

Convolutional Neural Networks on Graphs with Fast Localized Spectral Filtering

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Outline



- Introduction
- Learning Fast Localized Spectral Filters
- Graph Coarsening and Pooling
- Numerical Experiments
- Consultations

Introduction



- CNNs are good at learning local stationary structures and compose them to form multi-scale hierarchical patterns(only defined for regular grids)
- Extend CNN to graphs
 - How to define:
 - localized graph filters
 - Pooling operations
 - On non-Euclidean domains

图的傅里叶变换

图的定义: $\mathcal{G} = (\mathcal{V}, \mathcal{E}, W)$

- \mathcal{V} 是顶点集, \mathcal{E} 是边集, W 是顶点边权的邻接矩阵。
- X 是输入的信号, 可视作一维向量。

拉普拉斯矩阵及性质:

普通形式 $L = D - A$ 对称归一化 $L^{sys} = D^{-1/2} L D^{-1/2} = I - D^{-1/2} A D^{-1/2}$

- 半正定实对称矩阵: 特征向量相互正交, 可构成正交矩阵 U 作为GFT的基。
- 特征值非负, 最小特征值是0, 特征值可作为图的频率, 越小的特征值对应越低频的信息。
- 拉普拉斯矩阵利用傅里叶的基 U 通过 $L = U \Lambda U^T$ 对角化。

图的傅里叶变换形式

$$F(\lambda_l) = \hat{f}(\lambda_l) = \sum_{i=1}^N f(i) u_l(i)$$

$$f(i) = \sum_{l=1}^N \hat{f}(\lambda_l) u_l(i)$$

$$\begin{pmatrix} \hat{f}(\lambda_1) \\ \hat{f}(\lambda_2) \\ \vdots \\ \hat{f}(\lambda_N) \end{pmatrix} = \begin{pmatrix} u_1(1) & u_1(2) & \dots & u_1(N) \\ u_2(1) & u_2(2) & \dots & u_2(N) \\ \vdots & \vdots & \ddots & \vdots \\ u_N(1) & u_N(2) & \dots & u_N(N) \end{pmatrix} \begin{pmatrix} f(1) \\ f(2) \\ \vdots \\ f(N) \end{pmatrix}$$

$$\begin{pmatrix} f(1) \\ f(2) \\ \vdots \\ f(N) \end{pmatrix} = \begin{pmatrix} u_1(1) & u_2(1) & \dots & u_N(1) \\ u_1(2) & u_2(2) & \dots & u_N(2) \\ \vdots & \vdots & \ddots & \vdots \\ u_1(N) & u_2(N) & \dots & u_N(N) \end{pmatrix} \begin{pmatrix} \hat{f}(\lambda_1) \\ \hat{f}(\lambda_2) \\ \vdots \\ \hat{f}(\lambda_N) \end{pmatrix}$$

f 在 Graph 上傅里叶变换的矩阵形式为:

$$\hat{f} = U^T f$$

f 在 Graph 上傅里叶逆变换的矩阵形式为:

$$f = U \hat{f}$$

图信号的谱滤波

图的卷积定义：

$$(f * g)_G = U((U^T g) \odot (U^T f))$$

将 $U^T g$ 整体看作可学习的卷积核，这里可写作 \mathbf{g}_θ ：

$$(f * g)_G = U g_\theta U^T f$$

图谱卷积网络的关键就在于 \mathbf{g}_θ 的选择

$$X_{:,j}^{k+1} = \sigma\left(\sum_{i=1}^{f_{k-1}} U \Theta_{i,j}^k U^T X_{:,i}^k\right) \quad (j = 1, 2, \dots, f_k)$$

- $X^k \in \mathbb{R}^{N \times f_{k-1}}$ 是输入图信号,对应图上就是点的输入特征
- N 是节点数量
- f_{k-1} 是输入通道的数量
- f_k 是输出通道的数量
- $\Theta_{i,j}^k$ 是一个可学习参数的对角矩阵,就跟三层神经网络中的weight一样是任意的参数,通过初始化赋值然后利用误差反向传播进行调整
- $\sigma(\cdot)$ 是激活函数

缺点

- ⊗ Filters are basis-dependent \Rightarrow does not generalize across graphs
- ⊗ Only undirected graphs (symmetric Laplacian matrix required for orthogonal eigendecomposition)
- ⊗ $\mathcal{O}(n)$ parameters per layer
- ⊗ $\mathcal{O}(n^2)$ computation of forward / inverse Fourier transforms Φ^T, Φ
- ⊗ No guarantee of spatial localization of filters

基于多项式逼近的谱CNN

为解决谱CNN中滤波器无法定位到局部信息以及学习复杂度为 $O(n)$ 的缺陷，可以用多项式来做拟合：

$$g_{\theta} * x = U g_{\theta} U^T x \quad g_{\theta} = g_{\theta}(\Lambda) \quad g_{\theta}(\Lambda) = \sum_{k=0}^{K-1} \theta_k \Lambda^k$$

$d_G(i, j) > K$ implies $(L^K)_{i,j} = 0$, where d_G is the shortest path distance.

保证了K-localized，以及将参数复杂度降到了 $O(k)$

J. Bruna等人提出用B样条曲线来对上式做逼近

$$g_{\theta}(\Lambda) = B\theta$$

$B \in \mathbb{R}^{n \times K}$ is the cubic B-spline basis

parameter $\theta \in \mathbb{R}^K$ is a vector of control points

由于U是对称归一化的拉普拉斯矩阵，计算复杂度仍然是 $O(n^2)$ 。

切比雪夫多项式逼近

为了解决这个问题，Hammond et al.(2011)通过Chebyshev多项式 $T_k(x)$ 的 K th-阶截断展开来拟合 $g_\theta(\Lambda)$

$$g_\theta(\Lambda) = \sum_{k=0}^{K-1} \theta_k T_k(\tilde{\Lambda})$$

- $\tilde{\Lambda} = 2\Lambda/\lambda_{max} - I_N$ (为缩放后的特征向量矩阵, 缩放后范围是 $[-1, 1]$, 单位矩阵的特征值是 n 重1), 缩放的目的是为了满足Chebyshev多项式 $T_k(x)$ 的 K^{th} 阶截断展开的条件: 自变量范围需要在 $[-1, 1]$ 之间
- λ_{max} 是 L 的最大特征值, 也叫**谱半径**。
- $\theta \in \mathbb{R}^K$ 是切比雪夫系数的向量
- Chebyshev多项式递归定义为 $T_k(x) = 2xT_{k-1}(x) - T_{k-2}(x)$, 其中 $T_0(x) = 1$, $T_1(x) = x$ 。

Chebyshev谱CNN

如何解决计算复杂度的问题？

$$\begin{aligned} g_{\theta} * x &= U g_{\theta} U^T x \\ &= U g_{\theta}(\Lambda) U^T x \\ &= U \left(\sum_{k=0}^K \theta_k T_K(\tilde{\Lambda}) \right) U^T x \\ &= \left(\sum_{k=0}^K \theta_k T_K(U \tilde{\Lambda} U^T) \right) x \\ &= \sum_{k=0}^K \theta_k T_K(\tilde{L}) x \quad (5) \end{aligned}$$

利用数学归纳法证明



$$U T_k(\tilde{\Lambda}) U^T = T_k(U \tilde{\Lambda} U^T)$$

Chebyshev谱CNN

$$UT_k(\tilde{\Lambda})U^T = T_k(U\tilde{\Lambda}U^T)$$

Chebyshev多项式递归定义为 $T_k(x) = 2xT_{k-1}(x) - T_{k-2}(x)$ ，其中 $T_0(x) = 1$ ， $T_1(x) = x$ 。

当 $n=1$ 时显然成立

$$UT_0(\tilde{\Lambda})U^T = UU^T = 1 = T_0(U\tilde{\Lambda}U^T)$$

$$UT_1(\tilde{\Lambda})U^T = U\tilde{\Lambda}U^T = T_1(U\tilde{\Lambda}U^T)$$

假设 $n=k$ 时成立

$$UT_{k-2}(\tilde{\Lambda})U^T = T_{k-2}(U\tilde{\Lambda}U^T)$$

$$UT_{k-1}(\tilde{\Lambda})U^T = T_{k-1}(U\tilde{\Lambda}U^T)$$

证明 $n=k+1$ 时成立

$$\begin{aligned} UT_k(\tilde{\Lambda})U^T &= 2U\tilde{\Lambda}T_{k-1}(\tilde{\Lambda})U^T - UT_{k-1}(\tilde{\Lambda})U^T \\ &= 2(U\tilde{\Lambda}U^T) \left[UT_{k-1}(\tilde{\Lambda})U^T \right] - UT_{k-1}(\tilde{\Lambda})U^T \\ &= 2(U\tilde{\Lambda}U^T)T_{k-1}(U\tilde{\Lambda}U^T) - T_{k-1}(U\tilde{\Lambda}U^T) \\ &= T_k(U\tilde{\Lambda}U^T) \end{aligned}$$

Chebyshev谱CNN

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$$\begin{aligned} g_\theta * x &= U g_\theta U^T x \\ &= U g_\theta(\Lambda) U^T x \\ &= U \left(\sum_{k=0}^K \theta_k T_K(\tilde{\Lambda}) \right) U^T x \\ &= \left(\sum_{k=0}^K \theta_k T_K(U \tilde{\Lambda} U^T) \right) x \\ &= \sum_{k=0}^K \theta_k T_K(\tilde{L}) x \quad (5) \end{aligned}$$



利用数学归纳法证明
 $U T_k(\tilde{\Lambda}) U^T = T_k(U \tilde{\Lambda} U^T)$

整个运算的复杂度是 $O(K|E|)$ ，即与边数 E 呈线性关系。当graph是稀疏图的时候，计算加速尤为明显，这个时候复杂度远低于 $O(n^2)$ 。

Chebyshev谱CNN

图卷积第s个样本的第j个输出的特征图为：

$$y_{s,j} = \sum_{i=1}^{F_{in}} g_{\theta_{i,j}}(L)x_{s,i} \in \mathbb{R}^n,$$

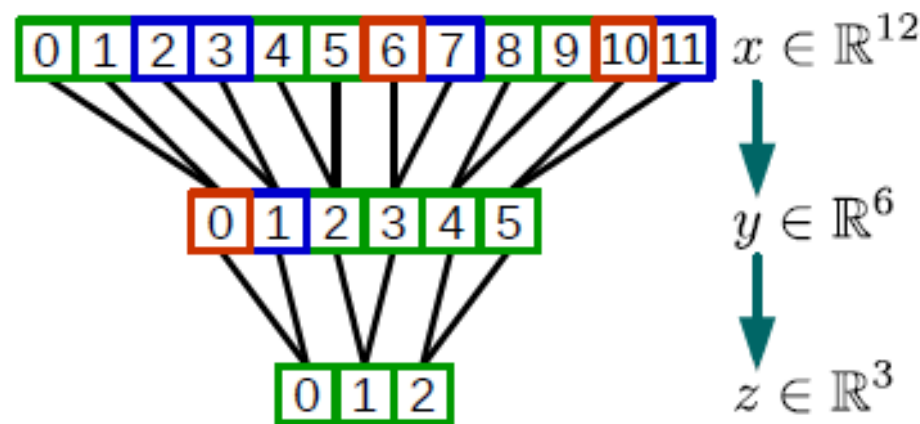
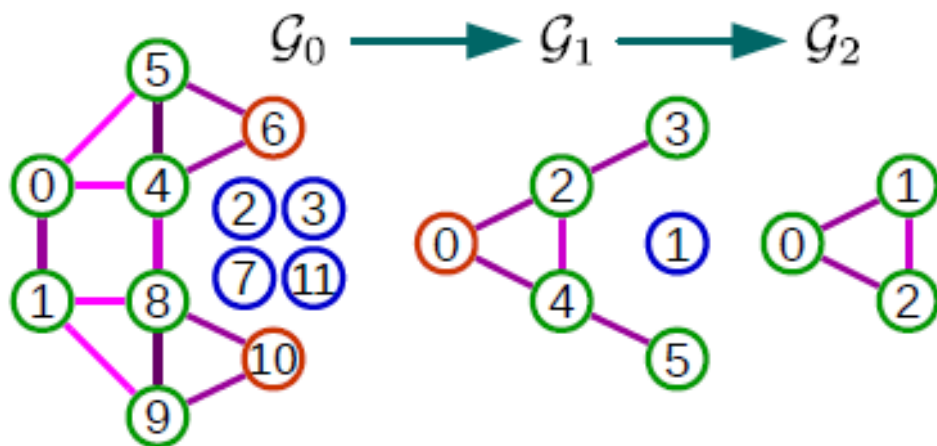
$x_{s,j}$ 表示输入的特征图， θ 是切比雪夫系数。

反向传播公式为：E为损失函数

$$\frac{\partial E}{\partial \theta_{i,j}} = \sum_{s=1}^S [\bar{x}_{s,i,0}, \dots, \bar{x}_{s,i,K-1}]^T \frac{\partial E}{\partial y_{s,j}}$$

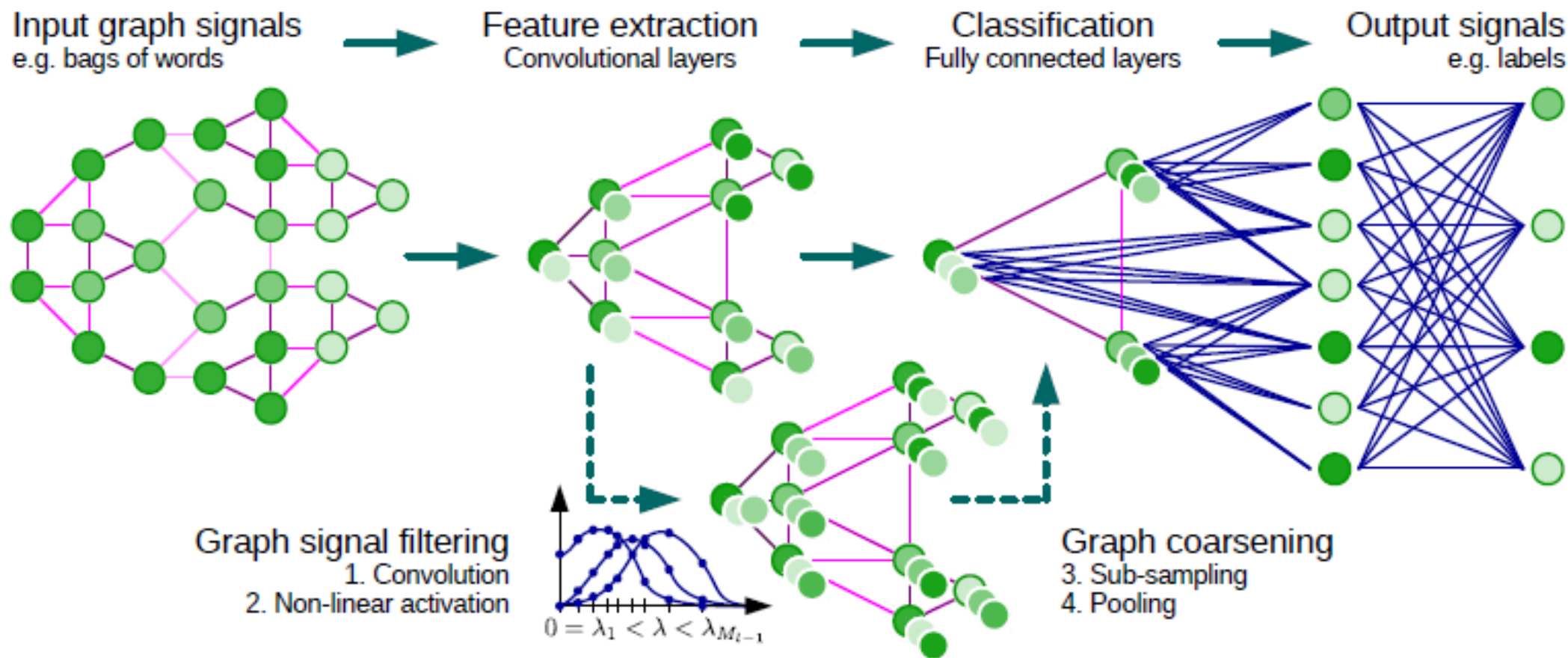
Graph Coarsening and Pooling

- 池化过程采用Graclus贪心粗化方法
- 蓝色的为随机初始化的假节点，保证黄色的单独节点成对匹配，池化过程成整除。
- 最后产生的池化结果 z 可以理解为



$$[\max(x_0, x_1), \max(x_4, x_5, x_6), \max(x_8, x_9, x_{10})]$$

Architecture of a CNN on graphs



Revisiting Classical CNNs on MNIST

- 8-NN graph, 976=784+192 fake nodes, $|\varepsilon| = 3198$ edges
- The weights of a k-NN similarity graph $W_{ij} = \exp\left(-\frac{\|z_i - z_j\|_2^2}{\sigma^2}\right)$
- $K = 25$

Model	Architecture	Accuracy
Classical CNN	C32-P4-C64-P4-FC512	99.33
Proposed graph CNN	GC32-P4-GC64-P4-FC512	99.14

Table 1: Classification accuracies of the proposed graph CNN and a classical CNN on MNIST.

Text Categorization on 20NEWS

- Each document x is represented using the bag-of-words model
- 16-NN graph, z_i is the word2vec embedding $W_{ij} = \exp\left(-\frac{\|z_i - z_j\|_2^2}{\sigma^2}\right)$
- $n = 10,000, |\varepsilon| = 132,834$

Model	Accuracy
Linear SVM	65.90
Multinomial Naive Bayes	68.51
Softmax	66.28
FC2500	64.64
FC2500-FC500	65.76
GC32	68.26

Table 2: Accuracies of the proposed graph CNN and other methods on 20NEWS.

Comparison between Spectral Filters and Computational Efficiency

- Non-Param, Spline, Chebyshev

$$g_{\theta}(\Lambda) = \text{diag}(\theta), \quad g_{\theta}(\Lambda) = B\theta, \quad g_{\theta}(\Lambda) = \sum_{k=0}^{K-1} \theta_k T_k(\tilde{\Lambda}),$$

Dataset	Architecture	Accuracy		
		Non-Param (2)	Spline (7) [4]	Chebyshev (4)
MNIST	GC10	95.75	97.26	97.48
MNIST	GC32-P4-GC64-P4-FC512	96.28	97.15	99.14

Table 3: Classification accuracies for different types of spectral filters ($K = 25$).

Comparison between Spectral Filters and Computational Efficiency

- Non-Param, Spline, Chebyshev

$$g_{\theta}(\Lambda) = \text{diag}(\theta), \quad g_{\theta}(\Lambda) = B\theta, \quad g_{\theta}(\Lambda) = \sum_{k=0}^{K-1} \theta_k T_k(\tilde{\Lambda}),$$

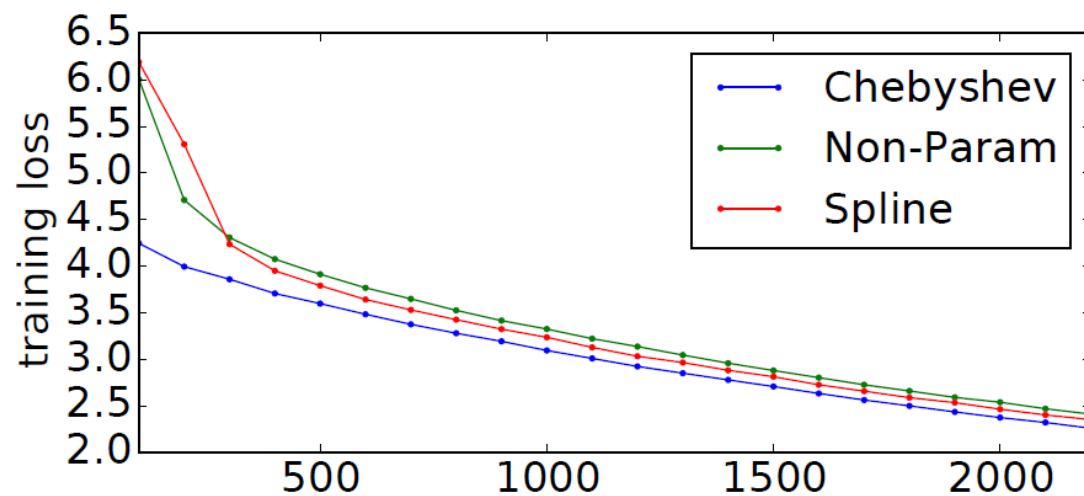
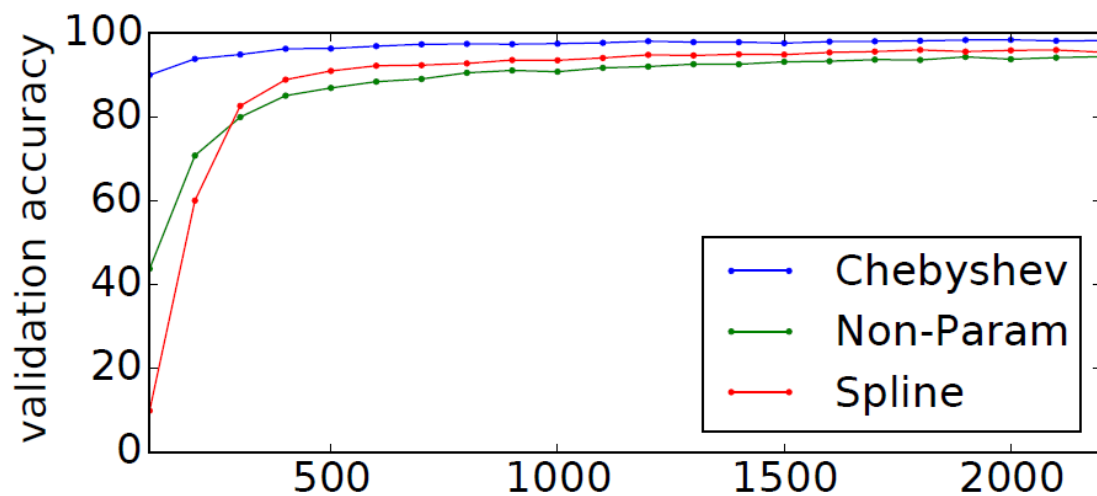


Figure 4: Plots of validation accuracy and training loss for the first 2000 iterations on MNIST.

Comparison between Spectral Filters and Computational Efficiency

- Non-Param, Spline, Chebyshev

$$g_{\theta}(\Lambda) = \text{diag}(\theta), \quad g_{\theta}(\Lambda) = B\theta, \quad g_{\theta}(\Lambda) = \sum_{k=0}^{K-1} \theta_k T_k(\tilde{\Lambda}),$$

$O(n^2)$ $O(n)$

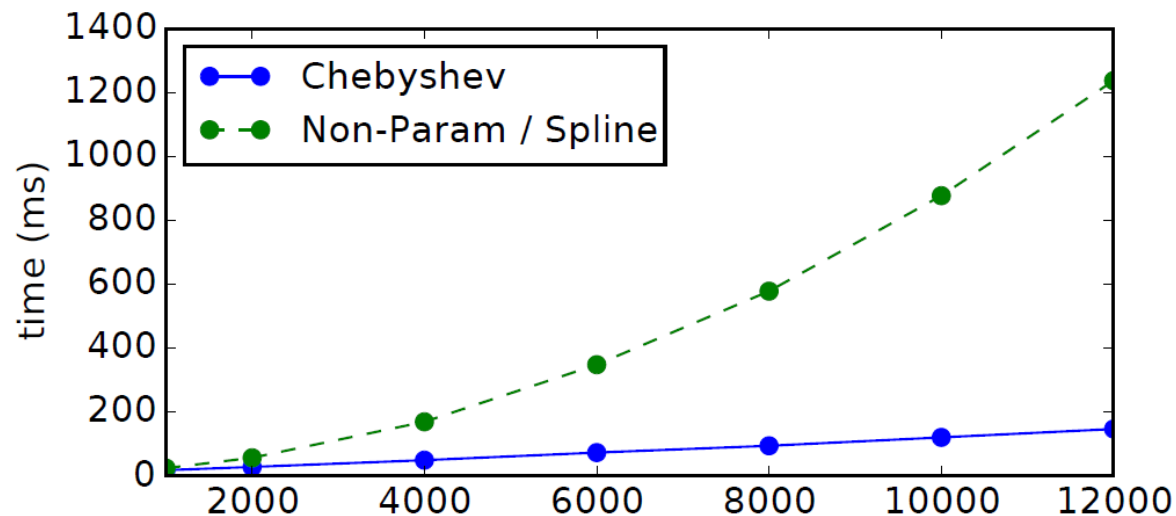


Figure 3: Time to process a mini-batch of $S = 100$ 20NEWS documents w.r.t. the number of words n .

Comparison between Spectral Filters and Computational Efficiency

- Non-Param, Spline, Chebyshev

$$g_{\theta}(\Lambda) = \text{diag}(\theta), \quad g_{\theta}(\Lambda) = B\theta, \quad g_{\theta}(\Lambda) = \sum_{k=0}^{K-1} \theta_k T_k(\tilde{\Lambda}),$$

Model	Architecture	Time (ms)		Speedup
		CPU	GPU	
Classical CNN	C32-P4-C64-P4-FC512	210	31	6.77x
Proposed graph CNN	GC32-P4-GC64-P4-FC512	1600	200	8.00x

Table 4: Time to process a mini-batch of $S = 100$ MNIST images.

Influence of Graph Quality

Architecture	8-NN on 2D Euclidean grid	random
GC32	97.40	96.88
GC32-P4-GC64-P4-FC512	99.14	95.39

Table 5: Classification accuracies with different graph constructions on MNIST.

word2vec				
bag-of-words	pre-learned	learned	approximate	random
67.50	66.98	68.26	67.86	67.75

Table 6: Classification accuracies of GC32 with different graph constructions on 20NEWS.

Conclusions

- Benefits
 - Chebyshev谱CNN是K-localized，具有局部连接性。
 - 参数复杂度为 $O(K)$
 - 整个运算的复杂度是 $O(K|\varepsilon|)$ ，当graph是稀疏图的时候，计算加速尤为明显，这个时候复杂度远低于 $O(n^2)$ 。

Q & A