Conversion of PyTorch Classification Models and Launch with OpenCV C++ {#pytorch_cls_c_tutorial_dnn_conversion}

@prev_tutorial{pytorch_cls_tutorial_dnn_conversion}

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|-----------------|-------------------|
| Compatibility | OpenCV >= 4.5 |

Goals

In this tutorial you will learn how to:

- convert PyTorch classification models into ONNX format
- run converted PyTorch model with OpenCV C/C++ API
- provide model inference

We will explore the above-listed points by the example of ResNet-50 architecture.

Introduction

Let's briefly view the key concepts involved in the pipeline of PyTorch models transition with OpenCV API. The initial step in conversion of PyTorch models into cv::dnn::Net is model transferring into ONNX format. ONNX aims at the interchangeability of the neural networks between various frameworks. There is a built-in function in PyTorch for ONNX conversion: torch.onnx.export. Further the obtained torch.onnx. export. Export torch.onnx. export. Export torch.onnx. export <a href="torc

Requirements

To be able to experiment with the below code you will need to install a set of libraries. We will use a virtual environment with python3.7+ for this:

```
virtualenv -p /usr/bin/python3.7 <env_dir_path>
source <env_dir_path>/bin/activate
```

For OpenCV-Python building from source, follow the corresponding instructions from the @ref tutorial_py_table_of_contents_setup.

Before you start the installation of the libraries, you can customize the <u>requirements.txt</u>, excluding or including (for example, opency-python) some dependencies. The below line initiates requirements installation into the previously activated virtual environment:

```
pip install -r requirements.txt
```

Practice

In this part we are going to cover the following points:

- 1. create a classification model conversion pipeline
- 2. provide the inference, process prediction results

Model Conversion Pipeline

The code in this subchapter is located in the samples/dnn/dnn_model_runner module and can be executed with the line:

```
python -m
dnn_model_runner.dnn_conversion.pytorch.classification.py_to_py_resnet50_onnx
```

The following code contains the description of the below-listed steps:

- 1. instantiate PyTorch model
- 2. convert PyTorch model into .onnx

```
# initialize PyTorch ResNet-50 model
original_model = models.resnet50(pretrained=True)

# get the path to the converted into ONNX PyTorch model
full_model_path = get_pytorch_onnx_model(original_model)
print("PyTorch ResNet-50 model was successfully converted: ", full_model_path)
```

get pytorch onnx model(original model) function is based on torch.onnx.export(...) call:

```
\# define the directory for further converted model save
onnx_model_path = "models"
# define the name of further converted model
onnx model name = "resnet50.onnx"
# create directory for further converted model
os.makedirs(onnx model path, exist ok=True)
# get full path to the converted model
full model path = os.path.join(onnx model path, onnx model name)
# generate model input
generated input = Variable(
    torch.randn(1, 3, 224, 224)
# model export into ONNX format
torch.onnx.export(
   original_model,
    generated input,
   full_model_path,
   verbose=True,
    input names=["input"],
    output names=["output"],
```

```
opset_version=11
)
```

After the successful execution of the above code we will get the following output:

```
PyTorch ResNet-50 model was successfully converted: models/resnet50.onnx
```

The proposed in <code>dnn/samples</code> module <code>dnn_model_runner</code> allows us to reproduce the above conversion steps for the following PyTorch classification models:

- alexnet
- vgg11
- vgg13
- vgg16
- vgg19
- resnet18
- resnet34
- resnet50
- resnet101
- resnet152
- squeezenet1_0
- squeezenet1_1
- resnext50_32x4d
- resnext101_32x8d
- wide_resnet50_2
- wide_resnet101_2

To obtain the converted model, the following line should be executed:

```
python -m dnn_model_runner.dnn_conversion.pytorch.classification.py_to_py_cls --
model_name <pytorch_cls_model_name> --evaluate False
```

For the ResNet-50 case the below line should be run:

```
python -m dnn_model_runner.dnn_conversion.pytorch.classification.py_to_py_cls --
model_name resnet50 --evaluate False
```

The default root directory for the converted model storage is defined in module <code>CommonConfig</code>:

```
@dataclass
class CommonConfig:
   output_data_root_dir: str = "dnn_model_runner/dnn_conversion"
```

Thus, the converted ResNet-50 will be saved in ${\tt dnn_model_runner/dnn_conversion/models}$.

Inference Pipeline

Now we can use models/resnet50.onnx for the inference pipeline using OpenCV C/C++ API. The implemented pipeline can be found in samples/dnn/classification.cpp. After the build of samples (BUILD_EXAMPLES flag value should be ON), the appropriate $example_dnn_classification$ executable file will be provided.

To provide model inference we will use the below <u>squirrel photo</u> (under <u>CCO</u> license) corresponding to ImageNet class ID 335:

```
fox squirrel, eastern fox squirrel, Sciurus niger
```



For the label decoding of the obtained prediction, we also need imagenet_classes.txt file, which contains the full list of the ImageNet classes.

In this tutorial we will run the inference process for the converted PyTorch ResNet-50 model from the build (samples/build) directory:

```
./dnn/example_dnn_classification --model=../dnn/models/resnet50.onnx --
input=../data/squirrel_cls.jpg --width=224 --height=224 --rgb=true --
scale="0.003921569" --mean="123.675 116.28 103.53" --std="0.229 0.224 0.225" --
crop=true --initial_width=256 --initial_height=256 --
classes=../data/dnn/classification_classes_ILSVRC2012.txt
```

Let's explore classification.cpp key points step by step:

1. read the model with cv::dnn::readNet, initialize the network:

```
Net net = readNet(model, config, framework);
```

The model parameter value is taken from --model key. In our case, it is resnet50.onnx.

• preprocess input image:

```
if (rszWidth != 0 && rszHeight != 0)
{
    resize(frame, frame, Size(rszWidth, rszHeight));
}

// Create a 4D blob from a frame
blobFromImage(frame, blob, scale, Size(inpWidth, inpHeight), mean, swapRB, crop);

// Check std values.
if (std.val[0] != 0.0 && std.val[1] != 0.0 && std.val[2] != 0.0)
{
    // Divide blob by std.
    divide(blob, std, blob);
}
```

In this step we use cv::dnn::blobFromImage function to prepare model input. We set Size(rszWidth, rszHeight) with --initial_width=256 --initial_height=256 for the initial image resize as it's described in PyTorch ResNet inference pipeline.

It should be noted that firstly in cv::dnn::blobFromImage mean value is subtracted and only then pixel values are multiplied by scale. Thus, we use --mean="123.675 116.28 103.53", which is equivalent to [0.485, 0.456, 0.406] multiplied by 255.0 to reproduce the original image preprocessing order for PyTorch classification models:

```
img /= 255.0
img -= [0.485, 0.456, 0.406]
img /= [0.229, 0.224, 0.225]
```

• make forward pass:

```
net.setInput(blob);
Mat prob = net.forward();
```

• process the prediction:

```
Point classIdPoint;
double confidence;
minMaxLoc(prob.reshape(1, 1), 0, &confidence, 0, &classIdPoint);
int classId = classIdPoint.x;
```

Here we choose the most likely object class. The classId result for our case is 335 - fox squirrel, eastern fox squirrel, Sciurus niger:

ResNet50 OpenCV C++ inference output