

Recall that a directed graph is *strongly connected* if every two nodes are connected by a directed path in each direction. Let

$$STRONGLY-CONNECTED = \{\langle G \rangle \mid G \text{ is a strongly connected graph}\}.$$

Show that *STRONGLY-CONNECTED* is NL-complete.

证明NL-complete的一般思路:

1. 本身是NL

2. 证明PATH/2SAT问题可以规约到这个问题

PATH问题本身是有向图吗, 无向和有向图之间的复杂度有区别吗

注意: path并不是指的直接连接, 只是一个可达的路径

1的一般论述: 非确定地选择一个xx, 在这个分支下, 想要证明这个xx符合题目定义, 需要的存储空间是yy (一般是)

2的一般论述:

证明  $PATH \leq_L STRONGLY-CONNECTED$  (对数空间归约)

需构造对数空间归约, 将 PATH 的实例  $\langle G, s, t \rangle$  转化为 STRONGLY-CONNECTED 的实例  $\langle G' \rangle$ , 满足:

2.1 G 中 s 到 t 有路径 等价于  $G'$  是强连通图。

2.2 归约过程的空间开销是对数级的

归约的构造步骤[construction]

归约正确性验证说明[correctness]

归约的空间开销分析[log-space reduction]

## Proof that STRONGLY-CONNECTED is NL-complete

To prove STRONGLY-CONNECTED is NL-complete, we must show:

1.  $STRONGLY-CONNECTED \in NL$
2. All problems in NL reduce to STRONGLY-CONNECTED (shown via  $PATH \leq_L STRONGLY-CONNECTED$ )

## STRONGLY-CONNECTED $\in$ NL

A directed graph is strongly connected if every pair of nodes has directed paths in both directions. We design a nondeterministic log-space algorithm:

- Nondeterministically pick a starting node  $s$  (storing  $s$  uses  $O(\log n)$  space)
- For every other node  $v$ :
  - Use the NL algorithm for PATH to verify there's a path from  $s$  to  $v$

- Use the same PATH algorithm to verify there's a path from  $v$  to  $s$
- Accept if all verifications pass; otherwise reject

Space complexity:  $O(\log n)$  for storing node indices and PATH computation rule.

## **PATH $\leq_L$ STRONGLY-CONNECTED**

We reduce PATH (directed s-t connectivity) to STRONGLY-CONNECTED in log space.

### **Construction:**

Given PATH instance  $\langle G, s, t \rangle$ , construct  $G'$  by:

- Keeping all original edges of  $G$
- Adding edge  $t \rightarrow s$
- For every node  $v$ , adding edges  $v \rightarrow s$  and  $s \rightarrow v$

### **Correctness:**

- If PATH accepts: There's an s-t path in  $G$ . Combined with added edges, all nodes become mutually reachable via  $s$ , making  $G'$  strongly connected.
- If PATH rejects: No s-t path exists. The added edges don't create new s-t paths, so  $G'$  cannot be strongly connected.

### **Log-space reduction:**

The reduction doesn't explicitly construct  $G'$ . Instead, when checking edges in  $G'$  (to decide whether it is strongly-connected):

- Check if  $u \rightarrow v$  exists in original  $G$ , OR
  - Check if  $(u = t \wedge v = s)$ , OR  $(v = s)$ , OR  $(u = s)$
- All checks use  $O(\log n)$  space to store node indices.

## **Conclusion**

Since  $\text{STRONGLY-CONNECTED} \in \text{NL}$  and  $\text{PATH} \leq_L \text{STRONGLY-CONNECTED}$  (where PATH is NL-complete), STRONGLY-CONNECTED is NL-complete.

**Prove that  $\text{TIME}(2^n) = \text{TIME}(2^{n+1})$ .**

定义:  $\text{TIME}(2^n)$ 也就是可以在这个时间内判定的语言的集合

即证明: 这两个时间复杂度类包含的问题是一样的

常数因子在O符号中可以被忽略 (constant factors are ignored in big-O notation)

# Proof that $\text{TIME}(2^n) = \text{TIME}(2^{n+1})$

In computational complexity theory, the complexity class  $\text{TIME}(t(n))$  denotes the set of all decision problems that can be solved by a deterministic Turing machine within time  $O(t(n))$ .

We aim to prove that:

$$\text{TIME}(2^n) = \text{TIME}(2^{n+1})$$

## Proof

Note that:

$$2^{n+1} = 2 \times 2^n$$

Therefore, for the time complexity:

$$O(2^{n+1}) = O(2 \times 2^n) = O(2^n)$$

since constant factors are ignored in big-O notation.

This implies that any problem solvable in  $O(2^{n+1})$  time is also solvable in  $O(2^n)$  time, and vice versa. Hence, the sets  $\text{TIME}(2^n)$  and  $\text{TIME}(2^{n+1})$  are identical.

Thus, we conclude:

$$\text{TIME}(2^n) = \text{TIME}(2^{n+1})$$