

## :c:type:`uv\_fs\_poll\_t` --- FS Poll handle

**System Message: ERROR/3 (D:\onboarding-resources\sample-onboarding-resources\node-master\deps\uv\docs\src\[node-master] [deps] [uv] [docs] [src] fs\_poll.rst, line 4); [backlink](#)**  
Unknown interpreted text role "c:type".

FS Poll handles allow the user to monitor a given path for changes. Unlike :c:type:`uv\_fs\_event\_t`, fs poll handles use *stat* to detect when a file has changed so they can work on file systems where fs event handles can't.

**System Message: ERROR/3 (D:\onboarding-resources\sample-onboarding-resources\node-master\deps\uv\docs\src\[node-master] [deps] [uv] [docs] [src] fs\_poll.rst, line 7); [backlink](#)**  
Unknown interpreted text role "c:type".

### Data types

**System Message: ERROR/3 (D:\onboarding-resources\sample-onboarding-resources\node-master\deps\uv\docs\src\[node-master] [deps] [uv] [docs] [src] fs\_poll.rst, line 15)**  
Unknown directive type "c:type".

```
.. c:type:: uv_fs_poll_t

    FS Poll handle type.
```

**System Message: ERROR/3 (D:\onboarding-resources\sample-onboarding-resources\node-master\deps\uv\docs\src\[node-master] [deps] [uv] [docs] [src] fs\_poll.rst, line 19)**  
Unknown directive type "c:type".

```
.. c:type:: void (*uv_fs_poll_cb)(uv_fs_poll_t* handle, int status, const uv_stat_t* prev, const uv_stat_t* cur)

    Callback passed to :c:func:`uv_fs_poll_start` which will be called repeatedly
    after the handle is started, when any change happens to the monitored path.

    The callback is invoked with `status < 0` if `path` does not exist
    or is inaccessible. The watcher is not stopped but your callback is
    not called again until something changes (e.g. when the file is created
    or the error reason changes).

    When `status == 0`, the callback receives pointers to the old and new
    :c:type:`uv_stat_t` structs. They are valid for the duration of the
    callback only.
```

### Public members

N/A

**System Message: ERROR/3 (D:\onboarding-resources\sample-onboarding-resources\node-master\deps\uv\docs\src\[node-master] [deps] [uv] [docs] [src] fs\_poll.rst, line 39)**  
Unknown directive type "seealso".

```
.. seealso:: The :c:type:`uv_handle_t` members also apply.
```

### API

**System Message: ERROR/3 (D:\onboarding-resources\sample-onboarding-resources\node-master\deps\uv\docs\src\[node-master] [deps] [uv] [docs] [src] fs\_poll.rst, line 45)**  
Unknown directive type "c:function".

```
.. c:function:: int uv_fs_poll_init(uv_loop_t* loop, uv_fs_poll_t* handle)

    Initialize the handle.
```

**System Message: ERROR/3 (D:\onboarding-resources\sample-onboarding-resources\node-master\deps\uv\docs\src\[node-master] [deps] [uv] [docs] [src] fs\_poll.rst, line 49)**  
Unknown directive type "c:function".

```
.. c:function:: int uv_fs_poll_start(uv_fs_poll_t* handle, uv_fs_poll_cb poll_cb, const char* path, unsigned int interval)

    Check the file at `path` for changes every `interval` milliseconds.

    .. note::
        For maximum portability, use multi-second intervals. Sub-second intervals will not detect
        all changes on many file systems.
```

**System Message: ERROR/3 (D:\onboarding-resources\sample-onboarding-resources\node-master\deps\uv\docs\src\node-master] [deps] [uv] [docs] [src]fs\_poll.rst, line 57)**

Unknown directive type "c:function".

```
.. c:function:: int uv_fs_poll_stop(uv_fs_poll_t* handle)
```

Stop the handle, the callback will no longer be called.

**System Message: ERROR/3 (D:\onboarding-resources\sample-onboarding-resources\node-master\deps\uv\docs\src\node-master] [deps] [uv] [docs] [src]fs\_poll.rst, line 61)**

Unknown directive type "c:function".

```
.. c:function:: int uv_fs_poll_getpath(uv_fs_poll_t* handle, char* buffer, size_t* size)
```

Get the path being monitored by the handle. The buffer must be preallocated by the user. Returns 0 on success or an error code < 0 in case of failure. On success, `buffer` will contain the path and `size` its length. If the buffer is not big enough `UV\_ENOBUFS` will be returned and `size` will be set to the required size.

```
.. versionchanged:: 1.3.0 the returned length no longer includes the terminating null byte,
    and the buffer is not null terminated.
```

```
.. versionchanged:: 1.9.0 the returned length includes the terminating null
    byte on `UV_ENOBUFS`, and the buffer is null terminated
    on success.
```

**System Message: ERROR/3 (D:\onboarding-resources\sample-onboarding-resources\node-master\deps\uv\docs\src\node-master] [deps] [uv] [docs] [src]fs\_poll.rst, line 77)**

Unknown directive type "seealso".

```
.. seealso:: The :c:type:`uv_handle_t` API functions also apply.
```