中山大学软件学院 2009 级软件工程专业(2009 秋季学期)

《线性代数》期末试题试卷(B)

(考试形式: 闭卷 考试时间: 2 小时)



《中山大学授予学士学位工作细则》第六条

考试作弊不授予学士学位

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1. Fill the blank (4 titles * 4 points/title = 16 points)

(1) The matrics A and B below are row equivalent.

$$A = \begin{bmatrix} -2 & -5 & 8 & 0 & -17 \\ 1 & 3 & -5 & 1 & 5 \\ 3 & 11 & -19 & 7 & 1 \\ 1 & 7 & -13 & 5 & -3 \end{bmatrix}; B = \begin{bmatrix} 1 & 3 & -5 & 1 & 5 \\ 0 & 1 & -2 & 2 & -7 \\ 0 & 0 & 0 & -4 & 20 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

A basis for Row A is _____

(2) If
$$A = \begin{bmatrix} 1 & -1 & -3 & 0 \\ 0 & 1 & 5 & 4 \\ -1 & 2 & 8 & 5 \\ 3 & -1 & -2 & 3 \end{bmatrix}$$
, then $\det A = \underline{\qquad}$.

(3) Find matrix
$$A = \underline{\qquad}$$
 such that $ColA = \begin{cases} 2s + 3t \\ r + s - 2t \\ 4r + s \\ 3r - s - t \end{cases}$: $r, s, t \in R$.

(4) If α_1 and α_2 are orthonormal vectors, and $x = \alpha_1 + 5\alpha_2$, $y = 4\alpha_1 - 3\alpha_2$, then $x \cdot y = \underline{\hspace{1cm}}$

2. Mark each statement True or False, and descript your reasons (3titles * 8 points/title = 24 points)

- (1) If AB = C and C has 5 columns, then A has 5 columns.
- (2) All polynomials of degree at most 5 consists of a vector space.
- (3) Let $A \in \mathbb{R}^{n \times n}$ and $\det(A) = a$, then $\det(3A) = 3a$.

- (4) If $A^T = A$ and if vectors u and v satisfy Au = 3u and Av = 4v, then $u \cdot v = 0$.
- (5) Let $A \in \mathbb{R}^{5\times 4}$ and rankA = 3, then dim NulA = 3.
- (6) $A \in \mathbb{R}^{n \times n}$ is invertible if and only if all columns of A are linear independent.
- (7) Nul $A = \{0\}$ if and only if the linear transformation $x \mapsto Ax$ is one to one.
- (8) If $A \in \mathbb{R}^{n \times n}$ is diagonalizable, then A has n distinct eigenvalues

3. Calculation issues (40 points)

(1) Make a change of variable, x = Py, that transforms the following quadratic form into one with no cross-product term. Give P and the new quadratic form. (12 points).

$$3x_1^2 + 6x_2^2 + 3x_3^2 - 4x_1x_2 + 8x_1x_3 + 4x_2x_3$$

(2) Let the system equations be $\begin{cases} (2-\lambda)x_1 + 2x_2 - 2x_3 = 1\\ 2x_1 + (5-\lambda)x_2 - 4x_3 = 2\\ -2x_1 - 4x_2 + (5-\lambda)x_3 = -\lambda - 1 \end{cases}$. Find the approxiate

values for λ to make the system have at most one solution, no solution, and infinite solutions, respectively. When the system has infinite solutions, write them in parametric vector form. (12 points).

(3) Find a least-squares solution of Ax = b, and compute the least-squares error. (10 points).

$$A = \begin{bmatrix} 1 & 3 & 5 \\ 1 & 1 & 0 \\ 1 & 1 & 2 \\ 1 & 3 & 3 \end{bmatrix}, b = \begin{bmatrix} 3 \\ 5 \\ 7 \\ -3 \end{bmatrix}$$

(4) Let $\mathfrak{B} = \{b_1, b_2, b_3\}$ be a basis for a vector space V, and let T: V--->V be a linear transformation with the property that $T(b_1) = b_1 + b_3$, $T(b_2) = 2b_1 - b_3$, and $T(b_3) = 3b_1 + 4b_2 + 5b_3$. Find the matrix of T relative to the basis (6 points).

4. Prove issues (20 points)

- (1) Let $\{\xi_1 \ \xi_2 \ \xi_3\}$ be a basis for R^3 , and $\alpha_1 = \xi_1 + \xi_2 2\xi_3$, $\alpha_2 = \xi_1 \xi_2 \xi_3$, $\alpha_3 = \xi_1 + \xi_3$, $\beta = 6\xi_1 \xi_2 \xi_3$. Prove that $\{\alpha_1 \ \alpha_2 \ \alpha_3\}$ is also a basis for R^3 , and find the coordinate vector of β relative to $\{\alpha_1 \ \alpha_2 \ \alpha_3\}$. (10 points)
- (2) Suppose A is a $m \times n$ matrix such that the matrix $A^T A$ is invertible. Let b be any vector in R^n . Show that the Linear system Ax = b has at most one solution. (10 points)