

# Basic Deep Learning

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# The plan for this class...

- Deep Learning is currently more an art than a science
- Practice makes perfect: the hands-on exercises will familiarize you with the basic deep learning workflow
- Let's have a conversation! Your input will be as important for your colleagues as whatever I have to say

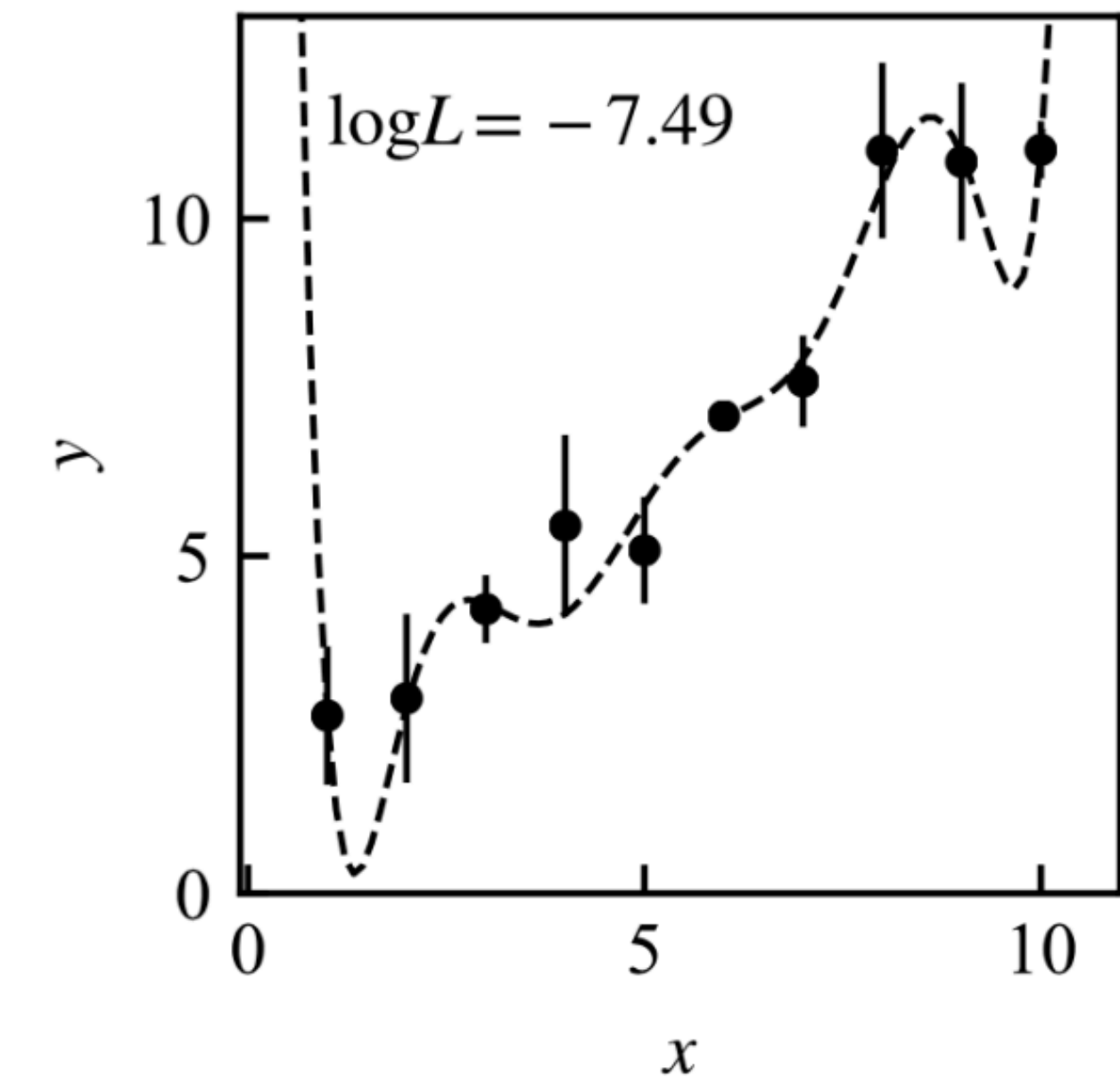
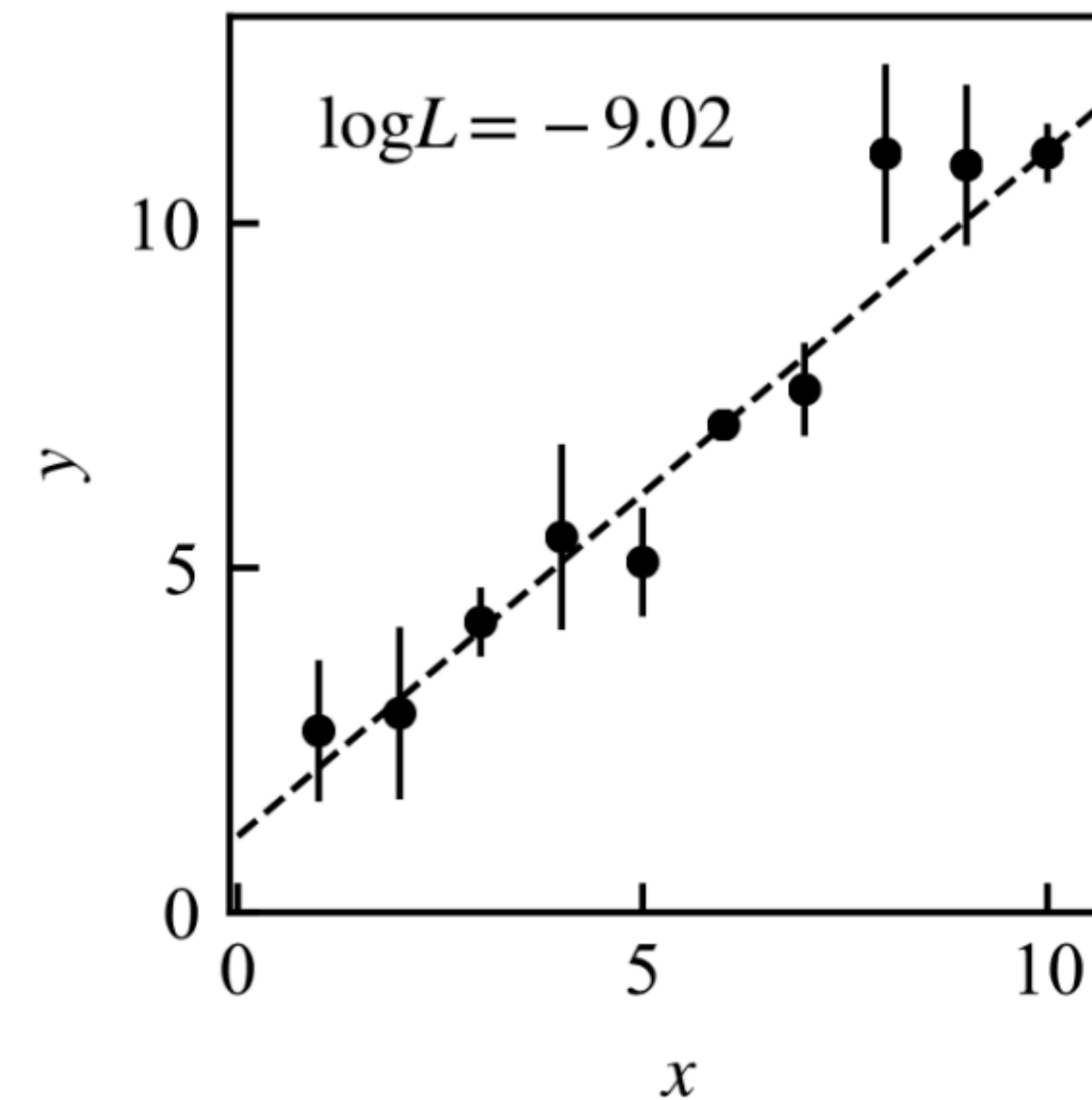
# The plan for this class...

- understand the utility of deep learning
- multi-layer perceptron
- training via stochastic gradient descent
- supervised learning: regression & classification
- how to train deep neural nets *systematically*

# Overfit and model selection

- **Overfit** = a statistical model describes random noise
  - The likelihood of a model often increases with the number of model parameters.
  - In high-dimensional problems, evaluating a model solely based on likelihood becomes inappropriate.
- **Model selection:**
  - If the model is too simple  $\rightarrow$  it cannot adequately explain the data.
  - If the model is too complex  $\rightarrow$  overfitting occurs.
  - It's essential to choose a model with the right level of complexity. = **model selection**
- Two approaches: **Information criteria** & **cross-validation**.

**Overfit =**  
**Low generalization error**



**When do we want/need to use  
Deep Learning in Science?**

# What we learned yesterday...

## Kernel functions

- Replacing covariances to the kernel functions:  $\sigma_{ij} = k(x_i, x_j)$
- RBF (Gaussian) kernel
  - The distance between two points  $\mathbf{x}_i, \mathbf{x}_j \sim$  their correlation.
  - Powerful for capturing smooth and continuous relationships in the data.
  - $\theta_2 = \text{length-scale}$
- Estimating a few kernel parameters from N data points  $\rightarrow$  Gaussian Process Regression

$$\Sigma = \begin{pmatrix} \sigma_{11} & \sigma_{12} & \sigma_{13} \\ \sigma_{21} & \sigma_{22} & \sigma_{23} \\ \sigma_{31} & \sigma_{32} & \sigma_{33} \end{pmatrix}$$

RBF kernel  $k(\mathbf{x}_i, \mathbf{x}_j) = \theta_1 \exp \left\{ -\frac{\|\mathbf{x}_i - \mathbf{x}_j\|_2^2}{\theta_2} \right\}$

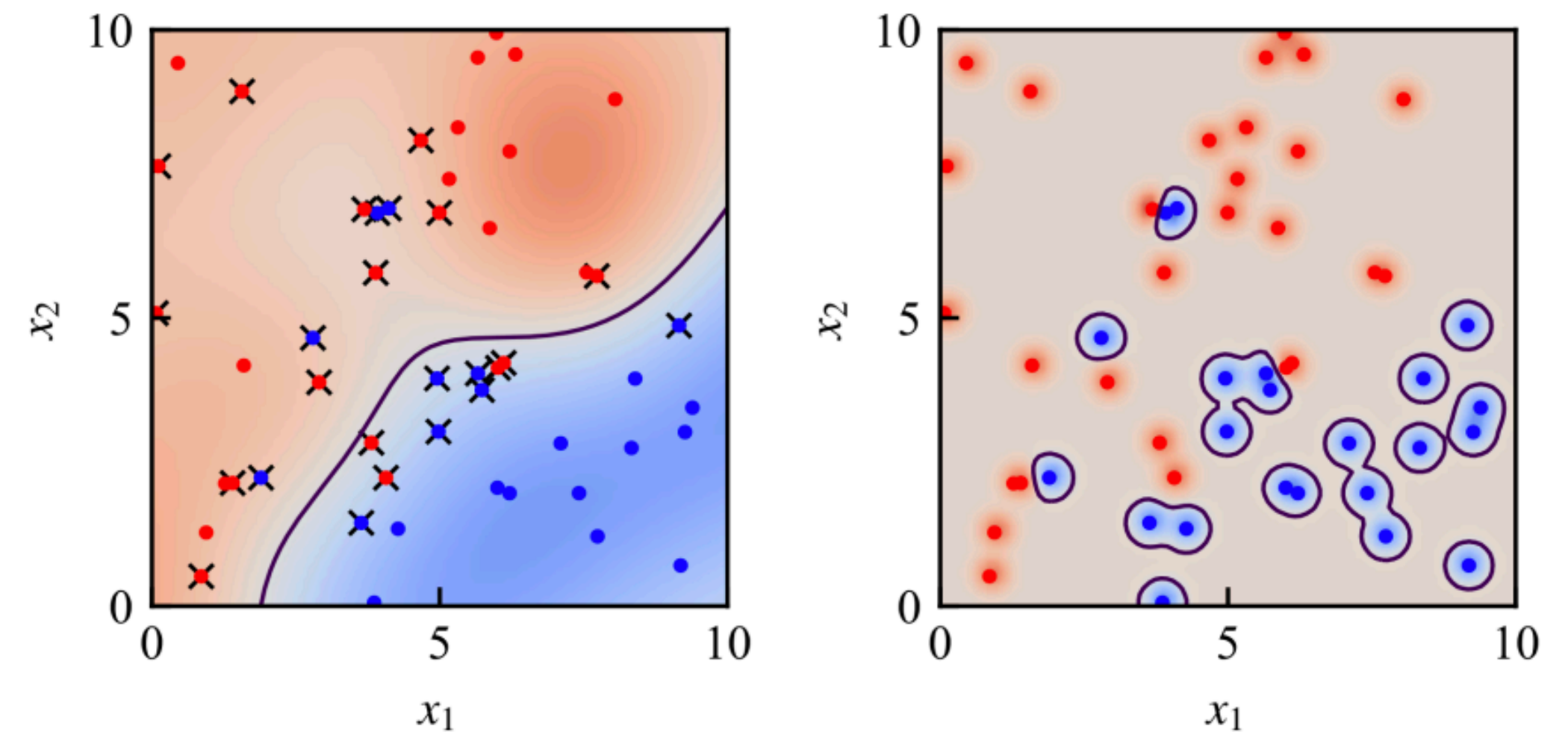
Exponential kernel  $k(\mathbf{x}_i, \mathbf{x}_j) = \theta_1 \exp \left\{ -\frac{\|\mathbf{x}_i - \mathbf{x}_j\|_2}{\theta_2} \right\}$

Periodic kernel  $k(\mathbf{x}_i, \mathbf{x}_j) = \theta_1 \exp \left\{ -\theta_2 \cos \frac{\|\mathbf{x}_i - \mathbf{x}_j\|_2}{\theta_3} \right\}$

Linear kernel  $k(\mathbf{x}_i, \mathbf{x}_j) = \theta_1 \mathbf{x}_i^T \mathbf{x}_j$

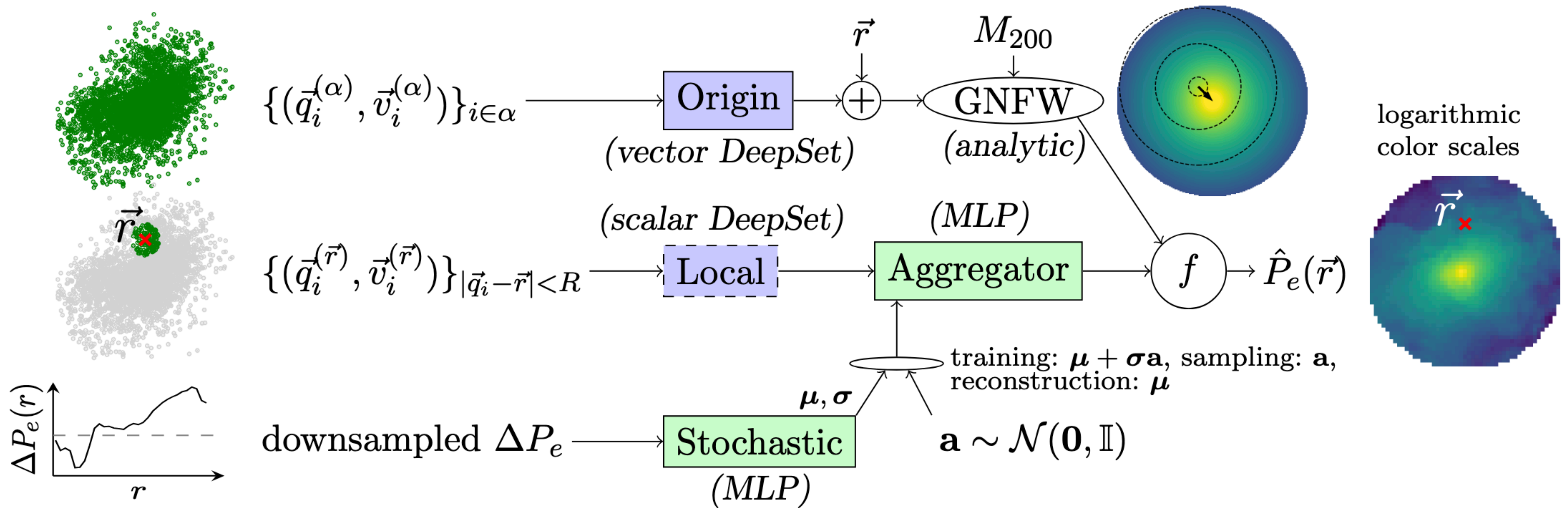
Matern kernel  $K(x, x') = \frac{2^{1-\nu}}{\Gamma(\nu)} \left( \frac{\sqrt{2\nu}|x-x'|}{\rho} \right)^\nu K_\nu \left( \frac{\sqrt{2\nu}|x-x'|}{\rho} \right)$

$K_\nu$  is the modified Bessel function of the second kind



- Use RBF kernel
- Determine **regularization** parameter C and **kernel** parameter  $\sigma$  by evaluating with **ROC-AUC** through **cross-validation**
- Left Figure: Best model
- Right Figure: **Overfitted** model
  - Kernel variance is small, and C is large.





Sometimes it is just super useful to be able to insert a maximally expressive function, subject to constraints.

This does not necessarily mean full going black box.

**What, actually, is Deep  
Learning?**



# Deep Learning is...

- ... hard

Getting everything conceptually right can be quite difficult. And deep learning tends to be unforgiving and difficult to debug.

Being completely in the wrong part of hyperparameter space can happen. With experience it gets easier to get out of there.

# Deep Learning is...

- ... hard
- ... easy

Once everything is correctly set up, and we're approximately right about the hyperparameters, neural nets are actually quite easy to optimize!

Hyperparameters tend to have predictable effects, getting us close to optimum quite fast.

# Deep Learning is...

- ... hard
- ... easy
- ... fun!

Setting up an architecture is a creative process. What works and what doesn't usually corresponds to real physics, so we're having a learning experience.

# Flavours

supervised (today):

- regression
- classification

unsupervised (Thursday) — generative models

# AIC (Akaike information criterion)

$$\text{AIC} = -2(\log L(\hat{\boldsymbol{\theta}}) - K) = -2 \log L(\hat{\boldsymbol{\theta}}) + 2K$$

- The log-likelihood  $\log L(\hat{\boldsymbol{\theta}})$  of the data can become biased when the model is too complex.
- To correct this bias, AIC introduces a penalty term, the number of model parameters  $K$ .

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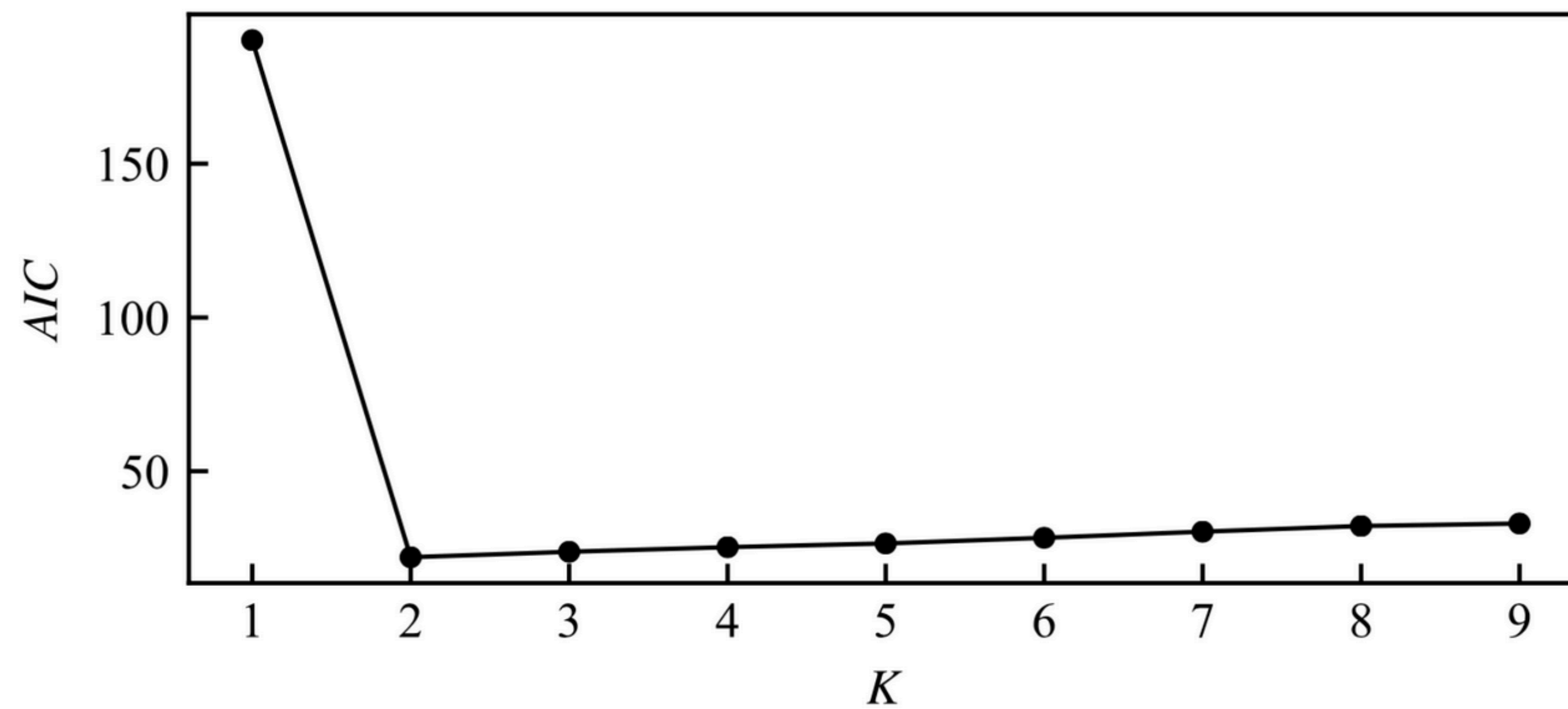
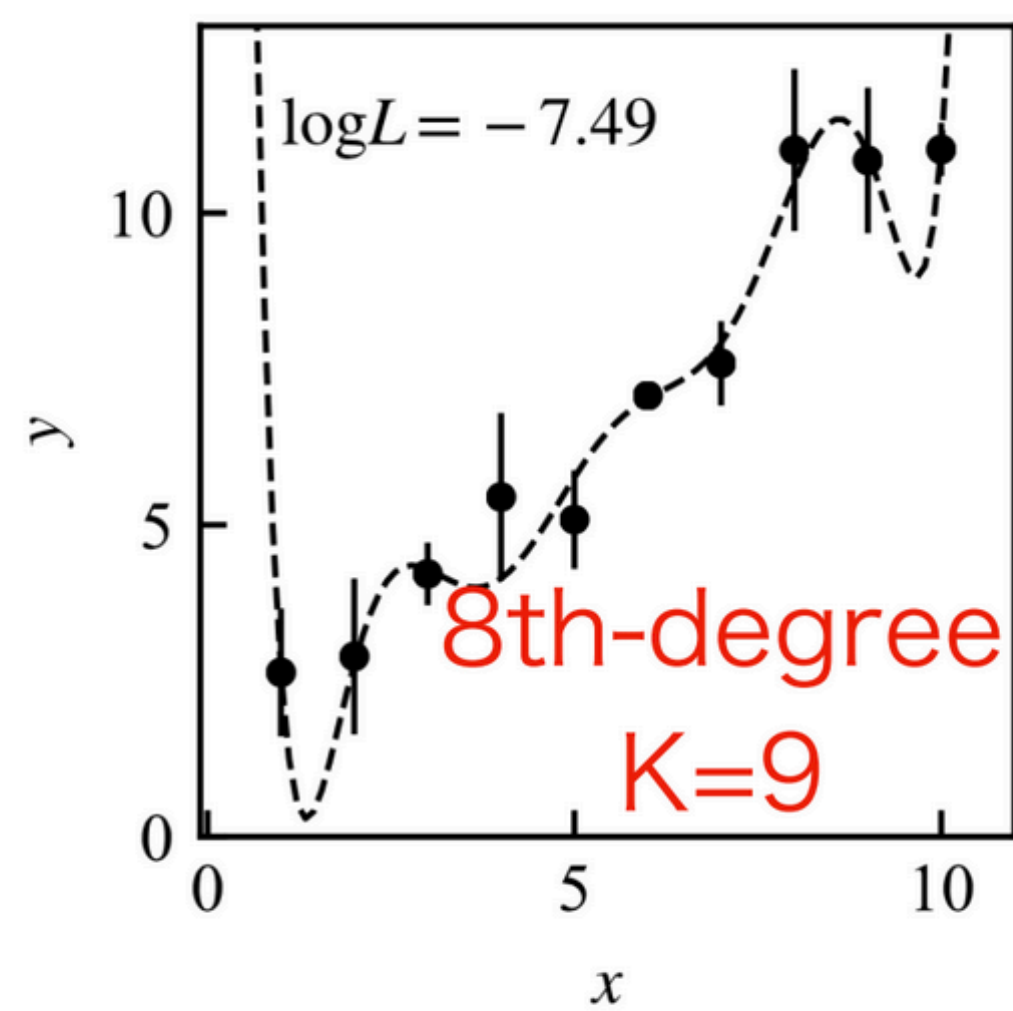
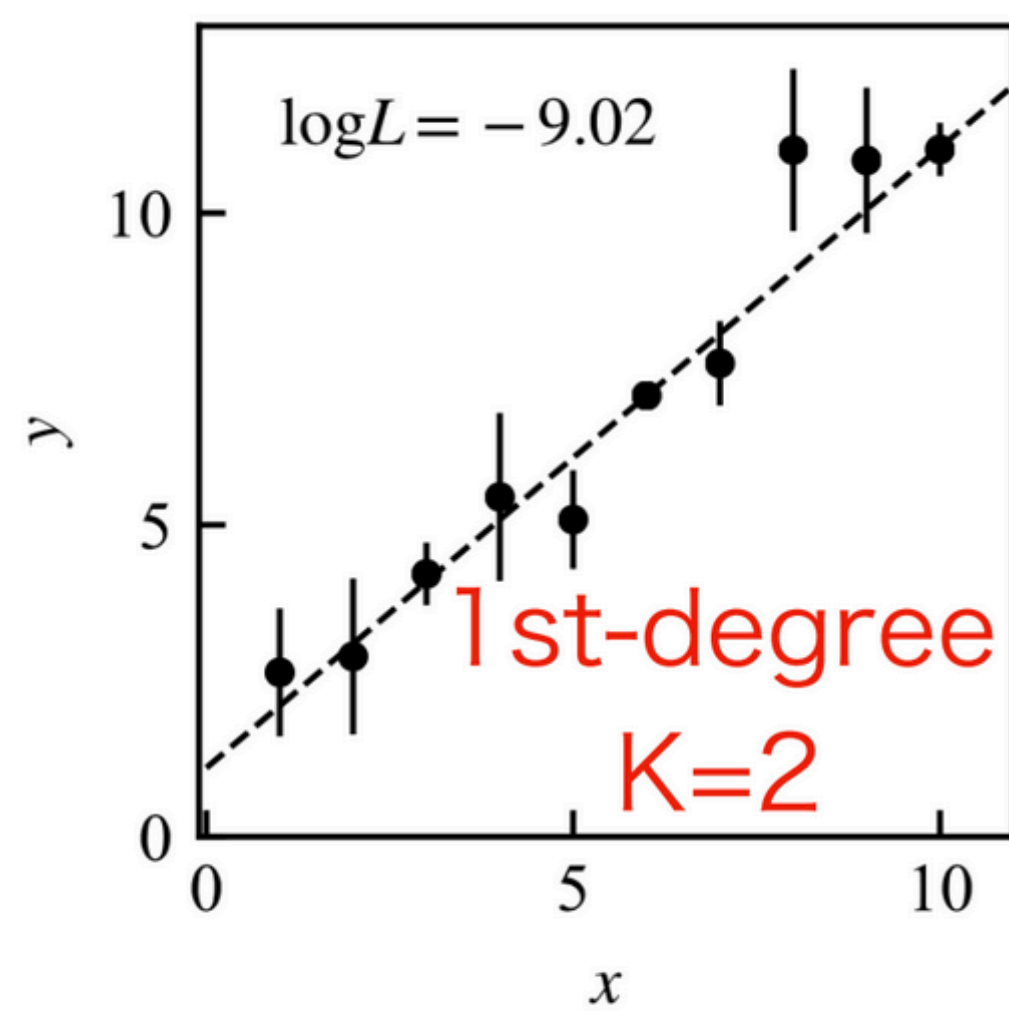
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Usually, this is our intuition a Bayesians — “Occam’s razor”.

Does this intuition apply for deep learning, though?

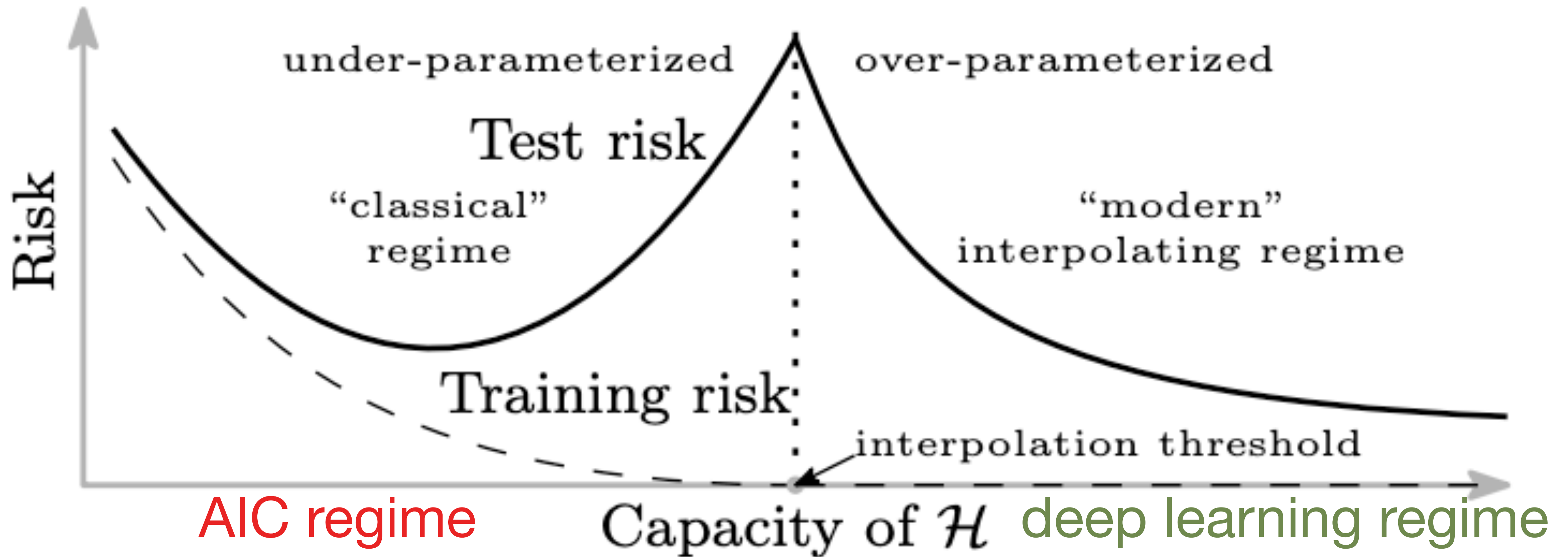
After all, a neural net is just a very complicated model, right?





“model capacity”

# Overparameterization



- parameter counting is usually not useful when constructing neural nets
- just choose the largest architecture that fits on your hardware
- overfitting is still very much possible, and we need to develop ways to deal with it
- regularization, as introduced yesterday, is key! But in the high-dimensional parameter spaces of neural nets, it can be as much about training/dynamics as about the formal loss function.

# Perceptron

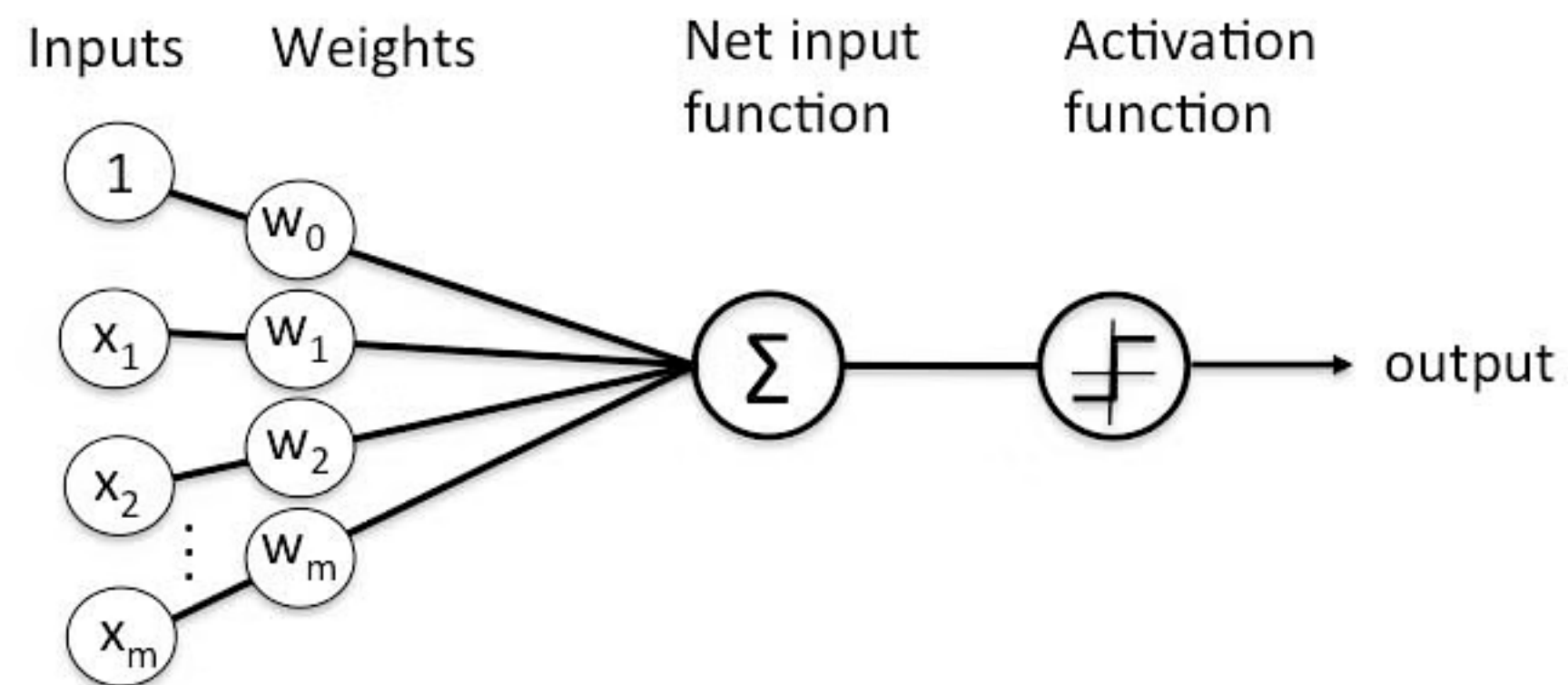
The building block of typical feed-forward neural nets

$$z(x) = f(Wx + b)$$

activation function

weight

bias



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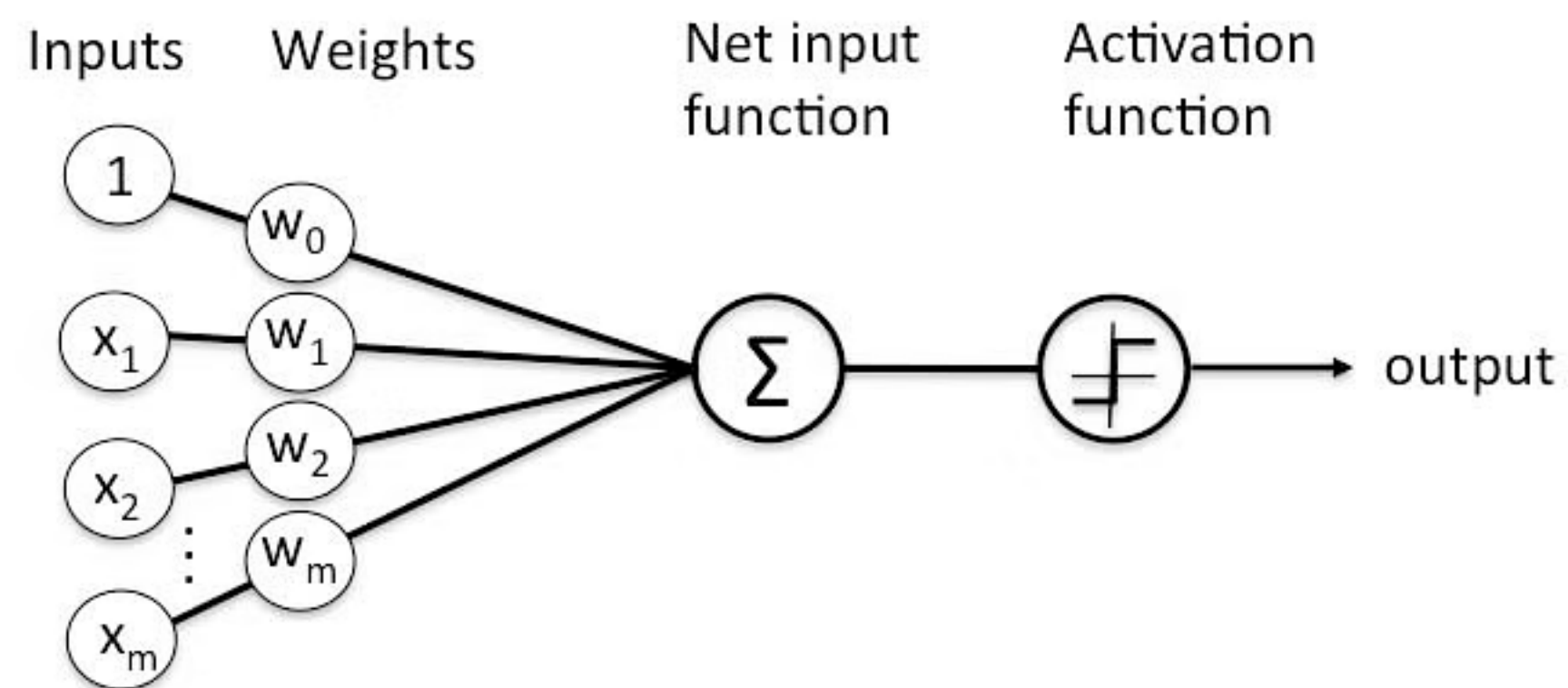
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Why this specific choice of a non-linear function?

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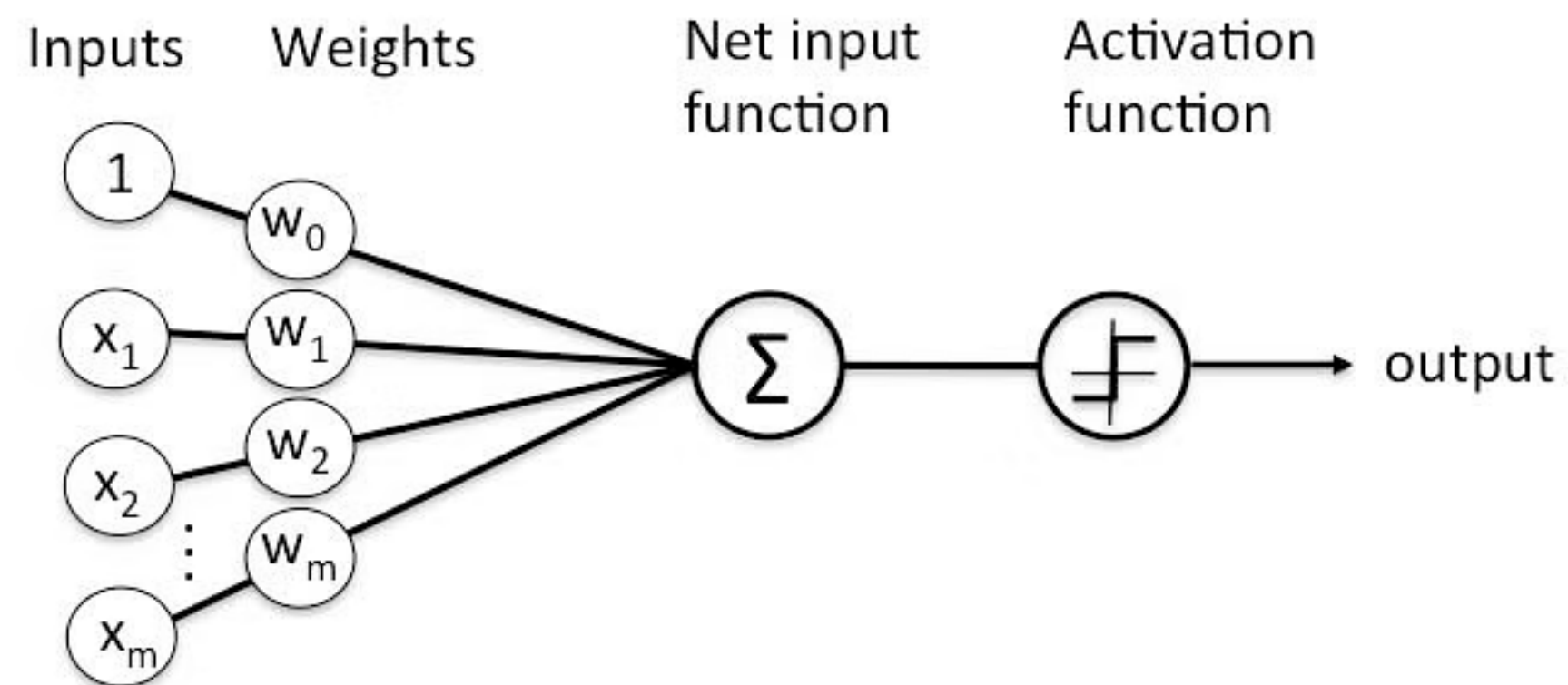
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What should we use as  
activation functions?

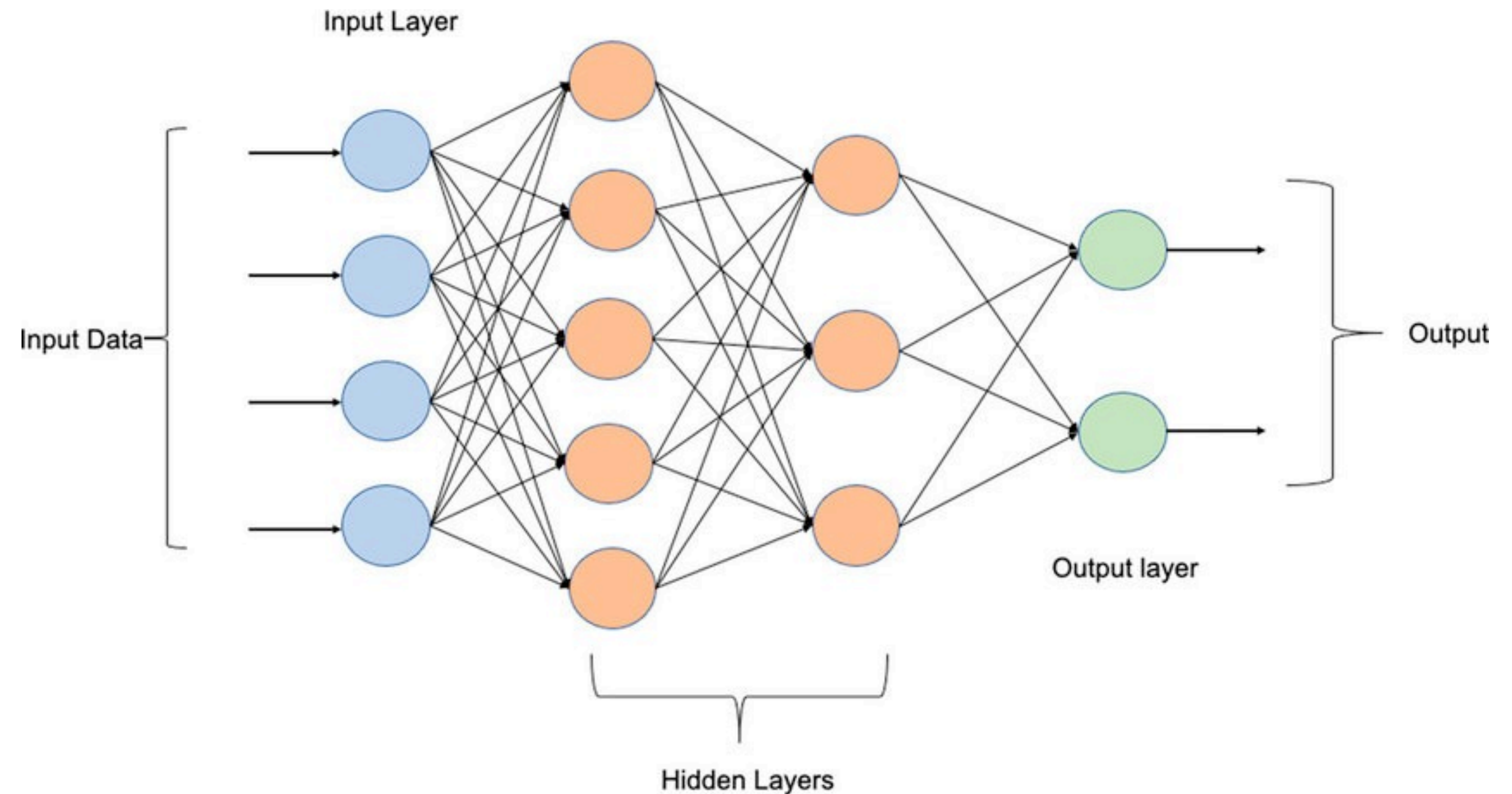


# Multi-layer perceptron (MLP)

easy: stack multiple perceptrons!

One subtlety: often we want to keep the output on the entire real line.

Just use a  $Wx+b$  affine transformation at the end.



# Hands-on #1: write an MLP

# How to train a neural net?

In general, training a neural net is a non-convex optimization problem.

It is actually often NP-hard to find the global optimum.

How can we hope to train such an object into a useful state?

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How can we hope to train such an object into a useful state?

Empirically, it works pretty well! Probably due to over-parameterization.

# How to train a neural net?

- pick a loss function. Needs to be adapted to the problem at hand (what are we trying to accomplish?).
- split data into training/validation/test sets (70/20/10 is a good guide).
- If constraints permit, multiple training/validation splits desirable (K-fold cross-validation)
- train by stochastic gradient descent

# Stochastic gradient descent

In the most basic form, SGD iterates over the following:

$$\theta \leftarrow \theta - \text{lr} \nabla_{\theta} L(\theta)$$

learning rate

global loss function

$$L(\theta) = \sum_{\text{training examples } x} L(\theta, x)$$



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In practice, this doesn't work super well, ...

# Usable gradient descent

- mini-batching
- some form of momentum

# How to compute gradients (efficiently)

Modern software, such as pytorch/tensorflow/..., has backpropagation.

This is an efficient way to compute the chain rule.

The math is not so difficult to understand, but not very enlightening and you won't need it very often.

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The key point for practitioners is that we need to tell the software which objects require gradients. Typically, network parameters have this set out-of-the-box, but sometimes we need to be explicit.

# Hands-on #2: train 1-d MLP

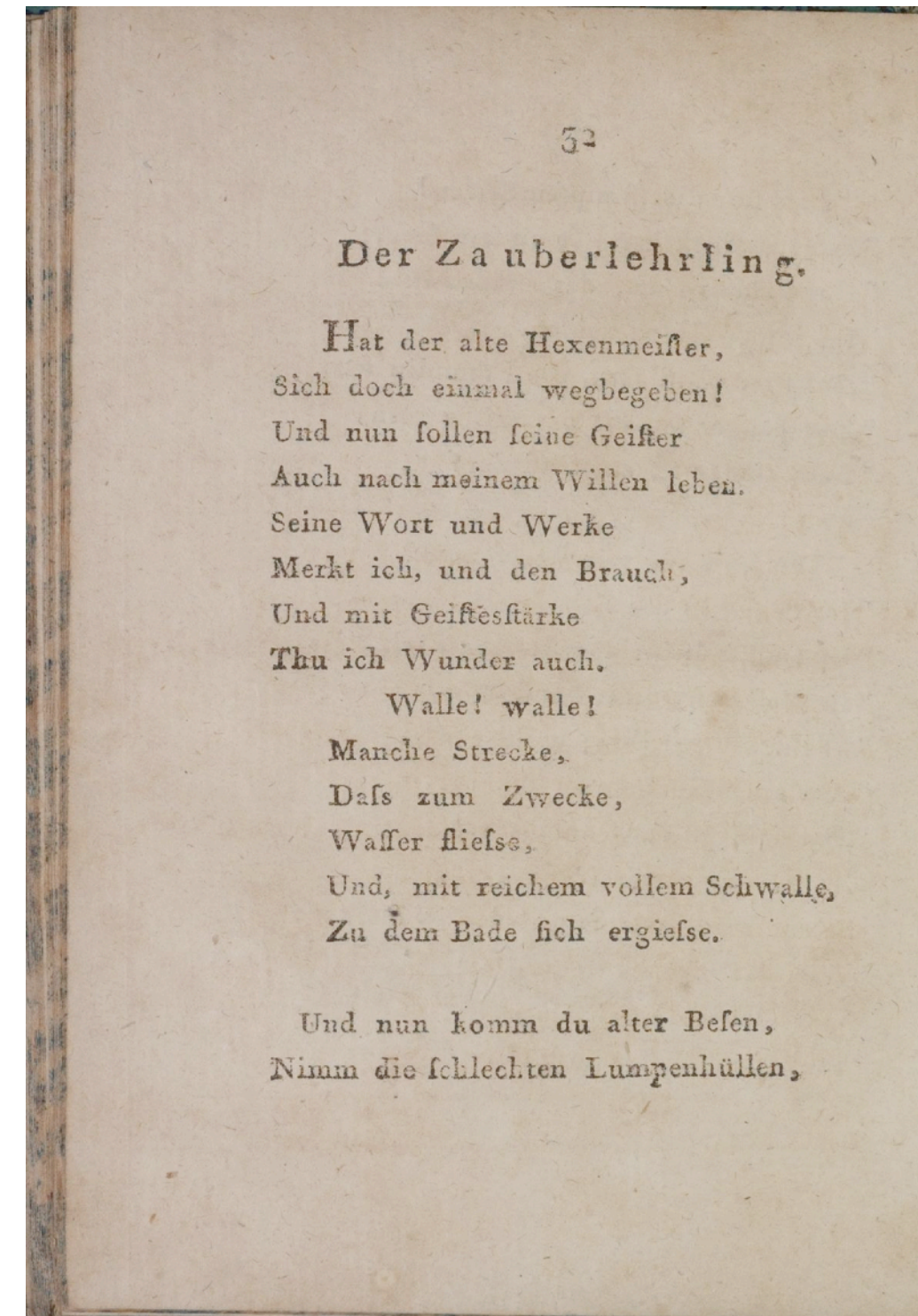
# Universal approximation theorem

## *Physicist's statement:*

Under reasonable conditions on the input function (i.e., physicist's functions), for any accuracy requirement there exists a multi-layer perceptron (MLP) able to approximate the function with the required accuracy.

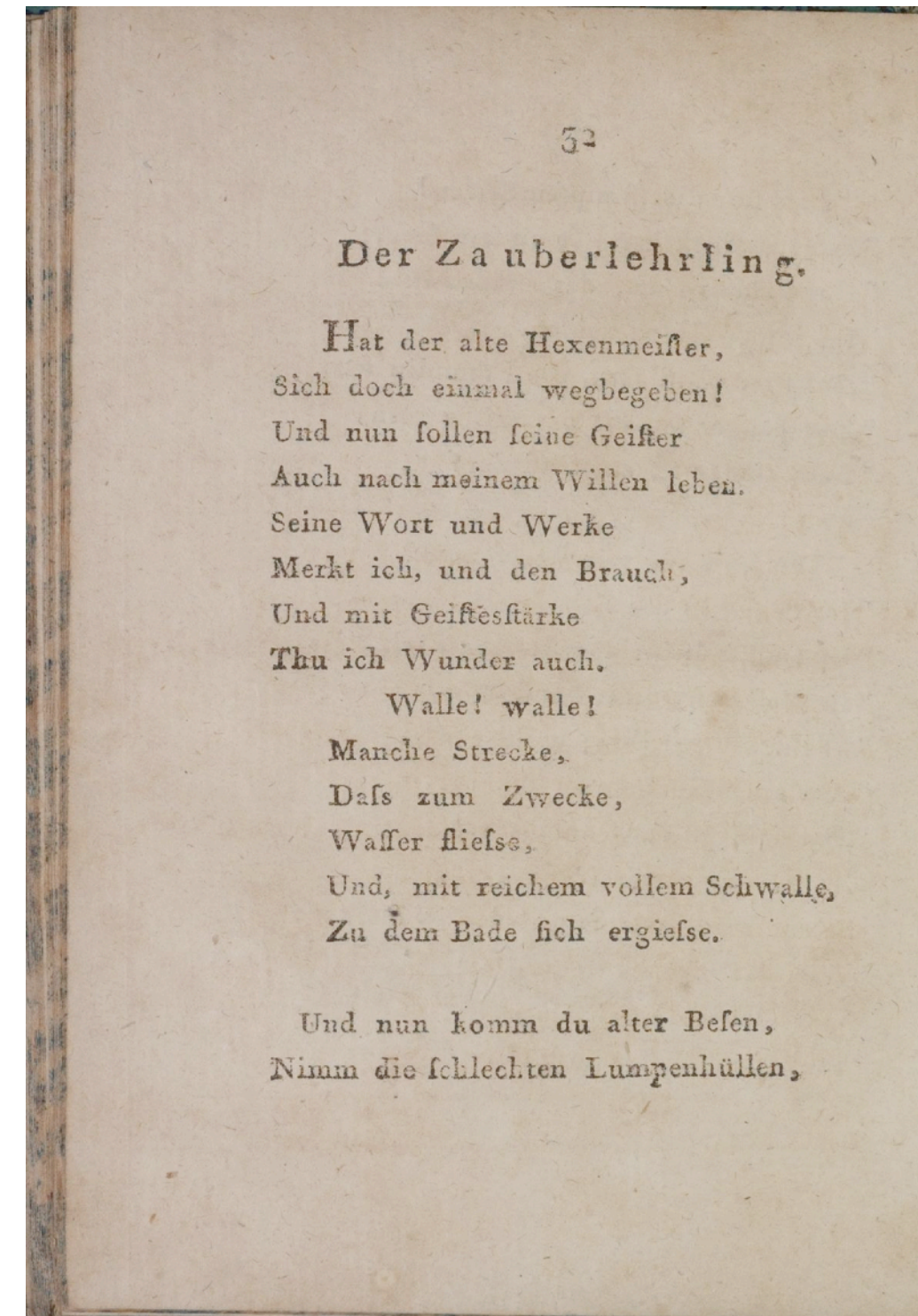


# There is some dark magic...





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Let's learn it together and from each other!



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Each of the 8 hack groups investigate one topic!

Slides linked in the Github. Find your group's slide and fill it with information about the specific topic.

Please answer the following: what's the motivation/problem, what's the intuition, when would you use which technique? If you can find original/seminal papers, please link them. Visualizations are great, too!

At the end, please be prepared to present your group's slide to the other participants.

# Deep learning workflow

1. formulate the problem. What do you want to learn? Does your problem have randomness (suggests generative model)? What is the performance metric you actually care about and how can you map this to a loss function?

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5. [ layernorm/batchnorm sometimes useful to prevent divergences ]
6. once it trains reasonably well, can start with secondary hyperparameters: architecture details, optimizer secondaries, regularization, ...

# Loss curve interpretation

typical problems:

- explosion, with and without recovery
- predicting the mean
- slow convergence, underfitting
- overfitting

# Hyperparameter search

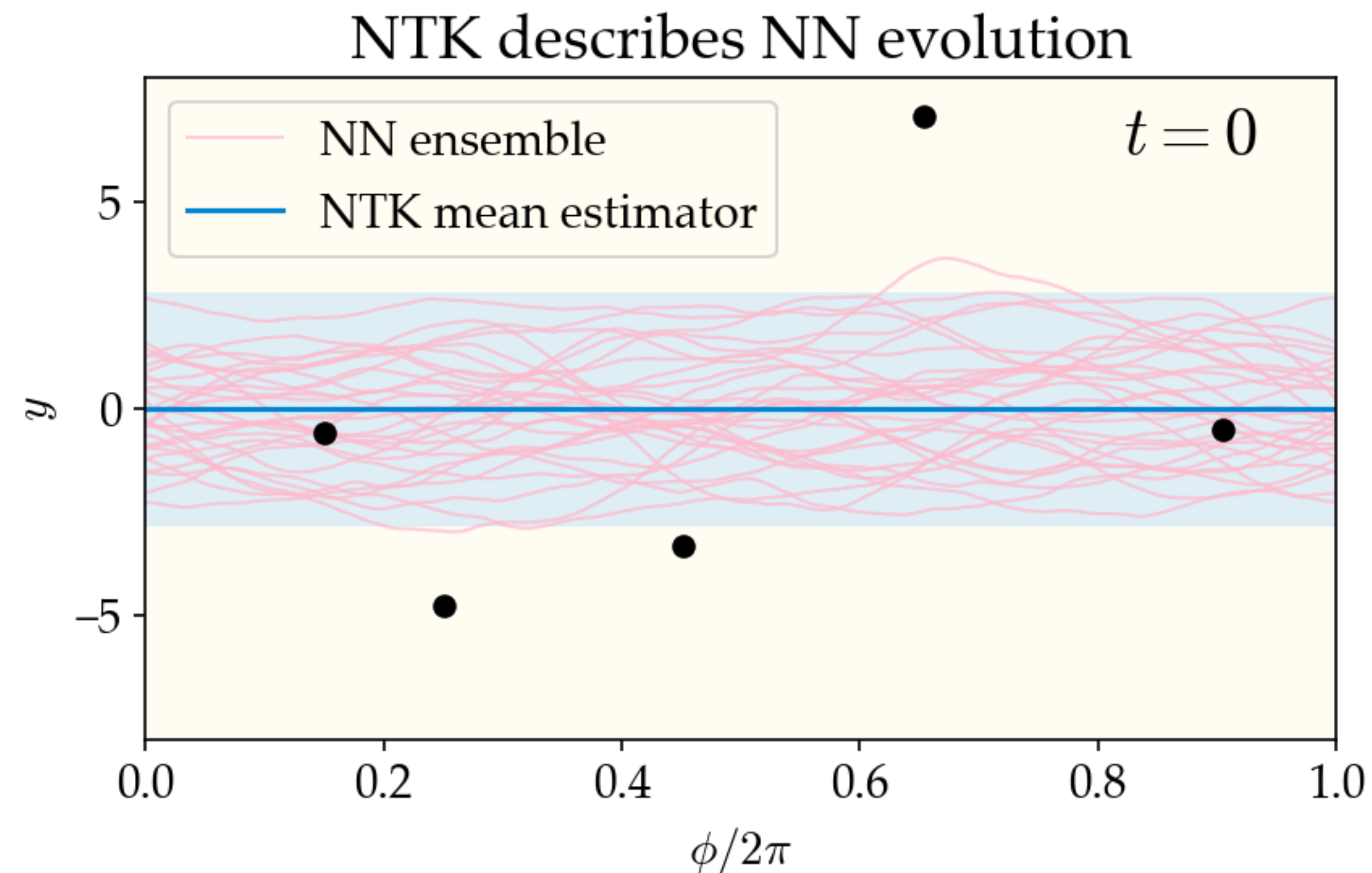
Automated tools for Bayesian Optimization such as optuna can make it easier. They do not replace the human experimenter!

Do not grid scan hyperparameters (except when there is only one). Usually they have vastly different levels of importance.

# Hands-on #3: classify MNIST

# Understanding deep learning

- neural tangent kernel: useful to study infinite width neural nets -> ensemble of infinite-width neural nets converges to Gaussian process



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For practical large-scale problems, the neural tangent kernel seems to be more of theoretical interest. It cannot, as of yet, replicate the performance of real-world neural nets.

But we'll see what the future holds...

# Understanding deep learning

- thermodynamics: connection between neural nets and critical phenomena