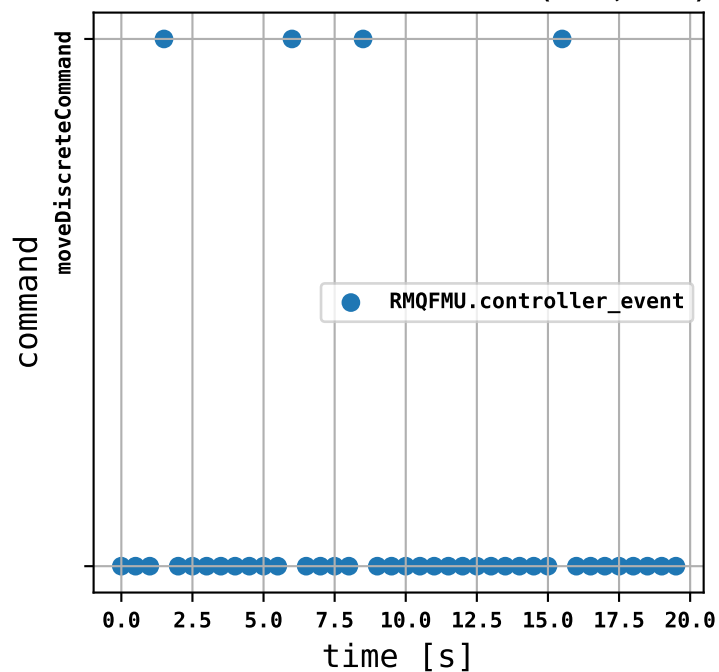
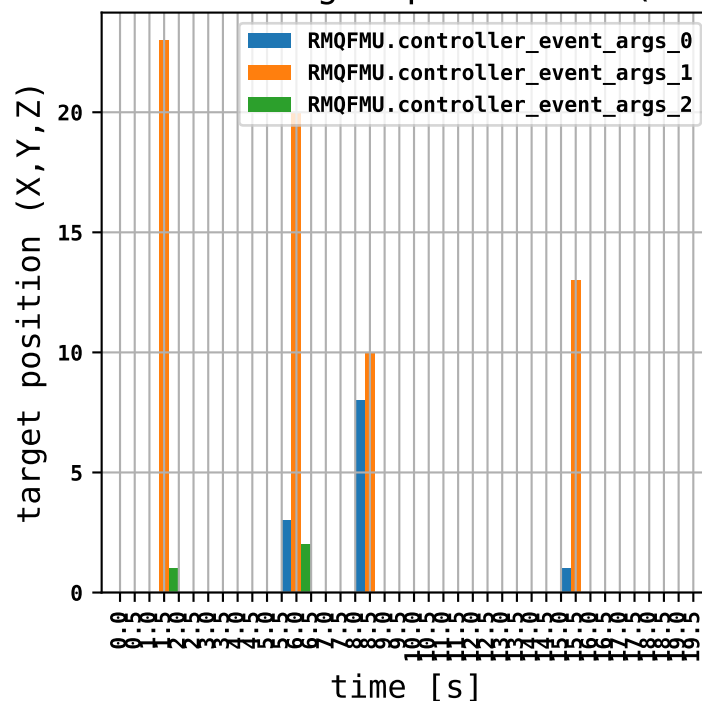


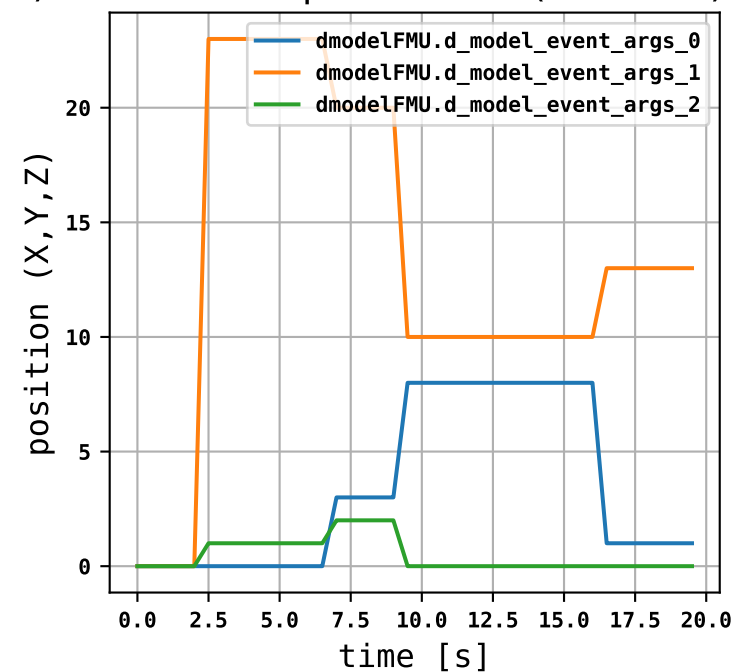
Controller commands (RMQFMU)



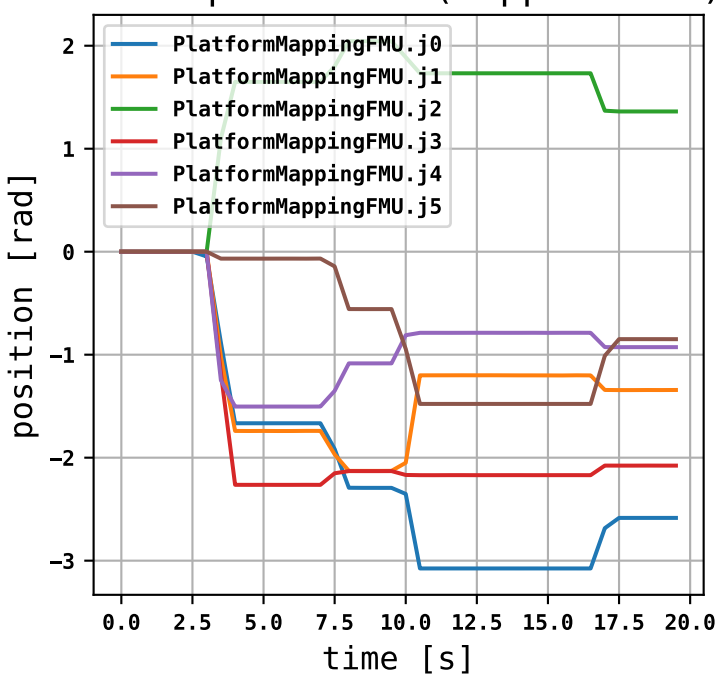
Controller target positions (RMQFMU)



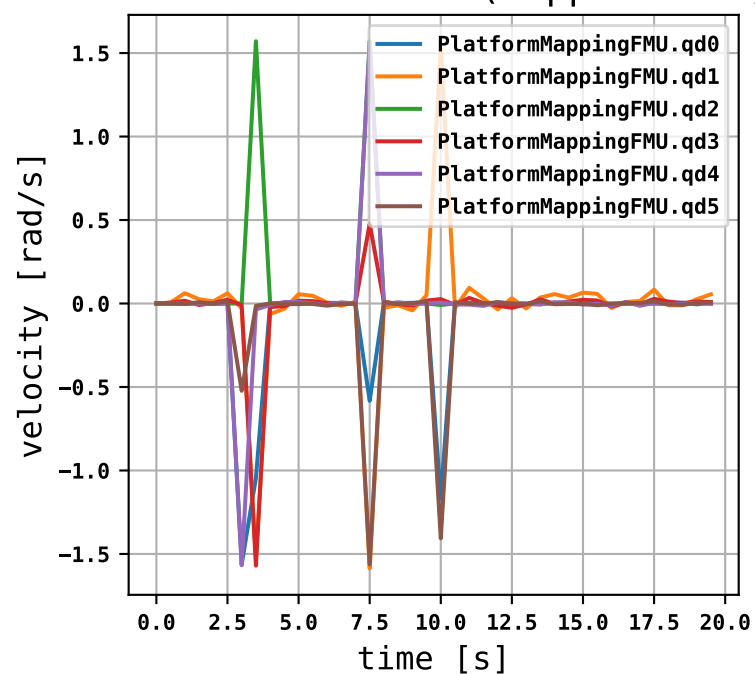
Discrete positions (D-Model)



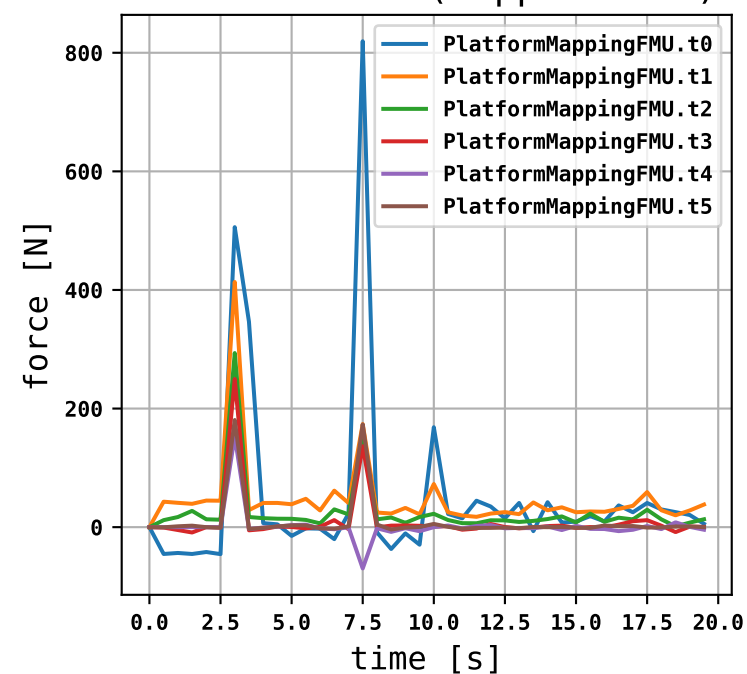
Joint positions (CoppeliaSim)



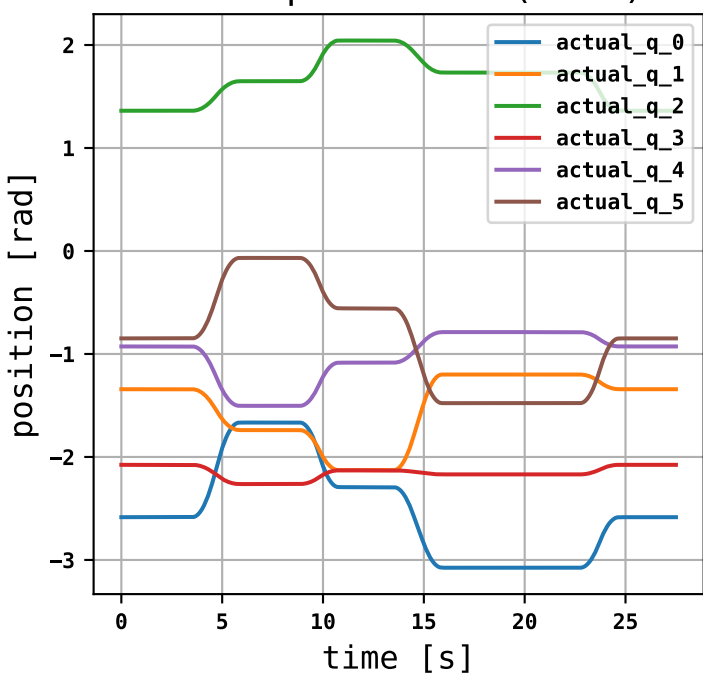
Joint velocities (CoppeliaSim)



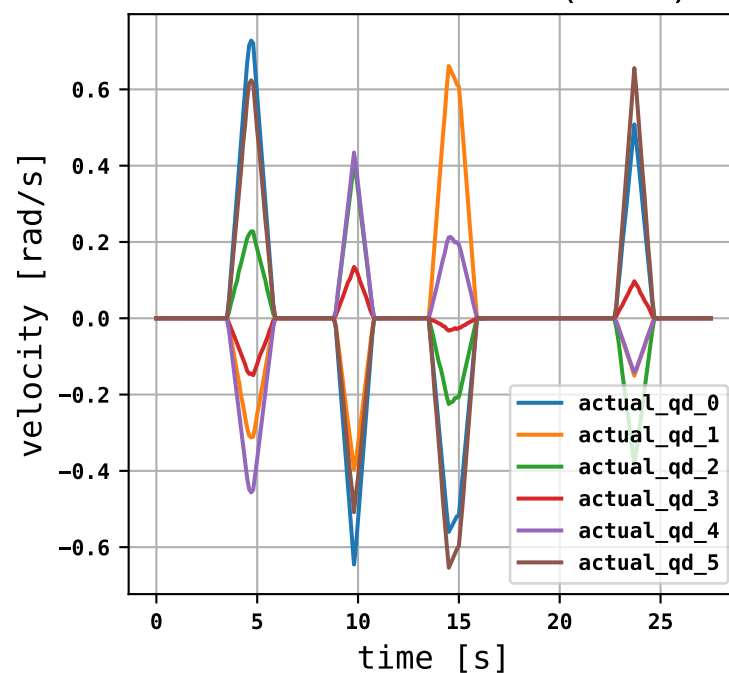
Joint forces (CoppeliaSim)



Joint positions (UR5e)



Joint velocities (UR5e)



Joint forces (UR5e)

