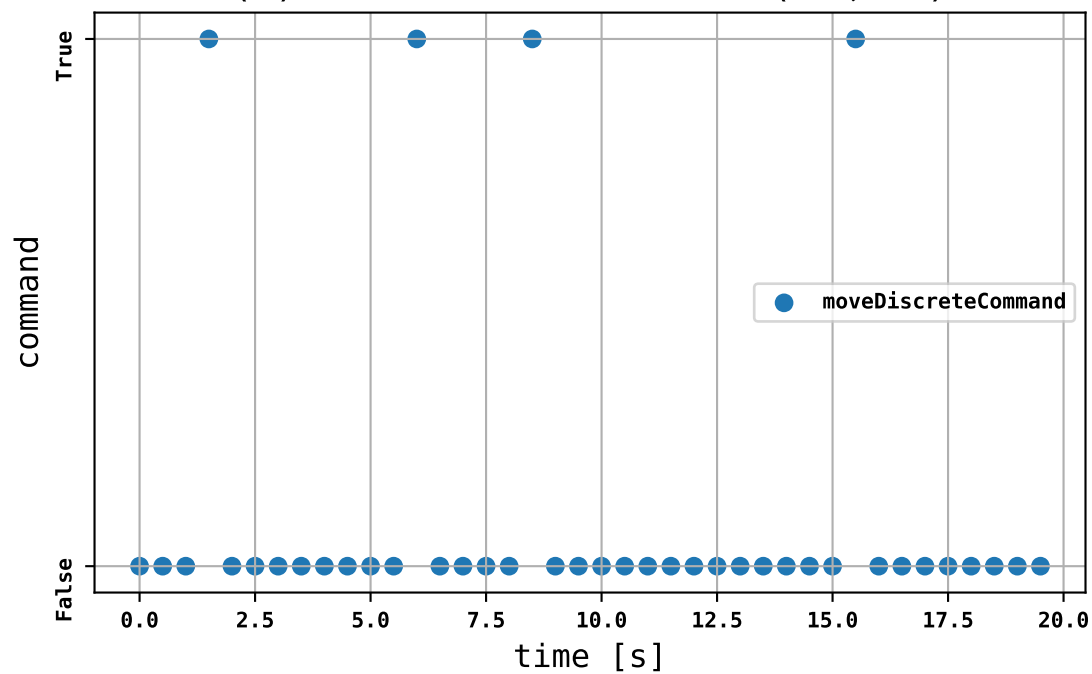
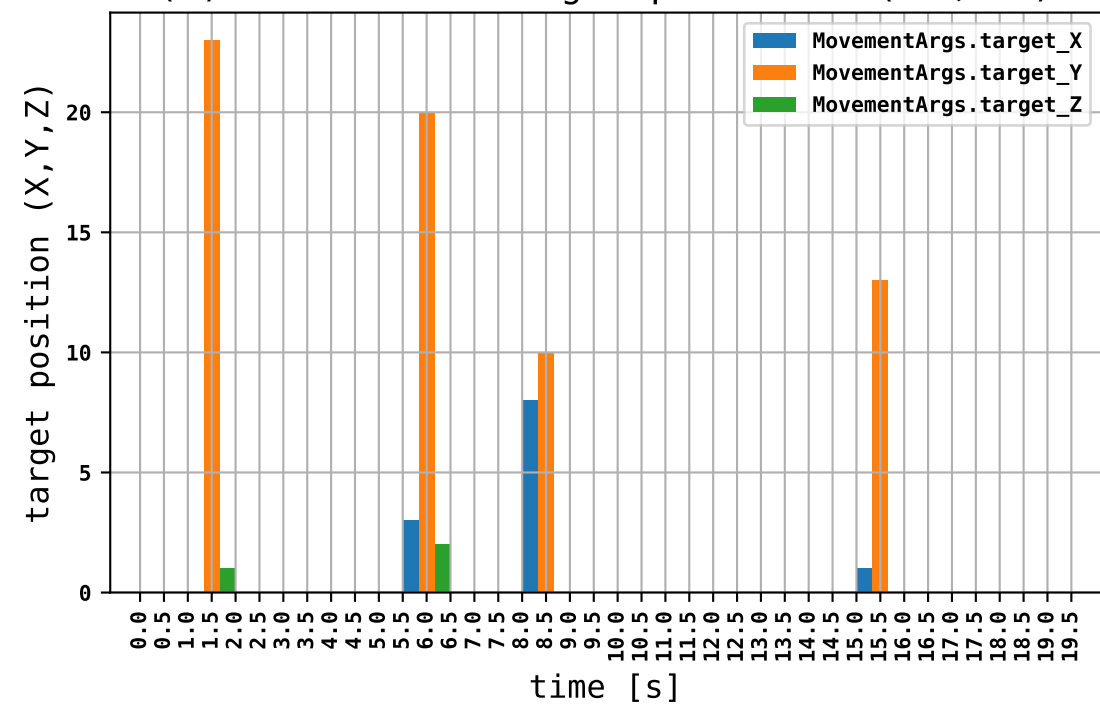


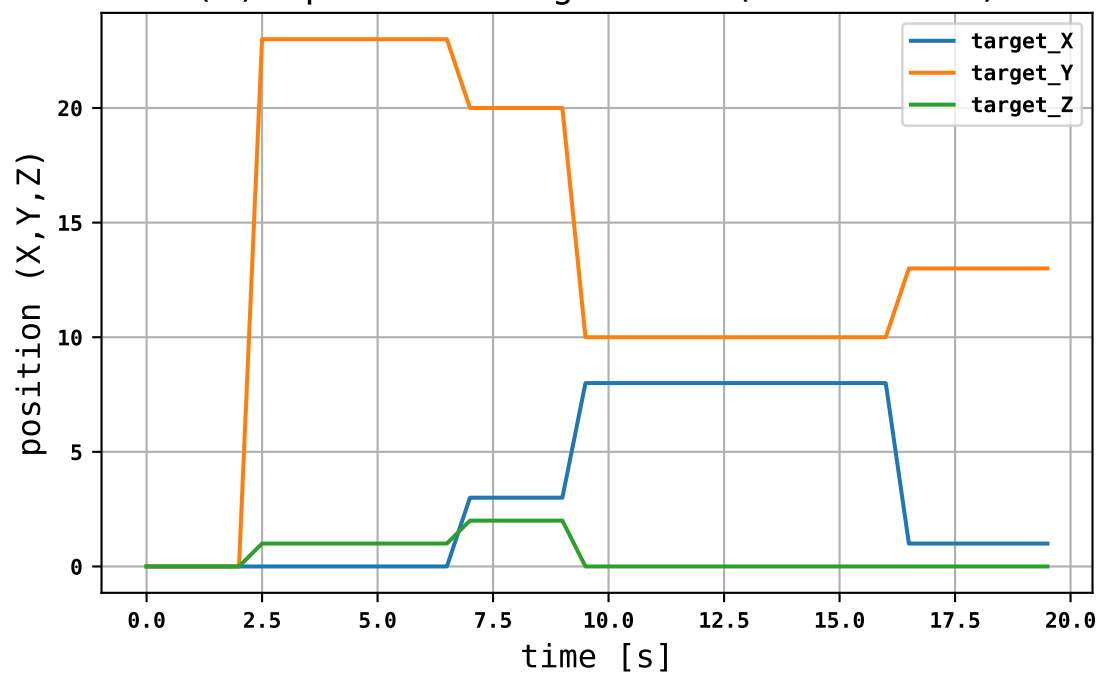
(1) Controller commands (RMQFMU)



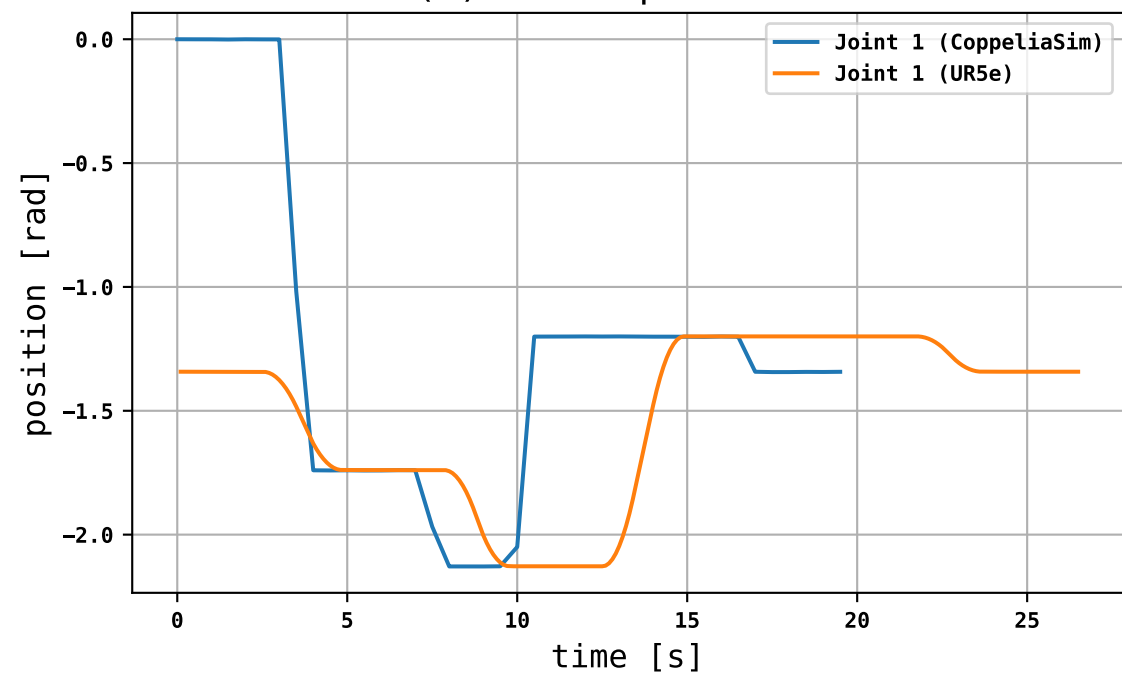
(2) Controller target positions (RMQFMU)



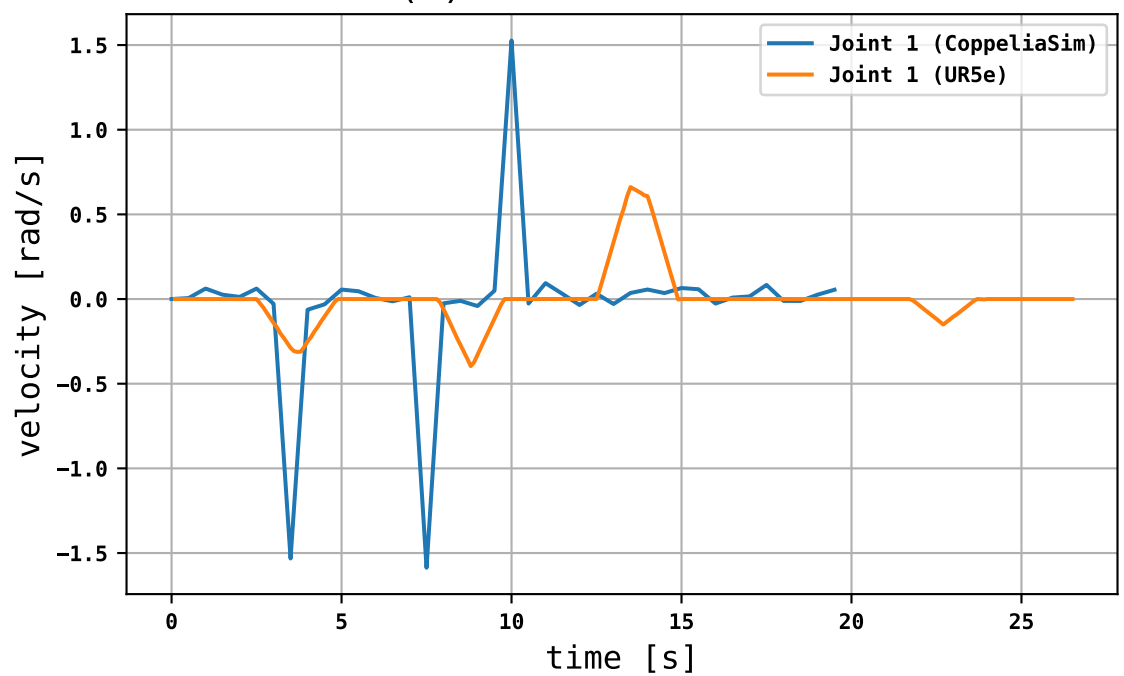
(3) Operation arguments (d-modelFMU)



(4) Joint positions



(5) Joint velocities



(6) Joint forces

