:c:type:`uv_signal_t` --- Signal handle

System Message: ERROR/3 (D:\onboarding-resources\sample-onboarding-resources\node-master\deps\uv\docs\src\[node-master] [deps] [uv] [docs] [src] signal.rst, line 4); backlink

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Signal handles implement Unix style signal handling on a per-event loop bases.

Windows notes

Reception of some signals is emulated:

- SIGINT is normally delivered when the user presses CTRL+C. However, like on Unix, it is not generated when terminal raw mode is enabled.
- SIGBREAK is delivered when the user pressed CTRL + BREAK.
- SIGHUP is generated when the user closes the console window. On SIGHUP the program is given approximately 10 seconds to perform cleanup. After that Windows will unconditionally terminate it.
- SIGWINCH is raised whenever libuv detects that the console has been resized. When a libuv app is running under a console emulator, or when a 32-bit libuv app is running on 64-bit system, SIGWINCH will be emulated. In such cases SIGWINCH signals may not always be delivered in a timely manner. For a writable ctype:"uv_tty_t handle libuv will only detect size changes when the cursor is moved. When a readable ctype:"uv_tty_t handle is used, resizing of the console buffer will be detected only if the handle is in raw mode and is being read.

System Message: ERROR/3 (D:\onboarding-resources\sample-onboarding-resources\node-master\deps\uv\docs\src\[node-master] [deps] [uv] [docs] [src] signal.rst, line 23); backlink

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System Message: ERROR/3 (D:\onboarding-resources\sample-onboarding-resources\node-master\deps\uv\docs\src\[node-master] [deps] [uv] [docs] [src] signal.rst, line 23); backlink

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- Watchers for other signals can be successfully created, but these signals are never received. These signals are: SIGILL, SIGABRT, SIGFPE, SIGSEGV, SIGTERM and SIGKILL.
- Calls to raise() or abort() to programmatically raise a signal are not detected by libuv; these will not trigger a signal watcher.

 $System\ Message: ERROR/3\ (D:\onboarding-resources\sample-onboarding-resources\node-master\deps\uv\docs\src\[node-master\] [deps]\ [uv]\ [docs]\ [src]\ signal.rst,\ line\ 39)$

Unknown directive type "versionchanged".

.. versionchanged:: 1.15.0 SIGWINCH support on Windows was improved.

System Message: ERROR/3 (D:\onboarding-resources\sample-onboarding-resources\node-master\deps\uv\docs\src\[node-master] [deps] [uv] [docs] [src] signal.rst, line 40)

Unknown directive type "versionchanged".

.. versionchanged:: 1.31.0 32-bit libuv SIGWINCH support on 64-bit Windows was rolled back to old implementation.

Unix notes

- SIGKILL and SIGSTOP are impossible to catch.
- Handling SIGBUS, SIGFPE, SIGILL or SIGSEGV via libuv results into undefined behavior.
- SIGABRT will not be caught by libuv if generated by *abort()*, e.g. through *assert()*.
- On Linux SIGRT0 and SIGRT1 (signals 32 and 33) are used by the NPTL pthreads library to manage threads. Installing
 watchers for those signals will lead to unpredictable behavior and is strongly discouraged. Future versions of libuv may simply

Data types

```
System Message: ERROR/3 (D:\onboarding-resources\sample-onboarding-resources\node-master\deps\uv\docs\src\[node-master][deps][uv][docs][src]signal.rst, line 60)

Unknown directive type "c:type".

.. c:type:: uv_signal_t

Signal handle type.
```

```
System Message: ERROR/3 (D:\onboarding-resources\sample-onboarding-resources\node-master\deps\uv\docs\src\[node-master][deps][uv][docs][src]signal.rst, line 64)

Unknown directive type "c:type".

.. c:type:: void (*uv_signal_cb) (uv_signal_t* handle, int signum)

Type definition for callback passed to :c:func:`uv_signal_start`.
```

Public members

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Unknown directive type "c:member".

```
.. c:member:: int uv_signal_t.signum
Signal being monitored by this handle. Readonly.
```

 $System\ Message: ERROR/3\ (\texttt{D:\onboarding-resources}\ sample-onboarding-resources\ node-master\ deps\ vv\ docs\ src\ [node-master]\ [deps]\ [uv]\ [docs]\ [src]\ signal.rst,\ line\ 76)$

Unknown directive type "seealso".

.. see also:: The :c:type:`uv_handle_t` members also apply.

API

Unknown directive type "c:function".

```
.. c:function:: int uv_signal_init(uv_loop_t* loop, uv_signal_t* signal)

Initialize the handle.
```

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Unknown directive type "c:function".

```
.. c:function:: int uv_signal_start(uv_signal_t* signal, uv_signal_cb cb, int signum)

Start the handle with the given callback, watching for the given signal.
```

 $System\,Message: ERROR/3\, (\mboarding-resources\sample-onboarding-resources\node-master\deps\uv\docs\src\[node-master\] [deps]\, [uv]\, [docs]\, [src]\, signal.rst, \ line\, 90)$

Unknown directive type "c:function".

- .. c:function:: int uv_signal_start_oneshot(uv_signal_t* signal, uv_signal_cb cb, int signum)
 .. versionadded:: 1.12.0
 - Same functionality as :c:func:`uv_signal_start` but the signal handler is reset the moment the signal is received.

System Message: ERROR/3 (D:\onboarding-resources\sample-onboarding-resources\node-master\deps\uv\docs\src\[node-master] [deps] [uv] [docs] [src] signal.rst, line 97)

Unknown directive type "c:function".

.. c:function:: int uv_signal_stop(uv_signal_t* signal)
 Stop the handle, the callback will no longer be called.

System Message: ERROR/3 (D:\onboarding-resources\sample-onboarding-resources\node-master\deps\uv\docs\src\[node-master] [deps] [uv] [docs] [src] signal.rst, line 101)

Unknown directive type "seealso".

.. seealso:: The :c:type:`uv_handle_t` API functions also apply.