

1. Description

1.1. Project

Project Name	UAV_CAN
Board Name	custom
Generated with:	STM32CubeMX 6.14.0
Date	03/17/2025

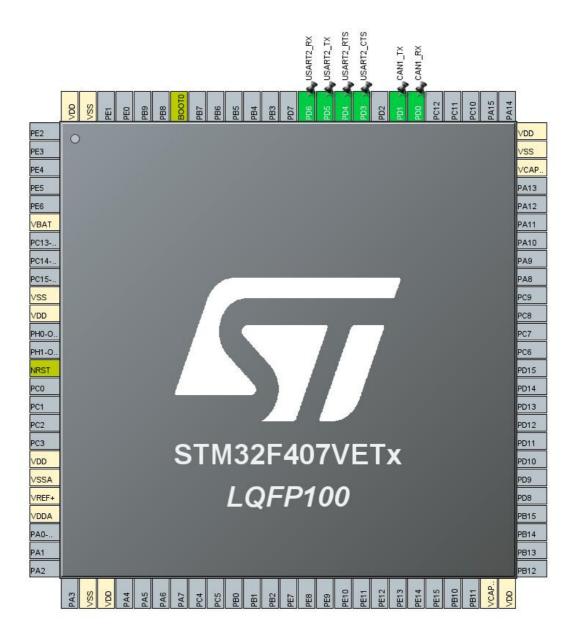
1.2. MCU

MCU Series	STM32F4
MCU Line	STM32F407/417
MCU name	STM32F407VETx
MCU Package	LQFP100
MCU Pin number	100

1.3. Core(s) information

Core(s)	Arm Cortex-M4

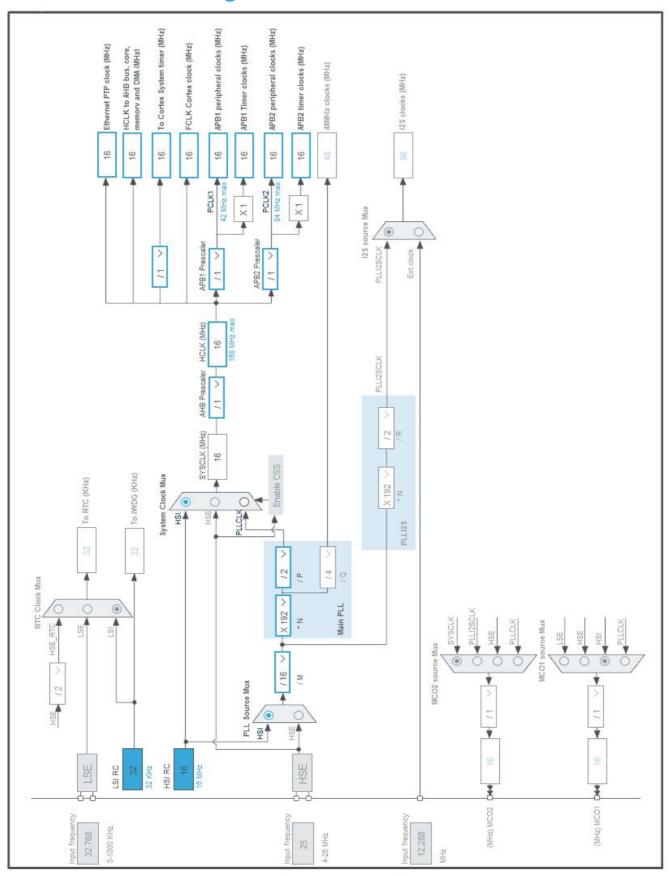
2. Pinout Configuration



3. Pins Configuration

Pin Number LQFP100	Pin Name (function after reset)	Pin Type	Alternate Function(s)	Label
6	VBAT	Power		
10	VSS	Power		
11	VDD	Power		
14	NRST	Reset		
19	VDD	Power		
20	VSSA	Power		
21	VREF+	Power		
22	VDDA	Power		
27	VSS	Power		
28	VDD	Power		
49	VCAP_1	Power		
50	VDD	Power		
73	VCAP_2	Power		
74	VSS	Power		
75	VDD	Power		
81	PD0	I/O	CAN1_RX	
82	PD1	I/O	CAN1_TX	
84	PD3	I/O	USART2_CTS	
85	PD4	I/O	USART2_RTS	
86	PD5	I/O	USART2_TX	
87	PD6	I/O	USART2_RX	
94	воото	Boot		
99	VSS	Power		
100	VDD	Power		

4. Clock Tree Configuration



Page 4

1. Power Consumption Calculator report

1.1. Microcontroller Selection

Series	STM32F4
Line	STM32F407/417
мси	STM32F407VETx
Datasheet	DS8626_Rev8

1.2. Parameter Selection

Temperature	25
Vdd	3.3

1.3. Battery Selection

Battery	Li-SOCL2(A3400)
Capacity	3400.0 mAh
Self Discharge	0.08 %/month
Nominal Voltage	3.6 V
Max Cont Current	100.0 mA
Max Pulse Current	200.0 mA
Cells in series	1
Cells in parallel	1

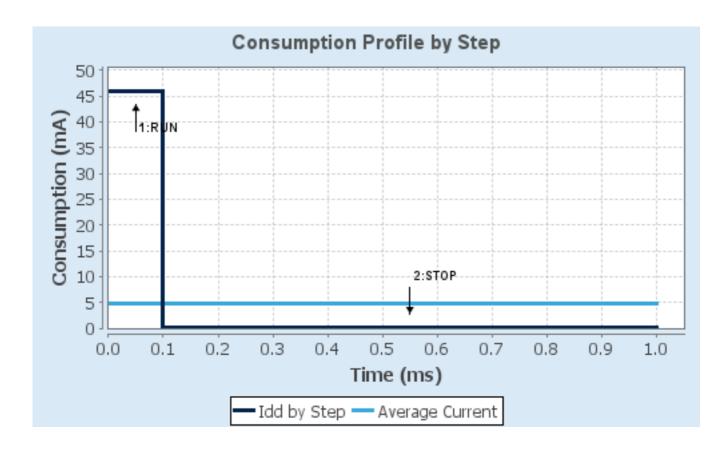
1.4. Sequence

	T	
Step	Step1	Step2
Mode	RUN	STOP
Vdd	3.3	3.3
Voltage Source	Battery	Battery
Range	Scale1-High	No Scale
Fetch Type	FLASH	n/a
CPU Frequency	168 MHz	0 Hz
Clock Configuration	HSE PLL	Regulator LP Flash-PwrDwn
Clock Source Frequency	4 MHz	0 Hz
Peripherals		
Additional Cons.	0 mA	0 mA
Average Current	46 mA	280 μΑ
Duration	0.1 ms	0.9 ms
DMIPS	210.0	0.0
Ta Max	98.47	104.96
Category	In DS Table	In DS Table

1.5. Results

Sequence Time	1 ms	Average Current	4.85 mA
Battery Life	29 days, 4 hours	Average DMIPS	210.0 DMIPS

1.6. Chart



2. Software Project

2.1. Project Settings

Name	Value
Project Name	UAV_CAN
Project Folder	C:\Users\Hyeonje\Documents\ \UAV_CAN\UAV_CAN
Toolchain / IDE	STM32CubeIDE
Firmware Package Name and Version	STM32Cube FW_F4 V1.28.1
Application Structure	Advanced
Generate Under Root	Yes
Do not generate the main()	No
Minimum Heap Size	0x200
Minimum Stack Size	0x400

2.2. Code Generation Settings

Name	Value
STM32Cube MCU packages and embedded software	Add necessary library files as reference in the toolchain project configuration file
Generate peripheral initialization as a pair of '.c/.h' files	No
Backup previously generated files when re-generating	No
Keep User Code when re-generating	Yes
Delete previously generated files when not re-generated	Yes
Set all free pins as analog (to optimize the power	No
consumption)	
Enable Full Assert	No

2.3. Advanced Settings - Generated Function Calls

Rank	Function Name	Peripheral Instance Name
1	SystemClock_Config	RCC
2	MX_GPIO_Init	GPIO
3	MX_CAN1_Init	CAN1
4	MX_USART2_UART_Init	USART2

3. Peripherals and Middlewares Configuration

3.1. CAN1

mode: Activated

3.1.1. Parameter Settings:

Bit Timings Parameters:

Prescaler (for Time Quantum) 16

Time Quantum

1000.0 *

Time Quanta in Bit Segment 1

1 Time

Time Quanta in Bit Segment 2

1 Time

Time for one Bit

3000 *

Baud Rate

333333 *

ReSynchronization Jump Width 1 Time

Basic Parameters:

Time Triggered Communication Mode

Automatic Bus-Off Management

Disable

Automatic Wake-Up Mode

Disable

Automatic Retransmission

Disable

Receive Fifo Locked Mode

Disable

Transmit Fifo Priority

Disable

Advanced Parameters:

Operating Mode Normal

3.2. RCC

3.2.1. Parameter Settings:

System Parameters:

VDD voltage (V) 3.3
Instruction Cache Enabled
Prefetch Buffer Enabled
Data Cache Enabled

Flash Latency(WS) 0 WS (1 CPU cycle)

RCC Parameters:

HSI Calibration Value 16
HSE Startup Timout Value (ms) 100
LSE Startup Timout Value (ms) 5000

Power Parameters:

Power Regulator Voltage Scale Power Regulator Voltage Scale 1

3.3. SYS

Timebase Source: SysTick

3.4. **USART2**

Mode: Asynchronous

Hardware Flow Control (RS232): CTS/RTS

3.4.1. Parameter Settings:

Basic Parameters:

Baud Rate 115200

Word Length 8 Bits (including Parity)

Parity None Stop Bits 1

Advanced Parameters:

Data Direction Receive and Transmit

Over Sampling 16 Samples

^{*} User modified value

4. System Configuration

4.1. GPIO configuration

IP	Pin	Signal	GPIO mode	GPIO pull/up pull down	Max Speed	User Label
CAN1	PD0	CAN1_RX	Alternate Function Push Pull	No pull-up and no pull-down	Very High	
	PD1	CAN1_TX	Alternate Function Push Pull	No pull-up and no pull-down	Very High	
USART2	PD3	USART2_CTS	Alternate Function Push Pull	No pull-up and no pull-down	Very High	
	PD4	USART2_RTS	Alternate Function Push Pull	No pull-up and no pull-down	Very High	
	PD5	USART2_TX	Alternate Function Push Pull	No pull-up and no pull-down	Very High	
	PD6	USART2_RX	Alternate Function Push Pull	No pull-up and no pull-down	Very High	

4.2. DMA configuration

nothing configured in DMA service

4.3. NVIC configuration

4.3.1. NVIC

Interrupt Table	Enable	Preenmption Priority	SubPriority	
Non maskable interrupt	true	0	0	
Hard fault interrupt	true	0	0	
Memory management fault	true	0	0	
Pre-fetch fault, memory access fault	true	0	0	
Undefined instruction or illegal state	true	0	0	
System service call via SWI instruction	true	0	0	
Debug monitor	true	0	0	
Pendable request for system service	true	0	0	
System tick timer	true	15	0	
PVD interrupt through EXTI line 16	unused			
Flash global interrupt	unused			
RCC global interrupt	unused			
CAN1 TX interrupts	unused			
CAN1 RX0 interrupts	unused			
CAN1 RX1 interrupt	unused			
CAN1 SCE interrupt	unused			
USART2 global interrupt	unused			
FPU global interrupt	unused			

4.3.2. NVIC Code generation

Enabled interrupt Table	Select for init	Generate IRQ handler	Call HAL handler
	sequence ordening	Hariulei	
Non maskable interrupt	false	true	false
Hard fault interrupt	false	true	false
Memory management fault	false	true	false
Pre-fetch fault, memory access fault	false	true	false
Undefined instruction or illegal state	false	true	false
System service call via SWI instruction	false	true	false
Debug monitor	false	true	false
Pendable request for system service	false	true	false
System tick timer	false	true	true

* User modified value

5. System Views

5.1. Category view

5.1.1. Current

6. Docs & Resources

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BSDL files https://www.st.com/resource/en/bsdl_model/stm32f405-415_407-

417_bsdl.zip

IBIS models https://www.st.com/resource/en/ibis_model/stm32f405-415_407-

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System View https://www.st.com/resource/en/svd/stm32f4-svd.zip

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