中山大学软件学院 2011 级软件工程专业(2011学年秋季学期)

《SE-103+线性代数》 期 末 试 题 答 案 (B)

1. Fill in the blank $(5\times4=20 \text{ Pts})$

(1)
$$(2a_0 + a_1) + (3a_1 - a_2)t + (a_0 - 2a_1 + 4a_2)t^2$$

(2) 3, Yes

(3)
$$A = PDP^{-1} = \begin{bmatrix} 2 & 1 & -1 \\ 1 & 2 & -1 \\ 1 & -1 & 2 \end{bmatrix}$$

(4) $a \neq 0$ and $a \neq 3$

(5)
$$\begin{bmatrix} x_1 & x_2 & x_3 \end{bmatrix} \begin{bmatrix} 3 & -1/2 & 0 \\ -1/2 & 5 & 4 \\ 0 & 4 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

- 2. Make each statement True or False, and descript your reasons. (5×4=20 Pts)
- (1) **F**
- (2) T
- (3) T
- (4) **F**
- (5) **F**

3. Calculation ($5 \times 8 = 40 \text{ Pts}$)

(1) **Solution** Since $B = [b_1 + b_2 + b_3 \quad b_1 + 2b_2 + 4b_3 \quad b_1 + 3b_2 + 9b_3]$

$$= [b_1 \ b_2 \ b_3] \begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 3 \\ 1 & 4 & 9 \end{bmatrix},$$

Then det
$$B = \det ([b_1 \ b_2 \ b_3] \begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 3 \\ 1 & 4 & 9 \end{bmatrix})$$

By the multiplicative property of determinants,
$$\det B = \det A \cdot \begin{vmatrix} 1 & 1 & 1 \\ 1 & 2 & 3 \\ 1 & 4 & 9 \end{vmatrix} = 1 \times 2 = 2$$

(2) Solution $\det (A - \lambda I) = (\lambda - 2)(\lambda - 1)$. The eigenvalues are 2 and 1, and the corresponding eigenvectors are $v_1 = \begin{bmatrix} 3 \\ 2 \end{bmatrix}$ and $v_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$. Next, form $P = \begin{bmatrix} 3 & 1 \\ 2 & 1 \end{bmatrix}$,

$$D = \begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix} \text{ ,and } P^{-1} = \begin{bmatrix} 1 & -1 \\ -2 & 3 \end{bmatrix}$$

Since
$$A = PDP^{-1}$$
, $A^6 = PD^6P^{-1} = \begin{bmatrix} 3 & 1 \\ 2 & 1 \end{bmatrix} \begin{bmatrix} 2^6 & 0 \\ 0 & 1^6 \end{bmatrix} \begin{bmatrix} 1 & -1 \\ -2 & 3 \end{bmatrix} = \begin{bmatrix} 190 & -189 \\ 126 & -125 \end{bmatrix}$

(3) Solution A typical element of H can be written as

$$\begin{bmatrix} 3a+7b-c \\ -5b+8c-2d \\ 3d-4e \\ 5b-8c-d+4e \end{bmatrix} = a \begin{bmatrix} 3 \\ 0 \\ 0 \\ 0 \end{bmatrix} + b \begin{bmatrix} 7 \\ -5 \\ 0 \\ 5 \end{bmatrix} + c \begin{bmatrix} -1 \\ 8 \\ 0 \\ -8 \end{bmatrix} + d \begin{bmatrix} 0 \\ -2 \\ 3 \\ -1 \end{bmatrix} + e \begin{bmatrix} 0 \\ 0 \\ -4 \\ 4 \end{bmatrix}$$

- a. H is a vector space because it is the set of all linear combinations of a set of vectors.
- h. Row reduce:

$$\begin{bmatrix} 3 & 7 & -1 & 0 & 0 \\ 0 & -5 & 8 & -2 & 0 \\ 0 & 0 & 0 & 3 & -4 \\ 0 & 5 & -8 & -1 & 4 \end{bmatrix} \sim \begin{bmatrix} 3 & 7 & -1 & 0 & 0 \\ 0 & -5 & 8 & -2 & 0 \\ 0 & 0 & 0 & 3 & -4 \\ 0 & 0 & 0 & -3 & 4 \end{bmatrix} \sim \begin{bmatrix} 3 & 7 & -1 & 0 & 0 \\ 0 & -5 & 8 & -2 & 0 \\ 0 & 0 & 0 & 3 & -4 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

The pivot columns are 1,2, and 4. So $\{u_1, u_2, u_4\}$ is a basis for H.

(4) Solution (a) Because the columns a_1 and a_2 of A are orthogonal, the orthogonal projection of b onto $\operatorname{Col} A$ is given by

$$\hat{b} = \frac{b \cdot a_1}{a_1 \cdot a_1} a_1 + \frac{b \cdot a_2}{a_2 \cdot a_2} a_2 = \frac{2}{7} a_1 + \frac{1}{7} a_2 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$$

(b) $\hat{x} = \begin{bmatrix} 2/7 \\ 1/7 \end{bmatrix}$, since we already know what weights to place on the columns of A to

produce $\stackrel{\,\,{}_\circ}{b}$.

(c)
$$||b - \hat{b}|| = \sqrt{(4-1)^2 + (-2-1)^2 + (-3)^2} = 3\sqrt{3}$$

(5) Solution Let
$$v_1 = x_1$$
 and $v_2 = x_2 - \frac{x_2 \cdot v_1}{v_1 \cdot v_1} v_1 = x_2 - \frac{1}{2} v_1 = \begin{bmatrix} 3 \\ 3/2 \\ 3/2 \end{bmatrix}$. Thus $\{v_1, v_2\}$

is an $\,$ orthogonal basis for $\,W\,$.

Since $||v_1|| = \sqrt{30}$ and $||v_2|| = \sqrt{27/2} = 3\sqrt{6}/2$, an orthonormal basis for W is

$$\left\{\frac{v_1}{\parallel v_1 \parallel}, \frac{v_2}{\parallel v_2 \parallel}\right\} = \left\{\begin{bmatrix} 2/\sqrt{30} \\ -5/\sqrt{30} \\ 1/\sqrt{30} \end{bmatrix}, \begin{bmatrix} 2/\sqrt{6} \\ 1/\sqrt{6} \\ 1/\sqrt{6} \end{bmatrix}\right\}.$$

4. Prove issues $(2\times6=12 \text{ Pts})$

(1) Solution If u and v in R^n , then

$$T(u+v) = [(u+v)^{T} w_{1}]w_{1} + [(u+v)^{T} w_{2}]w_{2} + \dots + [(u+v)^{T} w_{p}]w_{p}$$

$$= [(u^{T} + v^{T})w_{1}]w_{1} + [(u^{T} + v^{T})w_{2}]w_{2} + \dots + [(u^{T} + v^{T})w_{p}]w_{p}$$

$$= (u^{T} w_{1})w_{1} + (u^{T} w_{2})w_{2} + \dots + (u^{T} w_{p})w_{p}$$

$$+ (v^{T} w_{1})w_{1} + (v^{T} w_{2})w_{2} + \dots + (v^{T} w_{p})w_{p}$$

$$= T(u) + T(v)$$

It can be shown similarly that T(cu) = cT(u) for each scalar c, so T is a linear transformation.

(2) Solution Since A is similar to B, there is an invertible matrix P such that $A = PBP^{-1}$, then $A^3 - 3A + I = (PBP^{-1})^3 - 3(PBP^{-1}) + I$

$$= PB^{3}P^{-1} - 3(PBP^{-1}) + I$$

$$= P(B^3 - 3B + I)P^{-1}$$
- 0

Thus $B^3 - 3B + I = 0$ because P is an invertible matrix.

5. Synthesis (8 points)

Solution Since
$$x^{T}x = 1$$
, thus $Ax = (I - xx^{T})x = x - xx^{T}x = x - 1x = 0$.

Next, we know $x \neq 0$ because $x^Tx = 1$. Hence the homogeneous equation Ax = 0 has a nontrivial solution. This shows that the equation has at least one free variable, and rank(A) < n