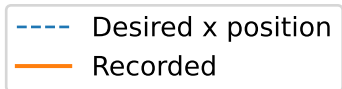
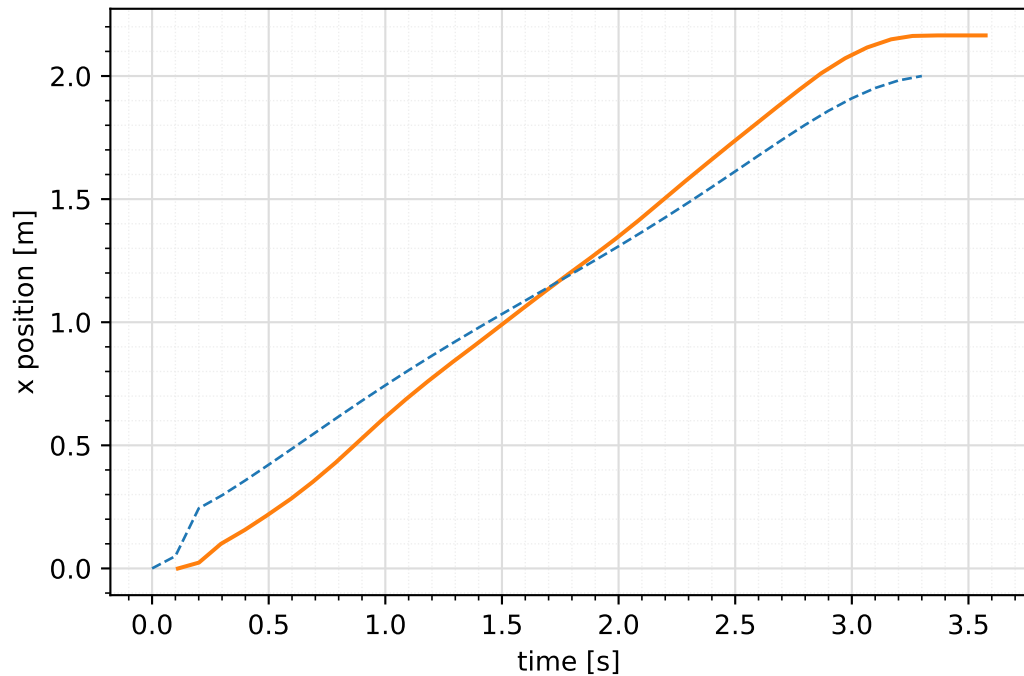
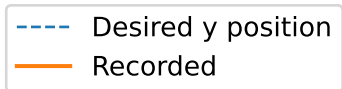


Pololu 3pi+ trajectory test (straight line)
trajectory: curve.json
file name : crv0_0_23.json
 $K_x = 1$ $K_y = 4$ $K_{\theta} = 4$

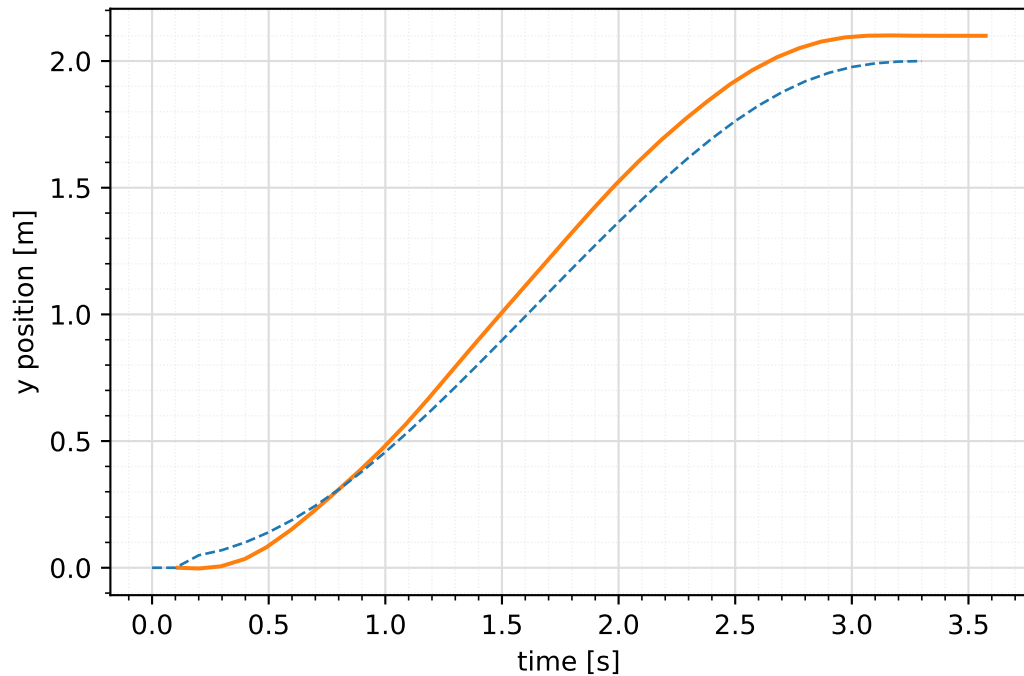


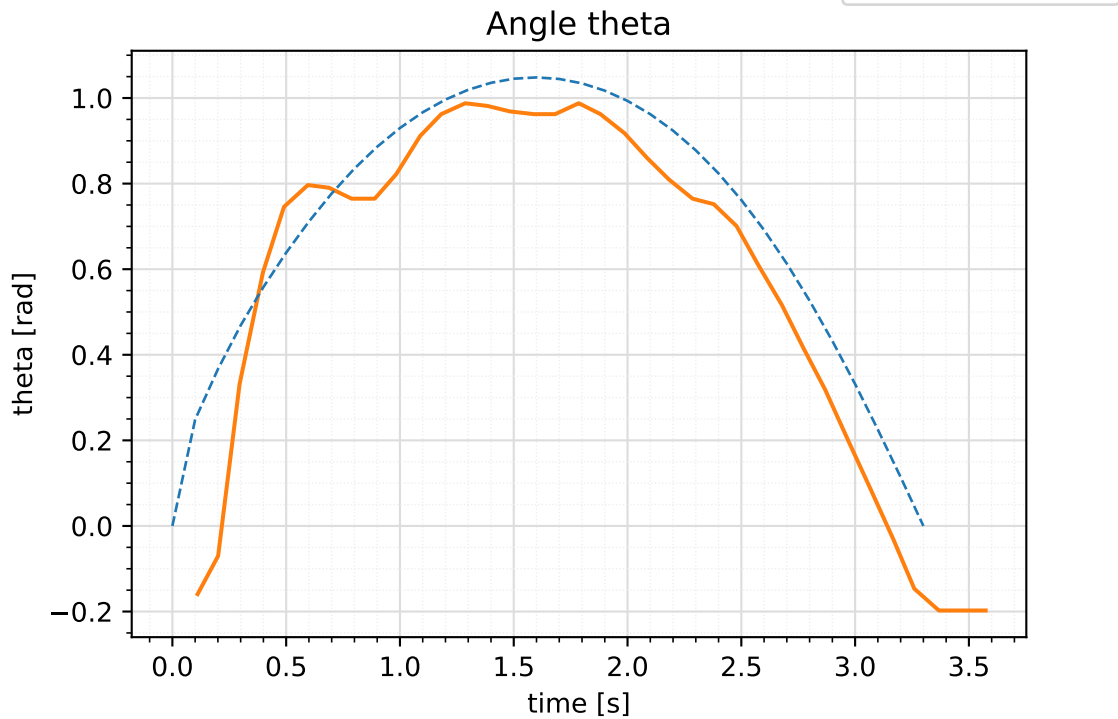
Trajectory x



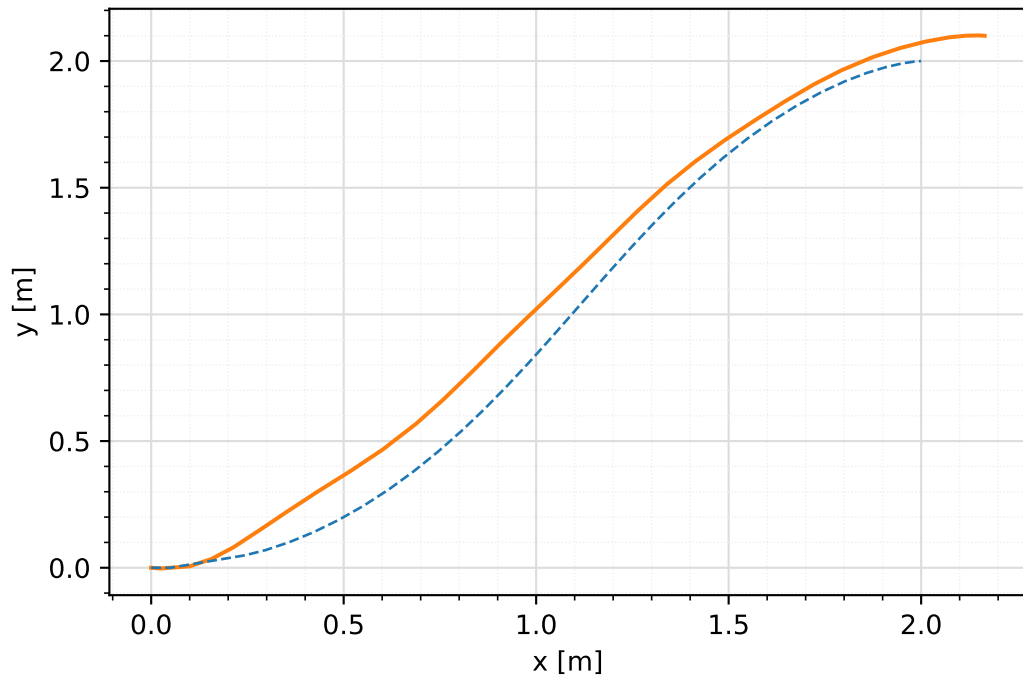


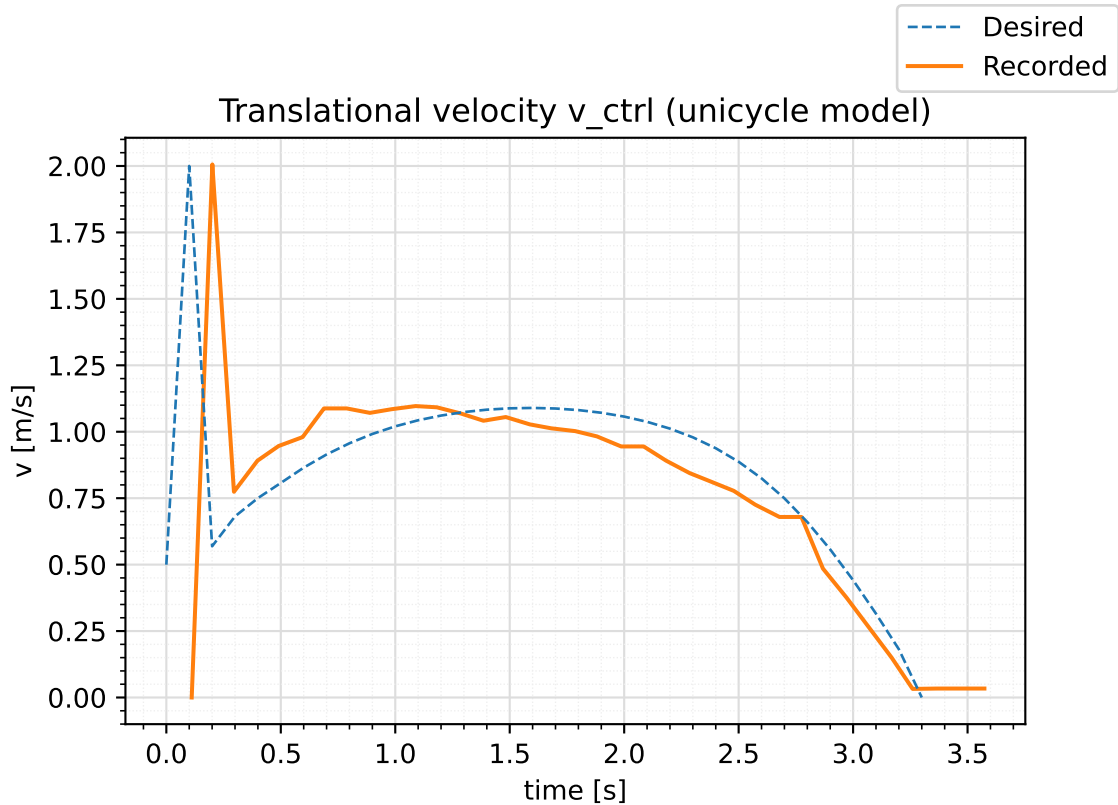
Trajectory y

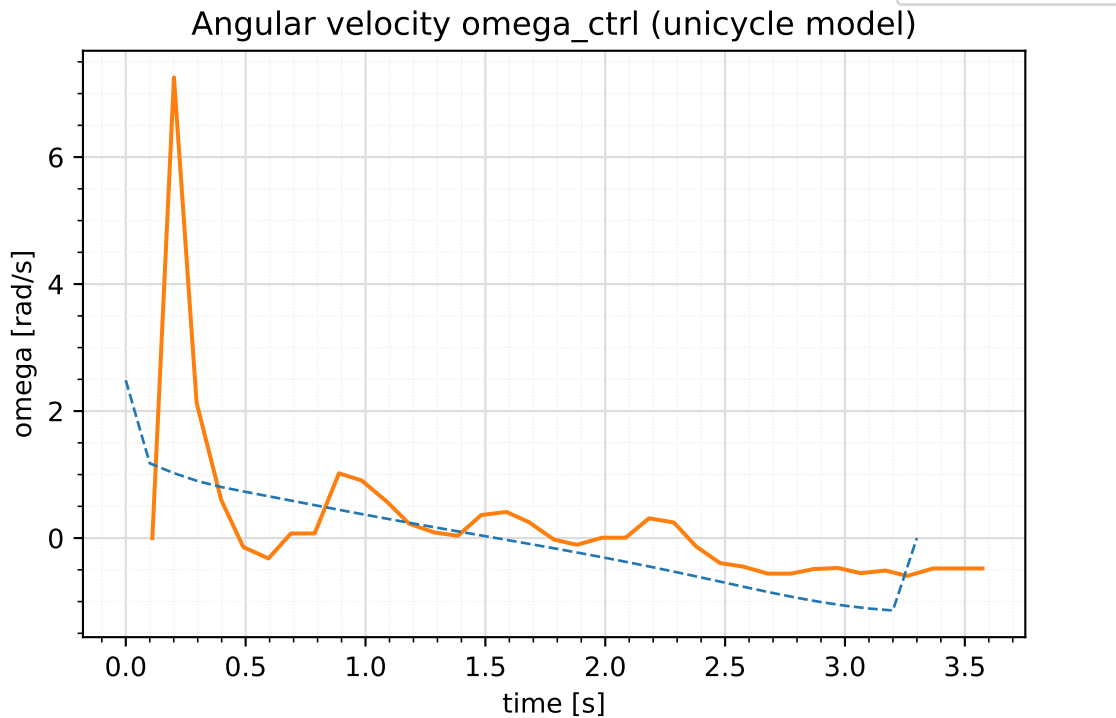




2D visualization







Left and right wheel angular velocities u_L & u_R

Desired
Recorded

