

Implementation of Dijkstra Algorithm:

Initialization:

- Create a set *sptSet* (Shortest Path Tree Set) to track vertices whose shortest path has been finalised.
- Initialise all distances to *infinity* except the source vertex, which is initialised to 0.

Iterative Process:

- While there are still vertices not included in the *sptSet*:
 - Pick the vertex *u* with the smallest distance that is not in *sptSet*.
 - Add *u* to *sptSet* (finalise its shortest path).
 - Update the distance values for all adjacent vertices *v* of *u*. If the sum of the distance of *u* and the weight of edge *u-v* is less than the current distance of *v*, update the distance of *v*.

Repeat:

- This process continues until all vertices are included in the *sptSet*, ensuring that the shortest paths to all vertices are computed.

