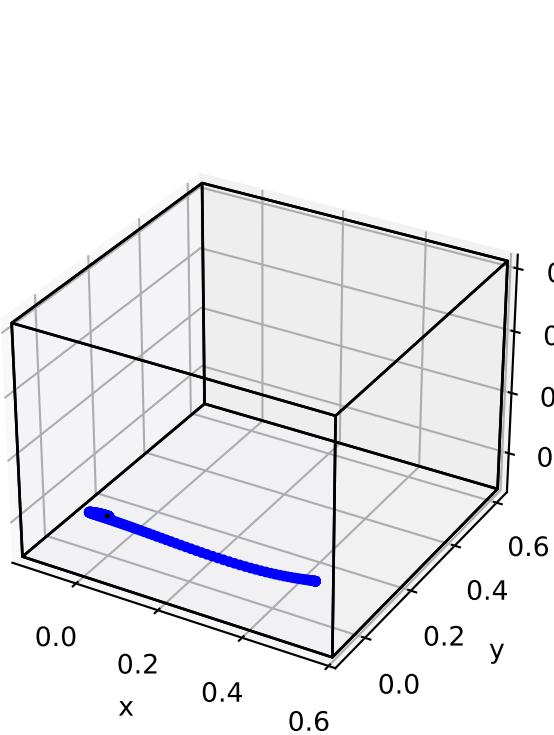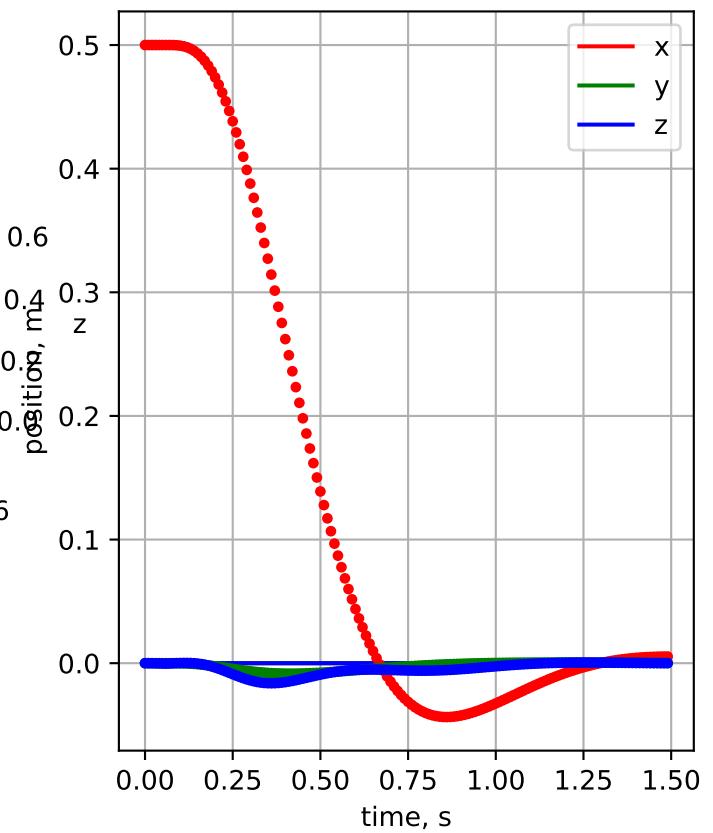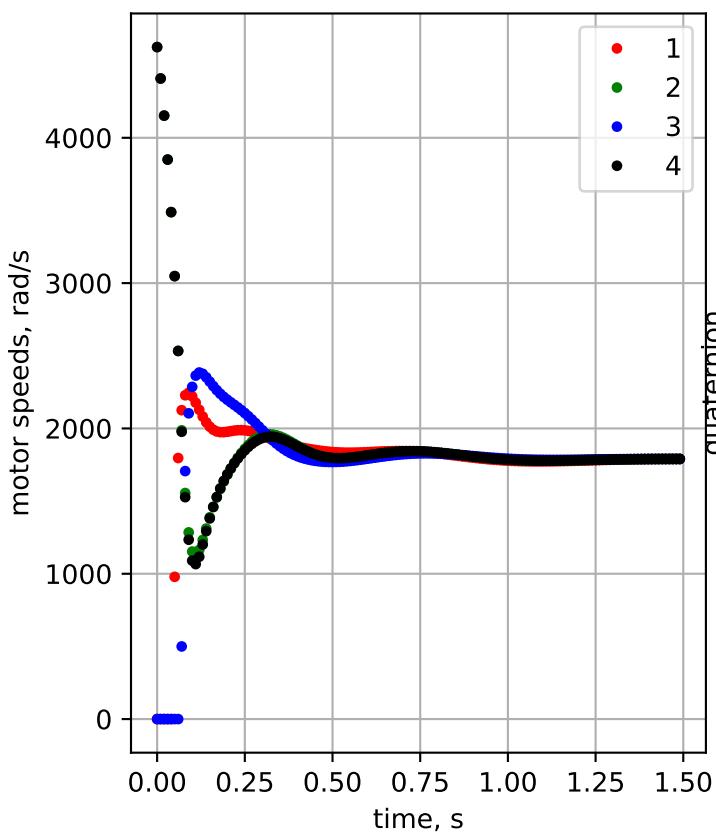step_pos_yaw