

# Kernel driver lm87

Supported chips:

- National Semiconductor LM87  
Prefix: 'lm87'  
Addresses scanned: I2C 0x2c - 0x2e  
Datasheet: <http://www.national.com/pf/LM/LM87.html>
- Analog Devices ADM1024  
Prefix: 'adm1024'  
Addresses scanned: I2C 0x2c - 0x2e  
Datasheet: <https://www.analog.com/en/prod/0,2877,ADM1024,00.html>

Authors:

- Frodo Looijaard <[frodol@dds.nl](mailto:frodol@dds.nl)> ,
- Philip Edelbrock <[phil@netroedge.com](mailto:phil@netroedge.com)> ,
- Mark Studebaker <[mdsxyz123@yahoo.com](mailto:mdsxyz123@yahoo.com)> ,
- Stephen Rousset <[stephen.rousset@rocketlogix.com](mailto:stephen.rousset@rocketlogix.com)> ,
- Dan Eaton <[dan.eaton@rocketlogix.com](mailto:dan.eaton@rocketlogix.com)> ,
- Jean Delvare <[jdelvare@suse.de](mailto:jdelvare@suse.de)> ,
- Original 2.6 port Jeff Oliver

## Description

This driver implements support for the National Semiconductor LM87 and the Analog Devices ADM1024.

The LM87 implements up to three temperature sensors, up to two fan rotation speed sensors, up to seven voltage sensors, alarms, and some miscellaneous stuff. The ADM1024 is fully compatible.

Temperatures are measured in degrees Celsius. Each input has a high and low alarm settings. A high limit produces an alarm when the value goes above it, and an alarm is also produced when the value goes below the low limit.

Fan rotation speeds are reported in RPM (rotations per minute). An alarm is triggered if the rotation speed has dropped below a programmable limit. Fan readings can be divided by a programmable divider (1, 2, 4 or 8) to give the readings more range or accuracy. Not all RPM values can accurately be represented, so some rounding is done. With a divider of 2, the lowest representable value is around 2600 RPM.

Voltage sensors (also known as IN sensors) report their values in volts. An alarm is triggered if the voltage has crossed a programmable minimum or maximum limit. Note that minimum in this case always means 'closest to zero'; this is important for negative voltage measurements.

If an alarm triggers, it will remain triggered until the hardware register is read at least once. This means that the cause for the alarm may already have disappeared! Note that in the current implementation, all hardware registers are read whenever any data is read (unless it is less than 1.0 seconds since the last update). This means that you can easily miss once-only alarms.

The lm87 driver only updates its values each 1.0 seconds; reading it more often will do no harm, but will return 'old' values.

## Hardware Configurations

The LM87 has four pins which can serve one of two possible functions, depending on the hardware configuration.

Some functions share pins, so not all functions are available at the same time. Which are depends on the hardware setup. This driver normally assumes that firmware configured the chip correctly. Where this is not the case, platform code must set the I2C client's platform\_data to point to a u8 value to be written to the channel register.

For reference, here is the list of exclusive functions:

- in0+in5 (default) or temp3
- fan1 (default) or in6
- fan2 (default) or in7
- VID lines (default) or IRQ lines (not handled by this driver)