Autograd

Autograd is a hotspot for PyTorch performance, so most of the heavy lifting is implemented in C++. This implies that we have to do some shuffling between Python and C++; and in general, we want data to be in a form that is convenient to manipulate from C++.

Our general model is that for any key data type that autograd manipulates, there are two implementations: a C++ type and a Python object type. For example, consider variables in autograd: we have both <code>Variable</code> in <code>variable.h</code> (the C++ type) and <code>THPVariable</code> in <code>python_variable.h</code> (the Python type.) (By the way, THP stands for TorcH Python, not to be confused with THPP, TorcH C++). <code>Variable</code> contains the payload of a variable, while <code>THPVariable</code> just contains a <code>shared_ptr</code> reference to <code>Variable</code>, as well as references to other Python objects which the Python runtime needs to know about. A lot of data accessor implementations in <code>python_variable.cpp</code> simply reach through to the underlying <code>Variable</code> and return the appropriate value.

The most complicated application of this principle is Function, which also supports users implementing custom behavior in Python. We have the following classes:

- Node in function.h , the C++ type.
- THPFunction in python_function.h , the Python object type. In python_function.cpp , you can see the boilerplate that tells the Python interpreter about this object.
- PyNode in python_function.h, a subclass of Node which forwards apply to a Python THPFunction. (NOT a Python object, despite its name!)

Outside of PyNode, the C++ objects largely avoid referencing Python objects (there are a few exceptions, like pyobj in Variable, and PyNode, whose whole point is to let C++ call into Python). And pyobj in Node to ensure uniqueness of the associated python wrapper (if it exists).