

# Supplementary Material for "Machine learning from crowds using candidate set-based labelling"

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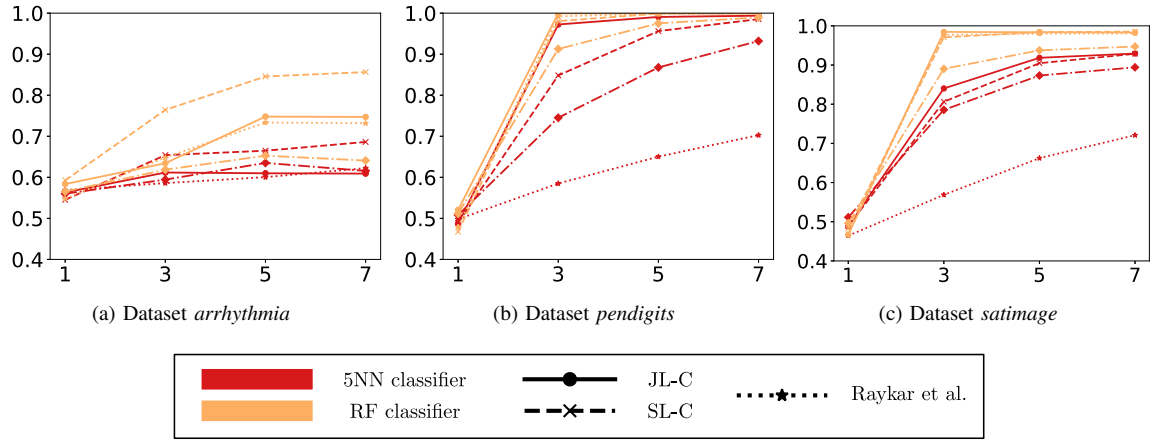
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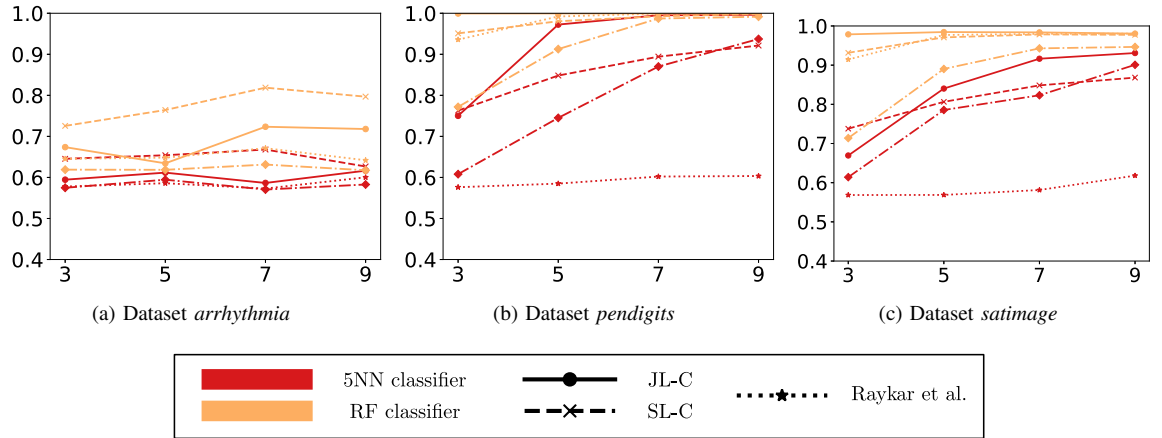
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$X$	Descriptive variable
$d$	Dimension of the descriptive variable
$x$	Instance of $X$
$\Omega_X$	Feature space
$C$	Class variable
$c$	Class label
$\Omega_C$	Set of possible class labels
$A$	Set of available annotators
$a$	Annotator from $A$
$l_x^a$	Label provided by annotator $a$ for instance $x$ (full labelling context)
$L_x^a$	Candidate set provided by annotator $a$ for instance $x$ (candidate labelling context)
$\mathcal{L}_x$	Labelling for instance $x$
$\mathcal{L}$	Set of labellings for the whole training set
$w_x$	Candidate voting estimate
$\omega$	Candidate voting function
$\alpha_{ck}^a$	(Parameter) Probability that annotator $a$ includes class label $k$ in the candidate set for class $c$
$\alpha$	Set of all $\alpha_{ck}^a$ parameters
$q_{\alpha}(c x)$	Estimate of the probability that instance $x$ belongs to class $c$ , based on the set of parameters $\alpha$ (SL-C method)
$h$	Probabilistic classifier
$\theta$	Parameter set of the probabilistic classifier
$q_{\hat{\alpha}, \hat{\theta}}(c x)$	Estimate of the probability that instance $x$ belongs to class $c$ , based on the set of parameters $\hat{\alpha}$ and $\hat{\theta}$ (JL-C method)
$n$	Total number of instances
$r$	Number of classes
$m$	Number of annotators
$\beta$	Label generation parameter that represents annotator expertise
$prop$	Proportion of sampled labels over the possible class labels when generating candidate labels
$g_a$	Probability distribution that represents annotator $a$ in the label generation process
$\mathcal{C}_x$	Set of partial labels associated to instance $x$

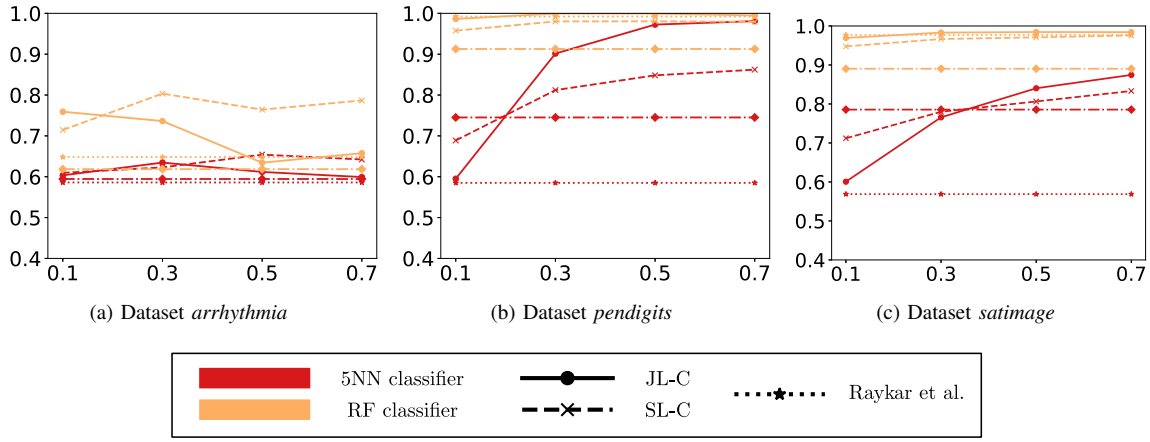
**Table 1. Notation used in the work.**



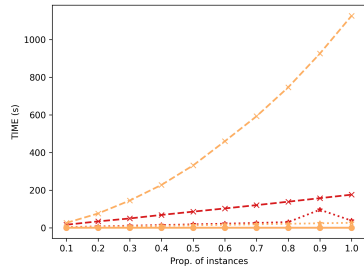
**Figure 1.** Experimental results throughout different values of the parameter  $\beta$  (annotator expertise), in terms of AUC metric, within different datasets (subplots). Results with classifiers RF and 5NN are displayed in orange and red colors, respectively. A different line style and marker is used for each method (SL-C, JL-C, RAY, DS). The rest of generative parameters are fixed to  $m = 5$  and  $prop = 0.5$ .



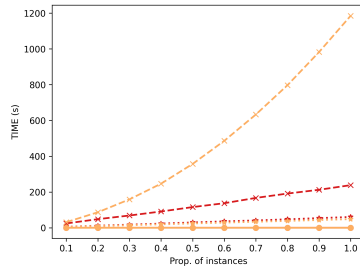
**Figure 2.** Experimental results throughout different values of the parameter  $m$  (number of annotators), in terms of AUC metric, within different datasets (subplots). Results with classifiers RF and 5NN are displayed in orange and red colors, respectively. A different line style and marker is used for each method (SL-C, JL-C, RAY, DS). The rest of generative parameters are fixed to  $\beta = 3$  and  $prop = 0.5$ .



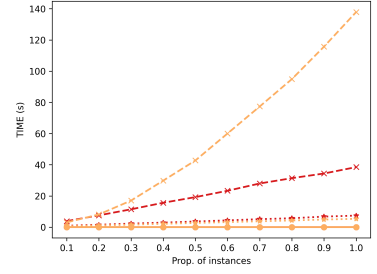
**Figure 3.** Experimental results throughout different values of the parameter  $prop$  (flexibility of the annotators), in terms of AUC metric, within different datasets (subplots). Results with classifiers RF and 5NN are displayed in orange and red colours, respectively. A different line style and marker is used for each method (SL-C, JL-C, RAY, DS). The rest of generative parameters are fixed to  $\beta = 3$  and  $m = 5$ .



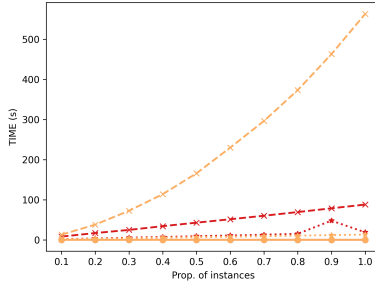
(a) Complete run, all classes,  $m = 3$



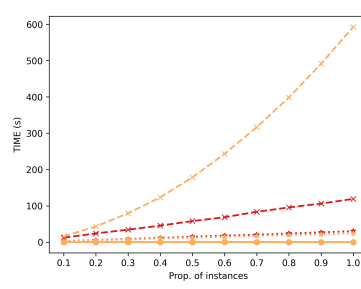
(b) Complete run, all classes,  $m = 6$



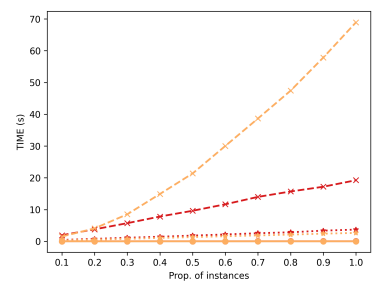
(c) Complete run, half classes,  $m = 3$



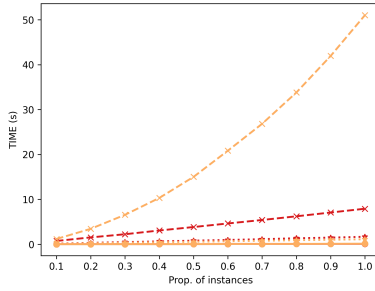
(d) One initialisation, all classes,  $m = 3$



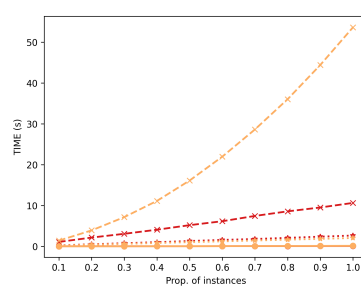
(e) One initialisation, all classes,  $m = 6$



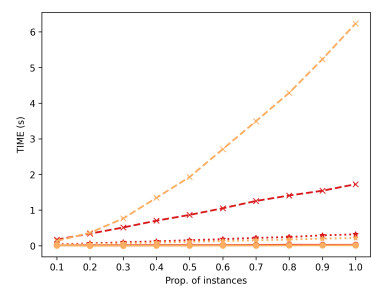
(f) One initialisation, half classes,  $m = 3$



(g) One iteration, all classes,  $m = 3$



(h) One iteration, all classes,  $m = 6$



(i) One iteration, half classes,  $m = 3$

**Figure 4.** Scalability test.