

How to create your own applications with planning

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Topic 1: solve 8-puzzle problems

- Build domain model
 - A set of predicates

```
(:predicates (on ?x ?y)
              (ontable ?x)
              (clear ?x)
              (handempty)
              (holding ?x)
              )
```

- A set of operators

```
(:action put-down
  :parameters (?x)
  :precondition (holding ?x)
  :effect
  (and (not (holding ?x))
        (clear ?x)
        (handempty)
        (ontable ?x)))
```

Topic 1: solve 8-puzzle problems (continued)

- Build objects, initial and goal states
 - **Objects**: all objects involved in your problem
 - **Initial state**: a full set of propositions
 - **Goal state**: a partial set of propositions

```
(:objects D A H G B J E I F C )  
(:INIT (CLEAR C) (CLEAR F) (ONTABLE I) (ONTABLE F) (ON C E) (ON E J) (ON J B)  
  (ON B G) (ON G H) (ON H A) (ON A D) (ON D I) (HANDEEMPTY))  
(:goal (AND (ON D C) (ON C F) (ON F J) (ON J E) (ON E H) (ON H B) (ON B A)  
  (ON A G) (ON G I)))  
)
```

Topic 1: solve 8-puzzle problems (continued)

- Main issues:
 - How many predicates?
 - Specifying locations of objects
 - Specifying adjacency of locations
 - How many operators?
 - move-up, move-down, move-left, move-right
 - How many objects?
 - 8 objects: 1, 2, 3, 4, 5, 6, 7, 8
 - 9 locations: A, B, C, D, E, F, G, H, I

Topic 1: solve 8-puzzle problems (continued)

- Input your domain and problem files to:
 - <http://editor.planning.domains>
- Test your files via solving the following problem:

7	2	4
5		6
8	3	1

Start State

1	2	3
4	5	6
7	8	

Goal State

Topic 2: car sharing system

- **Predicates:**

- Locations of drivers
- Locations of customers
- Adjacencies of locations
- Availability of drivers and customers
- Cost functions – about road length?

Replanning every other 5min!

- **Operators:**

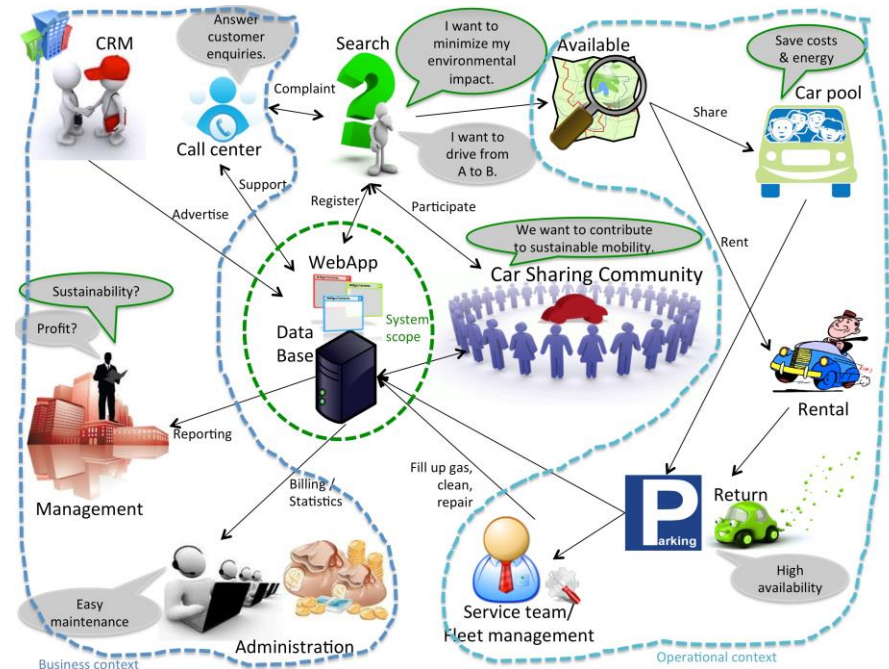
- move, pickup, dropoff

- **Objects:**

- Drivers: d_1, d_2, \dots, d_k
- Customers: c_1, c_2, \dots, c_t
- Locations: l_1, l_2, \dots, l_h

- **Initial and goal states:**

- Status of objects



Topic 3: Take-out scheduling system

- Objects ?
 - Orders
 - Runners
 - Maps
- Predicates ?
- Actions ?
- Initial and goal states ?

快跑者同城配送系统

为配送团队提供系统，帮助配送团队打造属于自己的本地生活配送服务平台



The end!

Build your own applications
easily!