$$\begin{aligned} & \operatorname{cov}\left(f,f'\right) = k(\mathbf{x},\mathbf{z}) = k(s), \ s = s(r,l), \ r = r(\mathbf{x},\mathbf{z}) \\ & \operatorname{cov}\left(f,\frac{\partial f'}{\partial z_j}\right) = \frac{\partial k(\mathbf{x},\mathbf{z})}{\partial z_j} = \frac{\partial k}{\partial s} \frac{\partial s}{\partial z_j} \\ & \operatorname{cov}\left(\frac{\partial f}{\partial x_i},f'\right) = \frac{\partial k(\mathbf{x},\mathbf{z})}{\partial x_i} = \frac{\partial k}{\partial s} \frac{\partial s}{\partial x_i} = \operatorname{cov}\left(f,\frac{\partial f'}{\partial z_i}\right) \text{(symmetry)} \\ & \operatorname{cov}\left(\frac{\partial f}{\partial x_i},\frac{\partial f'}{\partial z_j}\right) = \frac{\partial^2 k(\mathbf{x},\mathbf{z})}{\partial x_i\partial z_j} = \frac{\partial^2 k}{\partial s^2} \frac{\partial s}{\partial x_i} \frac{\partial s}{\partial z_j} + \frac{\partial k}{\partial s} \frac{\partial^2 s}{\partial x_i\partial z_j} \end{aligned}$$

$$\begin{split} \frac{\partial k}{\partial \log l} &= \frac{\partial k}{\partial s} \frac{\partial s}{\partial l} \frac{\partial \log l}{\partial l} = l \frac{\partial k}{\partial s} \frac{\partial s}{\partial l} \\ \frac{\partial^2 k}{\partial z_j \partial \log l} &= l \left(\frac{\partial^2 k}{\partial s^2} \frac{\partial s}{\partial z_j} \frac{\partial s}{\partial l} + \frac{\partial k}{\partial s} \frac{\partial^2 s}{\partial z_j \partial l} \right) \\ \frac{\partial^2 k}{\partial x_i \partial \log l} &= l \left(\frac{\partial^2 k}{\partial s^2} \frac{\partial s}{\partial x_i} \frac{\partial s}{\partial l} + \frac{\partial k}{\partial s} \frac{\partial^2 s}{\partial x_i \partial l} \right) \\ \frac{\partial^3 k}{\partial x_i \partial z_j \partial \log l} &= l \left(\frac{\partial^3 k}{\partial s^3} \frac{\partial s}{\partial x_i} \frac{\partial s}{\partial z_j} \frac{\partial s}{\partial l} + \frac{\partial^2 k}{\partial s^2} \left(\frac{\partial^2 s}{\partial x_i \partial z_j} \frac{\partial s}{\partial l} + \frac{\partial s}{\partial x_i} \frac{\partial^2 s}{\partial z_j \partial l} + \frac{\partial s}{\partial x_i} \frac{\partial^2 s}{\partial z_j \partial l} + \frac{\partial k}{\partial s} \frac{\partial^3 s}{\partial x_i \partial z_j \partial l} \right) \end{split}$$

Squared Exponential Covariance Function

$$k(\mathbf{x}, \mathbf{x'}) = \sigma_f^2 \exp(s), \quad s(r, l) = -\frac{r^2}{2l^2}, \quad r(\mathbf{x}, \mathbf{z}) = \sqrt{\sum_{i=1}^d (x_i - z_i)^2}$$

$$\begin{split} \frac{\partial k}{\partial s} &= k, \ \, \frac{\partial^2 k}{\partial s^2} &= k, \ \, \frac{\partial^3 k}{\partial s^3} &= k \\ \frac{\partial s}{\partial x_i} &= -\frac{x_i - z_i}{l^2}, \ \, \frac{\partial s}{\partial z_j} &= \frac{x_j - z_j}{l^2}, \ \, \frac{\partial^2 s}{\partial x_i \partial z_j} &= \frac{\delta(i,j)}{l^2} \\ \frac{\partial s}{\partial l} &= -\frac{2}{l} s, \ \, \frac{\partial^2 s}{\partial x_i \partial l} &= -\frac{2}{l} \frac{\partial s}{\partial x_i}, \ \, \frac{\partial^2 s}{\partial z_j \partial l} &= -\frac{2}{l} \frac{\partial s}{\partial x_i \partial z_j \partial l} &= -\frac{2}{l} \frac{\partial^2 s}{\partial x_i \partial z_j} \end{split}$$

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Gaussian Processes with Derivative Observations Mátern Covariance Function

$$\mathbf{k}_{\nu=3/2} = \sigma_f^2 (1-s) \exp(s), \quad s(r,l) = -\frac{\sqrt{3}r}{l}, \quad r(\mathbf{x}, \mathbf{z}) = \sqrt{\sum_{i=1}^d (x_i - z_i)^2}, \ \Rightarrow \ s^2 = \frac{3r^2}{l^2}$$

$$\begin{split} &\frac{\partial k}{\partial s} = \sigma_f^2 \left(-1 + (1-s) \right) \exp(s) = \sigma_f^2 \left(-s \right) \exp(s) \\ &\frac{\partial^2 k}{\partial s^2} = \sigma_f^2 \left(-1 - s \right) \exp(s) \\ &\frac{\partial^3 k}{\partial s^3} = \sigma_f^2 \left(-1 + (-1-s) \right) \exp(s) = \sigma_f^2 \left(-2 - s \right) \exp(s) \\ &\frac{\partial s}{\partial x_i} = \frac{3(x_i - z_i)}{l^2 s}, \quad \frac{\partial s}{\partial z_j} = -\frac{3(x_j - z_j)}{l^2 s} \\ &\Rightarrow s \frac{\partial s}{\partial x_i} = \frac{3(x_i - z_i)}{l^2} \Rightarrow \frac{\partial s}{\partial z_j} \frac{\partial s}{\partial x_i} + s \frac{\partial^2 s}{\partial x_i \partial z_j} = -\frac{3\delta(i,j)}{l^2} \\ &\Rightarrow \frac{\partial^2 s}{\partial x_i \partial z_j} = -\frac{3\delta(i,j)}{l^2 s} - \frac{1}{s} \frac{\partial s}{\partial x_i} \frac{\partial s}{\partial z_j} \\ &\frac{\partial s}{\partial l} = -\frac{1}{l} s, \quad \frac{\partial^2 s}{\partial x_i \partial l} = -\frac{1}{l} \frac{\partial s}{\partial x_i}, \quad \frac{\partial^2 s}{\partial z_j \partial l} = -\frac{1}{l} \frac{\partial s}{\partial z_j}, \quad \frac{\partial^3 s}{\partial x_i \partial z_j \partial l} = -\frac{1}{l} \frac{\partial^2 s}{\partial x_i \partial z_j} \end{split}$$

Sparse Covariance Function

$$k_{s<1}(s) = \sigma_f^2 \left(\frac{2 + \cos(2\pi s)}{3} (1 - s) + \frac{1}{2\pi} \sin(2\pi s) \right), \quad s(r, l) = \frac{r}{l}, r(\mathbf{x}, \mathbf{z}) = \sqrt{\sum_{i=1}^d (x_i - z_i)^2}, \Rightarrow s^2 = \frac{r^2}{l^2}$$

$$\frac{\partial k}{\partial s} = \sigma_f^2 \left(\frac{-2\pi \sin(2\pi s)}{3} (1 - s) - \frac{2 + \cos(2\pi s)}{3} + \cos(2\pi s) \right) = \frac{2\sigma_f^2}{3} \left(\cos(2\pi s) - \pi \sin(2\pi s) (1 - s) - 1 \right)$$

$$\frac{\partial^2 k}{\partial s^2} = \frac{2\sigma_f^2}{3} \left(-2\pi \sin(2\pi s) - 2\pi^2 \cos(2\pi s) (1 - s) + \pi \sin(2\pi s) \right) = \frac{-2\pi\sigma_f^2}{3} \left(\sin(2\pi s) + 2\pi \cos(2\pi s) (1 - s) \right)$$

$$\frac{\partial^3 k}{\partial s^3} = \frac{-2\pi\sigma_f^2}{3} \left(2\pi \cos(2\pi s) - 4\pi^2 \sin(2\pi s) (1 - s) - 2\pi \cos(2\pi s) \right) = \frac{8\pi^3 \sigma_f^2}{3} \sin(2\pi s) (1 - s)$$

$$\Rightarrow \frac{\partial s}{\partial z_j} \frac{\partial s}{\partial x_i} + s \frac{\partial^2 s}{\partial x_i \partial z_j} = -\frac{\delta(i,j)}{l^2} \Rightarrow \frac{\partial^2 s}{\partial x_i \partial z_j} = -\frac{\delta(i,j)}{l^2 s} - \frac{1}{s} \frac{\partial s}{\partial x_i} \frac{\partial s}{\partial z_j}$$

 $2s\frac{\partial s}{\partial x_i} = \frac{2(x_i - z_i)}{l^2} \Rightarrow \frac{\partial s}{\partial x_i} = \frac{x_i - z_i}{l^2s}, \frac{\partial s}{\partial z_i} = -\frac{x_j - z_j}{l^2s}$

$$\frac{\frac{\partial s}{\partial l}}{\partial l} = -\frac{1}{l}s, \quad \frac{\partial^2 s}{\partial x_i \partial l} = -\frac{1}{l}\frac{\partial s}{\partial x_i}, \quad \frac{\partial^2 s}{\partial z_j \partial l} = -\frac{1}{l}\frac{\partial s}{\partial z_j}, \quad \frac{\partial^3 s}{\partial x_i \partial z_j \partial l} = -\frac{1}{l}\frac{\partial^2 s}{\partial x_i \partial z_j}$$

Squared Exponential Covariance Function

$$\mathbf{k}(\mathbf{x}, \mathbf{x'}) = \sigma_f^2 \exp(s), \quad s(r, l) = -\frac{r^2}{2l^2}, \quad r(\mathbf{x}, \mathbf{z}) = \sqrt{\sum_{i=1}^d (x_i - z_i)^2}$$

$$\frac{\partial k}{\partial z_j} = \sigma_f^2 \exp(s) \frac{x_j - z_j}{l^2} = k \frac{x_j - z_j}{l^2}$$

$$\frac{\partial^2 k}{\partial \log l \partial z_j} = l \sigma_f^2 \exp(s) \frac{x_j - z_j}{l^2} \left(\frac{-2}{l} + \frac{-2}{l} s \right) = \frac{\partial k}{\partial z_j} \left(-2s - 2 \right)$$

$$\begin{split} \frac{\partial^2 k}{\partial x_i \partial z_j} &= \sigma_f^2 \exp(s) \left(\frac{\delta(i,j)}{l^2} - \frac{x_i - z_i}{l^2} \frac{x_j - z_j}{l^2} \right) = k \left(\frac{\delta(i,j)}{l^2} - \frac{x_i - z_i}{l^2} \frac{x_j - z_j}{l^2} \right) \\ \frac{\partial^3 k}{\partial \log l \partial x_i \partial z_j} &= \frac{\partial k}{\partial \log l} \left(\frac{\delta(i,j)}{l^2} - \frac{x_i - z_i}{l^2} \frac{x_j - z_j}{l^2} \right) + k \left(\frac{-2\delta(i,j)}{l^3} + 4 \frac{x_i - z_i}{l^2} \frac{x_j - z_j}{l^2} \right) \end{split}$$

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Gaussian Processes with Derivative Observations Mátern Covariance Function

$$\begin{split} k_{\nu=3/2} &= \sigma_f^2 \left(1-s\right) \exp(s), \quad s(r,l) = -\frac{\sqrt{3}r}{l}, \quad r(\mathbf{x},\mathbf{z}) = \sqrt{\sum_{i=1}^d (x_i-z_i)^2}, \ \Rightarrow \ s^2 = \frac{3r^2}{l^2} \\ &\frac{\partial k}{\partial z_j} = \sigma_f^2 \exp(s) \left(-\frac{3(x_j-z_j)}{l^2s}\right) \left(-1+(1-s)\right) = 3\sigma_f^2 \exp(s) \frac{(x_j-z_j)}{l^2} \\ &\frac{\partial^2 k}{\partial \log l \partial z_j} = l\sigma_f^2 \exp(s) \frac{3(x_j-z_j)}{l^2} \left(\frac{-2}{l} + \frac{\sqrt{3}r}{l^2}\right) = \frac{\partial k}{\partial z_j} \left(-s-2\right) \\ &\frac{\partial^2 k}{\partial x_i \partial z_j} = 3\sigma_f^2 \exp(s) \left(\frac{\delta(i,j)}{l^2} + \frac{3}{s} \frac{(x_i-z_i)}{l^2} \frac{(x_j-z_j)}{l^2}\right) \\ &\frac{\partial^3 k}{\partial \log l \partial x_i \partial z_j} = 3\sigma_f^2 \exp(s) \left(\frac{-2\delta(i,j)}{l^2} - \frac{9}{s} \frac{(x_i-z_i)}{l^2} \frac{(x_j-z_j)}{l^2}\right) - \frac{\partial^2 k}{\partial x_i \partial z_j} s \end{split}$$
 what if $s=0$?
$$\lim_{\mathbf{x} \to \mathbf{z}} \frac{\partial^2 k}{\partial \log l \partial x_i \partial z_j} = 3\sigma_f^2 \frac{\delta(i,j)}{l^2}$$

$$\lim_{\mathbf{x} \to \mathbf{z}} \frac{\partial^3 k}{\partial \log l \partial x_i \partial z_j} = -6\sigma_f^2 \frac{\delta(i,j)}{l^2}$$

Soohwan Kim Noisy Inputs

Sparse Covariance Function

$$\begin{split} \frac{\partial k}{\partial \log l} &= l \frac{\partial k}{\partial s} \frac{\partial s}{\partial l} = l \frac{\partial k}{\partial s} \left(\frac{-s}{l} \right) = -\frac{\partial k}{\partial s} s \\ \frac{\partial k}{\partial z_j} &= \frac{\partial k}{\partial s} \frac{\partial s}{\partial z_j} = -\frac{\partial k}{\partial s} \frac{x_j - z_j}{l^2 s} = -\frac{2\sigma_j^2}{3} \left(\cos(2\pi s) - \pi \sin(2\pi s)(1-s) - 1 \right) \frac{x_j - z_j}{l^2 s} \\ \frac{\partial^2 k}{\partial \log l \partial z_j} &= l \left(\frac{\partial^2 k}{\partial s^2} \frac{\partial s}{\partial l} \left(-\frac{x_j - z_j}{l^2 s} \right) - \frac{1}{l} \frac{\partial k}{\partial z_j} \right) = \frac{\partial^2 k}{\partial s^2} \frac{x_j - z_j}{l^2} - \frac{\partial k}{\partial z_j} \\ &= \frac{-2\pi\sigma_f^2}{3} \left(\sin(2\pi s) + 2\pi \cos(2\pi s)(1-s) \right) \frac{x_j - z_j}{l^2} - \frac{\partial k}{\partial z_j} \\ \frac{\partial^2 k}{\partial x_i \partial z_j} &= \frac{\partial^2 k}{\partial s^2} \left(\frac{x_i - z_i}{l^2 s} \right) \left(-\frac{x_j - z_j}{l^2 s} \right) + \frac{\partial k}{\partial s} \left(-\frac{\delta(i,j)}{l^2 s} - \frac{x_j - z_j}{l^2} \left(-\frac{1}{s^2} \right) \frac{x_i - z_i}{l^2 s} \right) \\ &= -\frac{\partial^2 k}{\partial s^2} \frac{x_i - z_i}{l^2 s} \frac{x_j - z_j}{l^2 s} + \frac{\partial k}{\partial s} \left(-\frac{\delta(i,j)}{l^2 s} + \frac{1}{s^3} \frac{x_i - z_i}{l^2} \frac{x_j - z_j}{l^2} \right) \\ &= \frac{2\pi\sigma_f^2}{3} \left(\sin(2\pi s) + 2\pi \cos(2\pi s)(1-s) \right) \frac{x_i - z_i}{l^2 s} \frac{x_j - z_j}{l^2 s} \\ &+ \frac{2\sigma_f^2}{3} \left(\cos(2\pi s) - \pi \sin(2\pi s)(1-s) - 1 \right) \left(-\frac{\delta(i,j)}{l^2 s} + \frac{1}{s^3} \frac{x_i - z_i}{l^2} \frac{x_j - z_j}{l^2} \right) \\ &\text{what if } s = 0?, \quad \lim_{\mathbf{x} \to \mathbf{z}} \frac{\partial k}{\partial z_j} = 0, \quad \lim_{\mathbf{x} \to \mathbf{z}} \frac{\partial^2 k}{\partial x_i \partial z_j} = \frac{4\pi^2\sigma_f^2}{3} \frac{\delta(i,j)}{l^2} \end{split}$$

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Noisy Inputs

Sparse Covariance Function

$$k_{s<1}(s) = \sigma_f^2 \left(\frac{2 + \cos(2\pi s)}{3} (1 - s) + \frac{1}{2\pi} \sin(2\pi s) \right), \quad s(r, l) = \frac{r}{l}, r(\mathbf{x}, \mathbf{z}) = \sqrt{\sum_{i=1}^d (x_i - z_i)^2}, \Rightarrow s^2 = \frac{r^2}{l^2}$$

$$\begin{split} &\frac{\partial^{3}k}{\partial \log l\partial x_{i}\partial z_{j}} = -l\frac{\partial^{3}k}{\partial s^{3}}\frac{x_{i}-z_{i}}{l^{2}s}\frac{x_{j}-z_{j}}{l^{2}s}\left(\frac{-s}{l}\right) - l\frac{\partial^{2}k}{\partial s^{2}}\frac{x_{i}-z_{i}}{l^{2}s}\frac{x_{j}-z_{j}}{l^{2}s}\left(\frac{-2}{l}\right) \\ &+ l\frac{\partial^{2}k}{\partial s^{2}}\left(-\frac{\delta(i,j)}{l^{2}s} + \frac{1}{s^{3}}\frac{x_{i}-z_{i}}{l^{2}}\frac{x_{j}-z_{j}}{l^{2}}\right)\left(\frac{-s}{l}\right) + l\frac{\partial k}{\partial s}\left(\frac{-\delta(i,j)}{l^{2}s} + \frac{1}{s^{3}}\frac{x_{i}-z_{i}}{l^{2}}\frac{x_{j}-z_{j}}{l^{2}}\right)\left(\frac{-1}{l}\right) \\ &= \frac{\partial^{3}k}{\partial s^{3}}\frac{x_{i}-z_{i}}{l^{2}}\frac{x_{j}-z_{j}}{l^{2}}\frac{1}{s} + \frac{\partial^{2}k}{\partial s^{2}}\left(\frac{\delta(i,j)}{l^{2}s} + \frac{1}{s^{2}}\frac{x_{i}-z_{i}}{l^{2}}\frac{x_{j}-z_{j}}{l^{2}}\right) + \frac{\partial k}{\partial s}\left(\frac{\delta(i,j)}{l^{2}s} - \frac{1}{s^{3}}\frac{x_{i}-z_{i}}{l^{2}}\frac{x_{j}-z_{j}}{l^{2}}\right) \\ &= \frac{8\pi^{3}\sigma_{f}^{2}}{3}\sin(2\pi s)(1-s)\frac{x_{i}-z_{i}}{l^{2}}\frac{x_{j}-z_{j}}{l^{2}}\frac{1}{s} \\ &+ \frac{-2\pi\sigma_{f}^{2}}{3}\left(\sin(2\pi s) + 2\pi\cos(2\pi s)(1-s)\right)\left(\frac{\delta(i,j)}{l^{2}s} + \frac{x_{i}-z_{i}}{l^{2}s}\frac{x_{j}-z_{j}}{l^{2}s}\right) \\ &+ \frac{2\sigma_{f}^{2}}{3}\left(\cos(2\pi s) - \pi\sin(2\pi s)(1-s) - 1\right)\left(\frac{\delta(i,j)}{l^{2}s} - \frac{1}{s^{3}}\frac{x_{i}-z_{i}}{l^{2}}\frac{x_{j}-z_{j}}{l^{2}}\right) \end{split}$$

$$\text{ what if } s = 0?, \quad \lim_{\mathbf{x} \to \mathbf{z}} \frac{\partial^3 k}{\partial \log l \partial x_i \partial z_i} = \frac{-8\pi^2 \sigma_f^2}{3} \frac{\delta(i,j)}{l^2}$$