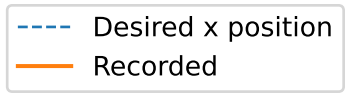
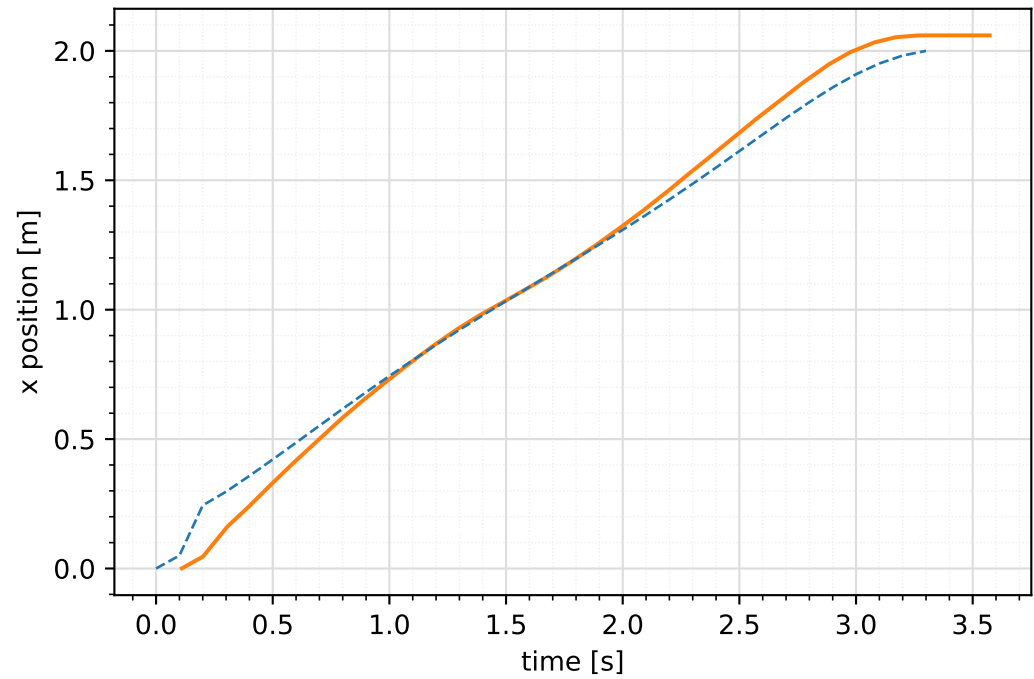
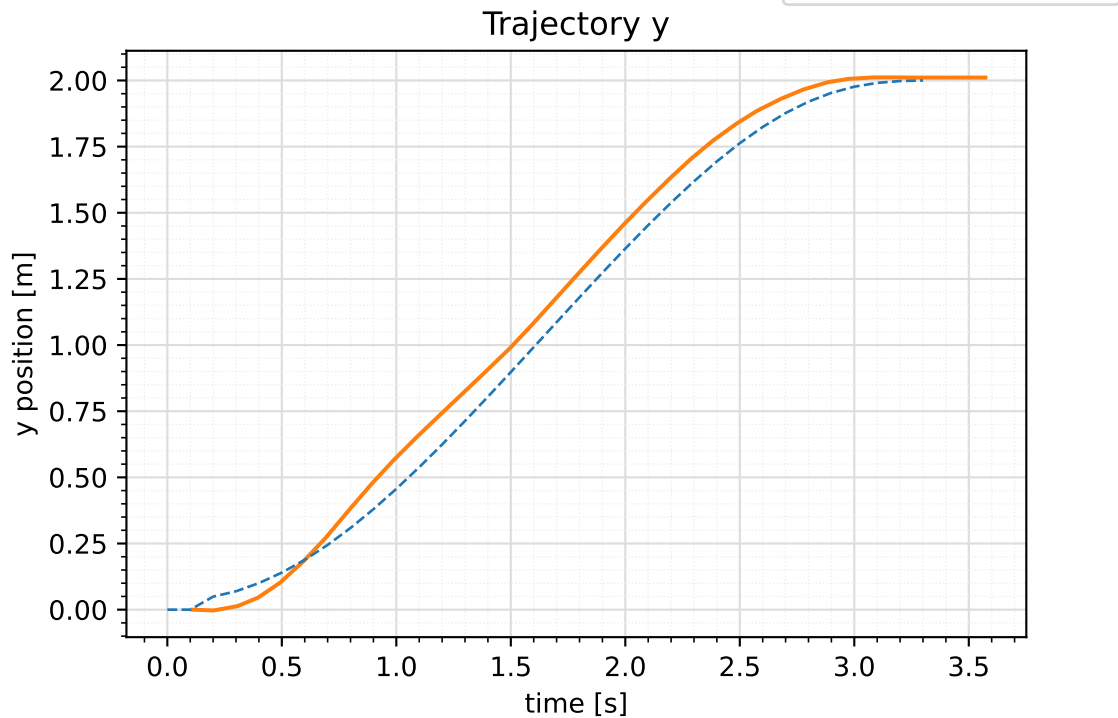


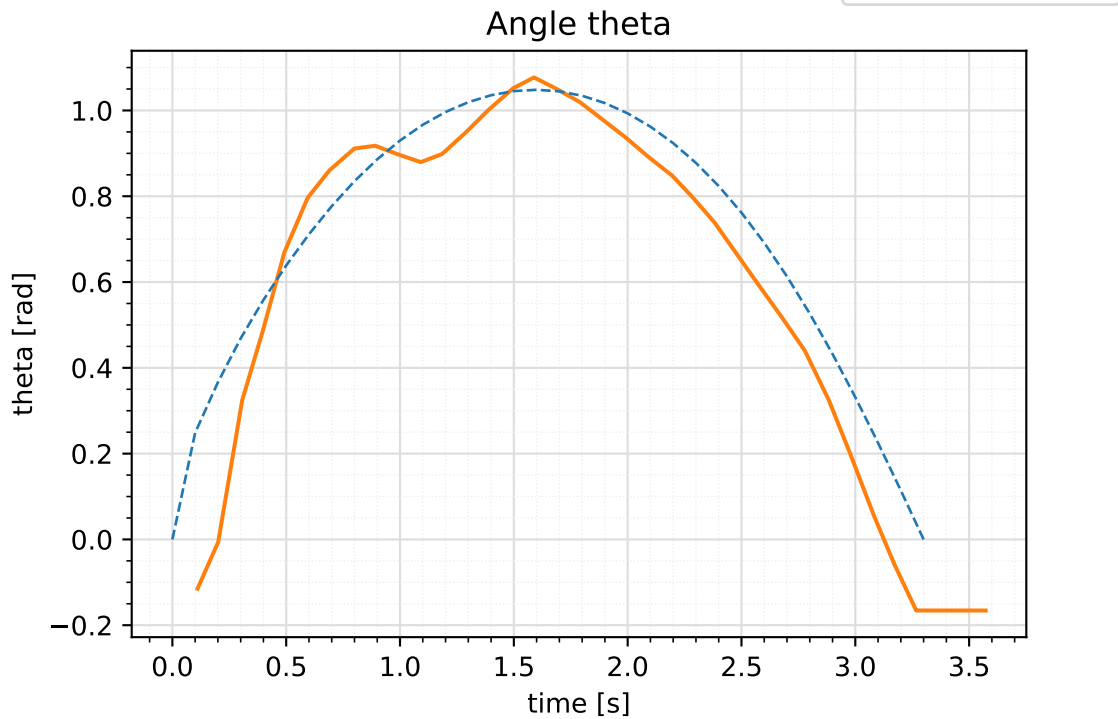
Pololu 3pi+ trajectory test (straight line)  
trajectory: curve.json  
file name : crv0\_0\_26.json  
 $K_x = 3$   $K_y = 3$   $K_{\theta} = 3$



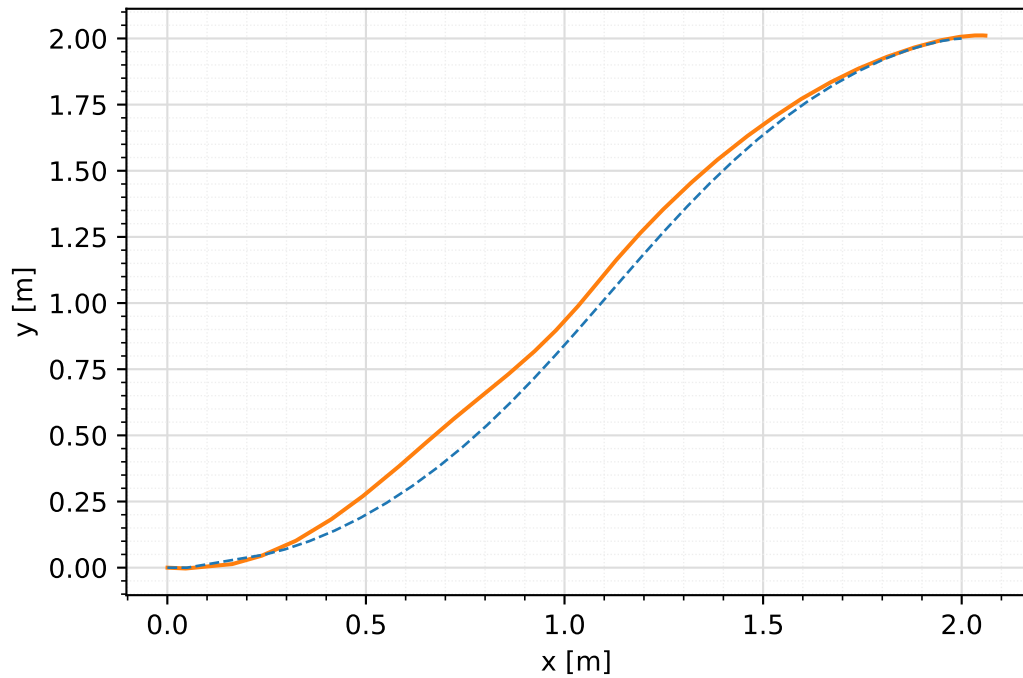
Trajectory x

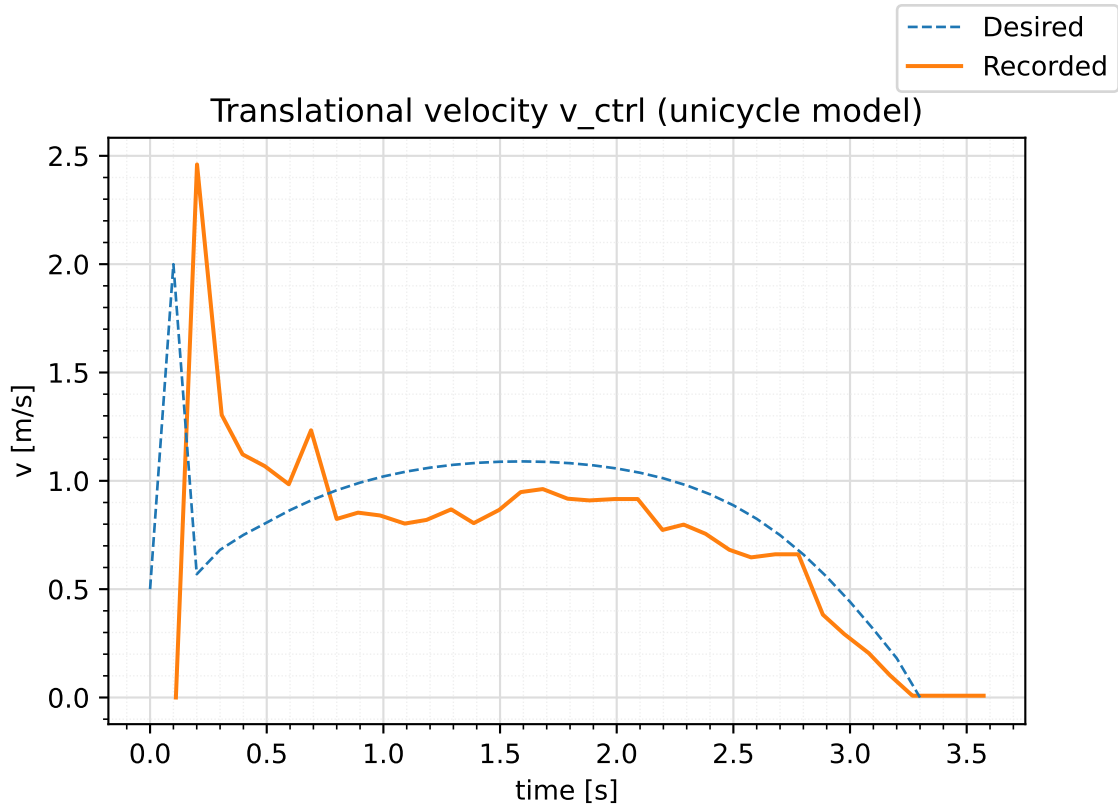


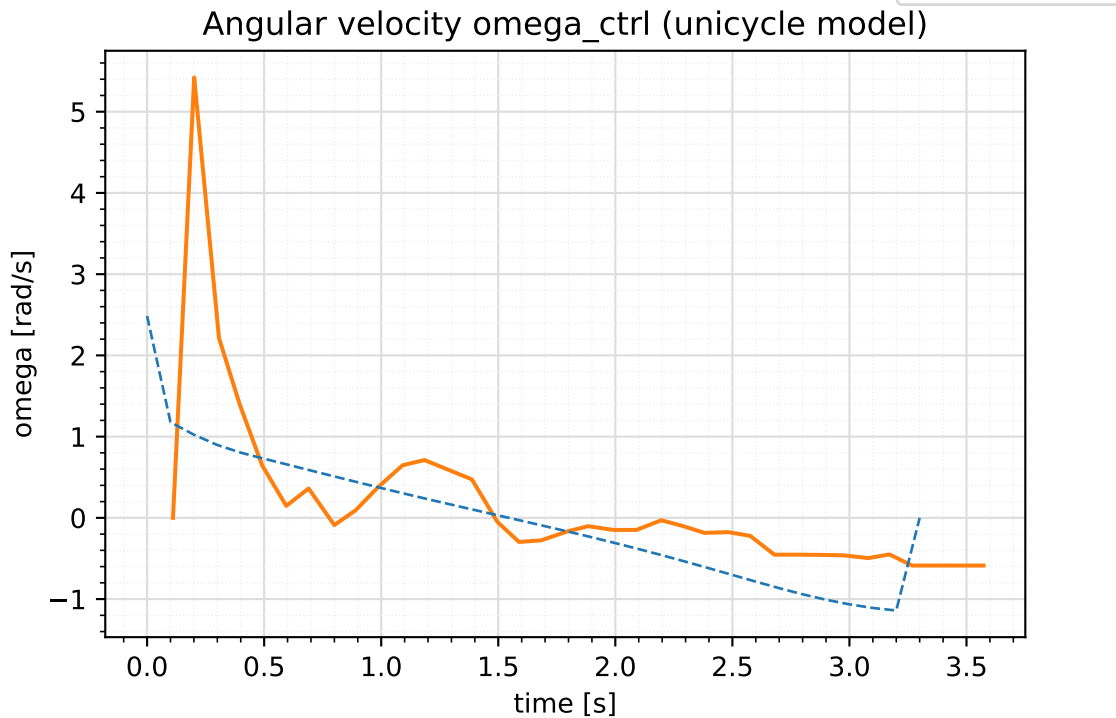




2D visualization







Left and right wheel angular velocities  $u_L$  &  $u_R$

Desired  
Recorded

