Conversion of PyTorch Classification Models and Launch with OpenCV Python {#pytorch_cls_tutorial_dnn_conversion}

@prev_tutorial{tutorial_dnn_OCR} @next_tutorial{pytorch_cls_c_tutorial_dnn_conversion}

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Compatibility	OpenCV >= 4.5

Goals

In this tutorial you will learn how to:

- convert PyTorch classification models into ONNX format
- run converted PyTorch model with OpenCV Python API
- obtain an evaluation of the PyTorch and OpenCV DNN models.

We will explore the above-listed points by the example of the ResNet-50 architecture.

Introduction

Let's briefly view the key concepts involved in the pipeline of PyTorch models transition with OpenCV API. The initial step in conversion of PyTorch models into cv.dnn.Net is model transferring into ONNX format. ONNX aims at the interchangeability of the neural networks between various frameworks. There is a built-in function in PyTorch for ONNX conversion: torch.onnx.export. Further the obtained onnx model is passed into cv.dnn.readNetFromONNX.

Requirements

To be able to experiment with the below code you will need to install a set of libraries. We will use a virtual environment with python3.7+ for this:

```
virtualenv -p /usr/bin/python3.7 <env_dir_path>
source <env_dir_path>/bin/activate
```

For OpenCV-Python building from source, follow the corresponding instructions from the @ref tutorial_py_table_of_contents_setup.

Before you start the installation of the libraries, you can customize the <u>requirements.txt</u>, excluding or including (for example, <u>opency-python</u>) some dependencies. The below line initiates requirements installation into the previously activated virtual environment:

```
pip install -r requirements.txt
```

Practice

In this part we are going to cover the following points:

- 1. create a classification model conversion pipeline and provide the inference
- 2. evaluate and test classification models

If you'd like merely to run evaluation or test model pipelines, the "Model Conversion Pipeline" part can be skipped.

Model Conversion Pipeline

The code in this subchapter is located in the dnn model runner module and can be executed with the line:

```
python -m dnn_model_runner.dnn_conversion.pytorch.classification.py_to_py_resnet50
```

The following code contains the description of the below-listed steps:

- 1. instantiate PyTorch model
- 2. convert PyTorch model into .onnx
- 3. read the transferred network with OpenCV API
- 4. prepare input data
- 5. provide inference

```
# initialize PyTorch ResNet-50 model
original model = models.resnet50(pretrained=True)
# get the path to the converted into ONNX PyTorch model
full_model_path = get_pytorch_onnx_model(original_model)
# read converted .onnx model with OpenCV API
opencv net = cv2.dnn.readNetFromONNX(full model path)
print("OpenCV model was successfully read. Layer IDs: \n",
opencv net.getLayerNames())
# get preprocessed image
input img = get preprocessed img("../data/squirrel cls.jpg")
# get ImageNet labels
imagenet labels =
get imagenet labels("../data/dnn/classification classes ILSVRC2012.txt")
# obtain OpenCV DNN predictions
get opencv dnn prediction(opencv net, input img, imagenet labels)
# obtain original PyTorch ResNet50 predictions
get pytorch dnn prediction(original model, input img, imagenet labels)
```

To provide model inference we will use the below <u>squirrel photo</u> (under <u>CCO</u> license) corresponding to ImageNet class ID 335:

```
fox squirrel, eastern fox squirrel, Sciurus niger
```



For the label decoding of the obtained prediction, we also need imagenet_classes.txt file, which contains the full list of the ImageNet classes.

Let's go deeper into each step by the example of pretrained PyTorch ResNet-50:

• instantiate PyTorch ResNet-50 model:

```
# initialize PyTorch ResNet-50 model
original_model = models.resnet50(pretrained=True)
```

• convert PyTorch model into ONNX:

```
# define the directory for further converted model save
onnx model path = "models"
# define the name of further converted model
onnx model name = "resnet50.onnx"
# create directory for further converted model
os.makedirs(onnx model path, exist ok=True)
# get full path to the converted model
full_model_path = os.path.join(onnx_model_path, onnx_model_name)
# generate model input
generated input = Variable(
   torch.randn(1, 3, 224, 224)
# model export into ONNX format
torch.onnx.export(
   original model,
   generated_input,
   full model path,
   verbose=True,
   input names=["input"],
   output names=["output"],
   opset_version=11
```

After the successful execution of the above code, we will get <code>models/resnet50.onnx</code> .

 read the transferred network with cv.dnn.readNetFromONNX passing the obtained in the previous step ONNX model into it:

```
# read converted .onnx model with OpenCV API
opencv_net = cv2.dnn.readNetFromONNX(full_model_path)
```

• prepare input data:

```
# read the image
input_img = cv2.imread(img_path, cv2.IMREAD_COLOR)
input img = input img.astype(np.float32)
input img = cv2.resize(input img, (256, 256))
# define preprocess parameters
mean = np.array([0.485, 0.456, 0.406]) * 255.0
scale = 1 / 255.0
std = [0.229, 0.224, 0.225]
# prepare input blob to fit the model input:
# 1. subtract mean
# 2. scale to set pixel values from 0 to 1
input blob = cv2.dnn.blobFromImage(
   image=input img,
   scalefactor=scale,
   size=(224, 224), # img target size
   mean=mean,
   swapRB=True, # BGR -> RGB
   crop=True # center crop
# 3. divide by std
input_blob[0] /= np.asarray(std, dtype=np.float32).reshape(3, 1, 1)
```

In this step we read the image and prepare model input with cv.dnn.blobFromImage function, which returns 4-dimensional blob. It should be noted that firstly in cv.dnn.blobFromImage mean value is subtracted and only then pixel values are multiplied by scale. Thus, mean is multiplied by 255.0 to reproduce the original image preprocessing order:

```
img /= 255.0
img -= [0.485, 0.456, 0.406]
img /= [0.229, 0.224, 0.225]
```

• OpenCV cv.dnn.Net inference:

```
# set OpenCV DNN input
opencv_net.setInput(preproc_img)

# OpenCV DNN inference
out = opencv_net.forward()
print("OpenCV DNN prediction: \n")
print("* shape: ", out.shape)

# get the predicted class ID
imagenet_class_id = np.argmax(out)

# get confidence
```

```
confidence = out[0][imagenet_class_id]
print("* class ID: {}, label: {}".format(imagenet_class_id,
imagenet_labels[imagenet_class_id]))
print("* confidence: {:.4f}".format(confidence))
```

After the above code execution we will get the following output:

```
OpenCV DNN prediction:
 * shape: (1, 1000)
 * class ID: 335, label: fox squirrel, eastern fox squirrel, Sciurus niger
 * confidence: 14.8308
```

• PyTorch ResNet-50 model inference:

```
original_net.eval()
preproc_img = torch.FloatTensor(preproc_img)

# inference
out = original_net(preproc_img)
print("\nPyTorch model prediction: \n")
print("* shape: ", out.shape)

# get the predicted class ID
imagenet_class_id = torch.argmax(out, axis=1).item()
print("* class ID: {}, label: {}".format(imagenet_class_id, imagenet_labels[imagenet_class_id]))

# get confidence
confidence = out[0][imagenet_class_id]
print("* confidence: {:.4f}".format(confidence.item()))
```

After the above code launching we will get the following output:

```
PyTorch model prediction:
* shape: torch.Size([1, 1000])
* class ID: 335, label: fox squirrel, eastern fox squirrel, Sciurus niger
* confidence: 14.8308
```

The inference results of the original ResNet-50 model and cv.dnn.Net are equal. For the extended evaluation of the models we can use <code>py_to_py_cls</code> of the <code>dnn_model_runner</code> module. This module part will be described in the next subchapter.

Evaluation of the Models

The proposed in samples/dnn dnn_model_runner module allows to run the full evaluation pipeline on the ImageNet dataset and test execution for the following PyTorch classification models:

- alexnet
- vgg11
- vgg13

- vgg16
- vgg19
- resnet18
- resnet34
- resnet50
- resnet101
- resnet152
- squeezenet1_0
- squeezenet1_1
- resnext50_32x4d
- resnext101_32x8d
- wide_resnet50_2
- wide_resnet101_2

This list can be also extended with further appropriate evaluation pipeline configuration.

Evaluation Mode

The below line represents running of the module in the evaluation mode:

```
python -m dnn_model_runner.dnn_conversion.pytorch.classification.py_to_py_cls --
model_name <pytorch_cls_model_name>
```

Chosen from the list classification model will be read into OpenCV cv.dnn.Net object. Evaluation results of PyTorch and OpenCV models (accuracy, inference time, L1) will be written into the log file. Inference time values will be also depicted in a chart to generalize the obtained model information.

Necessary evaluation configurations are defined in the <u>test config.py</u> and can be modified in accordance with actual paths of data location:

```
@dataclass
class TestClsConfig:
    batch_size: int = 50
    frame_size: int = 224
    img_root_dir: str = "./ILSVRC2012_img_val"
    # location of image-class matching
    img_cls_file: str = "./val.txt"
    bgr_to_rgb: bool = True
```

To initiate the evaluation of the PyTorch ResNet-50, run the following line:

```
python -m dnn_model_runner.dnn_conversion.pytorch.classification.py_to_py_cls --
model_name resnet50
```

After script launch, the log file with evaluation data will be generated in

dnn model runner/dnn conversion/logs:

```
The model PyTorch resnet50 was successfully obtained and converted to OpenCV DNN resnet50

===== Running evaluation of the model with the following params:

* val data location: ./ILSVRC2012_img_val
```

```
* log file location:
dnn_model_runner/dnn_conversion/logs/PyTorch_resnet50_log.txt
```

Test Mode

The below line represents running of the module in the test mode, namely it provides the steps for the model inference:

```
python -m dnn_model_runner.dnn_conversion.pytorch.classification.py_to_py_cls --
model_name <pytorch_cls_model_name> --test True --default_img_preprocess
<True/False> --evaluate False
```

Here <code>default_img_preprocess</code> key defines whether you'd like to parametrize the model test process with some particular values or use the default values, for example, <code>scale</code>, <code>mean</code> or <code>std</code>.

Test configuration is represented in <u>test config.py</u> TestClsModuleConfig class:

```
@dataclass
class TestClsModuleConfig:
   cls test data dir: str = "../data"
   test module name: str = "classification"
   test module path: str = "classification.py"
   input_img: str = os.path.join(cls_test_data_dir, "squirrel_cls.jpg")
   model: str = ""
   frame height: str = str(TestClsConfig.frame size)
   frame width: str = str(TestClsConfig.frame size)
   scale: str = "1.0"
   mean: List[str] = field(default factory=lambda: ["0.0", "0.0", "0.0"])
   std: List[str] = field(default factory=list)
   crop: str = "False"
   rgb: str = "True"
   rsz_height: str = ""
   rsz width: str = ""
   classes: str = os.path.join(cls test data dir, "dnn",
"classification_classes_ILSVRC2012.txt")
```

The default image preprocessing options are defined in <u>default preprocess config.py</u>. For instance:

```
BASE_IMG_SCALE_FACTOR = 1 / 255.0
PYTORCH_RSZ_HEIGHT = 256

PYTORCH_RSZ_WIDTH = 256

pytorch_resize_input_blob = {
    "mean": ["123.675", "116.28", "103.53"],
    "scale": str(BASE_IMG_SCALE_FACTOR),
    "std": ["0.229", "0.224", "0.225"],
    "crop": "True",
    "rgb": "True",
    "rsz_height": str(PYTORCH_RSZ_HEIGHT),
```

```
"rsz_width": str(PYTORCH_RSZ_WIDTH)
}
```

The basis of the model testing is represented in samples/dnn/classification.py classification.py can be executed autonomously with provided converted model in --input and populated parameters for cv.dnn.blobFromImage.

To reproduce from scratch the described in "Model Conversion Pipeline" OpenCV steps with dnn_model_runner execute the below line:

```
python -m dnn_model_runner.dnn_conversion.pytorch.classification.py_to_py_cls --
model_name resnet50 --test True --default_img_preprocess True --evaluate False
```

The network prediction is depicted in the top left corner of the output window:

