

# SCSI EH

This document describes SCSI midlayer error handling infrastructure. Please refer to Documentation/scsi/scsi\_mid\_low\_api.rst for more information regarding SCSI midlayer.

## 1. How SCSI commands travel through the midlayer and to EH

### 1.1 struct scsi\_cmnd

Each SCSI command is represented with struct `scsi_cmnd` (`= scmd`). A `scmd` has two `list_head`'s to link itself into lists. The two are `scmd->list` and `scmd->eh_entry`. The former is used for free list or per-device allocated `scmd` list and not of much interest to this EH discussion. The latter is used for completion and EH lists and unless otherwise stated `scmds` are always linked using `scmd->eh_entry` in this discussion.

### 1.2 How do `scmd`'s get completed?

Once LLDD gets hold of a `scmd`, either the LLDD will complete the command by calling `scsi_done` callback passed from midlayer when invoking `hostt->queuecommand()` or the block layer will time it out.

#### 1.2.1 Completing a `scmd` w/ `scsi_done`

For all non-EH commands, `scsi_done()` is the completion callback. It just calls `blk_complete_request()` to delete the block layer timer and raise `SCSI_SOFTIRQ`

`SCSI_SOFTIRQ` handler `scsi_softirq` calls `scsi_decide_disposition()` to determine what to do with the command. `scsi_decide_disposition()` looks at the `scmd->result` value and sense data to determine what to do with the command.

- **SUCCESS**

`scsi_finish_command()` is invoked for the command. The function does some maintenance chores and then calls `scsi_io_completion()` to finish the I/O. `scsi_io_completion()` then notifies the block layer on the completed request by calling `blk_end_request` and figures out what to do with the remainder of the data in case of an error.

- **NEEDS\_RETRY**
- **ADD\_TO\_MLQUEUE**

`scmd` is requeued to `blk` queue.

- **otherwise**

`scsi_eh_scmd_add(scmd)` is invoked for the command. See [1-3] for details of this function.

#### 1.2.2 Completing a `scmd` w/ timeout

The timeout handler is `scsi_times_out()`. When a timeout occurs, this function

1. invokes optional `hostt->eh_timed_out()` callback. Return value can be one of
  - **BLK\_EH\_RESET\_TIMER**  
This indicates that more time is required to finish the command. Timer is restarted.
  - **BLK\_EH\_DONE**  
`eh_timed_out()` callback did not handle the command. Step #2 is taken.
2. `scsi_abort_command()` is invoked to schedule an asynchronous abort which may issue a retry `scmd->allowed + 1` times. Asynchronous aborts are not invoked for commands for which the `SCSI_EH_ABORT_SCHEDULED` flag is set (this indicates that the command already had been aborted once, and this is a retry which failed), when retries are exceeded, or when the EH deadline is expired. In these cases Step #3 is taken.
3. `scsi_eh_scmd_add(scmd, SCSI_EH_CANCEL_CMD)` is invoked for the command. See [1-4] for more information.

### 1.3 Asynchronous command aborts

After a timeout occurs a command abort is scheduled from `scsi_abort_command()`. If the abort is successful the command will either be retried (if the number of retries is not exhausted) or terminated with `DID_TIME_OUT`.

Otherwise `scsi_eh_scmd_add()` is invoked for the command. See [1-4] for more information.

## 1.4 How EH takes over

scmds enter EH via `scsi_eh_scmd_add()`, which does the following.

1. Links `scmd->eh_entry` to `shost->eh_cmd_q`
2. Sets `SHOST_RECOVERY` bit in `shost->shost_state`
3. Increments `shost->host_failed`
4. Wakes up SCSI EH thread if `shost->host_busy == shost->host_failed`

As can be seen above, once any `scmd` is added to `shost->eh_cmd_q`, `SHOST_RECOVERY` `shost_state` bit is turned on. This prevents any new `scmd` to be issued from `blk` queue to the host; eventually, all `scmds` on the host either complete normally, fail and get added to `eh_cmd_q`, or time out and get added to `shost->eh_cmd_q`.

If all `scmds` either complete or fail, the number of in-flight `scmds` becomes equal to the number of failed `scmds` - i.e. `shost->host_busy == shost->host_failed`. This wakes up SCSI EH thread. So, once woken up, SCSI EH thread can expect that all in-flight commands have failed and are linked on `shost->eh_cmd_q`.

Note that this does not mean lower layers are quiescent. If a LLDD completed a `scmd` with error status, the LLDD and lower layers are assumed to forget about the `scmd` at that point. However, if a `scmd` has timed out, unless `host->eh_timed_out()` made lower layers forget about the `scmd`, which currently no LLDD does, the command is still active as long as lower layers are concerned and completion could occur at any time. Of course, all such completions are ignored as the timer has already expired.

We'll talk about how SCSI EH takes actions to abort - make LLDD forget about - timed out `scmds` later.

## 2. How SCSI EH works

LLDD's can implement SCSI EH actions in one of the following two ways.

- Fine-grained EH callbacks  
LLDD can implement fine-grained EH callbacks and let SCSI midlayer drive error handling and call appropriate callbacks. This will be discussed further in [2-1].
- `eh_strategy_handler()` callback  
This is one big callback which should perform whole error handling. As such, it should do all chores the SCSI midlayer performs during recovery. This will be discussed in [2-2].

Once recovery is complete, SCSI EH resumes normal operation by calling `scsi_restart_operations()`, which

1. Checks if door locking is needed and locks door.
2. Clears `SHOST_RECOVERY` `shost_state` bit
3. Wakes up waiters on `shost->host_wait`. This occurs if someone calls `scsi_block_when_processing_errors()` on the host. (*QUESTION* why is it needed? All operations will be blocked anyway after it reaches `blk` queue.)
4. Kicks queues in all devices on the host in the asses

### 2.1 EH through fine-grained callbacks

#### 2.1.1 Overview

If `eh_strategy_handler()` is not present, SCSI midlayer takes charge of driving error handling. EH's goals are two - make LLDD, host and device forget about timed out `scmds` and make them ready for new commands. A `scmd` is said to be recovered if the `scmd` is forgotten by lower layers and lower layers are ready to process or fail the `scmd` again.

To achieve these goals, EH performs recovery actions with increasing severity. Some actions are performed by issuing SCSI commands and others are performed by invoking one of the following fine-grained host EH callbacks. Callbacks may be omitted and omitted ones are considered to fail always.

```
int (* eh_abort_handler)(struct scsi_cmnd *);
int (* eh_device_reset_handler)(struct scsi_cmnd *);
int (* eh_bus_reset_handler)(struct scsi_cmnd *);
int (* eh_host_reset_handler)(struct scsi_cmnd *);
```

Higher-severity actions are taken only when lower-severity actions cannot recover some of failed `scmds`. Also, note that failure of the highest-severity action means EH failure and results in offlining of all unrecovered devices.

During recovery, the following rules are followed

- Recovery actions are performed on failed `scmds` on the to do list, `eh_work_q`. If a recovery action succeeds for a `scmd`, recovered `scmds` are removed from `eh_work_q`.  
Note that single recovery action on a `scmd` can recover multiple `scmds`. e.g. resetting a device recovers all failed `scmds` on the device.
- Higher severity actions are taken iff `eh_work_q` is not empty after lower severity actions are complete.

- EH reuses failed cmds to issue commands for recovery. For timed-out cmds, SCSI EH ensures that LLDD forgets about a cmd before reusing it for EH commands.

When a cmd is recovered, the cmd is moved from eh\_work\_q to EH local eh\_done\_q using scsi\_eh\_finish\_cmd(). After all cmds are recovered (eh\_work\_q is empty), scsi\_eh\_flush\_done\_q() is invoked to either retry or error-finish (notify upper layer of failure) recovered cmds.

cmds are retried iff its sdev is still online (not offlined during EH), REQ\_FAILFAST is not set and ++cmd->retries is less than cmd->allowed.

### 2.1.2 Flow of cmds through EH

#### 1. Error completion / time out

**ACTION:** scsi\_eh\_cmd\_add() is invoked for cmd

- add cmd to shost->eh\_cmd\_q
- set SHOST\_RECOVERY
- shost->host\_failed++

**LOCKING:** shost->host\_lock

#### 2. EH starts

**ACTION:** move all cmds to EH's local eh\_work\_q. shost->eh\_cmd\_q is cleared.

**LOCKING:** shost->host\_lock (not strictly necessary, just for consistency)

#### 3. cmd recovered

**ACTION:** scsi\_eh\_finish\_cmd() is invoked to EH-finish cmd

- scsi\_setup\_cmd\_retry()
- move from local eh\_work\_q to local eh\_done\_q

**LOCKING:** none

**CONCURRENCY:** at most one thread per separate eh\_work\_q to keep queue manipulation lockless

#### 4. EH completes

**ACTION:** scsi\_eh\_flush\_done\_q() retries cmds or notifies upper layer of failure. May be called concurrently but must have a no more than one thread per separate eh\_work\_q to manipulate the queue locklessly

- cmd is removed from eh\_done\_q and cmd->eh\_entry is cleared
- if retry is necessary, cmd is requeued using scsi\_queue\_insert()
- otherwise, scsi\_finish\_command() is invoked for cmd
- zero shost->host\_failed

**LOCKING:** queue or finish function performs appropriate locking

### 2.1.3 Flow of control

EH through fine-grained callbacks start from scsi\_unjam\_host().

scsi\_unjam\_host

1. Lock shost->host\_lock, splice\_init shost->eh\_cmd\_q into local eh\_work\_q and unlock host\_lock. Note that shost->eh\_cmd\_q is cleared by this action.
2. Invoke scsi\_eh\_get\_sense.

scsi\_eh\_get\_sense

This action is taken for each error-completed (!SCSI\_EH\_CANCEL\_CMD) commands without valid sense data. Most SCSI transports/LLDDs automatically acquire sense data on command failures (autosense). Autosense is recommended for performance reasons and as sense information could get out of sync between occurrence of CHECK CONDITION and this action.

Note that if autosense is not supported, cmd->sense\_buffer contains invalid sense data when error-completing the cmd with scsi\_done(). scsi\_decide\_disposition() always returns FAILED in such cases thus invoking SCSI EH. When the cmd reaches here, sense data is acquired and scsi\_decide\_disposition() is called again.

1. Invoke scsi\_request\_sense() which issues REQUEST\_SENSE command. If fails, no action. Note that taking no action causes higher-severity recovery to be taken for the cmd.
2. Invoke scsi\_decide\_disposition() on the cmd
  - SUCCESS
 

cmd->retries is set to cmd->allowed preventing scsi\_eh\_flush\_done\_q() from retrying the cmd and scsi\_eh\_finish\_cmd() is invoked.
  - NEEDS\_RETRY

scsi\_eh\_finish\_cmd() invoked

- otherwise

No action.

3. If !list\_empty(&eh\_work\_q), invoke scsi\_eh\_abort\_cmds().

scsi\_eh\_abort\_cmds

This action is taken for each timed out command when no\_async\_abort is enabled in the host template. hostt->eh\_abort\_handler() is invoked for each scmd. The handler returns SUCCESS if it has succeeded to make LLDD and all related hardware forget about the scmd.

If a timedout scmd is successfully aborted and the sdev is either offline or ready, scsi\_eh\_finish\_cmd() is invoked for the scmd. Otherwise, the scmd is left in eh\_work\_q for higher-severity actions.

Note that both offline and ready status mean that the sdev is ready to process new scmds, where processing also implies immediate failing; thus, if a sdev is in one of the two states, no further recovery action is needed.

Device readiness is tested using scsi\_eh\_tur() which issues TEST\_UNIT\_READY command. Note that the scmd must have been aborted successfully before reusing it for TEST\_UNIT\_READY.

4. If !list\_empty(&eh\_work\_q), invoke scsi\_eh\_ready\_devs()

scsi\_eh\_ready\_devs

This function takes four increasingly more severe measures to make failed sdevs ready for new commands.

1. Invoke scsi\_eh\_stu()

scsi\_eh\_stu

For each sdev which has failed scmds with valid sense data of which scsi\_check\_sense()'s verdict is FAILED, START\_STOP\_UNIT command is issued w/ start=1. Note that as we explicitly choose error-completed scmds, it is known that lower layers have forgotten about the scmd and we can reuse it for STU.

If STU succeeds and the sdev is either offline or ready, all failed scmds on the sdev are EH-finished with scsi\_eh\_finish\_cmd().

*NOTE* If hostt->eh\_abort\_handler() isn't implemented or failed, we may still have timed out scmds at this point and STU doesn't make lower layers forget about those scmds. Yet, this function EH-finish all scmds on the sdev if STU succeeds leaving lower layers in an inconsistent state. It seems that STU action should be taken only when a sdev has no timed out scmd.

2. If !list\_empty(&eh\_work\_q), invoke scsi\_eh\_bus\_device\_reset().

scsi\_eh\_bus\_device\_reset

This action is very similar to scsi\_eh\_stu() except that, instead of issuing STU, hostt->eh\_device\_reset\_handler() is used. Also, as we're not issuing SCSI commands and resetting clears all scmds on the sdev, there is no need to choose error-completed scmds.

3. If !list\_empty(&eh\_work\_q), invoke scsi\_eh\_bus\_reset()

scsi\_eh\_bus\_reset

hostt->eh\_bus\_reset\_handler() is invoked for each channel with failed scmds. If bus reset succeeds, all failed scmds on all ready or offline sdevs on the channel are EH-finished.

4. If !list\_empty(&eh\_work\_q), invoke scsi\_eh\_host\_reset()

scsi\_eh\_host\_reset

This is the last resort. hostt->eh\_host\_reset\_handler() is invoked. If host reset succeeds, all failed scmds on all ready or offline sdevs on the host are EH-finished.

5. If !list\_empty(&eh\_work\_q), invoke scsi\_eh\_offline\_sdevs()

scsi\_eh\_offline\_sdevs

Take all sdevs which still have unrecovered scmds offline and EH-finish the scmds.

5. Invoke scsi\_eh\_flush\_done\_q().

scsi\_eh\_flush\_done\_q

At this point all cmds are recovered (or given up) and put on eh\_done\_q by scsi\_ah\_finish\_cmd(). This function flushes eh\_done\_q by either retrying or notifying upper layer of failure of the cmds.

## 2.2 EH through transport->eh\_strategy\_handler()

transport->eh\_strategy\_handler() is invoked in the place of scsi\_unjam\_host() and it is responsible for whole recovery process. On completion, the handler should have made lower layers forget about all failed cmds and either ready for new commands or offline. Also, it should perform SCSI EH maintenance chores to maintain integrity of SCSI midlayer. IOW, of the steps described in [2-1-2], all steps except for #1 must be implemented by eh\_strategy\_handler().

### 2.2.1 Pre transport->eh\_strategy\_handler() SCSI midlayer conditions

The following conditions are true on entry to the handler.

- Each failed cmd's eh\_flags field is set appropriately.
- Each failed cmd is linked on cmd->eh\_cmd\_q by cmd->eh\_entry.
- SHOST\_RECOVERY is set.
- shost->host\_failed == shost->host\_busy

### 2.2.2 Post transport->eh\_strategy\_handler() SCSI midlayer conditions

The following conditions must be true on exit from the handler.

- shost->host\_failed is zero.
- Each cmd is in such a state that scsi\_setup\_cmd\_retry() on the cmd doesn't make any difference.
- shost->eh\_cmd\_q is cleared.
- Each cmd->eh\_entry is cleared.
- Either scsi\_queue\_insert() or scsi\_finish\_command() is called on each cmd. Note that the handler is free to use cmd->retries and ->allowed to limit the number of retries.

### 2.2.3 Things to consider

- Know that timed out cmds are still active on lower layers. Make lower layers forget about them before doing anything else with those cmds.
- For consistency, when accessing/modifying shost data structure, grab shost->host\_lock.
- On completion, each failed sdev must have forgotten about all active cmds.
- On completion, each failed sdev must be ready for new commands or offline.

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