

# Install Python and Visual Studio Code in Win10

---

# Install Python in Windows 10

Step 1: Download Python 3.6.4

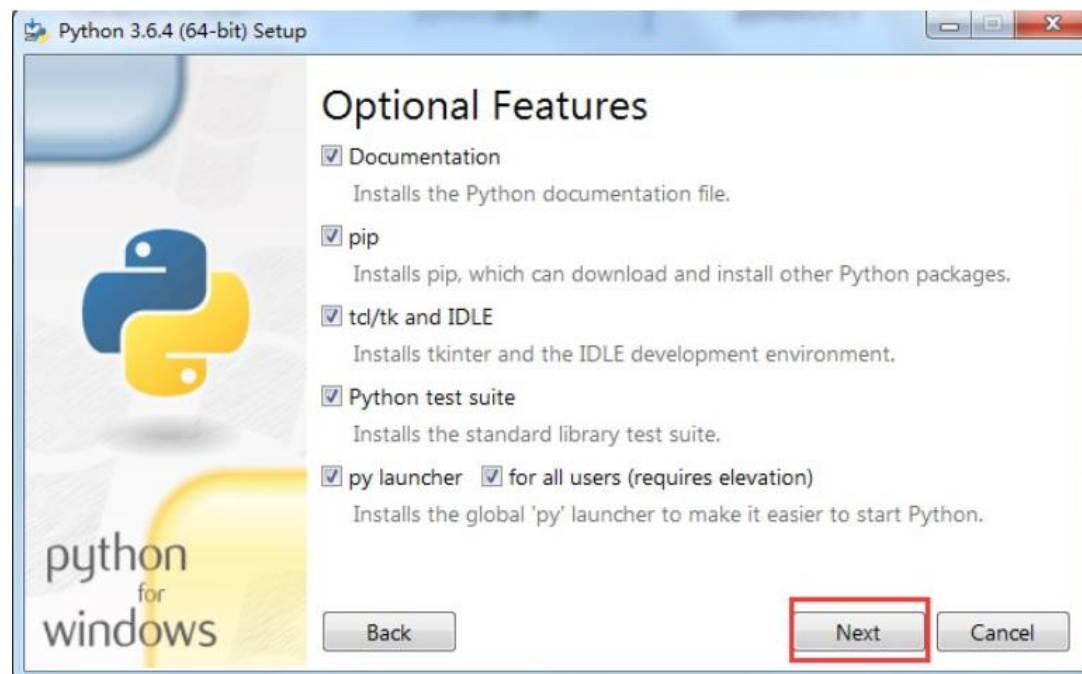
<https://www.python.org/ftp/python/3.6.4/python-3.6.4-amd64.exe>

Step 2: Install Python 3.6.4 in Windows 10

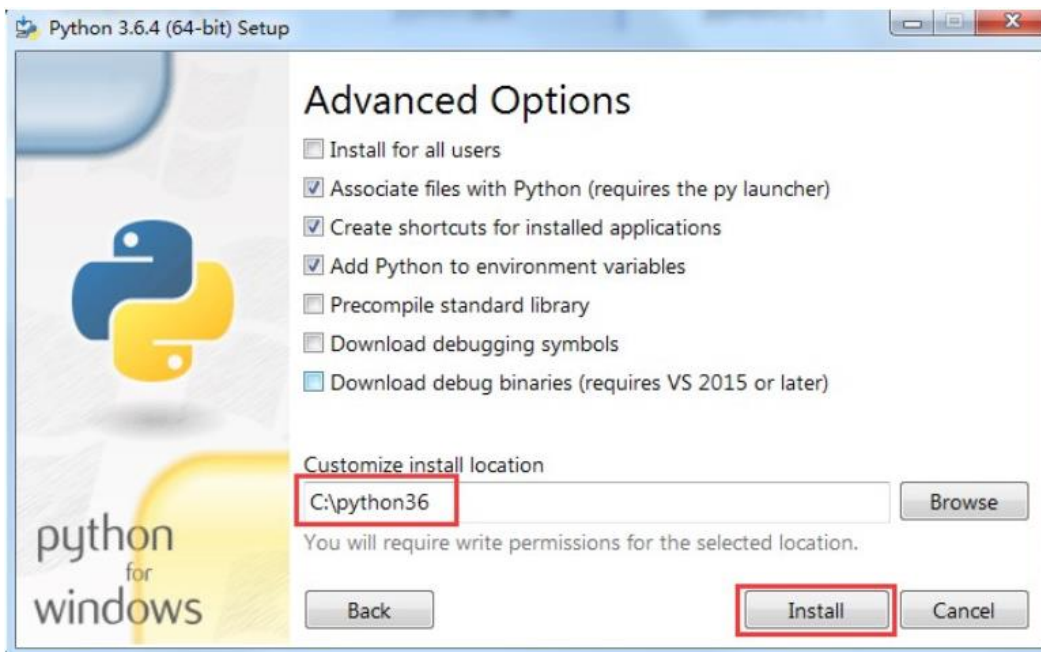


Python is an interpreted, high-level, general-purpose programming language. Created by Guido van Rossum and first released in 1991, Python's design philosophy emphasizes code readability with its notable use of significant whitespace.

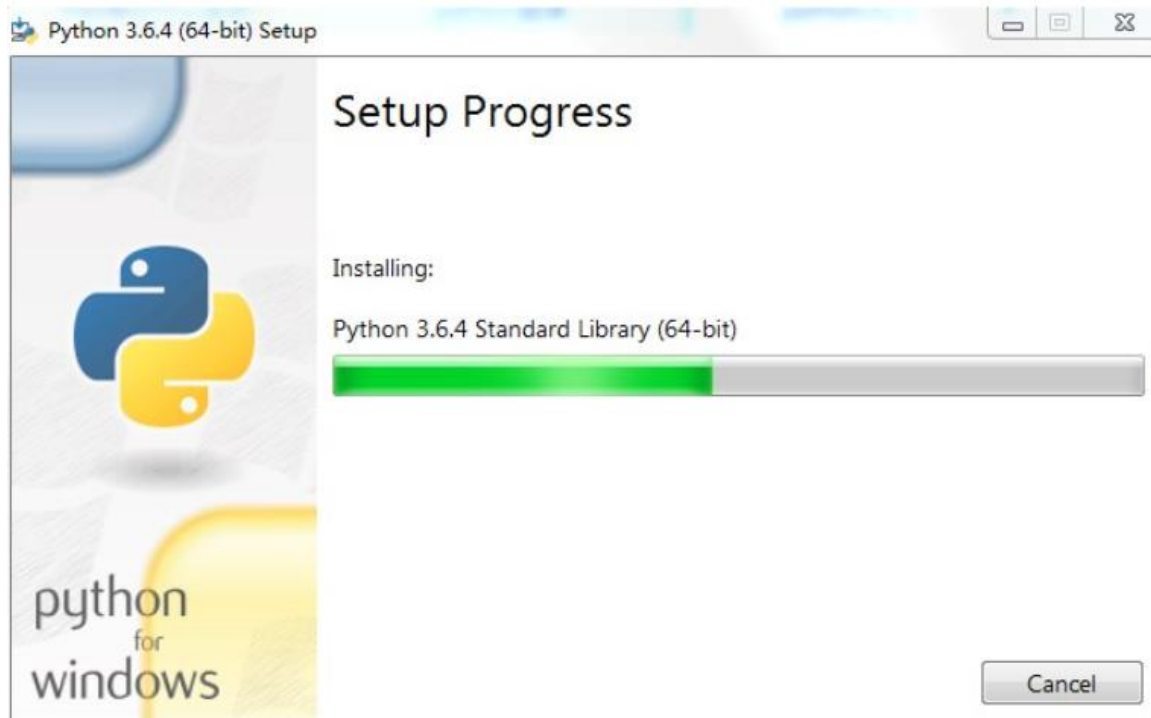
# Install Python in Windows 10



# Install Python in Windows 10



# Install Python in Windows 10



# Install Python in Windows 10

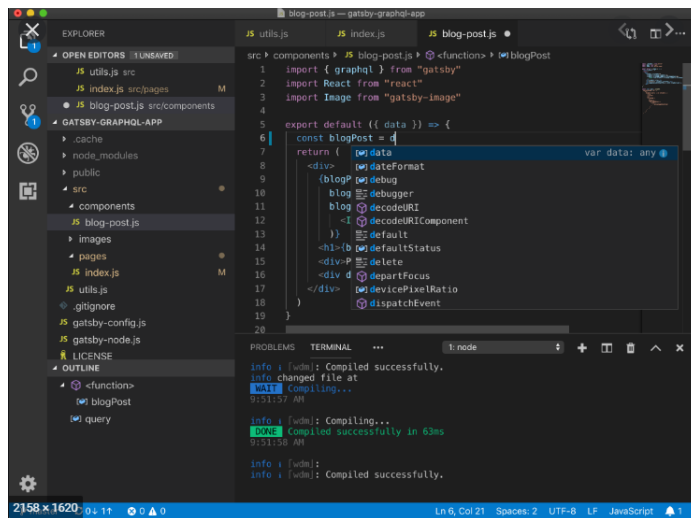


# Install VS code in Windows 10

Step 1: Download the latest VS code

<https://code.visualstudio.com/download>

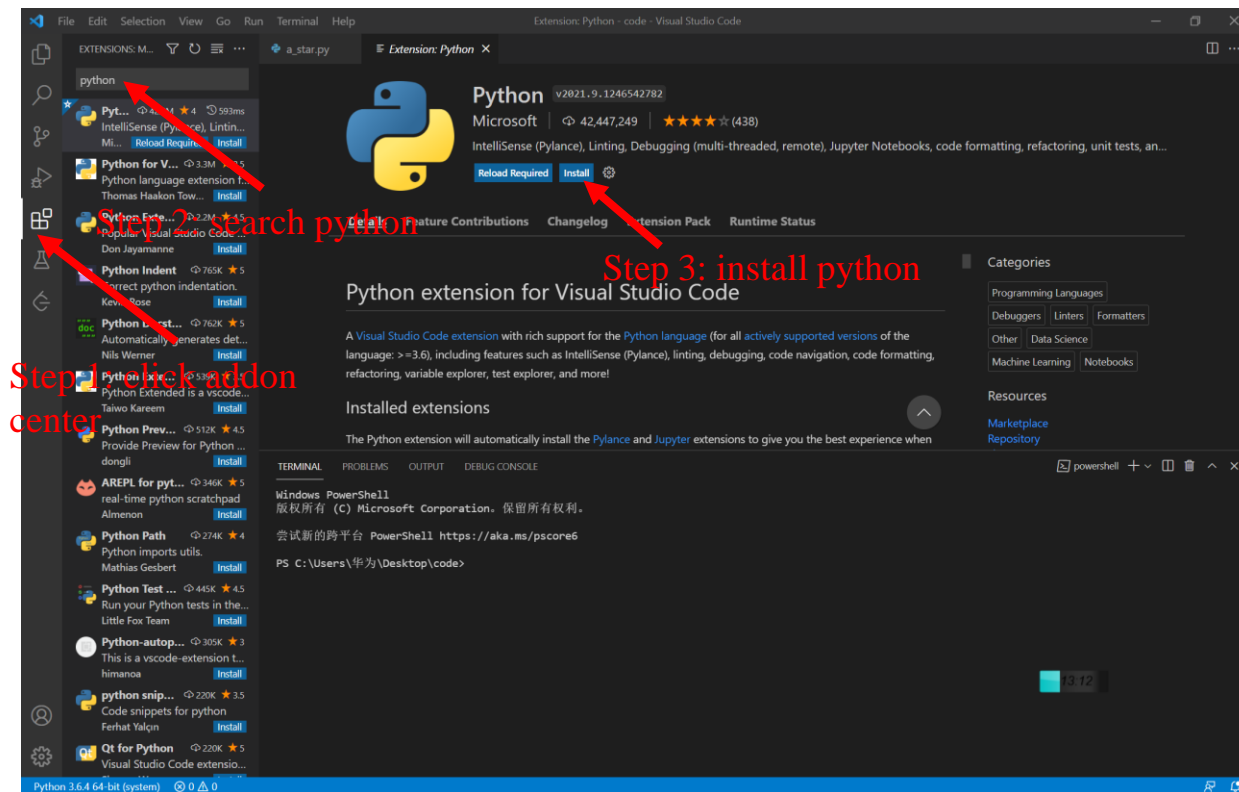
Step 2: Install latest VS code in Windows 10



Visual Studio Code is a free source-code editor made by Microsoft for Windows, Linux and macOS. Features include support for debugging, syntax highlighting, intelligent code completion, snippets, code refactoring, and embedded Git.

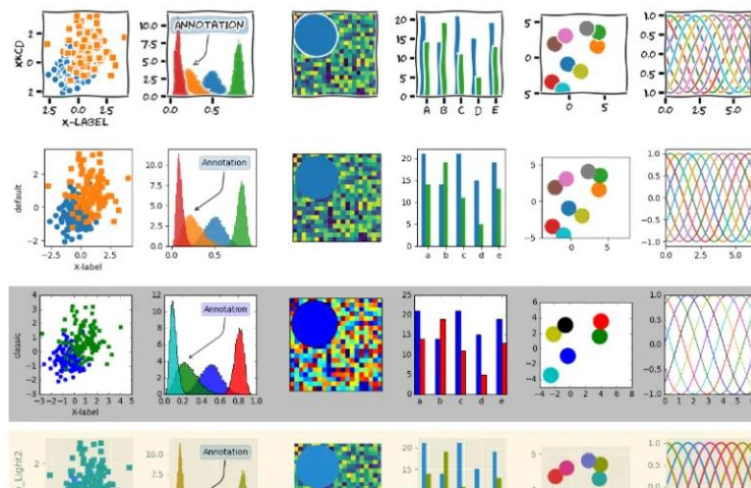


# Install Python **addon** in VS code in Windows 10





# Install matplotlib



Source:

<https://www.gnuband.org/2017/12/29/gallery-of-xkcd-and-other-python-matplotlib-styles/>

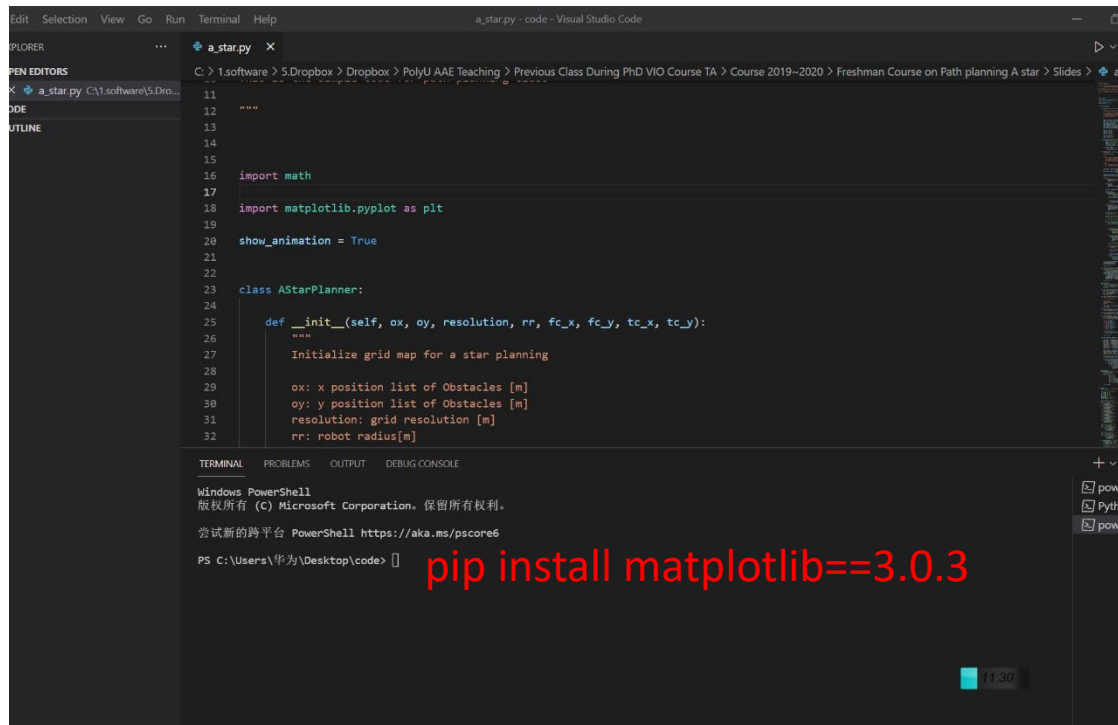
Matplotlib is a plotting library for the Python programming language and its numerical mathematics extension NumPy. It provides an object-oriented API for embedding plots into applications using general-purpose GUI toolkits like Tkinter, wxPython, Qt, or GTK+.

- step 1: Open VS code, and then click Terminal



# Install matplotlib

- step 2: Print following command into terminal>

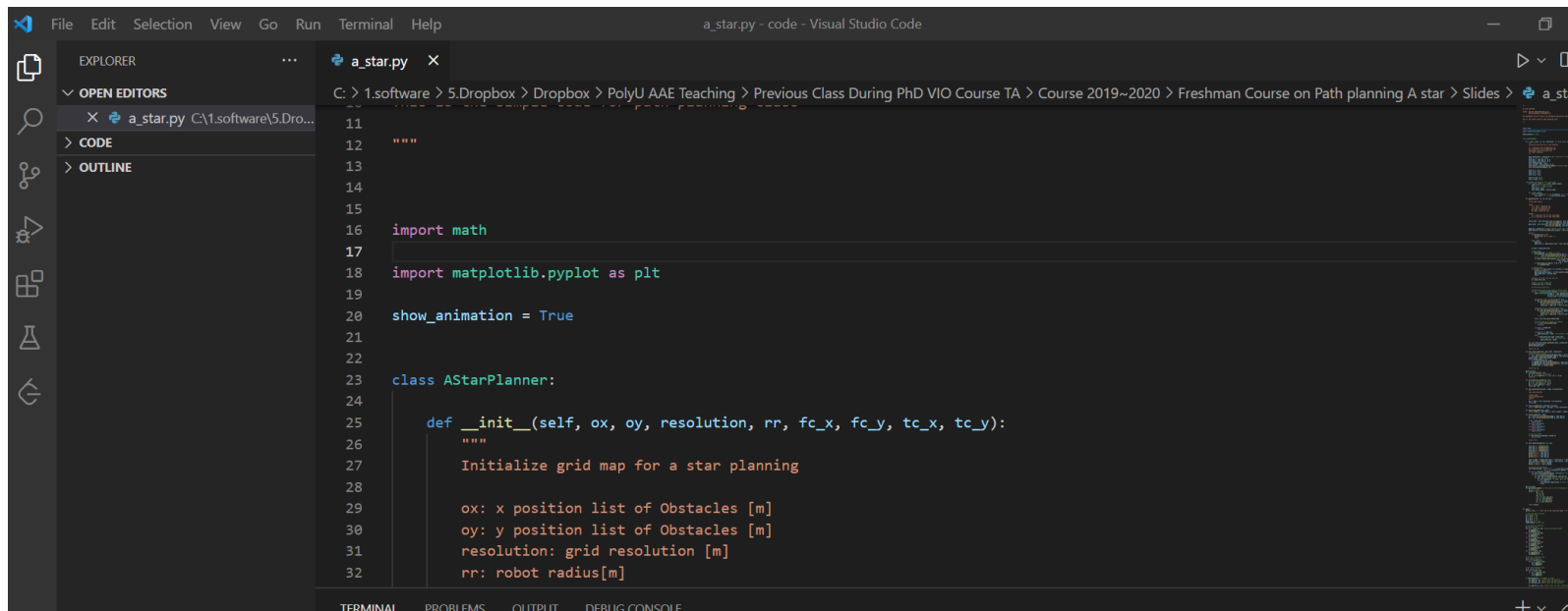


```
11  
12  
13  
14  
15  
16 import math  
17  
18 import matplotlib.pyplot as plt  
19  
20 show_animation = True  
21  
22  
23 class AStarPlanner:  
24  
25     def __init__(self, ox, oy, resolution, rr, fc_x, fc_y, tc_x, tc_y):  
26         """  
27         Initialize grid map for a star planning  
28  
29         ox: x position list of Obstacles [m]  
30         oy: y position list of Obstacles [m]  
31         resolution: grid resolution [m]  
32         rr: robot radius[m]
```

```
Windows PowerShell  
版权所有 (C) Microsoft Corporation. 保留所有权利。  
  
尝试新的跨平台 PowerShell https://aka.ms/pscore6  
  
PS C:\Users\华为\Desktop\code> pip install matplotlib==3.0.3
```

# Test matplotlib

- step 3: Open the code sample by VS code

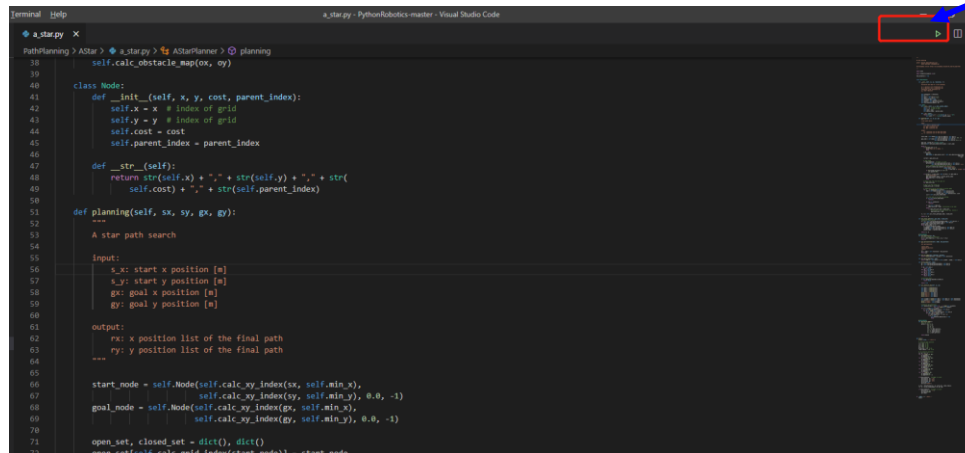


```
11
12
13
14
15
16 import math
17
18 import matplotlib.pyplot as plt
19
20 show_animation = True
21
22
23 class AStarPlanner:
24
25     def __init__(self, ox, oy, resolution, rr, fc_x, fc_y, tc_x, tc_y):
26         """
27         Initialize grid map for a star planning
28
29         ox: x position list of Obstacles [m]
30         oy: y position list of Obstacles [m]
31         resolution: grid resolution [m]
32         rr: robot radius[m]
```



# Run A Star in VS code

Run the code

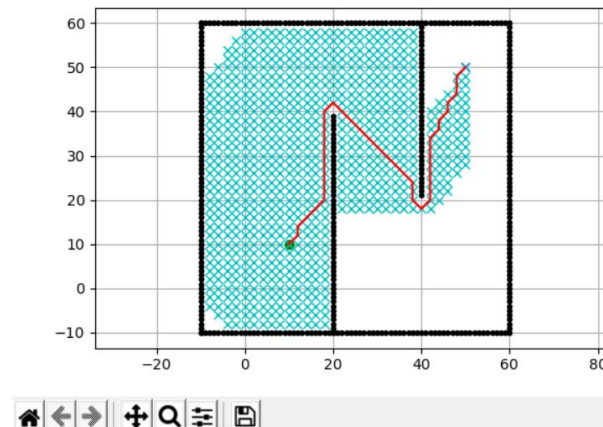


```

18 self.calc_obstacle_map(ox, oy)
19
20 class Node:
21     def __init__(self, x, y, cost, parent_index):
22         self.x = x # index of grid
23         self.y = y # index of grid
24         self.cost = cost
25         self.parent_index = parent_index
26
27     def __str__(self):
28         return str(self.x) + "," + str(self.y) + "," + str(
29             self.cost) + "," + str(self.parent_index)
30
31 def planning(self, sx, sy, gx, gy):
32     """
33     A star path search
34
35     input:
36     s.x: start x position [m]
37     s.y: start y position [m]
38     gx: goal x position [m]
39     gy: goal y position [m]
40
41     output:
42     rx: x position list of the final path
43     ry: y position list of the final path
44     """
45
46     start_node = self.Node(self.calc_xy_index(sx, self.min_x),
47                           self.calc_xy_index(sy, self.min_y), 0.0, -1)
48     goal_node = self.Node(self.calc_xy_index(gx, self.min_x),
49                           self.calc_xy_index(gy, self.min_y), 0.0, -1)
50
51     open_set, closed_set = dict(), dict()
52     open_set[self.calc_xy_index(start_node.x, start_node.y)] = start_node
  
```

A\* is a graph traversal and path search algorithm, which is often used in many fields of computer science due to its completeness, optimality, and optimal efficiency. One major practical drawback is its space complexity, as it stores all generated nodes in memory.

Figure 1



# Troubleshoot: Connect Github page via command in VS Code

- Input the command below to the terminal (change the blue to your info)
  - `git config --global user.name weisongwen`
  - `git config --global user.email wenwsrobo@gmail.com`

