

# S3C24XX GPIO Control

## Introduction

The s3c2410 kernel provides an interface to configure and manipulate the state of the GPIO pins, and find out other information about them.

There are a number of conditions attached to the configuration of the s3c2410 GPIO system, please read the Samsung provided data-sheet/users manual to find out the complete list.

See Documentation/arm/samsung/gpio.rst for the core implementation.

## GPIOLIB

With the event of the GPIOLIB in drivers/gpio, support for some of the GPIO functions such as reading and writing a pin will be removed in favour of this common access method.

Once all the extant drivers have been converted, the functions listed below will be removed (they may be marked as `__deprecated` in the near future).

The following functions now either have a `s3c_` specific variant or are merged into `gpiolib`. See the definitions in `arch/arm/mach-s3c/gpio-cfg.h`:

- `s3c2410_gpio_setpin()` `gpio_set_value()` or `gpio_direction_output()`
- `s3c2410_gpio_getpin()` `gpio_get_value()` or `gpio_direction_input()`
- `s3c2410_gpio_getirq()` `gpio_to_irq()`
- `s3c2410_gpio_cfgpin()` `s3c_gpio_cfgpin()`
- `s3c2410_gpio_getcfg()` `s3c_gpio_getcfg()`
- `s3c2410_gpio_pullup()` `s3c_gpio_setpull()`

## GPIOLIB conversion

If you need to convert your board or driver to use `gpiolib` from the phased out s3c2410 API, then here are some notes on the process.

1. If your board is exclusively using an GPIO, say to control peripheral power, then it will require to claim the `gpio` with `gpio_request()` before it can use it.  
It is recommended to check the return value, with at least `WARN_ON()` during initialisation.
2. The `s3c2410_gpio_cfgpin()` can be directly replaced with `s3c_gpio_cfgpin()` as they have the same arguments, and can either take the pin specific values, or the more generic special-function-number arguments.
3. `s3c2410_gpio_pullup()` changes have the problem that while the `s3c2410_gpio_pullup(x, 1)` can be easily translated to the `s3c_gpio_setpull(x, S3C_GPIO_PULL_NONE)`, the `s3c2410_gpio_pullup(x, 0)` are not so easy.  
The `s3c2410_gpio_pullup(x, 0)` case enables the pull-up (or in the case of some of the devices, a pull-down) and as such the new API distinguishes between the UP and DOWN case. There is currently no 'just turn on' setting which may be required if this becomes a problem.
4. `s3c2410_gpio_setpin()` can be replaced by `gpio_set_value()`, the old call does not implicitly configure the relevant `gpio` to output. The `gpio` direction should be changed before using `gpio_set_value()`.
5. `s3c2410_gpio_getpin()` is replaceable by `gpio_get_value()` if the pin has been set to input. It is currently unknown what the behaviour is when using `gpio_get_value()` on an output pin (`s3c2410_gpio_getpin` would return the value the pin is supposed to be outputting).
6. `s3c2410_gpio_getirq()` should be directly replaceable with the `gpio_to_irq()` call.

The `s3c2410_gpio` and `gpio_` calls have always operated on the same `gpio` numberspace, so there is no problem with converting the `gpio` numbering between the calls.

## Headers

See `arch/arm/mach-s3c/regs-gpio-s3c24xx.h` for the list of GPIO pins, and the configuration values for them. This is included by using `#include <mach/regs-gpio.h>`

## PIN Numbers

Each pin has an unique number associated with it in `regs-gpio.h`, e.g. `S3C2410_GPA(0)` or `S3C2410_GPF(1)`. These

defines are used to tell the GPIO functions which pin is to be used.

With the conversion to gpiolib, there is no longer a direct conversion from gpio pin number to register base address as in earlier kernels. This is due to the number space required for newer SoCs where the later GPIOs are not contiguous.

## Configuring a pin

The following function allows the configuration of a given pin to be changed.

```
void s3c_gpio_cfgpin(unsigned int pin, unsigned int function);
```

e.g.:

```
s3c_gpio_cfgpin(S3C2410_GPA(0), S3C_GPIO_SFN(1)); s3c_gpio_cfgpin(S3C2410_GPE(8),  
S3C_GPIO_SFN(2));
```

which would turn GPA(0) into the lowest Address line A0, and set GPE(8) to be connected to the SDIO/MMC controller's SDDAT1 line.

## Reading the current configuration

The current configuration of a pin can be read by using standard gpiolib function:

```
s3c_gpio_getcfg(unsigned int pin);
```

The return value will be from the same set of values which can be passed to s3c\_gpio\_cfgpin().

## Configuring a pull-up resistor

A large proportion of the GPIO pins on the S3C2410 can have weak pull-up resistors enabled. This can be configured by the following function:

```
void s3c_gpio_setpull(unsigned int pin, unsigned int to);
```

Where the to value is S3C\_GPIO\_PULL\_NONE to set the pull-up off, and S3C\_GPIO\_PULL\_UP to enable the specified pull-up. Any other values are currently undefined.

## Getting and setting the state of a PIN

These calls are now implemented by the relevant gpiolib calls, convert your board or driver to use gpiolib.

## Getting the IRQ number associated with a PIN

A standard gpiolib function can map the given pin number to an IRQ number to pass to the IRQ system.

```
int gpio_to_irq(unsigned int pin);
```

Note, not all pins have an IRQ.

## Author

Ben Dooks, 03 October 2004 Copyright 2004 Ben Dooks, Simtec Electronics