### 人工智能 一一人工神经网络 II

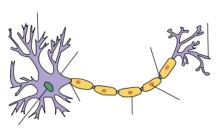


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- The study of artificial neural networks was inspired by attempts to simulate biological neural systems.
- The human brain consists of nerve cells called neurons (神经元) primarily.
- Neurons are linked together via strands of fiber called axons (轴突).
- Axons are used to transmit nerve impulses from one neuron to another whenever the neurons are stimulated.

- A neuron is connected to the axons of other neurons via dendrites (树突), which are extensions from the cell body of the neuron.
- The contact point between a dendrite and an axon is called a synapse (突触).
- The human brain learns by changing the strength of the synaptic connection between neurons upon repeated stimulation by the same impulse.





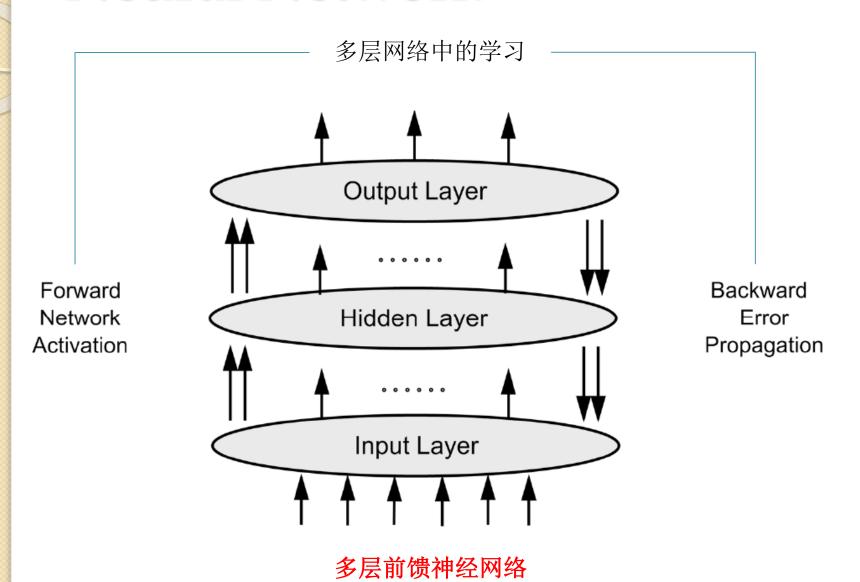
Dendrites Cell body
Collect Integrates incoming signals and generate outgoing signal to axon

Axon
Passes electrical signals
to dendrites of another
cell or to an effector cell

- A neural network consists of a large number of simple and interacting nodes (artificial neurons).
- Knowledge is represented by the strength of connections between these nodes.
- Knowledge is acquired by adjusting the connections through a process of learning.
- All the neurons process their inputs simultaneously and independently.

- The additional layers in between the input and output nodes are called hidden layers.
- The nodes embedded in these layers are called hidden nodes.
- We focus on feedforward neural networks, in which the nodes in one layer are connected only to the nodes in the next layer.
- The **backpropagation** learning algorithm is specifically designed for neural networks with multiple layers.

- There are two phases in each iteration of the training algorithm
  - The forward phase
  - The backward phase



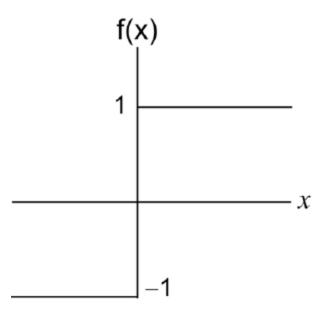
在前向阶段,利用前一次迭代得到的权重计算每个神经元的输出值

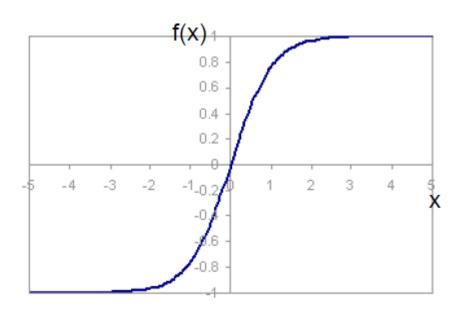
- During the forward phase, the weights obtained from the previous iteration are used to compute the output value of each neuron.
- Outputs of the neurons at level *l* are computed prior to computing the outputs at level *l*+1.

在计算L+1层神经元的输出之前,先计算L层神经元的输出

- During the backward phase, the weight update equation is applied in the reverse direction.
- In other words, the weights at level *l*+1 are updated before the weights at level level *l* are updated.
- The learning algorithm allows us to use the errors for neurons at layer *l*+1 to estimate the errors for neurons at layer *l*. 使用L+1层神经元的误差来估计L层神经元的误差

• For this type of network, instead of the threshold function, another activation function is used.



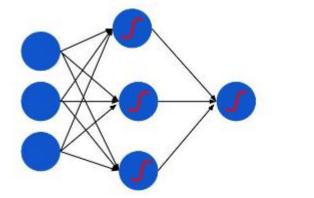


• A common activation function is the hyperbolic tangent function 双曲正切函数

$$f(x) = \frac{e^x - e^{-x}}{e^x + e^{-x}} = \frac{e^{2x} - 1}{e^{2x} + 1} \text{ main be parameter.}$$

• An important property of the function is that it is differentiable

$$f'(x) = 1 - f(x)^2$$





 Another common activation function is the sigmoid function

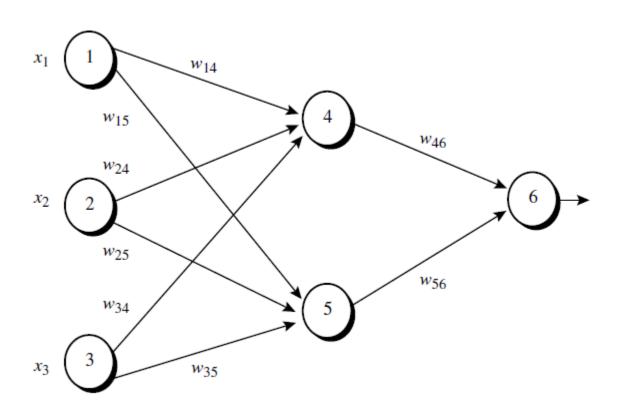
$$f(x) = \frac{1}{1 + e^{-x}}$$

This function is also differentiable

$$f'(x) = f(x)(1 - f(x))$$

## Example

• One training tuple X=(1,0,1), whose class label is 1.



# Example

偏移量 Initial input, weight, and bias values.

$x_1$	$x_2$	<i>x</i> <sub>3</sub>	$w_{14}$	w <sub>15</sub>	w <sub>24</sub>	w <sub>25</sub>	w <sub>34</sub>	w <sub>35</sub>	w <sub>46</sub>	w <sub>56</sub>	$\theta_4$	$\theta_5$	$\theta_6$
1	0	1	0.2	-0.3	0.4	0.1	-0.5	0.2	-0.3	-0.2	-0.4	0.2	0.1

The net input and output calculations.

Unit j	Net input, $I_j$	Output, $O_j$
4	0.2 + 0 - 0.5 - 0.4 = -0.7	$1/(1+e^{0.7})=0.332$
5	-0.3+0+0.2+0.2=0.1	$1/(1+e^{-0.1}) = 0.525$
6	(-0.3)(0.332) - (0.2)(0.525) + 0.1 = -0.105	$1/(1+e^{0.105}) = 0.474$

# Example

Calculation of the error at each node.

Unit j	$Err_j$
6	(0.474)(1-0.474)(1-0.474) = 0.1311
5	(0.525)(1-0.525)(0.1311)(-0.2) = -0.0065
4	(0.332)(1-0.332)(0.1311)(-0.3) = -0.0087

Calculations for weight and bias updating.

Weight or bias	New value
$w_{46}$	-0.3 + (0.9)(0.1311)(0.332) = -0.261
w <sub>56</sub>	-0.2 + (0.9)(0.1311)(0.525) = -0.138
$w_{14}$	0.2 + (0.9)(-0.0087)(1) = 0.192
$w_{15}$	-0.3 + (0.9)(-0.0065)(1) = -0.306
$w_{24}$	0.4 + (0.9)(-0.0087)(0) = 0.4
w <sub>25</sub>	0.1 + (0.9)(-0.0065)(0) = 0.1
w <sub>34</sub>	-0.5 + (0.9)(-0.0087)(1) = -0.508
w <sub>35</sub>	0.2 + (0.9)(-0.0065)(1) = 0.194
$\theta_6$	0.1 + (0.9)(0.1311) = 0.218
$\theta_5$	0.2 + (0.9)(-0.0065) = 0.194
$\theta_4$	-0.4 + (0.9)(-0.0087) = -0.408

- Given a unit j in a hidden or output layer, the net input,  $I_{j}$ , to unit j is  $I_j = \sum_i w_{ij} O_i + \theta_j$  前一层节点的输出乘以相应的权重再求和最后加上偏移量
- Propagate the where  $w_{ii}$  is the weight of the connection from unit i in the inputs forward previous layer to unit j;  $O_i$  is the output of unit i from the previous layer; and  $\theta_i$  is the bias of the unit.
  - Given the net input  $I_j$  to unit j, then  $O_j$ , the output of unit j, is computed as  $O_j = \frac{1}{1 + e^{-I_j}}$

#### Backpropagate

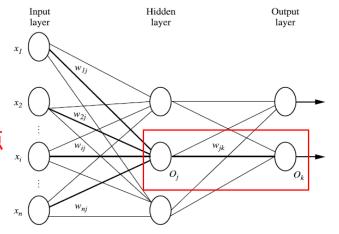
For a unit k in the output layer, the error  $Err_k$  is computed by

$$Err_k = O_k(1 - O_k)(T_k - O_k)$$
 Tk表示实际结果

• The error of a hidden layer unit *j* is

$$Err_j = O_j(1-O_j) \sum_k Err_k w_{jk}$$
 求和表示该节  
点有多个输出  
• Weights are updated by k为下一层节点

$$w_{jk} = w_{jk} + \eta Err_k O_j$$
$$\theta_{\nu} = \theta_{\nu} + \eta Err_{\nu}$$



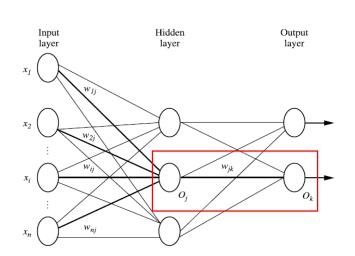
- Minimize the error of node  $O_k$
- We define it as  $E = \frac{1}{2}e^2 = \frac{1}{2}(T O)^2$
- To adjust weight  $w_{jk}$ , we first calculate the partial derivation of E on  $w_{jk}$

$$\frac{\partial E}{\partial w_{jk}} = \frac{\partial E}{\partial e} \times \frac{\partial e}{\partial O_k} \times \frac{\partial O_k}{\partial w_{jk}}$$

$$= -(e) \times (O_k (1 - O_k)) \times (O_j)$$

$$= -(T_k - O_k) O_k (1 - O_k) O_j$$

and then use the "gradient decent"



- Backpropagation learning is based on the idea of an error surface.
- The surface represents cumulative error over a data set as a function of network weights.
- Each possible network weight configuration is represented by a point on the surface.

- The goal of the learning algorithm is to determine a set of weights that minimize the error.
- The learning algorithm should be designed to find the direction on the surface which most rapidly reduces the error.
- This can be achieved by moving in the opposite direction of the gradient vector at each surface point (i.e., by employing the gradient descent learning method). 通过在每个表面点沿梯度向量的相反方向移动来实现

#### Weakness

<sup>很长的训练时间</sup>○ Long training time

- best determined empirically, e.g., the network topology or "structure".
- 。 Poor interpretability 解释能力差
  - · Difficult to interpret the symbolic meaning behind the learned weights and of "hidden units" in the network

很难解释所学的权重背后的含义和网络中的"隐藏单元"

#### Strength

- High tolerance to noisy data
- Well-suited for continuous-valued inputs
- and outputs

  o Successful on a wide array of real-world data

最近已开发出从训练过的神经网络中提取规则的技术。
Techniques have recently been developed for the extraction of rules from trained neural networks

- Rule extraction from networks: network pruning
  - Simplify the network structure by removing weighted links that have the least effect on the trained network
  - 研究一组输入和激活值来推导出描述输入和隐藏单元层之间关系的规则。
    The set of input and activation values are studied to derive rules describing the relationship between the input and hidden unit layers
- Sensitivity analysis: assess the impact that a given input variable has on a network output. The knowledge gained from this analysis can be represented in rules

评估给定输入变量对网络输出的影响,从这个分析中获得的知识可以用规则表示