# ioctl VIDIOC\_G\_PARM, VIDIOC\_S\_PARM

```
System Message: ERROR/3 (D:\onboarding-resources\sample-onboarding-resources\linux-
master\Documentation\userspace-api\media\v41\[linux-master][Documentation][userspace-
api][media][v41]vidioc-g-parm.rst, line 2)
Unknown directive type "c:namespace".
.. c:namespace:: V4L
```

#### Name

VIDIOC G PARM - VIDIOC S PARM - Get or set streaming parameters

#### **Synopsis**

```
System Message: ERROR/3 (D:\onboarding-resources\sample-onboarding-resources\linux-master\Documentation\userspace-api\media\v41\[linux-master][Documentation][userspace-api][media][v41]vidioc-g-parm.rst, line 18)

Unknown directive type "cmacro".

.. c:macro:: VIDIOC_G_PARM
```

int ioctl(int fd, VIDIOC G PARM, v412 streamparm \*argp)

```
System Message: ERROR/3 (D:\onboarding-resources\sample-onboarding-resources\linux-master\Documentation\userspace-api\media\v41\[linux-master][Documentation][userspace-api][media][v41]vidioc-g-parm.rst, line 22)

Unknown directive type "c:macro".

.. c:macro:: VIDIOC_S_PARM
```

int ioctl(int fd, VIDIOC S PARM, v412 streamparm \*argp)

### Arguments

fd

File descriptor returned by :c:func:`open()`.

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[Documentation] [userspace-api] [media] [v41]vidioc-g-parm.rst, line 30); backlink
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arqp

Pointer to struct :c:type:\v412\_streamparm\.

System Message: ERROR/3 (D:\onboarding-resources\sample-onboarding-resources\linux-master\Documentation\userspace-api\media\v41\[linux-master] [Documentation] [userspace-api] [media] [v41] vidioc-g-parm.rst, line 33); backlink Unknown interpreted text role "c:type".

## **Description**

Applications can request a different frame interval. The capture or output device will be reconfigured to support the requested frame interval if possible. Optionally drivers may choose to skip or repeat frames to achieve the requested frame interval.

For stateful encoders (see refiencoder) this represents the frame interval that is typically embedded in the encoded video stream

```
System\ Message: ERROR/3\ (\mbox{D:\noboarding-resources}\scample-onboarding-resources\linux-master)\ [Documentation]\ [userspace-api]\ [media]\ [v41]\ vidioc-g-parm.rst, line\ 43); \ backlink
```

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Changing the frame interval shall never change the format. Changing the format, on the other hand, may change the frame interval. Further these ioctls can be used to determine the number of buffers used internally by a driver in read/write mode. For implications see the section discussing the :c:func:'read()' function.

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To get and set the streaming parameters applications call the ref. VIDIOC\_G\_PARM < VIDIOC\_G\_PARM > ` and ref. VIDIOC\_S\_PARM < VIDIOC\_G\_PARM > ` ioctl, respectively. They take a pointer to a struct :c.type: `v4l2\_streamparm` which contains a union holding separate parameters for input and output devices.

```
System Message: ERROR/3 (D:\onboarding-resources\sample-onboarding-resources\linux-master\Documentation\userspace-api\media\v41\[linux-master] [Documentation] [userspace-api] [media] [v41] vidioc-g-parm.rst, line 53); backlink
```

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Unknown interpreted text role "c:type".

System Message: ERROR/3 (D:\onboarding-resources\sample-onboarding-resources\linux-master\Documentation\userspace-api\media\v41\[linux-master] [Documentation] [userspace-api] [media] [v41]vidioc-g-parm.rst, line 59)

Unknown directive type "tabularcolumns".

```
.. tabularcolumns:: |p{3.7cm}|p{3.5cm}|p{10.1cm}|
```

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Unknown directive type "c:type".

```
.. c:type:: v4l2_streamparm
```

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Unknown directive type "flat-table".

```
.. flat-table:: struct v412_streamparm
    :header-rows: 0
    :stub-columns: 0
    :widths: 1 1 2

* - u32
```

 $System\ Message: ERROR/3\ (\mbox{D:\noboarding-resources}\scample-onboarding-resources\linux-master)\ [Documentation]\ [userspace-api]\ [media]\ [v41]\ vidioc-g-parm.rst,\ line\ 90)$ 

Unknown directive type "tabularcolumns".

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.. tabularcolumns:: |p{4.4cm}|p{4.4cm}|p{8.5cm}|
```

System Message: ERROR/3 (D:\onboarding-resources\sample-onboarding-resources\linux-master\Documentation\userspace-api\media\v41\[linux-master] [Documentation] [userspace-api] [media] [v41]vidioc-g-parm.rst, line 92)

Unknown directive type "c:type".

```
.. c:type:: v4l2_captureparm
```

System Message: ERROR/3 (D:\onboarding-resources\sample-onboarding-resources\linux-master\Documentation\userspace-api\media\v41\[linux-master] [Documentation] [userspace-api] [media] [v41] vidioc-g-parm.rst, line 94)

Unknown directive type "flat-table".

zero.

```
.. flat-table:: struct v412 captureparm
   :header-rows: 0
   :stub-columns: 0
   :widths:
     - _u32
- ``capability``
     - See :ref:`parm-caps`.
   * - _u32
- ``capturemode``
     - Set by drivers and applications, see :ref:`parm-flags`.
    * - struct :c:type:`v412_fract`
     - ``timeperframe`
      - This is the desired period between successive frames captured by
       the driver, in seconds.
    * - :cspan:`2`
       This will configure the speed at which the video source (e.g. a sensor)
        generates video frames. If the speed is fixed, then the driver may
        choose to skip or repeat frames in order to achieve the requested
        frame rate.
        For stateful encoders (see :ref:`encoder`) this represents the
        frame interval that is typically embedded in the encoded video stream.
       Applications store here the desired frame period, drivers return
        the actual frame period.
        Changing the video standard (also implicitly by switching
        the video input) may reset this parameter to the nominal frame
```

period. To reset manually applications can just set this field to

```
Drivers support this function only when they set the
     `V4L2 CAP TIMEPERFRAME`` flag in the ``capability`` field.
     u32
 - ``extendedmode``
 - Custom (driver specific) streaming parameters. When unused,
   applications and drivers must set this field to zero. Applications
    using this field should check the driver name and version, see
   :ref:`querycap`.
 - _u32
- ``readbuffers``
  - Applications set this field to the desired number of buffers used
    internally by the driver in :c:func:`read()` mode.
   Drivers return the actual number of buffers. When an application
    requests zero buffers, drivers should just return the current
   setting rather than the minimum or an error code. For details see
   :ref:`rw`.
* - __u32
- ``reserved``\ [4]
 - Reserved for future extensions. Drivers and applications must set
   the array to zero.
```

System Message: ERROR/3 (D:\onboarding-resources\sample-onboarding-resources\linux-master\Documentation\userspace-api\media\v41\[linux-master] [Documentation] [userspace-api] [media] [v41]vidioc-g-parm.rst, line 149)

Unknown directive type "tabularcolumns".

```
.. tabularcolumns:: |p{4.4cm}|p{4.4cm}|p{8.5cm}|
```

System Message: ERROR/3 (D:\onboarding-resources\sample-onboarding-resources\linux-master\Documentation\userspace-api\media\v41\[linux-master] [Documentation] [userspace-api] [media] [v41]vidioc-g-parm.rst, line 151)

Unknown directive type "c:type".

```
.. c:type:: v4l2_outputparm
```

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Unknown directive type "flat-table".

```
.. flat-table:: struct v412 outputparm
   :header-rows: 0
    :stub-columns: 0
   :widths:
                   1 1 2
     - _u32
- ``capability``
     - See :ref:`parm-caps`.
    * - u32
- ``outputmode``
     - Set by drivers and applications, see :ref: `parm-flags`.
    * - struct :c:type:`v412_fract`
       ``timeperframe
     - This is the desired period between successive frames output by the
       driver, in seconds.
    * - :cspan: `2`
       The field is intended to repeat frames on the driver side in
        :c:func:`write()` mode (in streaming mode timestamps
        can be used to throttle the output), saving I/O bandwidth.
        For stateful encoders (see :ref:`encoder`) this represents the
        frame interval that is typically embedded in the encoded video stream
```

Applications store here the desired frame period, drivers return the actual frame period.  $\,$ 

and it provides a hint to the encoder of the speed at which raw

Changing the video standard (also implicitly by switching

frames are queued up to the encoder.

the video output) may reset this parameter to the nominal frame period. To reset manually applications can just set this field to zero. Drivers support this function only when they set the ``V4L2 CAP TIMEPERFRAME`` flag in the ``capability`` field. - <u>u</u>32 - ``extendedmode`` - Custom (driver specific) streaming parameters. When unused, applications and drivers must set this field to zero. Applications using this field should check the driver name and version, see :ref:`querycap`. - \_\_u32 - ``writebuffers`` - Applications set this field to the desired number of buffers used internally by the driver in :c:func:`write()` mode. Drivers return the actual number of buffers. When an application requests zero buffers, drivers should just return the current setting rather than the minimum or an error code. For details see :ref:`rw`. - \_u32 - ``reserved``\ [4] - Reserved for future extensions. Drivers and applications must set the array to zero.

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Unknown directive type "tabularcolumns".

.. tabularcolumns::  $|p{6.6cm}|p{2.2cm}|p{8.5cm}|$ 

System Message: ERROR/3 (D:\onboarding-resources\sample-onboarding-resources\linux-master\Documentation\userspace-api\media\v41\[linux-master] [Documentation] [userspace-api] [media] [v41]vidioc-g-parm.rst, line 213)

Unknown directive type "flat-table".

System Message: ERROR/3 (D:\onboarding-resources\sample-onboarding-resources\linux-master\Documentation\userspace-api\media\v41\[linux-master] [Documentation] [userspace-api] [media] [v41]vidioc-g-parm.rst, line 224)

Unknown directive type "tabularcolumns".

```
.. tabularcolumns:: |p{6.6cm}|p{2.2cm}|p{8.5cm}|
```

System Message: ERROR/3 (D:\onboarding-resources\sample-onboarding-resources\linux-master\Documentation\userspace-api\media\v41\[linux-master][Documentation][userspace-api][media][v41]vidioc-g-parm.rst, line 228)

Unknown directive type "flat-table".

- High quality imaging mode. High quality mode is intended for still imaging applications. The idea is to get the best possible image quality that the hardware can deliver. It is not defined how the driver writer may achieve that; it will depend on the hardware and the ingenuity of the driver writer. High quality mode is a different mode from the regular motion video capture modes. In high quality mode:
  - The driver may be able to capture higher resolutions than for motion capture.
  - The driver may support fewer pixel formats than motion capture (eg; true color).
  - The driver may capture and arithmetically combine multiple successive fields or frames to remove color edge artifacts and reduce the noise in the video data.
  - The driver may capture images in slices like a scanner in order to handle larger format images than would otherwise be possible.
  - An image capture operation may be significantly slower than motion capture.
  - Moving objects in the image might have excessive motion blur.
  - Capture might only work through the :c:func:`read()` call.

#### Return Value

On success 0 is returned, on error -1 and the errno variable is set appropriately. The generic error codes are described at the ref. Generic Error Codes <gen-errors>` chapter.

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