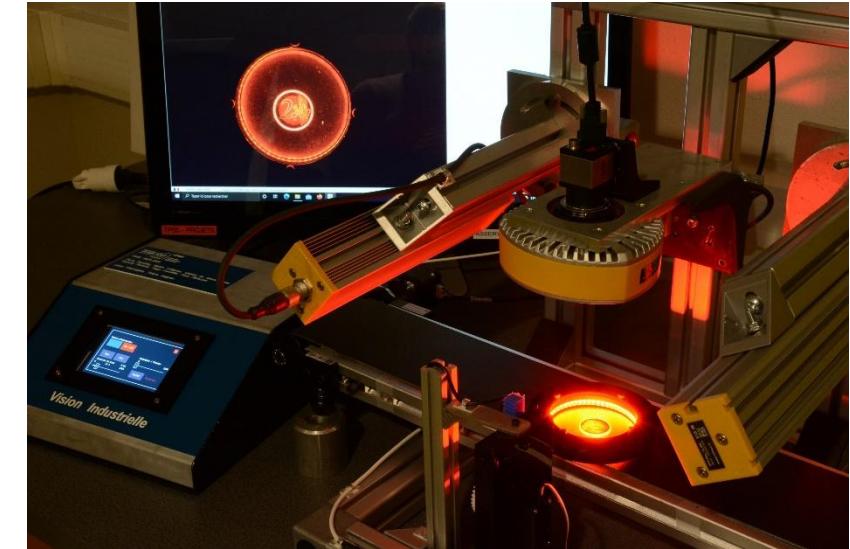
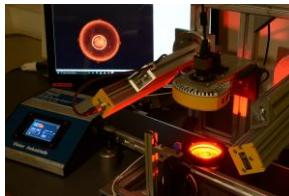


Traitements d'image

Pré-traitement / Segmentation / Classification





Traitement d'images



Image brute 'RAW' / Caméra

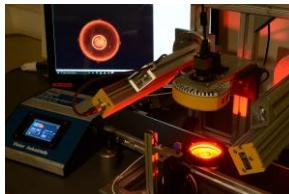
- **Bruitée**
- Mauvais contraste
- Eclairage non uniforme
- ...



Image souhaitée / Contours bien définis

- Zones homogènes
- Transitions nettes

Objectif



Traitement d'images

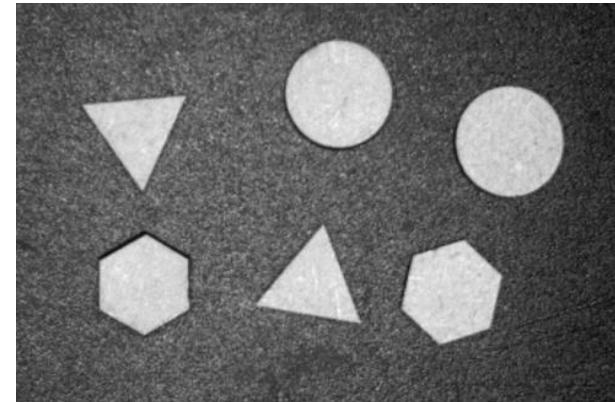


Image brute 'RAW' / Caméra

- **Bruitée**
- Mauvais contraste
- Eclairage non uniforme
- ...

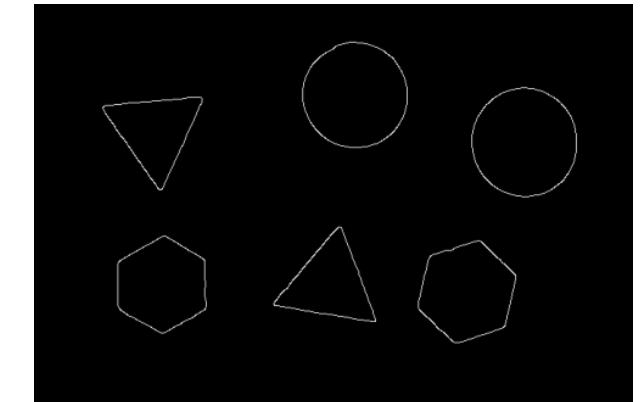
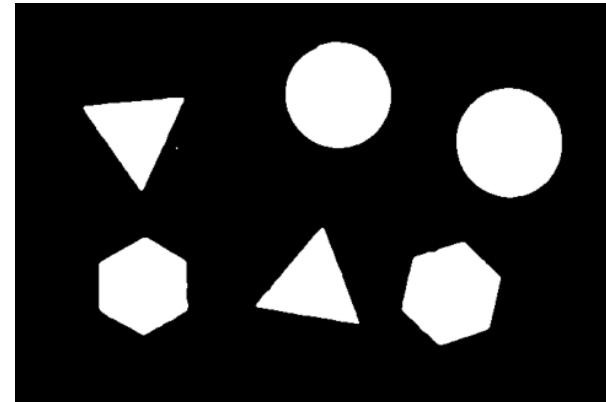
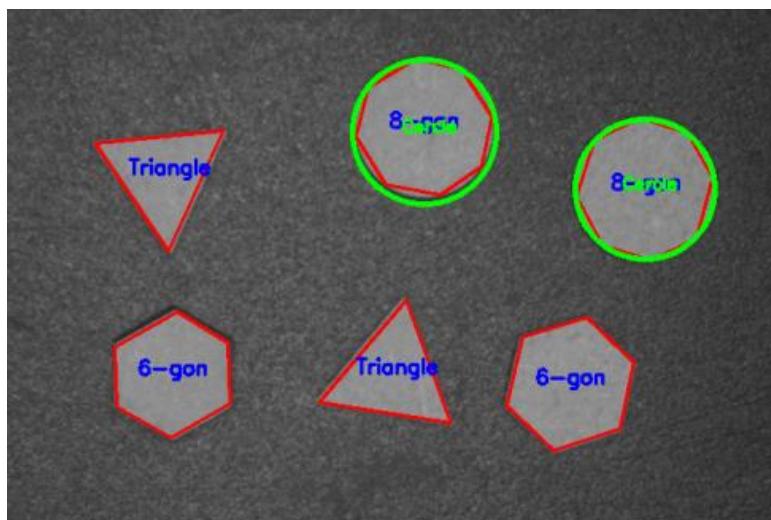
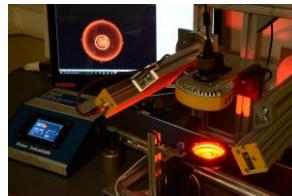


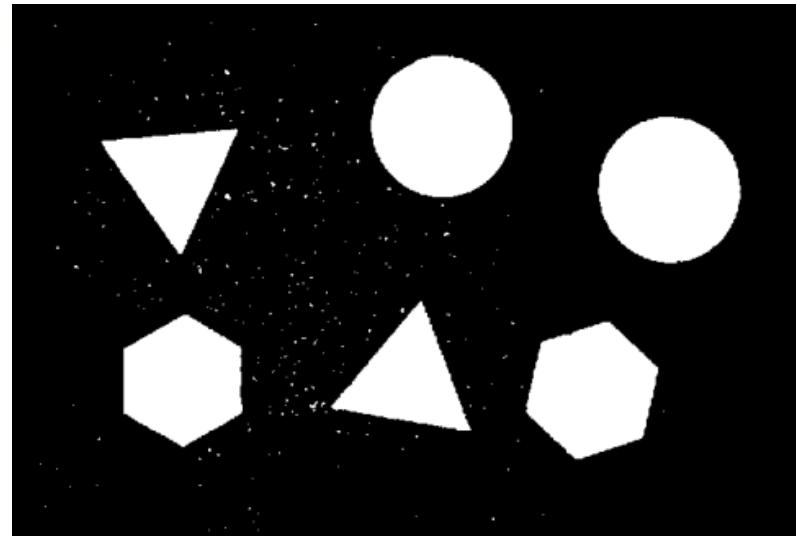
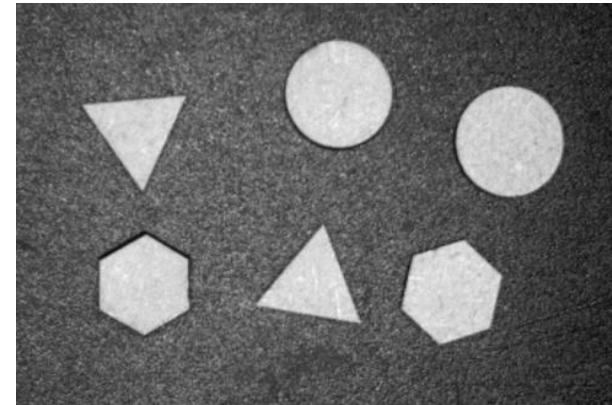
Image souhaitée / Contours bien définis

- Zones homogènes
- Transitions nettes

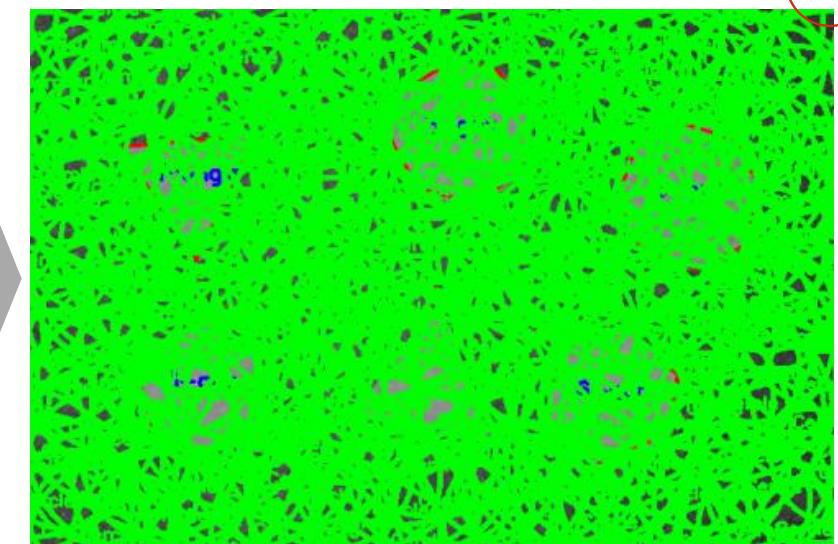
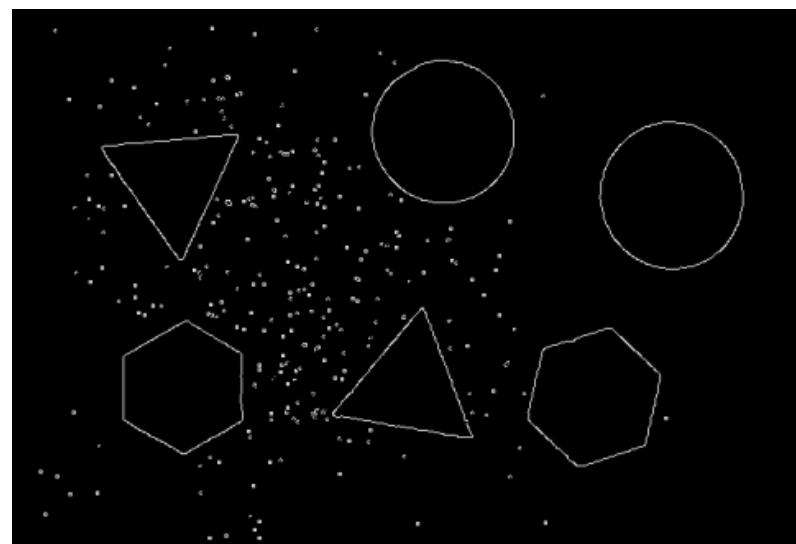
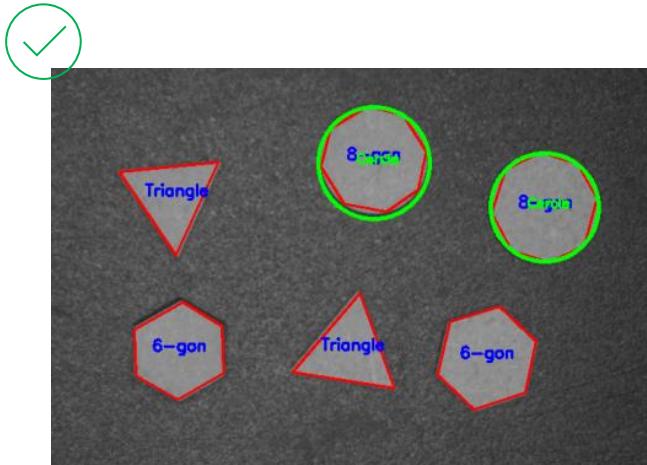


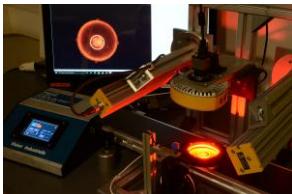


Traitement d'images



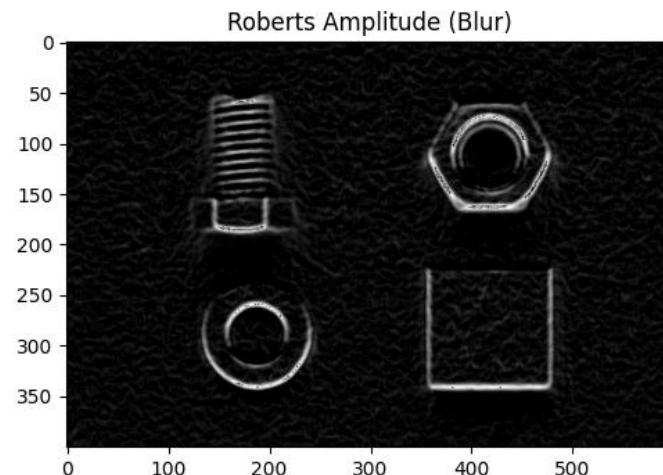
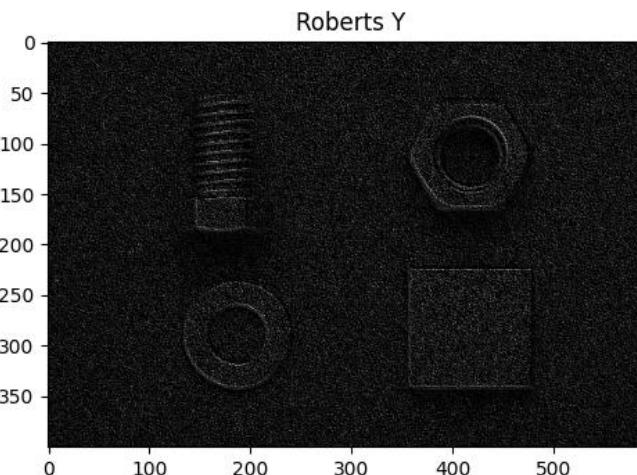
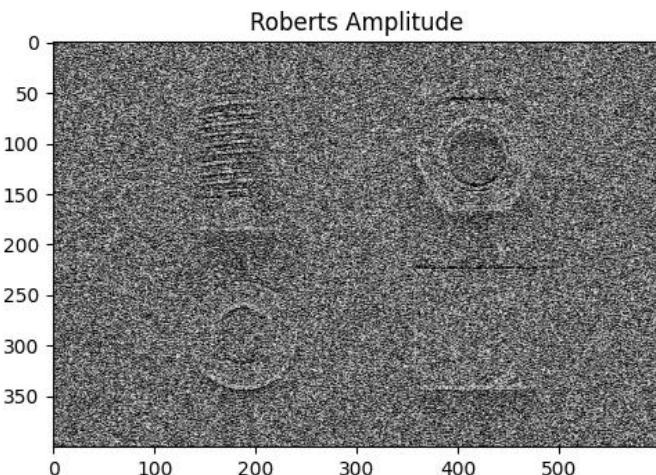
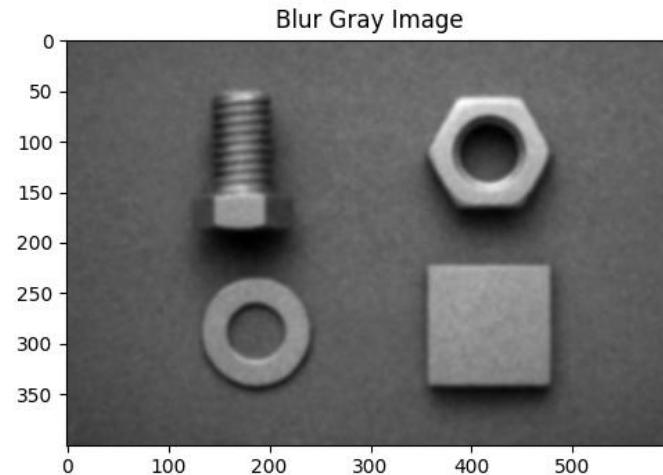
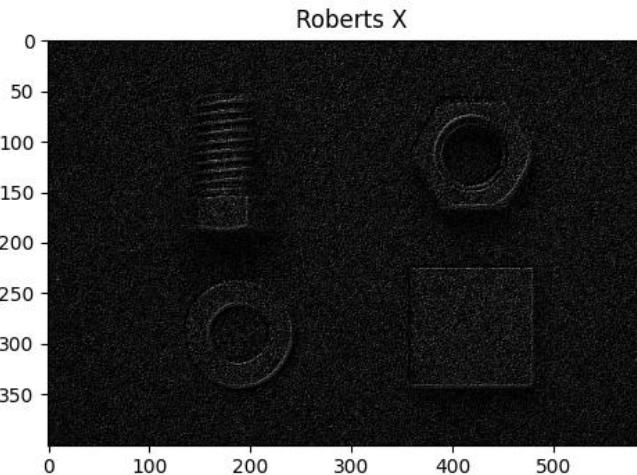
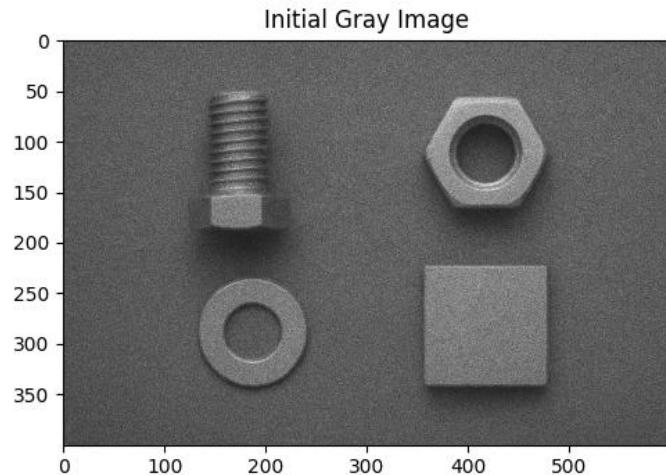
Mauvais traitement

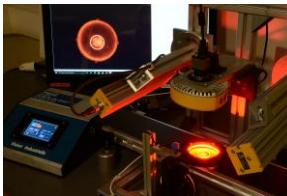




Traitement d'images

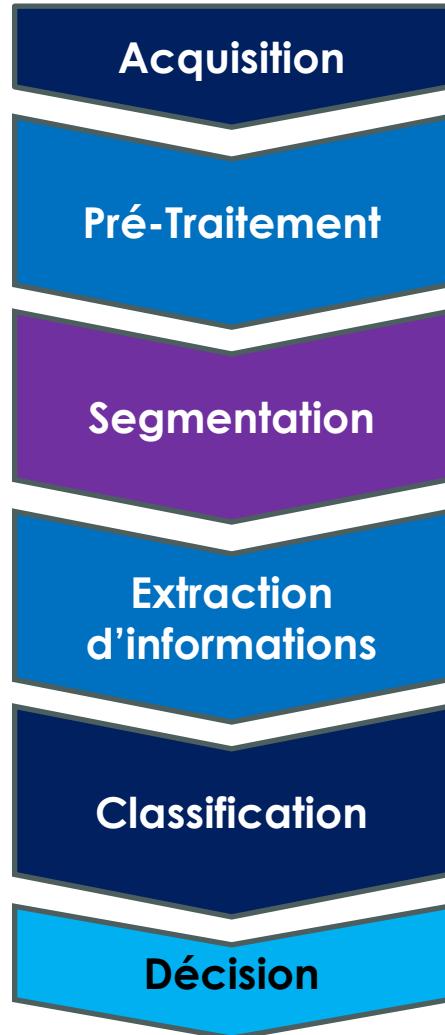
Exemple industriel





Traitement d'images

Objectif



Eclairage, caméra...

Filtrage / Réduction bruit
Amélioration contraste
Normalisation

Segmentation

Seuillage
Détection de contours
Sélection de régions d'intérêt

Extraction d'informations

Formes géométriques
Analyse de textures
Zones uniformes

Classification

Détection d'objets
Reconnaissance
Classification

Décision

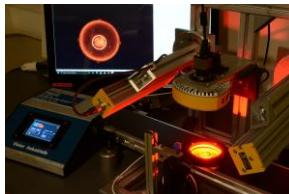
Tolérances, pièce valide/non valide, retour en temps réel...

Améliorer la clarté de l'image / réduire les informations indésirables
Faire ressortir les caractéristiques d'intérêt
Standardiser l'échelle ou l'intensité de l'image

Isoler les objets de la région d'intérêt (ROI)
Séparer les objets de l'arrière-plan
Identifier les limites et les contours
Se concentrer uniquement sur les parties pertinentes de l'image

Extraire des données (taille, forme, position...)
Reconnaitre des formes, des symboles ou des points d'intérêt

Identifier et nommer des objets
Vérifier si les données mesurées sont en accord avec un cahier des charges
Catégoriser des objets dans des groupes spécifiques



Traitement d'images

Images numériques

Image continue

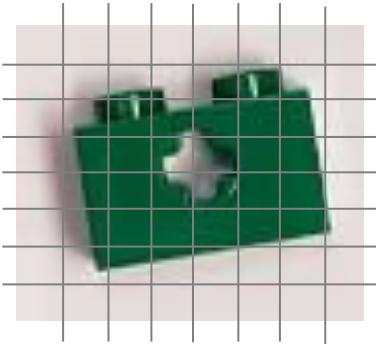
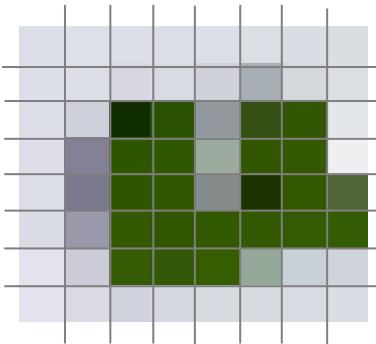


Image numérique

Représentation d'une **image**
sous forme numérique

*Pour être **sauvegardée**, **traitée**
et **affichée** par des ordinateurs
ou des systems numériques.*

Image numérique : projection sur une matrice d'une image continue



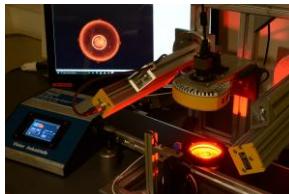
8 x 8 grid



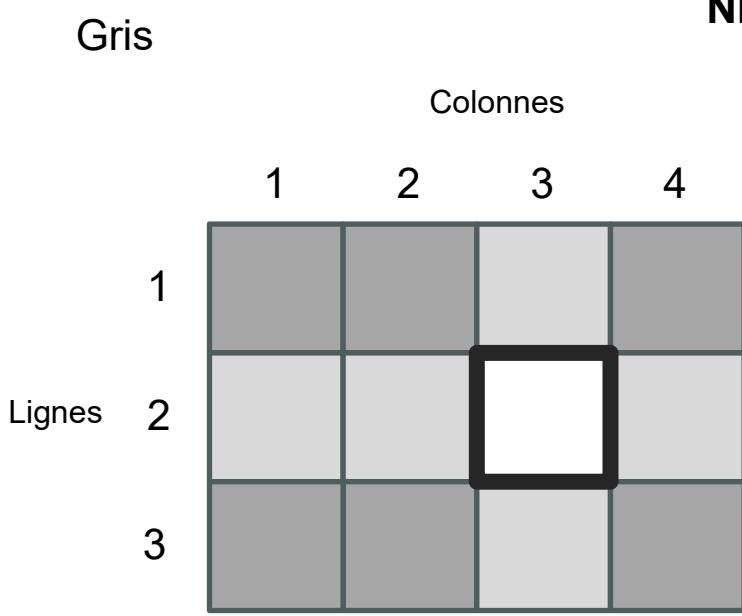
16 x 16 grid



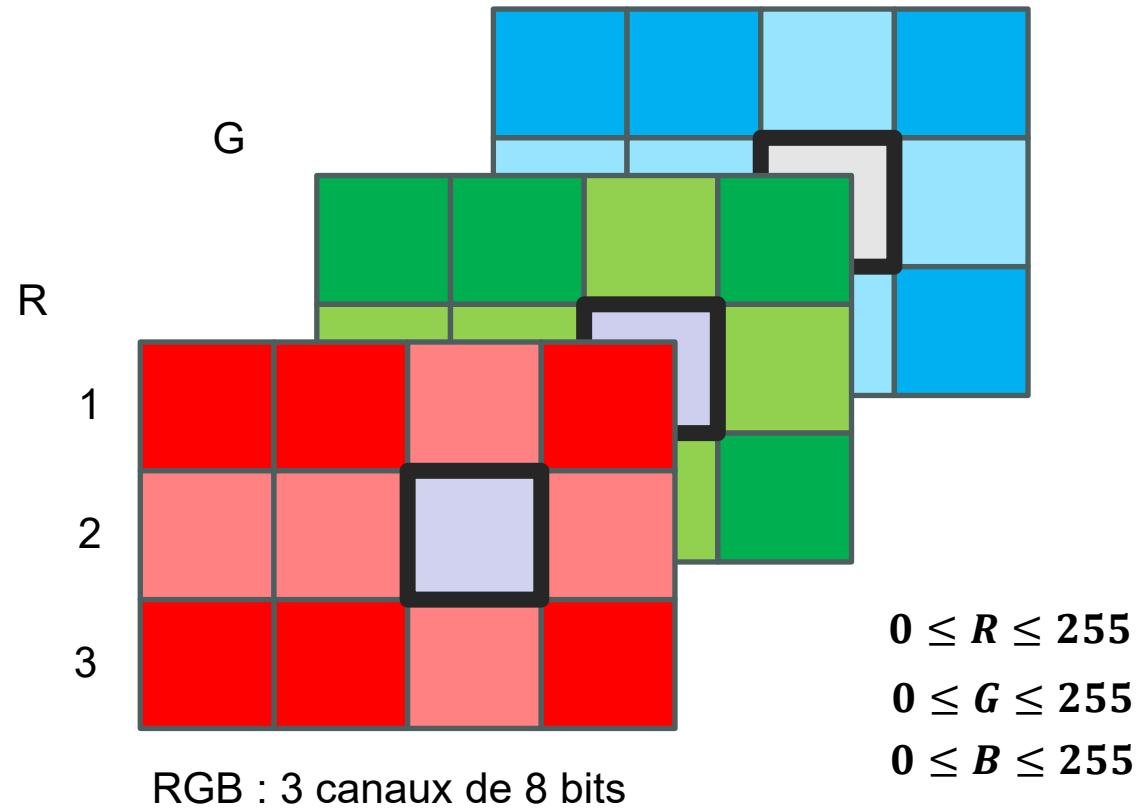
32 x 32 grid

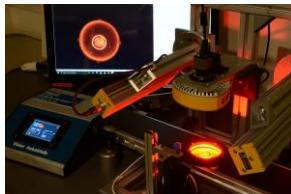


Traitement d'images



Chaque pixel est converti sur **n** bits.





Traitement d'images

OpenCV

Open Source Computer Vision

Une bibliothèque de **traitement d'images**
et de **Machine learning**

Développés sur de *multiple environnement*,
comme Python, C++, Java, and MATLAB



<https://opencv.org>

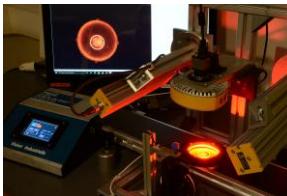


- Traitement d'images**
- Reconnaissance**
- Algorithmes Vidéo**
- Machine Learning**

- Filtrage, détection de contours, transformations...
- Détection d'objets dans des images et des vidéos
- Suivi de mouvement, Reconstruction 3D...
- Classification d'images, Reconnaissance de formes

OpenCV 4.5.0 and higher versions are licensed under the [Apache 2 License](#).

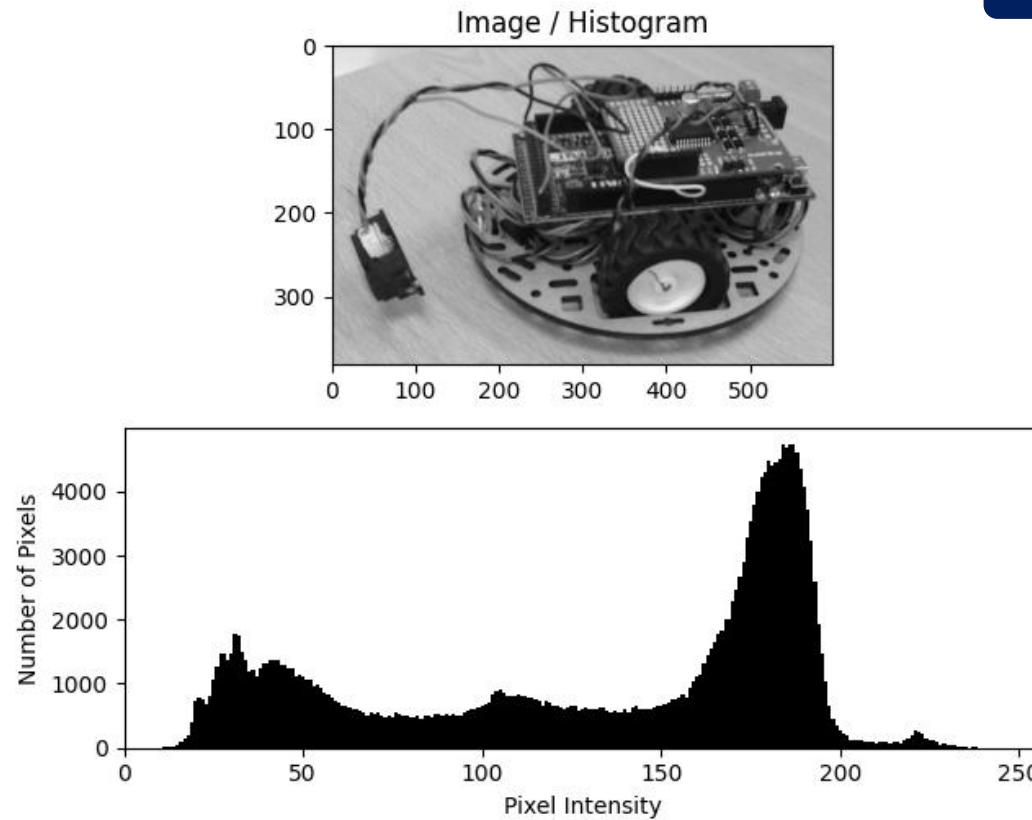
OpenCV 4.4.0 and lower versions, including OpenCV 3.x, OpenCV 2.x, and OpenCV 1.x, are licensed under the [3-clause BSD license](#).



Traitement d'images

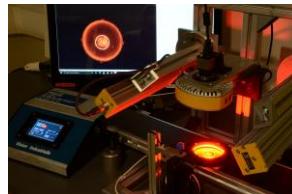
Filtrage par TF

Acquisition

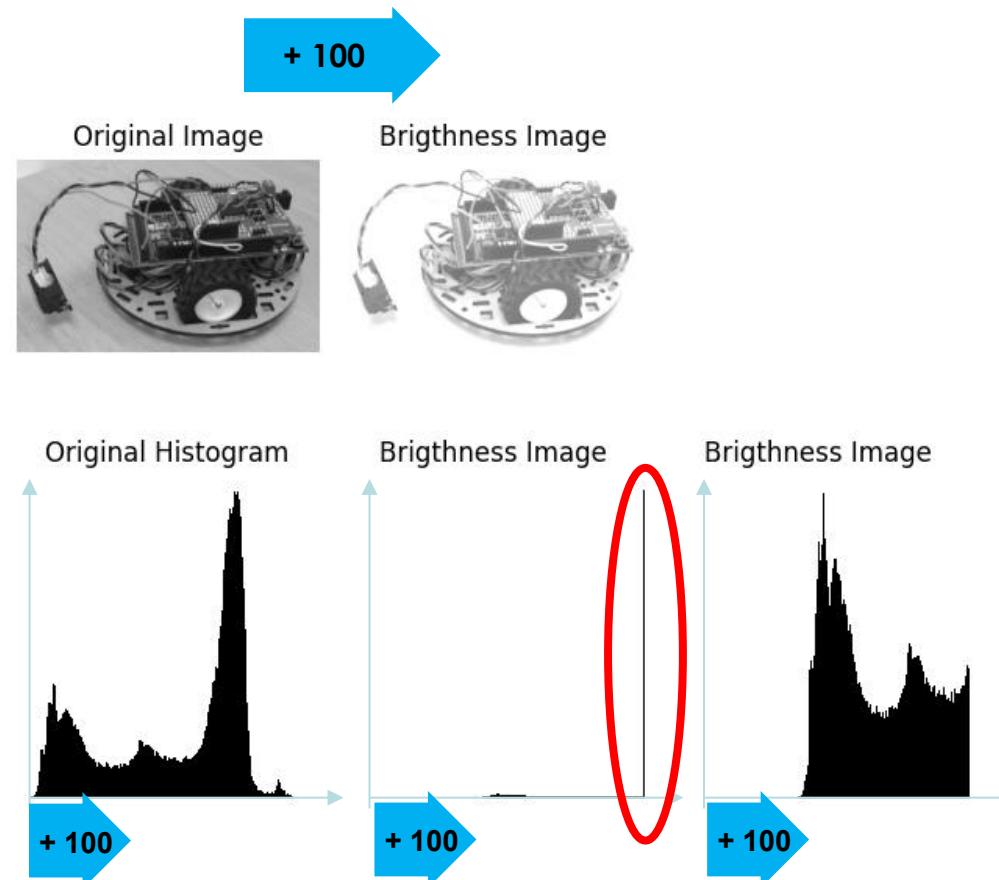


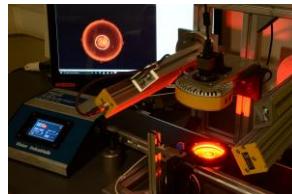
Histogramme

Représentation graphique
montrant la **distribution des**
valeurs de niveaux de gris des
pixels de l'image

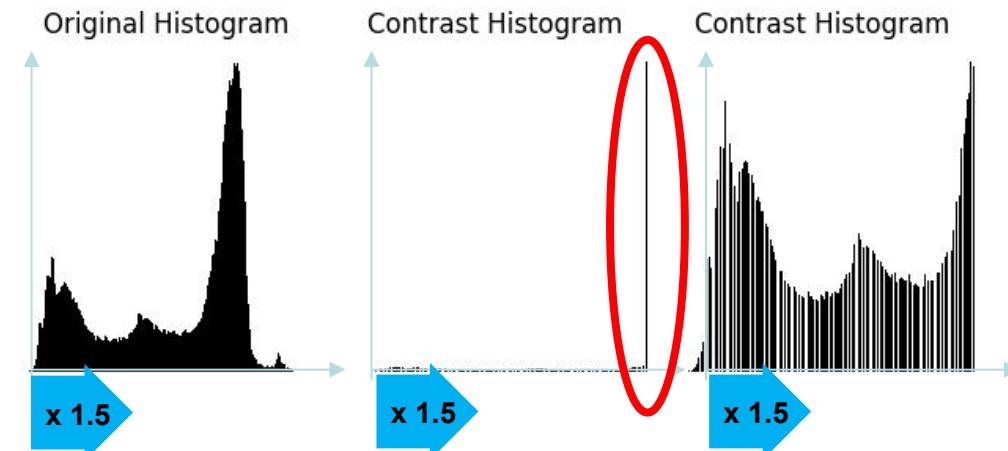
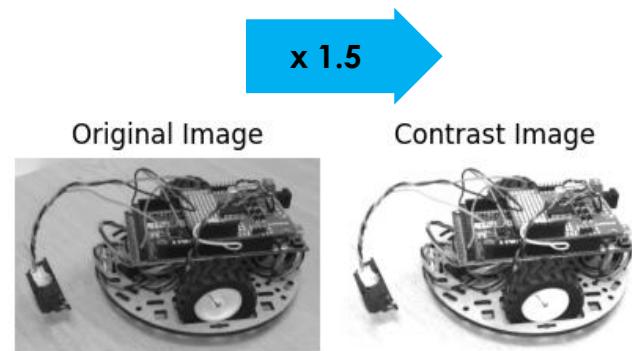


Traitement d'images

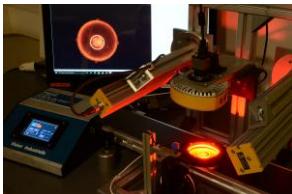




Traitement d'images



Amélioration de l'image



Traitement d'images



kernel

-1	0	-2
1	5	1
-2	0	-1

original image

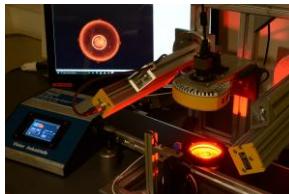
5	8	4	2	3	1	5
9	5	1	8	7	6	2
5	7	1	5	6	8	7
5	8	2	8	4	3	3
5	6	6	7	2	5	1

Filtrage / Convolution

5	8	4	2	3	1	5
9	5	1	8	7	6	2
x -1	x 0	x -2				
5	7	1	5	6	8	7
x 1	x 5	x 1				
5	8	2	8	4	3	3
x -2	x 0	x -1				
5	6	7	2	5	1	

filtered image

$$\begin{aligned} R &= -8 + 0 - 12 + 5 + 30 + 8 - 16 + 0 - 3 \\ R &= 4 \end{aligned}$$

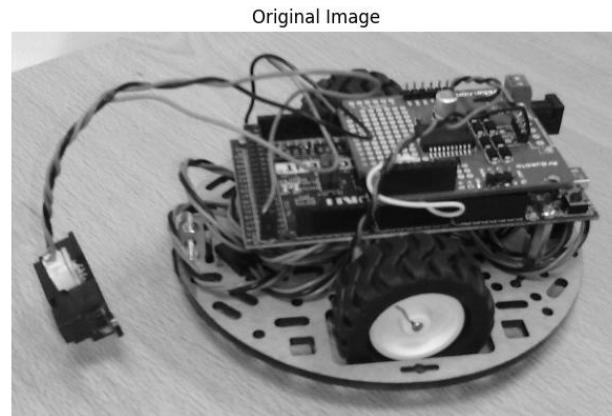


Traitement d'images

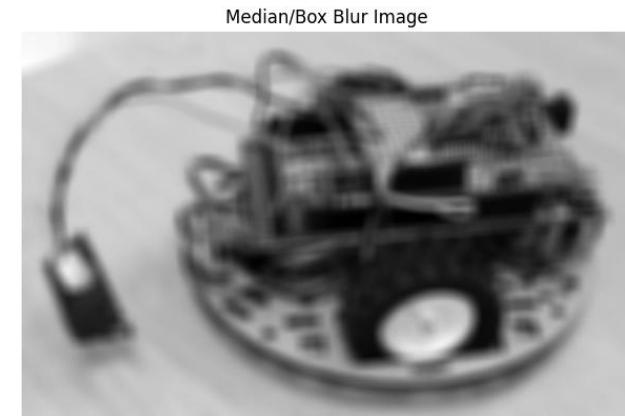
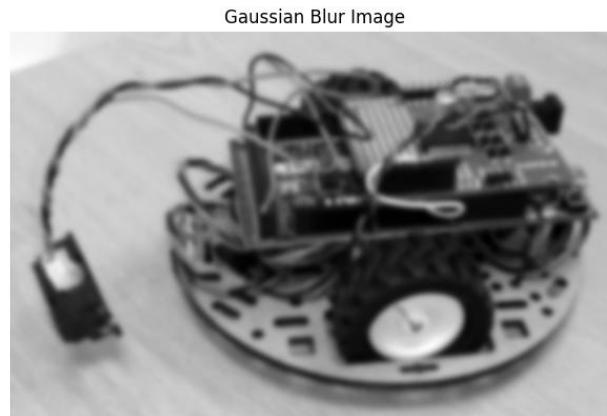
Filtrage / Convolution

Acquisition

Pre Processing



Suppression de détails insignifiants

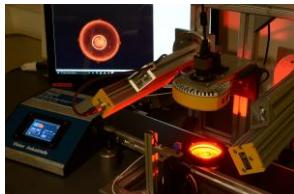


1	4	7	4	1
4	16	26	16	4
7	26	41	26	7
4	16	26	16	4
1	4	7	4	1

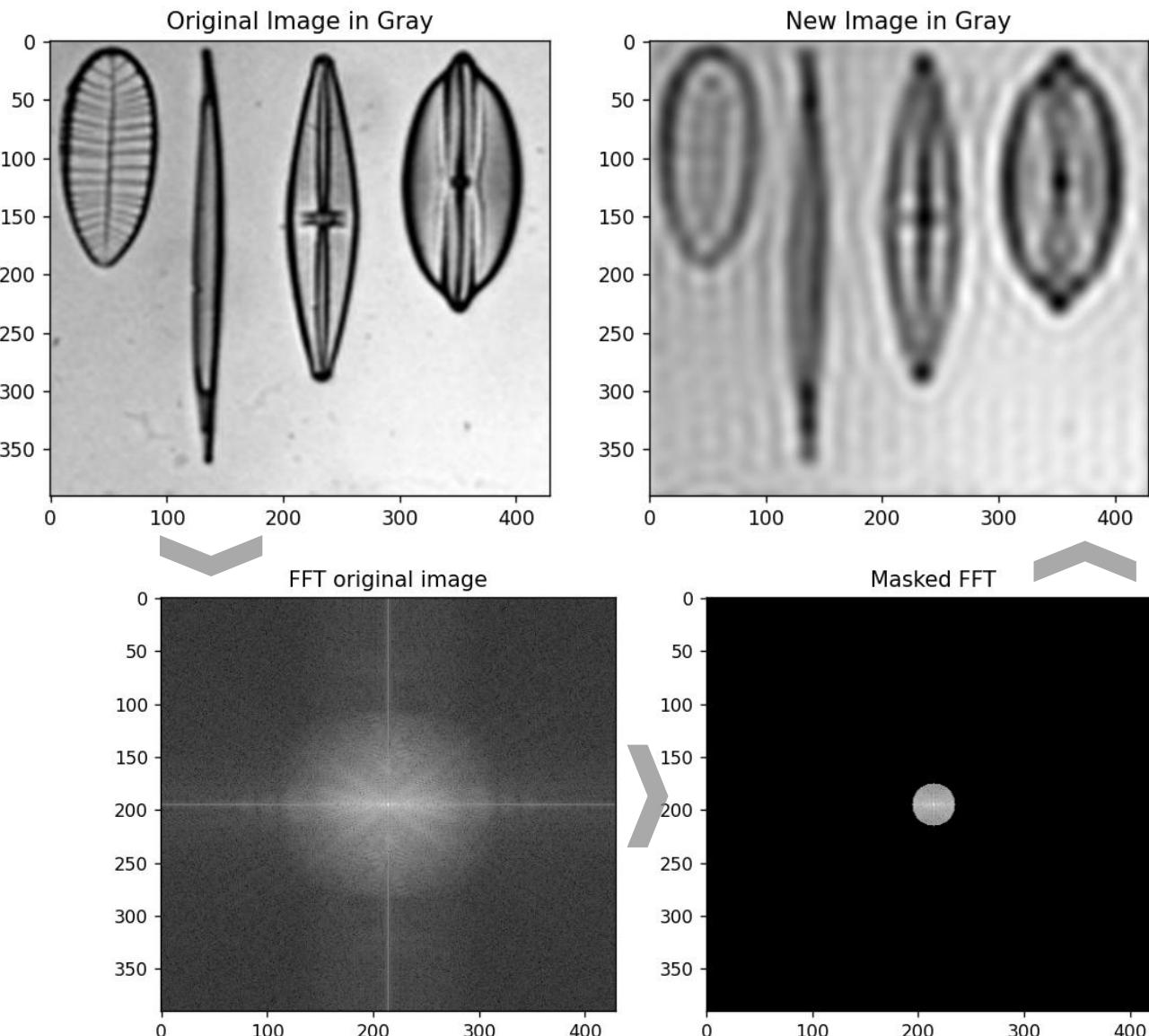
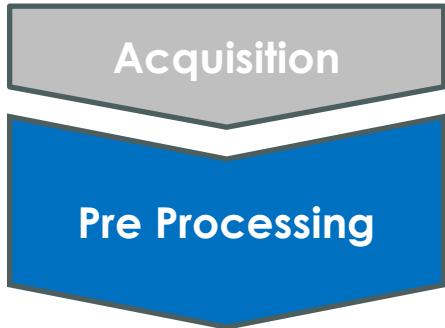
Gaussian Kernel
(x 1/273)

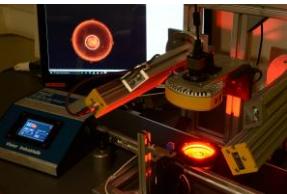
1/9	1/9	1/9
1/9	1/9	1/9
1/9	1/9	1/9

Mean Kernel (x 1/(N*M))

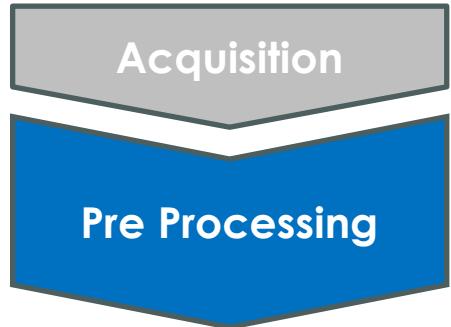


Traitement d'images

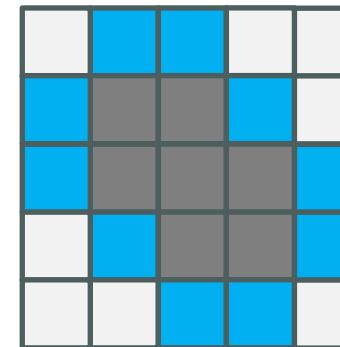
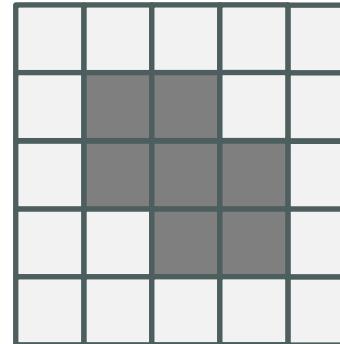
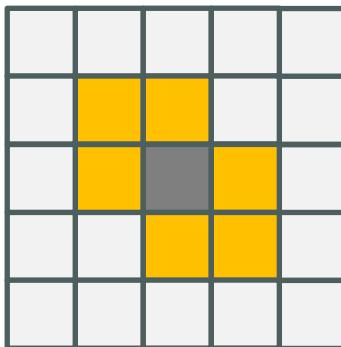




Traitement d'images



- Pixels originaux
- Pixels retirés



Erosion / Dilatation

- Pixels ajoutés

kernel

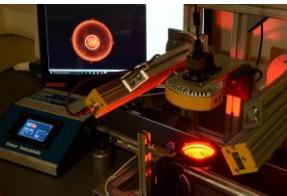
0	1	0
1	1	1
0	1	0

Erosion

Réduire le premier plan en retirant progressivement les pixels le long des contours des objets

Dilatation

Étendre le premier plan en ajoutant des pixels le long des contours des objets



Traitement d'images



Eroded Image



Original Image



Dilated Image



kernel

0	1	0
1	1	1
0	1	0

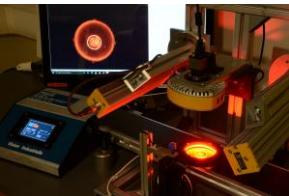
Erosion

Réduire le premier plan en retirant progressivement les pixels le long des contours des objets

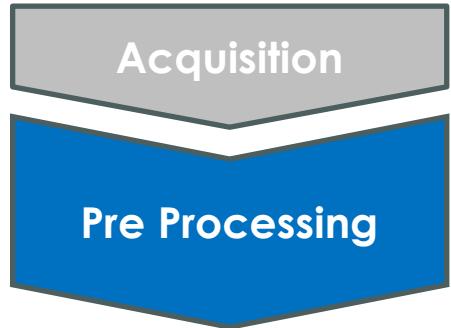
Dilatation

Étendre le premier plan en ajoutant des pixels le long des contours des objets

Erosion / Dilatation



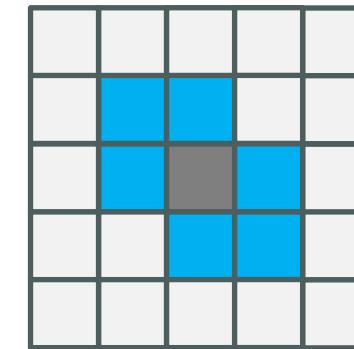
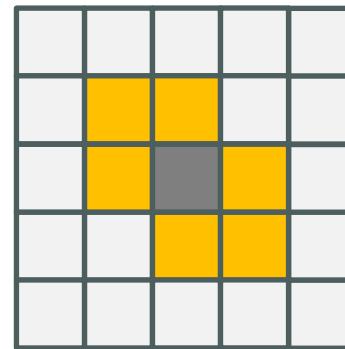
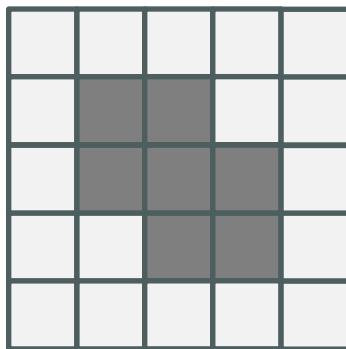
Traitement d'images



- Original pixels
- Removed pixels

Ouverture / Fermeture

- Added pixels



kernel

0	1	0
1	1	1
0	1	0

Ouverture

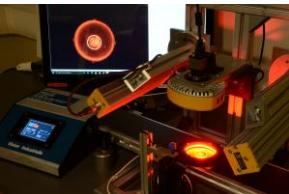
Erosion puis Dilatation

Retire des petits objets

Fermeture

Dilatation puis Erosion

Remplit des petites zones



Traitement d'images



Opening Image



Original Image



Closing Image



kernel

0	1	0
1	1	1
0	1	0

Ouverture

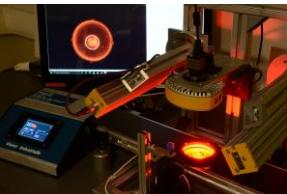
Erosion puis Dilatation

Retire des petits objets

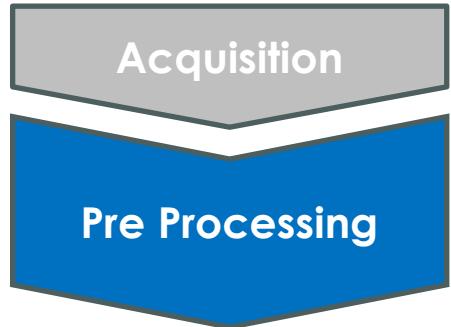
Fermeture

Dilatation puis Erosion

Remplit des petites zones



Traitement d'images



Opening Image



Original Image



Closing Image



kernel

0	1	0
1	1	1
0	1	0

Ouverture

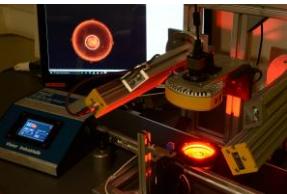
Erosion puis Dilatation

Retire des petits objets

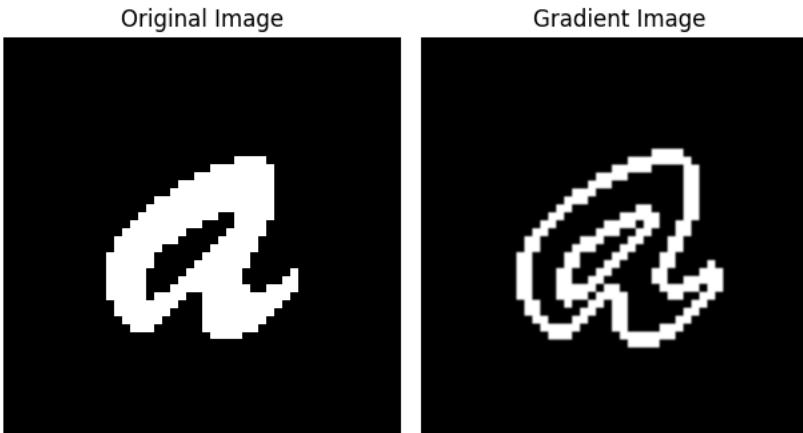
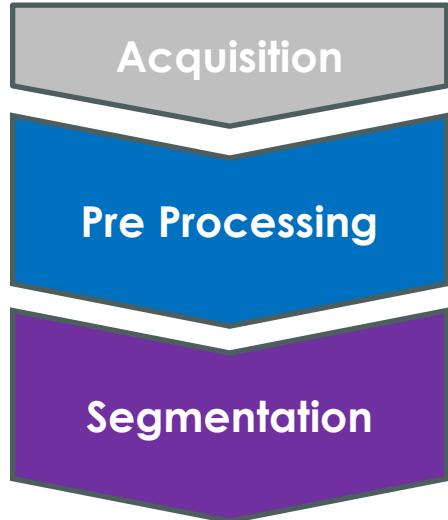
Fermeture

Dilatation puis Erosion

Remplit des petites zones



Traitement d'images



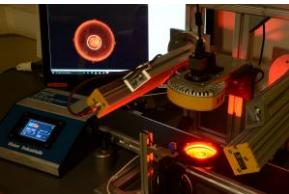
kernel

0	1	0
1	1	1
0	1	0

Gradient

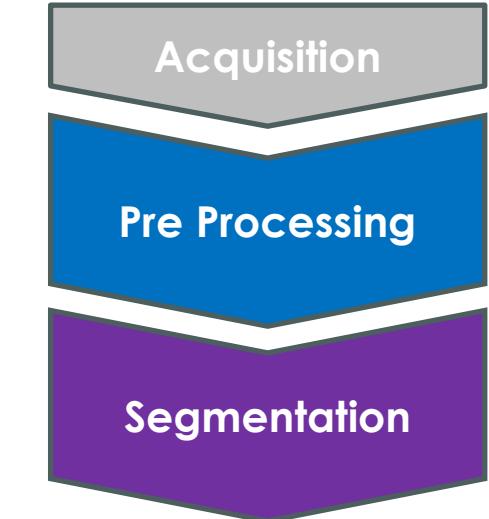
Difference entre une **dilatation** et une **érosion**

Classification des pixels : scène (background) ou objets (foreground) ?



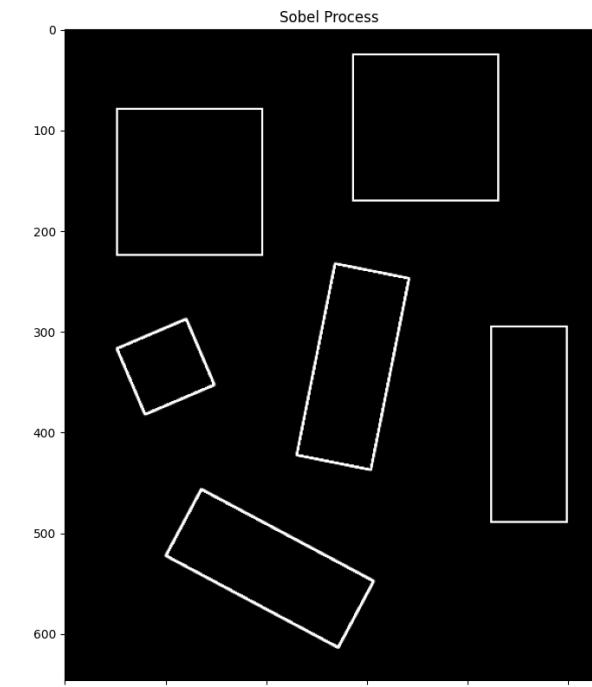
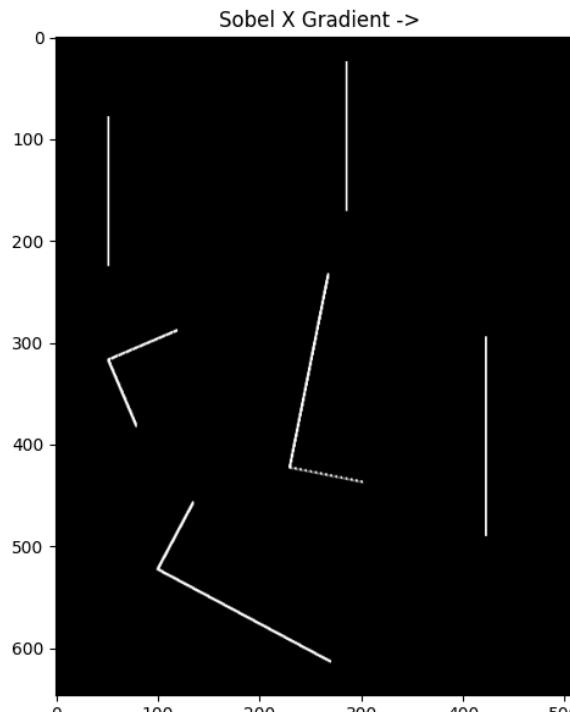
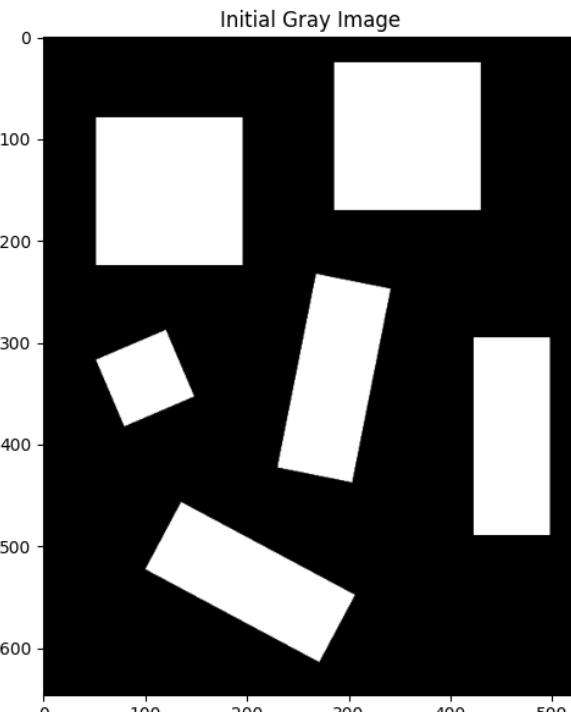
Traitement d'images

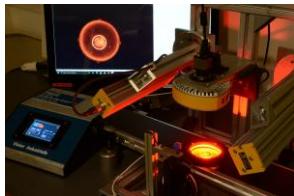
Opérateur de Sobel



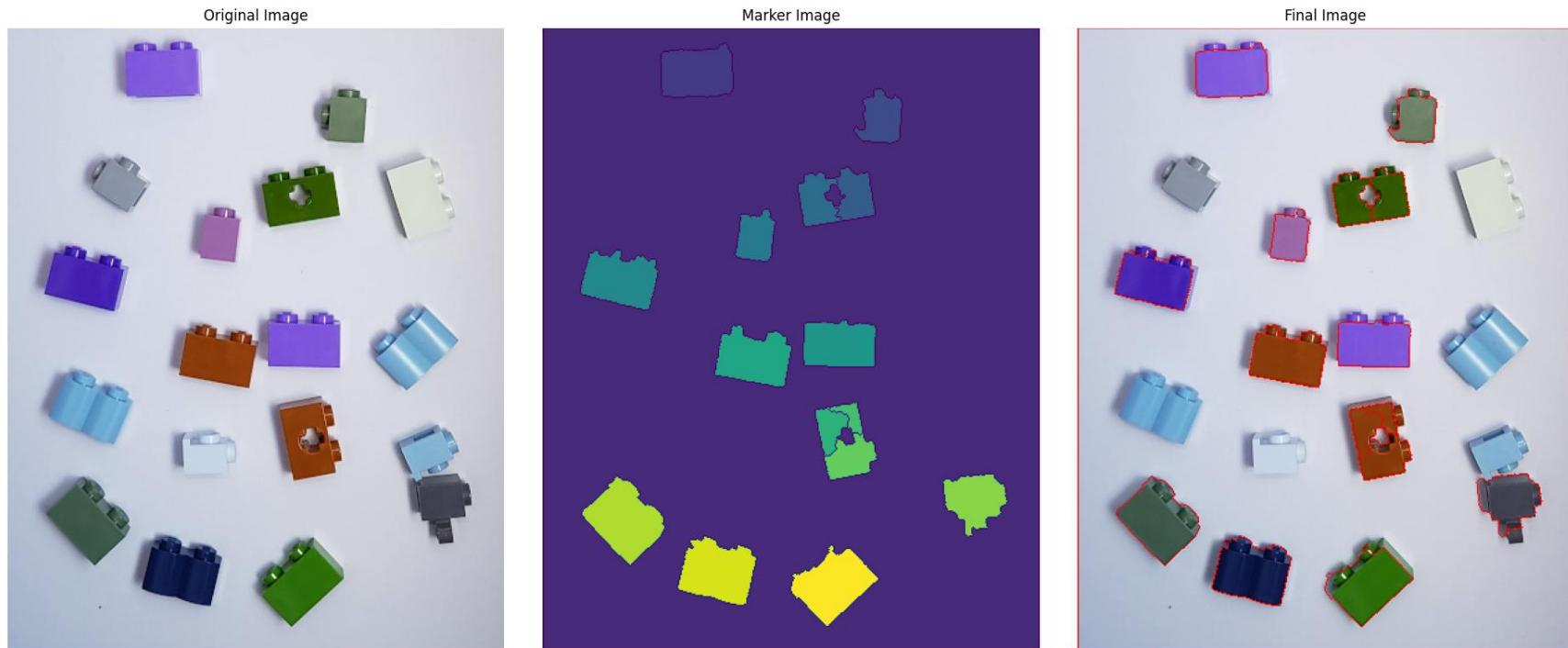
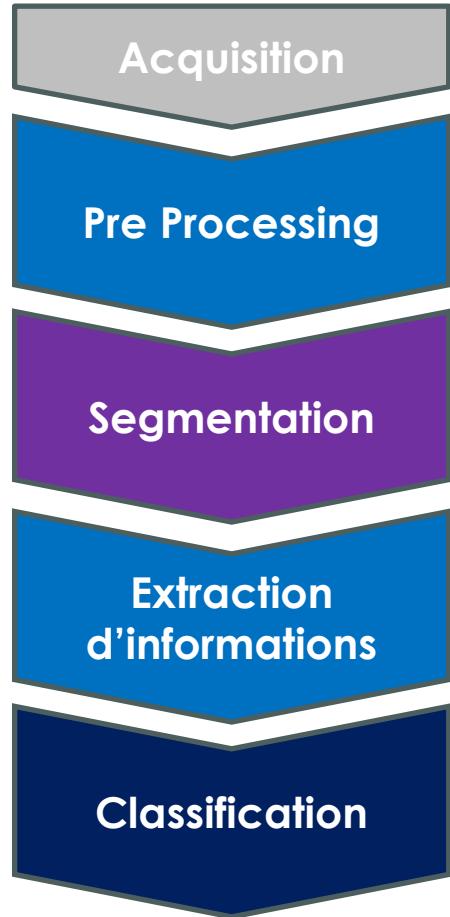
kernel

-1	0	1
-2	0	2
-1	0	1

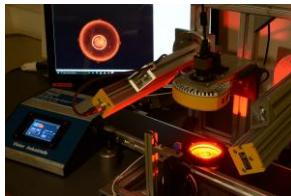




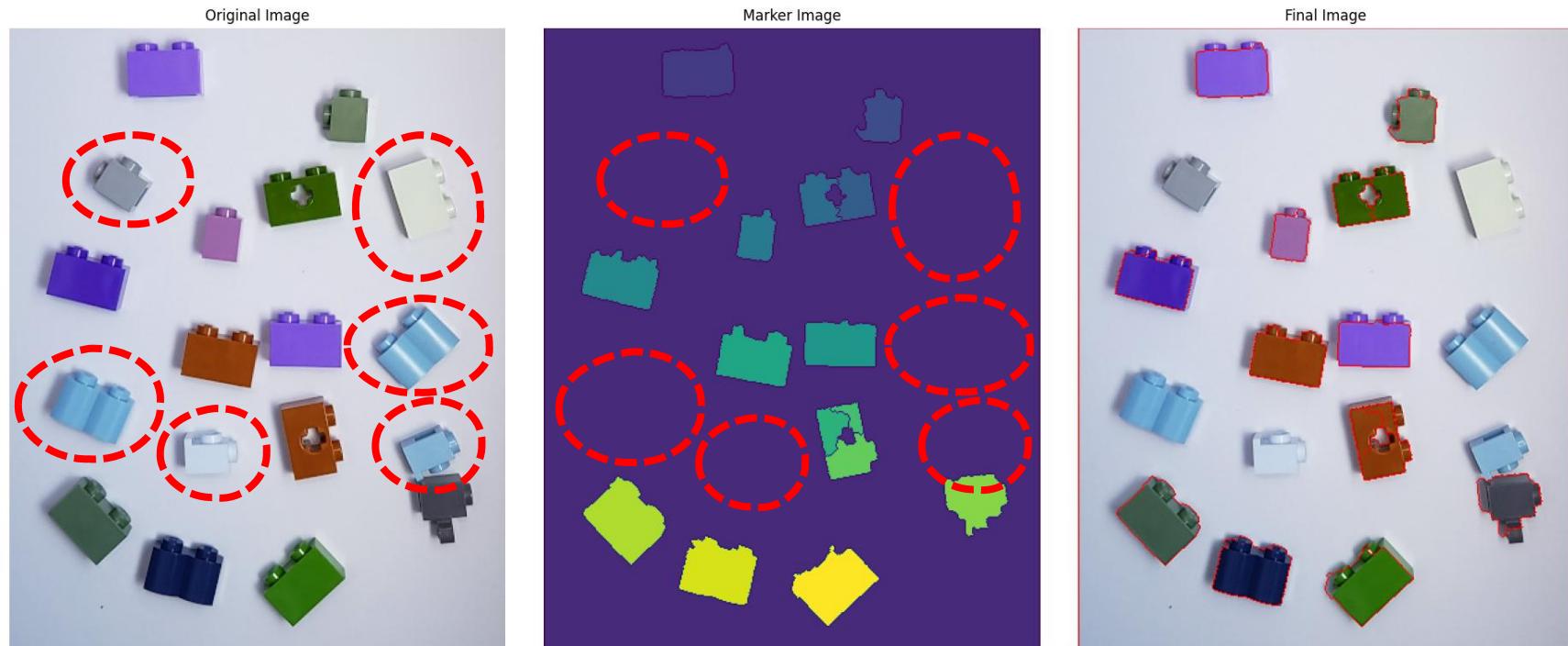
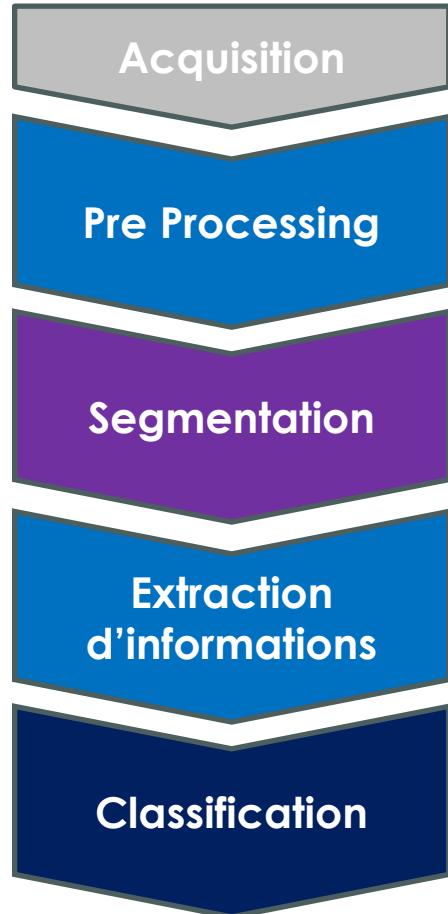
Traitement d'images



Méthode de Watershed



Traitement d'images



Méthode de Watershed