

# **UVC Camera Software Manual**

Date	Version	Description
2023-10-19	V1.0	First Released

Support: support@inno-maker.com Bulk Price: <u>sales@inno-maker.com</u>



# 1 Description

- UVC cameras comply with UVC protocol and work with web-camera applications out-of-box
- UVC Cameras support windows, linux, MacOs Compatible with UVC drivers

## 1.1 What is UVC Camera

- UVC Camera is camera with a USB interface that meets the standards set for the USB Video
  Class. This means that every UVC Camera is a USB camera, but not all USB cameras are UVC
  Cameras, because they might adopt the USB interface without meeting the Video class
  requirements.
- Therefore, a major advantage of the UVC cameras is their universal compatibility and flexibility. As they meet the video class standard, you can easily use them on different platforms with a USB port without handling the driver issue, like the Raspberry Pi or a smartphone. It also makes it easier for you to migrate your applications from one platform to another.
- At present, our UVC cameras support Windows, Linux, MAC, and Android systems, but do not support the iPhone system.

# 2 Works on Windows

#### **2.1 AMCAP**

AMCAP is a free and easily use UVC Camera test tools.

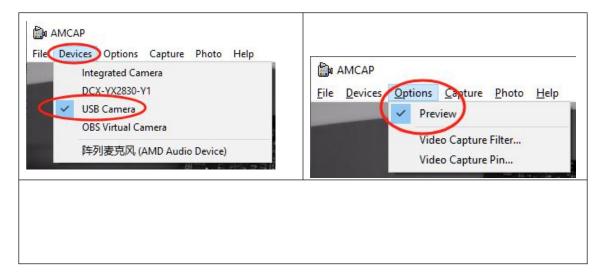
#### 2.1.1 Preview

Open AMCAP.EXE, Select USB Camera From "Devices", Select "Preview" from "Options"

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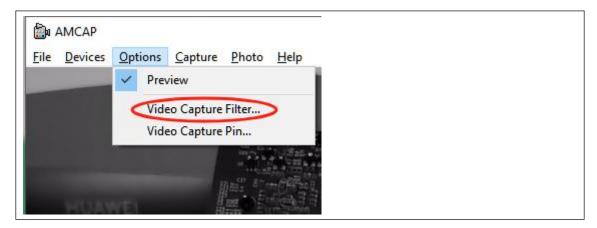
Github: https://github.com/INNO-MAKER





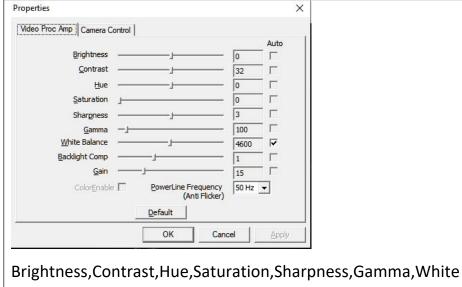
## 2.1.2 Video Capture Filter

You Can find most of Controllable Parameters from "Options", "Video Capture Filter".



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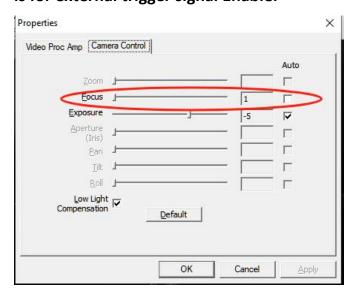


Balance, Backlight Comp, Gain, Exposure, PowerLine Frequency, Low Light

Compensation

## 2.1.3 External Trigger Parameters

From "Video Capture Filter" "Camera Control", The "Focus" Parameter is for external trigger signal Enable.



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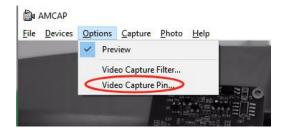


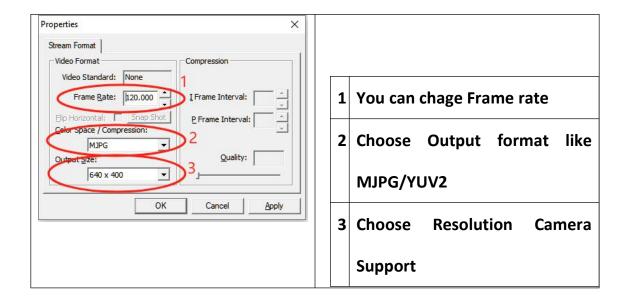
Wiki: wiki.inno-maker.com

Github: https://github.com/INNO-MAKER

## 2.1.3 Video Capture Pin

You Can find most of Controllable Parameters from "Options", "Video Capture Pin".





#### 2.1.4 Status Bar

You can find live frame Rate, Output Resolution



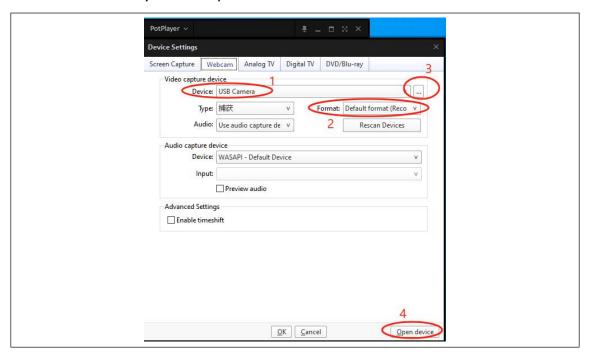


# 2.2 PotPlayer

Potplayer is another free Windows Tools which easily get video and images of UVC and U3V,UVC3.0 Cameras.

## 2.2.1 Open UVC Camera

Use Shortcut Key ALT+D open window as above

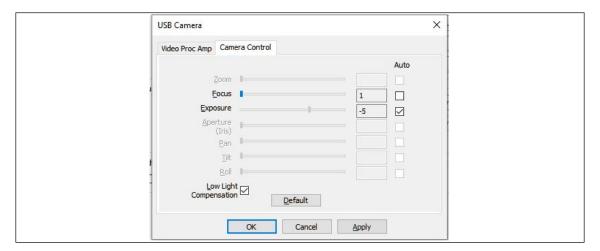


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1	Choose UVC Camera Deivce
2	Choose Output format ,resolution,frame rate
3	Camera Parameters Settings
4	Open Device

## 2.2.2 Live Working Status

Use shortkey TAB Open window as below

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```
PotPlayer > CAM | TV/CAM/device
William (FifCHA) device (Cam or Device)
Local June: 14.50:46Elapsed/Total Frames: 0
Preset: *Default preset, CPU: 4/8%, GPU: 12%, Clock: 400MHz, VRAM: 62/384.5MB PotPlayer/OS Version: 280005(1.7.21999), Windows 10 22 12 (10.0.19045)
Video Codec: Bufft-in FFmpeg Decoder(mjpeg, Thread Frame)
Input: MJPG(24 bits), 1280×800(1.6:1/1.6:1), FPS: 30, Bitrate: 28468 kbps
Transform: 1280×800p, Format: yuvj422p, Range: pc, ColorSpace: bt470bg, Location: center
 Output: NV12(12 bits), 1280×800(1.6:1/1.6:1), FPS: 30(30.54)
- Formats: NV12(Input->Mixer)-> RGB(Wideo->BackBuffer->Display)
- Resizer: Disabled, Presentation: DSD 9Ext Discard, Render Devices (NV)
 - Played/Dropped Frames: 233/0, Queue: 2, Jitter: ms, Sync Offset: 0/0ms, Refresh Rate: 59Hz
Frame Size: 1280 \times 800(1.6:1) - 1280 \times 800(1.6:1) = 0 \times 0(0 \times 0\%)
 Audio Codec: PCM
Input: ExtPCM(0xfffe), 44100 Hz, 2 Channels, 32-bit, 2822(2802) kbps
 Output: PCM(0x1), 44100 Hz, 2 Channels, 16-bit, 1411 kbps
 Rendering: PCM(0x1), 44100 Hz, 2 Channels, 16-bit, 1411 kbps
 Renderer: Null
```

## 2.3 OpenCV Python

## 2.3.1 Install Python3

Download from below link, check from cmd.exe after install successfully

https://www.python.org/downloads/release/

```
python --version
pip --version
```

```
C:\Users\zhouj>python --version
Python 3.11.6
```

```
C:\Users\zhouj>pip --version
pip 23.3 from C:\Users\zhouj\AppData\Loca1\Packages\P
packages\Python311\site-packages\pip (python 3.11)
```

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## 2.3.2 Install numpy

pip install numpy

## 2.3.3 Install Opency

pip install opency-python

If you have error for installing, update your pip by below command:

python -m pip install --upgrade pip

## 2.3.4 Run OpenCV Python

## Example1:

```
import cv2

cv2.namedWindow("preview")
vc = cv2.VideoCapture(0)

if vc.isOpened(): # try to get the first frame
    rval, frame = vc.read()
else:
    rval = False

while rval:
    cv2.imshow("preview", frame)
    rval, frame = vc.read()
    key = cv2.waitKey(20)
    if key == 27: # exit on ESC
        break

vc.release()
cv2.destroyWindow("preview")
```

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## Example2:

```
# import the opency library
import cv2
# define a video capture object
vid = cv2.VideoCapture(0)
while(True):
    # Capture the video frame
    # by frame
    ret, frame = vid.read()
    # Display the resulting frame
    cv2.imshow('frame', frame)
    # the 'q' button is set as the
    # quitting button you may use any
    # desired button of your choice
    if cv2.waitKey(1) & 0xFF == ord('q'):
          break
# After the loop release the cap object
vid.release()
# Destroy all the windows
cv2.destroyAllWindows()
```

## 2.3.5 Cited information

## You can refer to the below link for any updates:

https://stackoverflow.com/a/606154 https://www.geeksforgeeks.org/python-opencv-capture-video-from-camera/

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## 3 Works on Linux

## 3.1 Guvcview

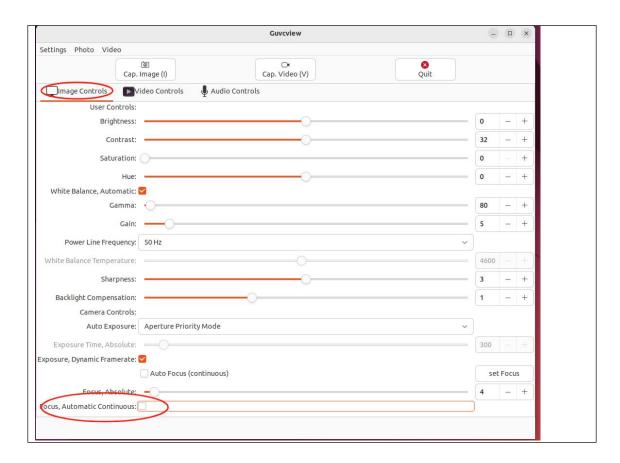
#### 3.1.1 Install

Guvcview is free and easy operation tools for linux, Install and run:

sudo apt install guvcview

sudo guvcview

## 3.1.2 Image Controls



You can find the control parameters from Image Controls.

## 3.1.3 External Trigger Control

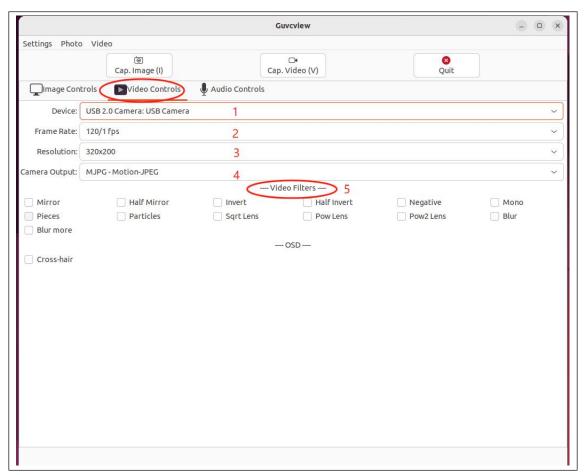
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Focus, Automatic Continuous is for external trigger. Uncheck it to enable external trigger mode.

## 3.1.4 Video Controls



#### From Video Controls,

1	Select Device
2	Select Frame Rate
3	Select Resolution
4	Select Output format
5	Video Filters

# 3.2 qv4l2

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#### 3.2.1 Install

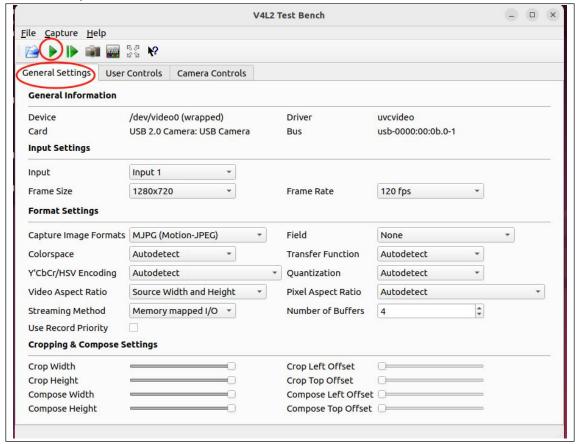
qv4l2 is free and easy operation tools for linux, Install and run:

sudo apt install qv4l2

sudo qv4l2

## 3.2.2 General Settings

Choose Output Devices, Resolution, Frame Rate



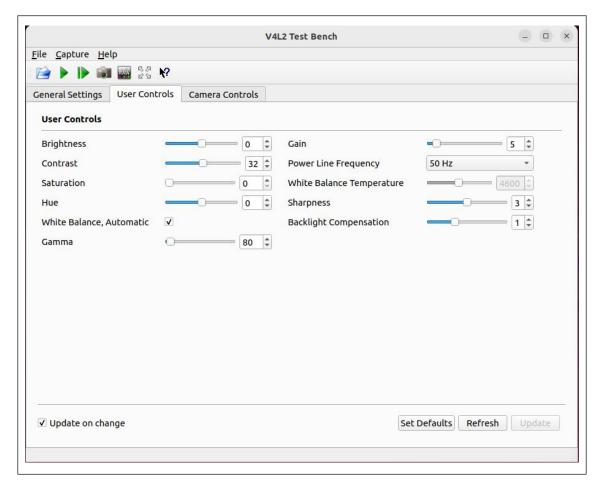
#### 3.2.3 User Controls

control parameters



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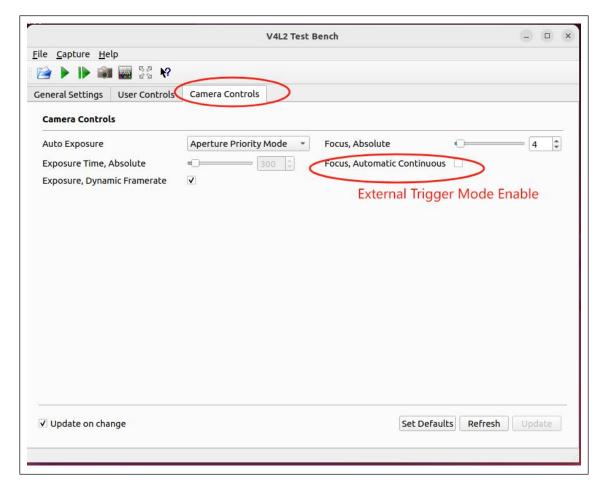
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## 3.2.4 Camera Controls

You can uncheck the External Trigger from this options.





# 3.3 V4L utility Tools

## 3.3.1 Install V4L utility packages

sudo apt-get update sudo apt-get install v4l-utils

#### 3.3.2 List UVC devices

```
v4l2-ctl--list-devices

joez@joez-VirtualBox:-$ v4l2-ctl --list-devices

USB Camera: USB Camera (usb-0000:00:0c.0-2):

/dev/video0

/dev/video1

/dev/media0
```

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## 3.3.3 List the supported formats

v4l2-ctl --list-formats -d

#### 3.3.4 List resolutions and frame

v4l2-ctl --list-formats-ext -d 0

```
joez@joez-VirtualBox:-$ v4l2-ctl --list-formats-ext -d 0
ioctl: VIDIOC ENUM FMT
        Type: Video Capture
        [0]: 'MJPG' (Motion-JPEG, compressed)
                Size: Discrete 640x480
                        Interval: Discrete 0.033s (30.000 fps)
                        Interval: Discrete 0.033s (30.000 fps)
                Size: Discrete 800x600
                        Interval: Discrete 0.033s (30.000 fps)
                Size: Discrete 1024x768
                        Interval: Discrete 0.033s (30.000 fps)
                Size: Discrete 1280x720
                        Interval: Discrete 0.033s (30.000 fps)
                Size: Discrete 1920x1080
                        Interval: Discrete 0.033s (30.000 fps)
        [1]: 'YUYV' (YUYV 4:2:2)
                Size: Discrete 1920x1080
                        Interval: Discrete 0.200s (5.000 fps)
                Size: Discrete 640x480
                        Interval: Discrete 0.033s (30.000 fps)
                Size: Discrete 800x600
                        Interval: Discrete 0.050s (20.000 fps)
                        Interval: Discrete 0.067s (15.000 fps)
                        Interval: Discrete 0.100s (10.000 fps)
                        Interval: Discrete 0.200s (5.000 fps)
                Size: Discrete 1024x768
                        Interval: Discrete 0.200s (5.000 fps)
                Size: Discrete 1280x720
                        Interval: Discrete 0.100s (10.000 fps)
                        Interval: Discrete 0.200s (5.000 fps)
                Size: Discrete 1280x1024
                        Interval: Discrete 0.200s (5.000 fps)
```

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#### 3.3.5 List Control parameters



v4l2-ctl -d /dev/video0 -list

```
joez@joez-VirtualBox:~$ v4l2-ctl -d /dev/video0 -list
Video input set to 0 (Input 1: Camera, ok)
User Controls
                     brightness 0x00980900 (int)
                                                    : min=-64 ma
                       contrast 0x00980901 (int)
                                                    : min=0 max=
                     saturation 0x00980902 (int)
                                                    : min=0 max=
                            hue 0x00980903 (int)
                                                    : min=-180 m
        white balance automatic 0x0098090c (bool)
                                                    : default=1
                          gamma 0x00980910 (int)
                                                    : min=100 ma
                           gain 0x00980913 (int)
                                                    : min=1 max=
           power_line_frequency 0x00980918 (menu)
                                                    : min=0 max=
      white balance_temperature 0x0098091a (int)
                                                    : min=2800 m
                      sharpness 0x0098091b (int)
                                                    : min=0 max=
         backlight compensation 0x0098091c (int)
                                                    : min=0 max=
Camera Controls
                  auto_exposure 0x009a0901 (menu)
                                                    : min=0 max=
         exposure_time_absolute 0x009a0902 (int)
                                                    : min=50 max
     exposure_dynamic_framerate 0x009a0903 (bool)
                                                    : default=0
```

#### 3.3.6 Set User/Camera controls

For example, set camera brightness to 64

v4l2-ctl -d /dev/video0 --set-ctrl=brightness=64

joez@joez-VirtualBox:~\$ v4l2-ctl -d /dev/video0 --set-ctrl=brightness=64

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## 3.4 OpenCV Python

#### 3.4.1 Install Opency-Python

Check python pip version



python3 --version

pip --version

Run below command if not find the pip.

joez@joez-VirtualBox:~\$ pip --version
Command 'pip' not found, but can be installed with:
sudo apt install python3-pip

sudo apt install python3-pip

#### Install opency-python

sudo pip install OpenCV-python

## \* If you en count download errors

sudo pip install opency-python -i https://pypi.tuna.tsinghua.edu.cn/simple

## 3.4.2 Set user controls parameters.

Below code sample set brightness as 64, contrast as 0

# open video0
cap = cv2.VideoCapture(0)

# The control range can be viewed through v4l2-ctl -L
cap.set(cv2.CAP\_PROP\_BRIGHTNESS, 64)
cap.set(cv2.CAP\_PROP\_CONTRAST, 0)

while(True):

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```
# Capture frame-by-frame

ret, frame = cap.read()

# Display the resulting frame

cv2.imshow('frame', frame)

if cv2.waitKey(1) & 0xFF == ord('q'):

break

# When everything done, release the capture

cap.release()

cv2.destroyAllWindows()
```

SAVE File name as 1.py, then run

sudo python3 1.py

## 3.4.3 Controlling values through code

import cv2
import time
# open video0
cap = cv2.VideoCapture(0)
cap.grab()

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```
cap.set(cv2.CAP_PROP_AUTOFOCUS, 1)
time.sleep(2)
cap.set(cv2.CAP_PROP_AUTOFOCUS, 0)
time.sleep(2)
cap.set(cv2.CAP_PROP_FOCUS, 123)
cap.set(cv2.CAP_PROP_FRAME_WIDTH, 640)
cap.set(cv2.CAP_PROP_FRAME_HEIGHT, 480)
while(True):
    # Capture frame-by-frame
    ret, frame = cap.read()
    # Display the resulting frame
    cv2.imshow('frame', frame)
    if cv2.waitKey(1) & 0xFF == ord('q'):
         break
# When everything done, release the capture
cap.release()
```

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## cv2.destroyAllWindows()

SAVE File name as 2.py, then run

sudo python3 2.py

## 3.4.4 Controlling values through UI interface

```
import cv2
import argparse
import configparser
from pathlib import Path
import time
parser = argparse.ArgumentParser()
parser.add_argument("-v", "--vid", default="0", help="Video sourse,
default 0")
parser.add_argument(
    "-f", "--auto_focus", action="store_true", default=False, help="Turn
on auto focus"
)
parser.add_argument(
```

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```
"-c",
     "--config",
    default="focus.ini",
     help="Focus config file, default focus.ini",
)
args = parser.parse_args()
try:
    vid = int(args.vid)
except ValueError:
    vid = args.vid
                                       (Path(__file__).parent
config_path
Path(args.config)).resolve().absolute()
print("config file :", config_path)
config = configparser.ConfigParser()
config.read(config_path, encoding="utf-8")
cap = cv2.VideoCapture(vid)
```

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```
cap.grab()
cap.set(cv2.CAP_PROP_AUTOFOCUS, 1)
if not args.auto_focus and config.has_section("Focus"):
    auto_focus = (
         config.getint("Focus", "auto_focus")
         if config.has_option("Focus", "auto_focus")
         else 1
    )
    focus = (
         config.getint("Focus", "focus")
         if config.has_option("Focus", "focus")
         else int(cap.get(cv2.CAP_PROP_FOCUS))
    )
else:
    auto_focus = 1
    focus = None
print("config auto_focus = %s" % auto_focus)
print("config focus = %s" % focus)
print("*" * 10)
```



```
if not auto_focus:
    cap.set(cv2.CAP_PROP_AUTOFOCUS, 0)
time.sleep(2)
if focus:
    cap.set(cv2.CAP_PROP_FOCUS, focus)
cv2.namedWindow("frame")
def set_auto_focus(x):
    cap.set(cv2.CAP_PROP_AUTOFOCUS, x)
cv2.createTrackbar(
    "0: OFF\r\n 1: ON\r\nauto_focus",
    "frame",
    int(cap.get(cv2.CAP_PROP_AUTOFOCUS)),
    1,
    set_auto_focus,
```

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```
)
def set_focus(x):
    cap.set(cv2.CAP_PROP_FOCUS, x)
cv2.createTrackbar("focus", "frame", int(cap.get(cv2.CAP_PROP_FOCUS)),
1023, set_focus)
while cap.isOpened():
    # cap frame-by-frame
    ret, frame = cap.read()
    if not ret:
         break
    focus = int(cap.get(cv2.CAP_PROP_FOCUS))
    cv2.setTrackbarPos("focus", "frame", focus)
    af = int(cap.get(cv2.CAP_PROP_AUTOFOCUS))
    cv2.setTrackbarPos("0: OFF\r\n 1: ON\r\nauto_focus", "frame", af)
```



```
cv2.imshow("frame", frame)
    if cv2.waitKey(1) & 0xFF == ord("q"):
         break
# When everything done, release the cap
cap.release()
cv2.destroyAllWindows()
if not config.has_section("Focus"):
    config.add_section("Focus")
print("set auto_focus = 0")
config.set("Focus", "auto_focus", "0")
print("set focus = %s" % focus)
config.set("Focus", "focus", str(focus))
config.write(open(config_path, "w"))
```

SAVE File name as cvtui.py, then run

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sudo python3 cvtui.py

## 3.5 Gstreamer

GStreamer becomes a popular and powerful open-source multimedia framework to help users to build their own video streaming, playback, editing applications with various codec and functionalities on top of its high-level APIs.

#### 3.5.1 Set Video Output Format

#### **MJPEG**

```
gst-launch-1.0 v4l2src device=/dev/video0 ! \
image/jpeg,width=1920,height=1080,framerate=30/1 ! \
decodebin ! autovideosink
```

#### YUV

```
gst-launch-1.0 -vv v4l2src device=/dev/video0 ! \ video/x-raw, format=YUY2, width=1280, height=720, framerate=10/1 ! \ \ videoconvert ! autovideosink
```

## 3.6 Read Serial Number

When you need to use multiple cameras, we need to use unique serial ID.

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## 3.6.1 Linux udev

sudo udevadm info --query=all /dev/video0 | grep 'VENDOR\_ID\|MODEL\_ID\|SERIAL\_SHORT'

```
joez@joez-VirtualBox:~/Desktop$ sudo udevadm info --query=all /dev/video0 | grep
'VENDOR_ID\|MODEL_ID\|SERIAL_SHORT'
E: ID_VENDOR_ID=0bda
E: ID_MODEL_ID=3035
E: ID_SERIAL_SHORT=200901010001
```

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