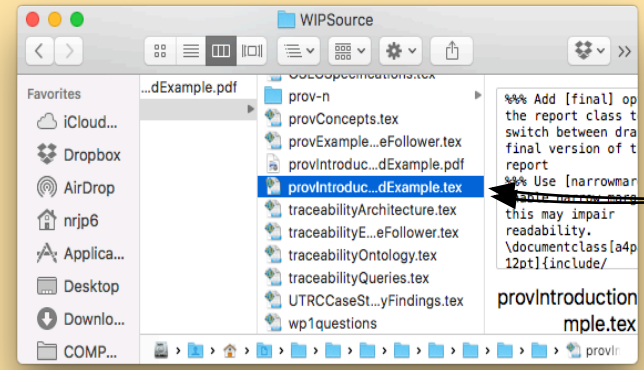
File System



OSLC_Elab

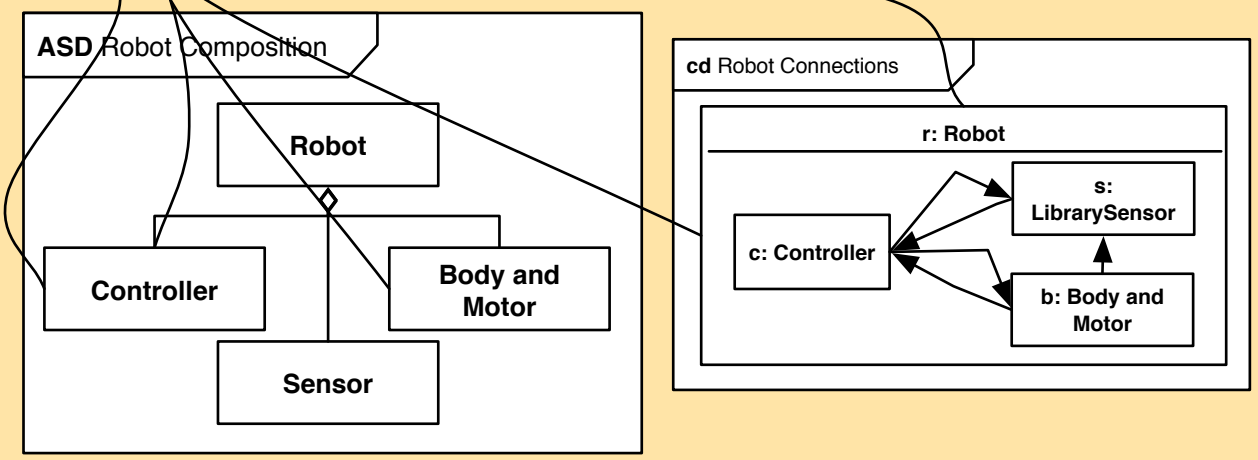
Line Follow Robot Excel Requirement Document

Context ID	Context Name
C1	System Engineer
C2	Sensor Manufacturer
C3	Actuator Manufacturer

Requirement ID	Name	Description	Trace to Source
R1	Sense Line	The robot must sense a black line	URI#1
R2	Robot Speed	The robot must move faster than 5cm/sec	URI#2

Requirement ID	Stakeholder ID
R1	C1
R1	C2
R2	C1
R2	C3

OSLC_Sat



Line Follow Robot SysML Architectural Model