

GateNet: Gating-Enhanced Deep Network for Click-Through Rate Prediction

Tongwen Huang*
Tencent Corp, China
towanhuang@tencent.com

Qingyun She, Zhiqiang Wang, Junlin Zhang
Sina Weibo Corp, China
{qingyun,zhiqiang36,junlin6}@staff.weibo.com

ABSTRACT

Advertising and feed ranking are essential to many Internet companies such as Facebook. Among many real-world advertising and feed ranking systems, click through rate (CTR) prediction plays a central role. In recent years, many neural network based CTR models have been proposed and achieved success such as Factorization-Machine Supported Neural Networks, DeepFM and xDeepFM. Many of them contain two commonly used components: embedding layer and MLP hidden layers. On the other side, gating mechanism is also widely applied in many research fields such as computer vision(CV) and natural language processing(NLP). Some research has proved that gating mechanism improves the trainability of non-convex deep neural networks. Inspired by these observations, we propose a novel model named GateNet which introduces either the feature embedding gate or the hidden gate to the embedding layer or hidden layers of DNN CTR models, respectively. The feature embedding gate provides a learnable feature gating module to select salient latent information from the feature-level. The hidden gate helps the model to implicitly capture the high-order interaction more effectively. Extensive experiments conducted on three real-world datasets demonstrate its effectiveness to boost the performance of various state-of-the-art models such as FM, DeepFM and xDeepFM on all datasets.

1 INTRODUCTION

Advertising and feed ranking are essential to many Internet companies such as Facebook. The main technique behind these tasks is click-through rate prediction which is known as CTR. Many models have been proposed in this field such as logistic regression (LR)[19], polynomial-2 (Poly2)[12], tree based models[10], tensor-based models[14], Bayesian models[8], and factorization machines based models[12, 21].

With the great success of deep learning in many research fields such as computer vision[15] and natural language processing[2, 20], many deep learning based CTR models have been proposed in recent years[1, 9, 16, 25]. Many of them contain two commonly used components: embedding layer and MLP hidden layers. On the other side, gating mechanism is also widely applied in many research fields such as computer vision(CV) and natural language processing(NLP). Some research works have proved that gating mechanism improves the trainability of non-convex deep neural networks. Inspired by these observations, a model named GateNet is proposed to select salient latent information from the feature-level and implicitly capture the high-order interaction more effectively for CTR prediction.

Our main contributions are listed as follows:

- We propose the **feature embedding gate layer** to replace the traditional embedding and enhance the model ability. Inserting the feature embedding gate into the embedding layer of many classical models such as FM, DeepFM, DNN and XDeepFM, we observe a significant performance improvement.
- The MLP layers are an essential component to implicitly capturing the high-order feature interaction in the canonical DNN models, we introduce the hidden gate to the MLP parts of deep models and improve the performance of the the classical models.
- It is simple and effective to enhance the standard DNN model by inserting hidden gate and we can achieve comparable performance with other state-of-the-art model baselines such as DeepFM and XDeepFM.

The rest of this paper is organized as follows. In Section 2, we review related works which are relevant with our proposed model, followed by introducing our proposed model in Section 3. We will present experimental explorations on three real-world datasets in Section 4. Finally, we conclude this work in Section 5.

2 RELATED WORK

2.1 Deep Learning based CTR Models

Many deep learning based CTR models have also been proposed in recent years[1, 9, 16, 24, 25]. How to effectively model the feature interactions is the key factor for most of these neural network based models. Factorization-Machine Supported Neural Networks (FNN)[25] is a forward neural network using FM to pre-train the embedding layer. However, FNN can capture only high-order feature interactions. Wide & Deep model(WDL)[1] jointly trains wide linear models and deep neural networks to combine the benefits of memorization and generalization for recommendation systems. However, expertise feature engineering is still needed on the input to the wide part of WDL. To alleviate manual efforts in feature engineering, DeepFM[9] replaces the wide part of WDL with FM and shares the feature embedding between the FM and deep component.

In addition, Deep & Cross Network (DCN)[24] and eXtreme Deep Factorization Machine (xDeepFM)[16] are recent deep learning methods which explicitly model the feature interactions.

2.2 Gating Mechanisms in Deep Learning

Gating mechanism is widely used in many deep learning fields, such as computer vision(CV), natural language processing(NLP), and recommendation systems.

The gate mechanism is used in computer vision, such as Highway Network [23], they utilize the transform gate and the carry gate to express how much of the output is produced by transforming the input and carrying the output, respectively.

*Work done at Sina Weibo.

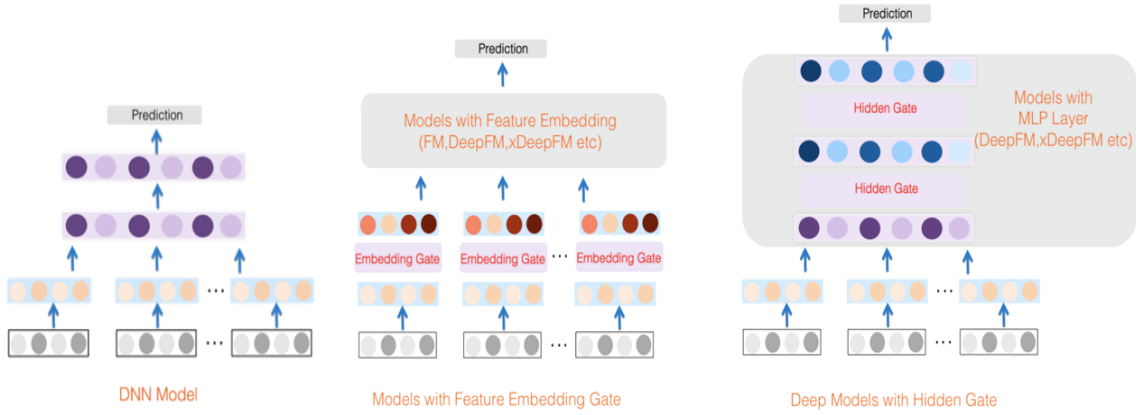


Figure 1: The architecture of our proposed GateNet. The left diagram is the standard DNN network, the middle of diagram is the models with feature embedding gate and the right diagram is the deep models with hidden gate.

The gate mechanism is widely applied to NLP, such as LSTM[6], GRU[2], language modeling[4], sequence to sequence learning[5] and they utilize the gate to prevent the gradients vanishing and resolve the long-term dependency problem.

In addition, [18] uses the gates to automatically adjust parameters between modeling shared information and modeling task-specific information in recommendation systems. Another recommendation system applying the gate mechanism is hierarchical gating network(HGN)[17] and they apply feature-level and instance-level gating modules to adaptively control what item latent features and which relevant item can be passed to the downstream layers.

3 OUR PROPOSED MODEL

Deep learning models are widely used in industrial recommendation systems, such as WDL, YouTubeNet[3] and DeepFM. The DNN model is a sub-component in many current DNN ranking systems, and its network structure is shown in the left of Figure 1.

We can find two commonly used components in most of the current DNN ranking systems: the embedding layer and MLP hidden layer. We aim to enhance the model ability and propose the model named GateNet for CTR prediction tasks. First, we propose the feature embedding gating layer which can convert embedding features into gate-aware embedding features and helps to select salient latent information from the feature-level. Second, we also propose the hidden gate which can adaptively control what latent features and which relevant feature interaction can be passed to the downstream layer. The DNN model with feature embedding gate and DNN model with hidden gate are depicted as the middle and right in Figure 1. In the following subsections, we will describe the feature embedding layer and hidden gate layer in GateNet in detail.

3.1 Feature Embedding Gate

The sparse input layer and embedding layer are widely used in deep learning based CTR models such as DeepFM[9]. The sparse input layer adopts a sparse representation for raw input features.

The embedding layer is able to embed the sparse feature into a low dimensional, dense real-value vector. The output of embedding layer is a wide concatenated field embedding vector:

$$E = [e_1, e_2, \dots, e_i, \dots, e_f]$$

where f denotes the number of fields, $e_i \in R^k$ denotes the embedding of i -th field, and k is the dimension of embedding layer.

On the other side, recent research results show that gate can improve the train-ability in training non-convex deep neural networks[7]. In this work, firstly we propose the feature embedding gate to select salient latent information from the feature-level in the DeepCTR model. The basic steps of the feature embedding gate can be described as followed:

First, for every field embedding e_i , we calculate the gate value which represents the feature-level importance of embedding. We formalize this step as the following formula:

$$g_i = \sigma(W_i \cdot e_i) \quad (1)$$

where σ is the activation function of gate, $e_i \in R^k$ is the original embedding, W_i is the learned parameters of the i -th gate and the total number of learned parameter matrix $W = [W_1, \dots, W_i, \dots, W_f]$, $i = 1, \dots, f$.

Second, we assign the gate value to the corresponding feature embedding and generate a gate-aware embedding.

$$ge_i = e_i \odot g_i \quad (2)$$

where \odot denotes the Hadamard or element-wise product, $e_i \in R^k$ is the i -th original embedding, $i = 1, \dots, f$.

Third, we collect all gate-aware embeddings and regard it as gated feature embedding.

$$GE = [ge_1, ge_2, \dots, ge_i, \dots, ge_f] \quad (3)$$

It is a common practice to make gate output a scalar which represents the importance of the whole feature embedding. To learn the bit level salient important information in the feature embedding, we can make this gate output a vector which contains fine-grained information about the feature embedding. And we call

this embedding gate ‘bit-wise’ gate and the common gate ‘vector-wise’ gate. The vector-wise and bit-wise feature embedding gate can be depicted as Figure 2.

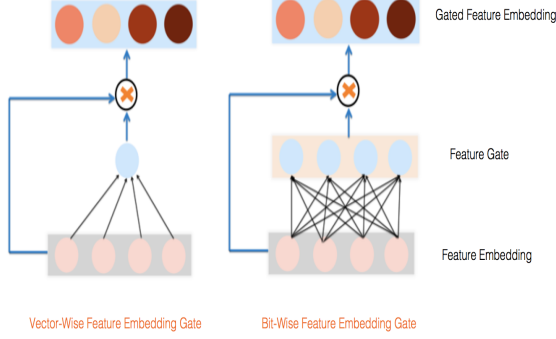


Figure 2: The Feature Embedding Gate. The left diagram represents vector-wise feature embedding gate and the right diagram is bit-wise feature embedding gate.

Seen from the figure, we compare the difference of vector-wise feature gate and bit-wise feature is as follows:

Vector-wise: $g_i \in R$, $W_i \in R^{k \times 1}$, $W \in R^{f \times k \times 1}$.

Bit-wise: $g_i \in R^k$, $W_i \in R^{k \times k}$, $W \in R^{f \times k \times k}$.

We can see that the output of bit-wise gate is a vector which is related to each bit of feature embedding and it can be regarded as using the same value to each bit of feature embedding. The performance comparison of vector-wise and bit-wise feature embedding gate will be discussed in Section 4.2.

Moreover, as some previous works such as FiBiNet[11] does, we will explore the parameter sharing mechanism of the feature embedding gate layer. Each gate in the feature embedding gate layer has its own parameters to explicitly learn the salient feature information, we also can make all the gates share parameters in order to reduce the number of parameters. We call this gate ‘field sharing’ and previous gate ‘field private’. From a mathematical perspective, the biggest difference between ‘field sharing’ and ‘field private’ is the learned gate parameters W_i . W_i is shared among all the fields in ‘field sharing’ while W_i is different for each field in ‘field private’. The performance of ‘field sharing’ and ‘field private’ will be compared in Section 4.2.

3.2 Hidden Gate

The deep part of many DNN ranking systems usually consists of several full-connected layers, which implicitly captures high-order features interactions. As shown in Figure 1, the input of deep network is the flatten of embedding layer. Let $a^{(0)} = [ge_1, \dots, ge_i, \dots, ge_f]$ denotes the outputs of embedding layer, where $ge_i \in R^k$ represents the i -th feature embedding. Then, $a^{(0)}$ is fed into multi-layer perceptron network, and the feed forward process is:

$$a^{(l)} = \sigma(W^{(l)}a^{(l-1)} + b^{(l)}) \quad (4)$$

where l is the depth and σ is the activation function. $W^{(l)}, b^{(l)}, a^{(l)}$ are the model weight, bias and output of the l -th layer.

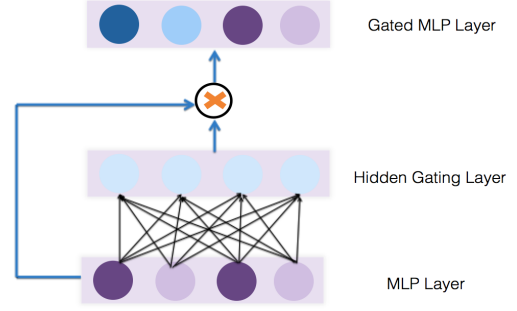


Figure 3: The Hidden Gate Layer

Similar to the bit-wise feature embedding gate, we proposed the hidden gate which can be applied to the hidden layer. As depicted as Figure 3, we use this gate as follows:

$$g^{(l)} = a^{(l)} \odot \sigma_g(W_g^{(l)}a^{(l)}) \quad (5)$$

where \odot denotes the element-wise product, σ_g is the gate activation function, $W_g^{(l)}$ is the l -th layer parameter of hidden gate. Likewise, we can stack multiple hidden gate layers like the classic DNN models.

3.3 Output Layer

To summarize, we give the overall formulation of our proposed model’s output as:

$$\hat{y} = \sigma(W^{|L|}g^{|L|} + b^{|L|}) \quad (6)$$

where $\hat{y} \in (0, 1)$ is the predicted value of CTR, σ is the sigmoid function, $b^{|L|}$ is the bias and $|L|$ is the depth of DNN. The learning process aims to minimize the following objective function (cross entropy):

$$loss = -\frac{1}{N} \sum_{i=1}^N (y_i \log(\hat{y}_i) + (1 - y_i) * \log(1 - \hat{y}_i)) \quad (7)$$

where y_i is the ground truth of i -th instance, \hat{y}_i is the predicted CTR, and N is the total size of samples.

4 EXPERIMENTS

In this section, we conduct extensive experiments to answer the following research questions:

(RQ1) Can the feature embedding gate enhance the ability of the baseline models?

(RQ2) Can the hidden gate enhance the ability of the baseline models?

(RQ3) Can we combine the two gates in one model to achieve further improvements?

(RQ4) How do the settings of networks influence the performance of our model?

We will answer these questions after presenting some fundamental experimental settings.

4.1 Experimental Testbeds and Setup

4.1.1 Data Sets. 1) Criteo. The Criteo¹ dataset is widely used in many CTR model evaluation. It contains click logs with 45 millions data instances. There are 26 anonymous categorical fields and 13 continuous feature fields in Criteo dataset. We split the dataset randomly into two parts: 90% is for training, while the rest is for testing. 2) ICME. The ICME² dataset consists of several days of **short video click datas**. It contains click logs with 19 millions data instances in track2. For each click data, we choose 5 fields(user_id, user_city, item_id,author_id,item_city) to predict the like probability of short video. We split it randomly into two parts: 70% is for training, while the rest is for testing. 3) SafeDriver. The SafeDriver³ dataset is used to predict the probability that an auto insurance policy holder files a claim. There are 57 anonymous fields in SafeDriver dataset and these features are divided into similar groups:binary features, categorical features, continuous features and ordinal features. It contains 595K data instances. We split the dataset randomly into two parts: 90% is for training, while the rest is for testing.

4.1.2 Evaluation Metrics. In our experiment, we adopt AUC(Area Under ROC) as metric. AUC is a widely used metric in evaluating classification problems. Besides, some work validates AUC as a good measurement in CTR prediction[8]. AUC is insensitive to the classification threshold and the positive ratio. The upper bound of AUC is 1, and the larger the better.

4.1.3 Baseline Methods. To verify the effect of the gate layer added in various mainstream models, we choose some widely used CTR models as our baseline models including FM[21, 22], DNN, DeepFM[9], and XDeepFM[16].

Main goal of this work is not intent to propose a new model instead of enhancing these baseline models via gating mechanism that we proposed. Note that an improvement of 1% in AUC is usually regarded as significant for the CTR prediction because it will bring a large increase in a company’s revenue if the company has a very large user base.

4.1.4 Implementation Details. We implement all the models with Tensorflow⁴ in our experiments. For the embedding layer, the dimension of embedding layer is set to 10. For the optimization method, we use the Adam[13] with a mini-batch size of 1000, and the learning rate is set to 0.0001. For all deep models, the depth of layers is set to 3, all activation functions are RELU, the number of neurons per layer is 400, and the dropout rate is set to 0.5. The default activation function of feature embedding gate is Sigmoid and activation function of hidden gate is Tanh. We conduct our experiments with 2 Tesla K40 GPUs.

4.2 Performance of Feature Embedding Gate(RQ1)

In this subsection, we show the performance gains of chosen baseline models after inserting feature embedding gate into a typical embedding layer. The experiments are conducted on Criteo,ICME and SafeDriver datasets and results are shown in Table 1.

¹<http://labs.criteo.com/downloads/>

²<https://biendata.com/competition/icmechallenge2019>

³<https://www.kaggle.com/c/porto-seguro-safe-driver-prediction>

⁴TensorFlow: <https://www.tensorflow.org/>

Table 1: The overall performance improvements of baseline models after inserting feature embedding gate into a typical embedding layer. Unless specially mentioned in our paper, ‘field private’ and ‘vec-wise’ model are used as the default setting in the embedding gate model. The suffix with ‘e’ stands for applying the embedding gate to this model.

Model	ICME	Criteo	SafeDriver
FM	0.8696	0.7923	0.6302
FM _e	0.8973	0.7970	0.6327
Δ	0.0277	0.0047	0.0025
DNN	0.8912	0.8067	0.6344
DNN _e	0.9166	0.8096	0.6359
Δ	0.0254	0.0029	0.0015
DeepFM	0.9027	0.8087	0.6276
DeepFM _e	0.9097	0.8097	0.6349
Δ	0.0070	0.0010	0.0073
XDeepFM	0.9052	0.8091	0.6324
XDeepFM _e	0.9178	0.8098	0.6336
Δ	0.0126	0.0007	0.0012

Inserting the feature embedding gate into these baseline models, we find our proposed embedding gate mechanisms can consistently boost the baseline model’s performance on these three datasets as shown in Table 1. These results indicate that carefully selecting salient latent information from the feature-level is useful to enhance the model ability and make the baseline models achieve better performance. Among all the baseline models, FM with the feature embedding gate gets a significant improvement which outperforms the classic FM model by almost 2% on ICME dataset. We assume that FM is a shallow model that has only a set of latent vectors to learn, there’s no other component in FM to explicitly or implicitly adjust the feature in FM, so the gate mechanism is a good way to adjust the feature weight. Instead of FM, there are many deep models such as DeepFM and XDeepFM, our models with feature embedding gate can enhance these models’ ability and make further improvements.

Moreover, we design some further research about feature embedding gate. First, we conduct some experiments to compare parameter sharing mechanism of gate(‘field sharing’ and ‘field private’) in Table 2.

Table 2: Parameter sharing mechanism of feature embedding gate: field private vs field sharing.

Model	ICME		Criteo	
	Private	Share	Private	Share
FM	0.8973	0.8861	0.7970	0.7957
DNN	0.9166	0.9076	0.8096	0.8099
DeepFM	0.9097	0.8985	0.8097	0.8098
XDeepFM	0.9178	0.9039	0.8098	0.8096

From the Table 2, we can find that the performance of ‘field private’ gate is much better than the ‘field sharing’ gate for many base models on ICME dataset while it is not significant on Criteo dataset.

Although the ‘field sharing’ can reduce the number of learned parameters, the performance also decreases. These results indicate that the performance of different parameter sharing mechanisms of gate depend on specific task. On the whole, it is a better choice to choose the ‘field private’ in our experiments.

Second, we conduct some experiments to explore the vector-wise and bit-wise feature embedding gate. The results in Table 3 show

Table 3: Embedding gate mechanism: vector-wise vs bit-wise. The default gate share mechanism is ‘field private’.

Model	ICME		Criteo	
	vec-wise	bit-wise	vec-wise	bit-wise
FM	0.8973	0.8937	0.7970	0.7985
DNN	0.9166	0.9018	0.8096	0.8098
DeepFM	0.9097	0.9112	0.8097	0.8098
XDeepFM	0.9178	0.9175	0.8098	0.8100

that bit-wise is a little better than vector-wise on Criteo dataset, while we cannot draw an obvious conclusion on the ICME data. The reason behind this needs further exploration.

4.3 Performance of Hidden Gate(RQ2)

In this subsection, the overall performance gains of chosen baseline models after inserting hidden gate into a typical MLP layer will be reported on these three test sets in Table 4.

Table 4: The overall performance improvements of baseline models with hidden gates. The suffix with ‘h’ stands for applying the hidden gate to this model.

Model	ICME	Criteo	SafeDriver
DNN	0.8912	0.8067	0.6344
DNN _h	0.9105	0.8093	0.6348
Δ	0.0193	0.0026	0.0004
DeepFM	0.9027	0.8087	0.6276
DeepFM _h	0.9121	0.8090	0.6324
Δ	0.0094	0.0003	0.0048
XDeepFM	0.9052	0.8091	0.6324
XDeepFM _h	0.9084	0.8092	0.6344
Δ	0.0032	0.0001	0.0020

Replacing the traditional MLP with the hidden gate layer, our proposed hidden gate mechanisms consistently enhance these baseline models and achieve performance improvements on the ICME, Criteo and SafeDriver dataset as shown in Table 4. The experimental results indicate that the hidden gate helps the model to implicitly capture the high-order interaction more effectively.

Although applying hidden gate to MLP layers is simple, it is an effective way to improve the performance of baseline models. Therefore, we conduct experiments to compare hidden gate DNN with some complex base models in the Table 5.

From the Table 5, the standard DNN by inserting hidden gate outperforms some canonical deep learning models such as DeepFM, XDeepFM. It is a simple way to enhance the standard DNN to gain

Table 5: Compare the performance between standard DNN by inserting hidden gate and other base models. The Safe denotes SafeDrive dataset and XDFM represents XDeepFM.

Dataset	DNN	DeepFM	XDFM	FiBiNet	DNN _h
Criteo	0.8063	0.8087	0.8091	0.8102	0.8093
ICME	0.8912	0.9027	0.9052	0.9030	0.9105
Safe	0.6344	0.6276	0.6324	0.6342	0.6348

improvement, which makes the DNN model much more practicable in industrial recommendation systems.

4.4 Performance of model Combining FE-Gate and Hidden Gate(RQ3)

As mentioned previously, we find the feature embedding gate and hidden gate can enhance the model ability and gain good performance, respectively. Can we combine the feature embedding gate and hidden gate in one model to achieve further performance? We conduct some experiments to answer this research question on Criteo and ICME datasets.

Table 6: The overall performance of baseline models with feature embedding gate and hidden gate models. The ‘EGate’, ‘HGate’, ‘Both’ denote the feature embedding gate, hidden gate and feature embedding gate plus hidden gate, respectively.

Dataset	Model	Base	EGate	HGate	Both
ICME	DNN	0.8912	0.9166	0.9195	0.9054
	DeepFM	0.9027	0.9097	0.9121	0.9114
	XDeepFM	0.9052	0.9178	0.9084	0.9054
Criteo	DNN	0.8067	0.8096	0.8093	0.8097
	DeepFM	0.8087	0.8097	0.8090	0.8097
	XDeepFM	0.8091	0.8098	0.8092	0.8098

It can be seen from Table 6 that combining feature embedding gate and hidden gate in one model can not gain further performance improvements. Specifically, there is not much performance improvements on Criteo and some performance decrease on ICME. The feature embedding gate can influence the implicit and explicit feature interaction while the hidden gate can influence the implicit feature interaction, we assume that the implicit feature interactions have been done twice and the implicit feature representations are damaged. The real reason behind this need to conduct further experiments to justify this assumption.

4.5 Hyper-parameter Study(RQ4)

We conduct some experiments to study the influence of hyper-parameter in our proposed gate mechanisms. We test different settings in our proposed GateNet on the SafeDriver dataset and we treat DeepFM, DeepFM_e and DeepFM_h as the baseline models.

So we divide the hyper-parameters into the following three parts:

- Gate activation function. Both embedding and hidden gate include the gate activation functions.

- Embedding size. We change the embedding size from 10 to 50, and compare the performance of baseline model with embedding gate model.
- Hidden layers. We change the number of layers from 2 to 6, and observe the performance of baseline model and hidden gate model.

Table 7: The overall performance of different activation functions in the feature embedding gate and hidden gate.

Model	Linear	Relu	Sigmoid	Tanh
DeepFM _e	0.6356	0.6343	0.6320	0.6349
DeepFM _h	0.6321	0.6320	0.6311	0.6324

4.5.1 Activation function in Gate. The test results on SafeDriver dataset with different activation functions in the feature embedding gate and hidden gate are presented in Table 7. We observe that the best activation function in feature embedding gate is linear while the best activation function is Tanh in hidden gate.

Table 8: The performance of different embedding sizes in Feature Embedding gate.

Model	10	20	30	40	50
DeepFM	0.6276	0.6297	0.6271	0.6284	0.6235
DeepFM _e	0.6349	0.6322	0.6319	0.6329	0.6307

4.5.2 Embedding Size in Feature Embedding Gate. We change the embedding size from 10 to 50 in feature embedding gate and summarize the range of performances in Table 8. From the results, we find that embedding size has little influence on the GateNet. Specifically, the standard DeepFM has a good performance with the embedding size 20, while the embedding size of DeepFM_e is 10. Therefore, these results show that DeepFM_e requires less parameter than DeepFM to train a good model.

4.5.3 Number of Layers in Hidden Gate. In deep part, we can change the number of neurons per layer, depths of DNN, activation functions and dropout rates. For brevity, we just study the impact of different depths in DNN part. We change the number of layers from 2 to 6 in hidden gate and conclude the performance in Table 9.

Table 9: The performance of different number of layers in DNN.

#Layers	2	3	4	5	6
DeepFM	0.6219	0.6276	0.6281	0.6290	0.6279
DeepFM _h	0.6328	0.6324	0.6312	0.6321	0.6286

Increasing the number of layers, the performance of DeepFM increases, while DeepFM_h decreases. These results indicate that our DeepFM_h can learn much better than DeepFM with less parameters on SafeDriver dataset.

5 CONCLUSIONS

Recently, many neural network based CTR models have been proposed and some recent research results found that gating mechanisms can improve the trainability in training non-convex deep neural networks. Inspired by these observations, we proposed a novel model named GateNet which introduces either the feature embedding gate or the hidden gate to the embedding layer or hidden layers of DNN CTR models, respectively. Extensive experiments conducted on three real-world datasets demonstrate its effectiveness to boost the performance of various state-of-the-art models such as FM, DeepFM and xDeepFM on three real-world datasets.

REFERENCES

- [1] Heng-Tze Cheng, Levent Koc, Jeremiah Harmsen, Tal Shaked, Tushar Chandra, Hrishu Aradhye, Glen Anderson, Greg Corrado, Wei Chai, Mustafa Ipsir, et al. 2016. Wide & deep learning for recommender systems. In *Proceedings of the 1st Workshop on Deep Learning for Recommender Systems*. ACM, 7–10.
- [2] Kyunghyun Cho, Bart van Merriënboer, Caglar Gulcehre, Dzmitry Bahdanau, Fethi Bougares, Holger Schwenk, and Yoshua Bengio. 2014. Learning Phrase Representations using RNN Encoder-Decoder for Statistical Machine Translation. *arXiv:cs.CL/1406.1078*
- [3] Paul Covington, Jay Adams, and Emre Sargin. 2016. Deep neural networks for youtube recommendations. In *Proceedings of the 10th ACM conference on recommender systems*. ACM, 191–198.
- [4] Yann N Dauphin, Angela Fan, Michael Auli, and David Grangier. 2017. Language modeling with gated convolutional networks. In *Proceedings of the 34th International Conference on Machine Learning-Volume 70*. JMLR. org, 933–941.
- [5] Jonas Gehring, Michael Auli, David Grangier, Denis Yarats, and Yann N Dauphin. 2017. Convolutional sequence to sequence learning. In *Proceedings of the 34th International Conference on Machine Learning-Volume 70*. JMLR. org, 1243–1252.
- [6] Felix A Gers, Jürgen Schmidhuber, and Fred Cummins. 1999. Learning to forget: Continual prediction with LSTM. (1999).
- [7] Xavier Glorot and Yoshua Bengio. 2010. Understanding the difficulty of training deep feedforward neural networks. In *Proceedings of the thirteenth international conference on artificial intelligence and statistics*. 249–256.
- [8] Thore Graepel, Joaquin Quinonero Candela, Thomas Borchert, and Ralf Herbrich. 2010. Web-scale bayesian click-through rate prediction for sponsored search advertising in microsoft’s bing search engine. Omnipress.
- [9] Huifeng Guo, Ruiming Tang, Yunming Ye, Zhenguo Li, and Xiuqiang He. 2017. Deepfm: a factorization-machine based neural network for ctr prediction. *arXiv preprint arXiv:1703.04247* (2017).
- [10] Xinran He, Junfeng Pan, Ou Jin, Tianbing Xu, Bo Liu, Tao Xu, Yanxin Shi, Antoine Atallah, Ralf Herbrich, Stuart Bowers, et al. 2014. Practical lessons from predicting clicks on ads at facebook. In *Proceedings of the Eighth International Workshop on Data Mining for Online Advertising*. ACM, 1–9.
- [11] Tongwen Huang, Zhiqi Zhang, and Junlin Zhang. 2019. FiBiNET: combining feature importance and bilinear feature interaction for click-through rate prediction. In *Proceedings of the 13th ACM Conference on RecSys 2019*. 169–177.
- [12] Yuchin Juan, Yong Zhuang, Wei-Sheng Chin, and Chih-Jen Lin. 2016. Field-aware factorization machines for CTR prediction. In *Proceedings of the 10th ACM Conference on Recommender Systems*. ACM, 43–50.
- [13] Diederik P Kingma and Jimmy Ba. 2014. Adam: A method for stochastic optimization. *arXiv preprint arXiv:1412.6980* (2014).
- [14] Yehuda Koren, Robert Bell, and Chris Volinsky. 2009. Matrix factorization techniques for recommender systems. *Computer* 8 (2009), 30–37.
- [15] Alex Krizhevsky, Ilya Sutskever, and Geoffrey E Hinton. 2012. Imagenet classification with deep convolutional neural networks. In *Advances in neural information processing systems*. 1097–1105.
- [16] Jianxun Lian, Xiaohuan Zhou, Fuzheng Zhang, Zhongxia Chen, Xing Xie, and Guangzhong Sun. 2018. xDeepFM: Combining Explicit and Implicit Feature Interactions for Recommender Systems. *arXiv preprint arXiv:1803.05170* (2018).
- [17] Chen Ma, Peng Kang, and Xue Liu. 2019. Hierarchical Gating Networks for Sequential Recommendation. *arXiv preprint arXiv:1906.09217* (2019).
- [18] Jiaqi Ma, Zhe Zhao, Xinyang Yi, Jilin Chen, Lichan Hong, and Ed H Chi. 2018. Modeling task relationships in multi-task learning with multi-gate mixture-of-experts. In *Proceedings of the 24th ACM SIGKDD International Conference on Knowledge Discovery & Data Mining*. ACM, 1930–1939.
- [19] H Brendan McMahan, Gary Holt, David Sculley, Michael Young, Dietmar Ebner, Julian Grady, Lan Nie, Todd Phillips, Eugene Davydov, Daniel Golovin, et al. 2013. Ad click prediction: a view from the trenches. In *Proceedings of the 19th ACM SIGKDD international conference on Knowledge discovery and data mining*. ACM, 1222–1230.

- [20] Tomáš Mikolov, Martin Karafiát, Lukáš Burget, Jan Černocký, and Sanjeev Khudanpur. 2010. Recurrent neural network based language model. In *Eleventh Annual Conference of the International Speech Communication Association*.
- [21] Steffen Rendle. 2010. Factorization machines. In *Data Mining (ICDM), 2010 IEEE 10th International Conference on*. IEEE, 995–1000.
- [22] Steffen Rendle. 2012. Factorization machines with libfm. *ACM Transactions on Intelligent Systems and Technology (TIST)* 3, 3 (2012), 57.
- [23] Rupesh Kumar Srivastava, Klaus Greff, and Jürgen Schmidhuber. 2015. Highway networks. *arXiv preprint arXiv:1505.00387* (2015).
- [24] Ruoxi Wang, Bin Fu, Gang Fu, and Mingliang Wang. 2017. Deep & cross network for ad click predictions. In *Proceedings of the ADKDD'17*. ACM, 12.
- [25] Weinan Zhang, Tianming Du, and Jun Wang. 2016. Deep learning over multi-field categorical data. In *European conference on information retrieval*. Springer, 45–57.