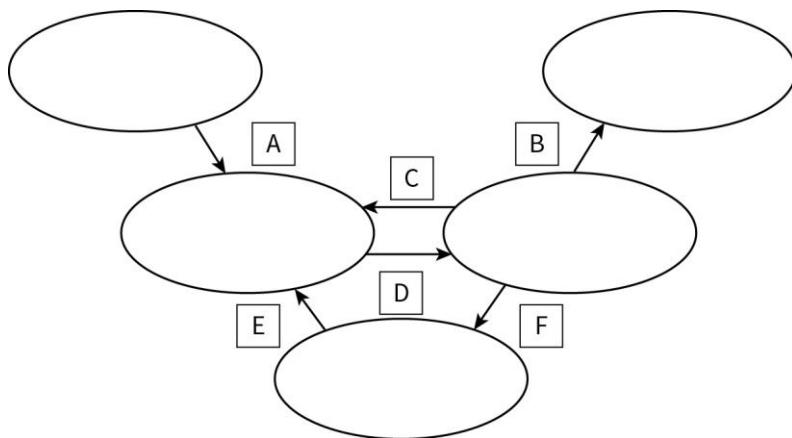


# Worksheet 20.1: for testing basic understanding

- 1 An operating system can be structured to contain a kernel.
  - a Identify two alternative possible approaches to this structuring.
  - b Describe three activities that only the kernel can undertake.
- 2 Two of the possible states for a process are the ready state and the waiting state.
  - a Describe the differences between these two states.
  - b Is it possible for a process to change from one of these states to the other?
  - c Explain the reason for your answer and describe any conditions or events that are relevant to it.
- 3 Explain two differences between partitioning memory and using paging.
- 4 The schematic diagram below represents the different states possible for a process (but they are not explicitly identified) and the possible transitions between them. The transitions have been labelled A to F.



Match the transition labels, **A–F**, with the following descriptions, **a–f**:

- a** A new process arrives in memory and a process control block is created; it changes to the ready state.
  - b** A process in the ready state is given access to the CPU by the dispatcher; it changes to the running state.
  - c** A process in the running state cannot progress until some event has occurred (I/O perhaps); it changes to the waiting state (sometimes called the ‘suspended’ or ‘blocked’ state).
  - d** A process in the running state completes execution; it changes to the terminated state.
  - e** A process in the running state is halted by an interrupt; it returns to the ready state.
  - f** A process in the waiting state is notified that an event is completed; it returns to the ready state.
- 5 Choose the correct word or phrase from the list, **A–K**, to complete the blank spaces in the following sentences.
- The simplest possible scheduling algorithm is \_\_\_\_\_. This is a \_\_\_\_\_ algorithm and can be implemented by placing the processes in the \_\_\_\_\_ in a \_\_\_\_\_.
- Alternatively, a \_\_\_\_\_ algorithm allocates a \_\_\_\_\_ to each process and is, therefore, \_\_\_\_\_ because a process will be halted when its \_\_\_\_\_ has run out. It can be implemented as a \_\_\_\_\_.

By comparison, a \_\_\_\_\_ scheduling algorithm is more complicated. Possible criteria are: estimated \_\_\_\_\_ ; length of time \_\_\_\_\_ ; whether the process is \_\_\_\_\_ .

- A already spent in the ready queue
- B first come first served (FCFS)
- C first-in first-out (FIFO) queue
- D I/O bound or CPU bound
- E non-preemptive
- F preemptive
- G priority-based
- H ready state
- I round-robin
- J time of process execution
- K time slice