Regulator Machine Driver Interface

The regulator machine driver interface is intended for board/machine specific initialisation code to configure the regulator subsystem. Consider the following machine:

The drivers for consumers A & B must be mapped to the correct regulator in order to control their power supplies. This mapping can be achieved in machine initialisation code by creating a struct regulator consumer supply for each regulator:

This maps Regulator-1 to the 'Vcc' supply for Consumer B and maps Regulator-2 to the 'Vcc' supply for Consumer A.

Constraints can now be registered by defining a struct regulator_init_data for each regulator power domain. This structure also maps the consumers to their supply regulators:

The name field should be set to something that is usefully descriptive for the board for configuration of supplies for other regulators and for use in logging and other diagnostic output. Normally the name used for the supply rail in the schematic is a good choice. If no name is provided then the subsystem will choose one.

Regulator-1 supplies power to Regulator-2. This relationship must be registered with the core so that Regulator-1 is also enabled when Consumer A enables its supply (Regulator-2). The supply regulator is set by the supply regulator field below and co:

```
static struct regulator_init_data regulator2_data = {
    .supply_regulator = "Regulator-1",
    .constraints = {
        .min_uV = 1800000,
        .max_uV = 2000000,
        .valid_ops_mask = REGULATOR_CHANGE_VOLTAGE,
        .valid_modes_mask = REGULATOR_MODE_NORMAL,
    },
    .num_consumer_supplies = ARRAY_SIZE(regulator2_consumers),
    .consumer_supplies = regulator2_consumers,
};
```

Finally the regulator devices must be registered in the usual manner:

```
},
};
/* register regulator 1 device */
platform_device_register(&regulator_devices[0]);
/* register regulator 2 device */
platform_device_register(&regulator_devices[1]);
```