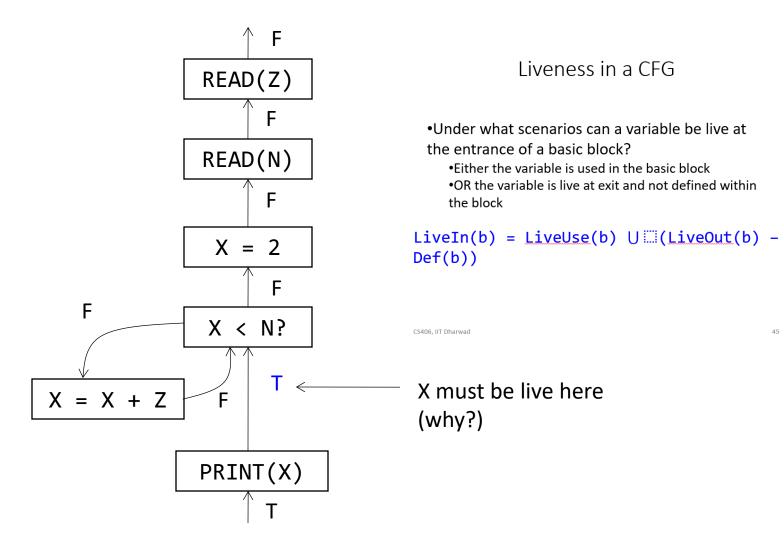
At a program point can the liveness information change?

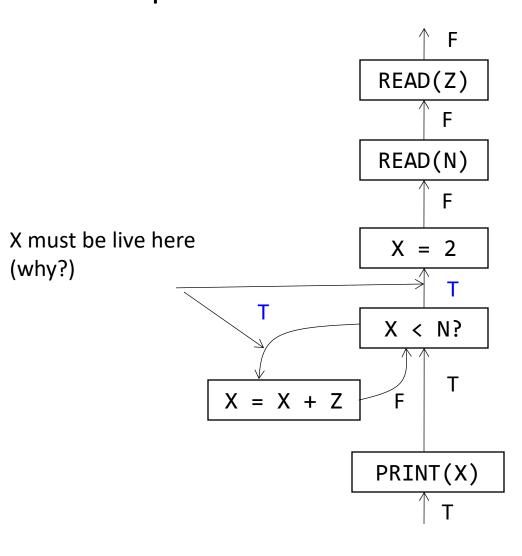
• Yes, Liveness information changes from false to true and not otherwise.



CFG with edges reversed (and initialized) for backwards analysis: is X live? (F=false, T=true)



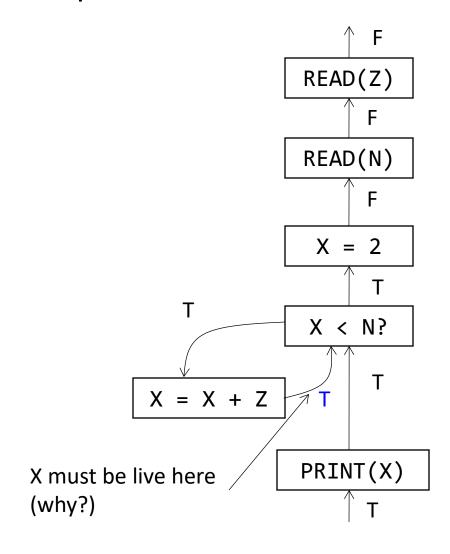




#### Liveness in a CFG

- •Under what scenarios can a variable be live at the entrance of a basic block?
  - •Either the variable is used in the basic block
  - •OR the variable is live at exit and not defined within the block

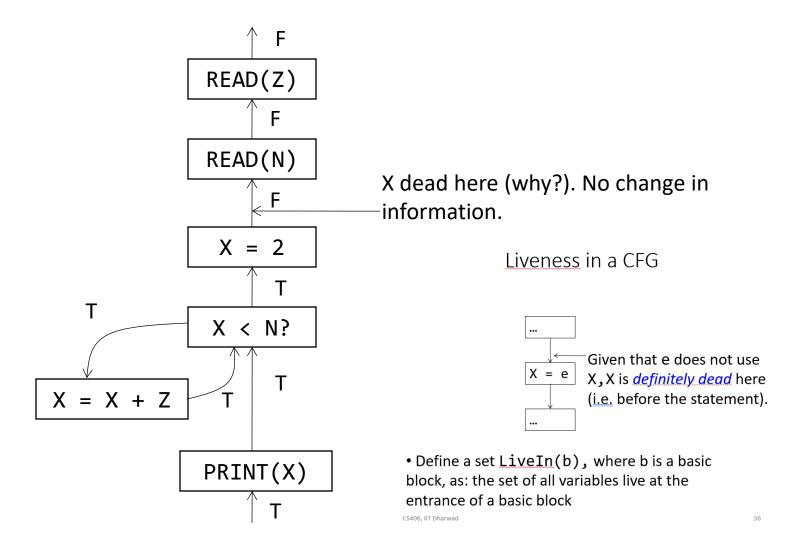
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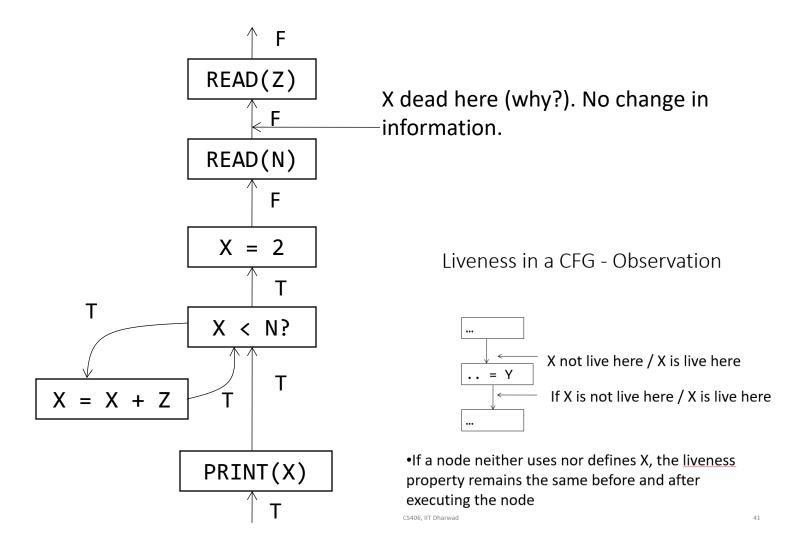


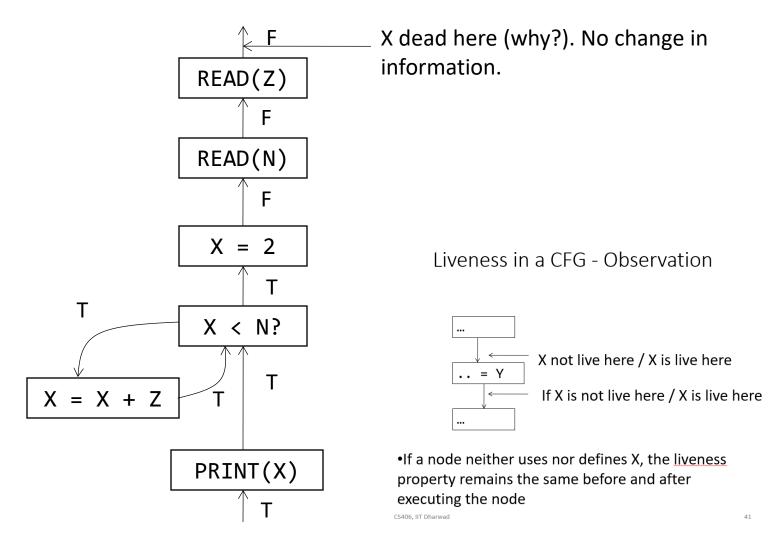
#### Liveness in a CFG

- •Under what scenarios can a variable be live at the entrance of a basic block?
  - •Either the variable is used in the basic block
  - •OR the variable is live at exit and not defined within the block

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# Reaching Definitions - Example

- Goal: to know where in a program each variable x may have been defined when control reaches block b
- Definition d reaches block b if there is a path from point immediately following d to b, such that the variable defined in d is not redefined / killed along that path

```
In(b) = \bigcup_{i \in Pred(b)} Out(i)
```

```
entry
1: i=m-1
 2: j=n
 3: a=u1
4: i=i+1
            6: i=u3
   i=u3
  exit
```

```
Out(b) = gen(b) \cup (In(b) - kill(b))
```

//set that contains all statements that may define some variable x in b. E.g.  $gen(1:a=3;2:a=4)=\{2\}$ 

//set that contains all statements that define a variable x that is also defined in b. E.g. 66

 $kill(1:a=3; 2:a=4)=\{1,2\}$