

Run Bayesian Parameter Estimation

estimate_params.m

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Summary

Use bayesian methods to estimate some of the parameters. First, set up our priors about the individual parameters, and locate the posterior mode. Then, run a posterior simulator (adaptive random-walk Metropolis) to obtain the whole distributions of the parameters.

Contents

1	Clear Workspace	2
2	Load Solved Model Object and Historical Database	2
3	Set Up Estimation Input Structure	2
4	Visualise Prior Distributions	3
5	Maximise Posterior Distribution to Locate Its Mode	5
6	Print Some Estimation Results	8
7	Visualise Prior Distributions and Posterior Modes	9
8	User Supplied Optimisation Routine	11
9	Covariance Matrix of Parameter Estimates	12
10	Examine Neighbourhood Around Optimum	13
11	Run Metropolis Random Walk Posterior Simulator	15
12	Visualise Priors and Posteriors	16
13	Save Model Object with Estimated Parameters	18
14	Help on IRIS Functions Used in This File	18

1 Clear Workspace

Clear workspace, close all graphics figures, clear command window, and check the IRIS version.

```
14 clear;
15 close all;
16 clc;
17 irisrequired 20140315;
18 %#ok<*NOPTS>
```

2 Load Solved Model Object and Historical Database

Load the solved model object built `read_model`, and the example database created in `read_data`. Run `read_model` and `read_data` at least once before running this m-file.

```
26 load read_model.mat m;
27 load read_data.mat d startHist endHist;
```

3 Set Up Estimation Input Structure

The estimation input struct describes which parameters to estimate and how to estimate them. A struct needs to be created with one field for each parameter that is to be estimated. Each parameter can be then assigned a cell array with up to four pieces of information:

```
E.parameter_name = {starting}
E.parameter_name = {starting,lower}
E.parameter_name = {starting,lower,upper}
E.parameter_name = {starting,lower,upper,logdist}
```

where `starting` is a starting value for the iteration, `lower` and `upper` are the lower and upper bounds, respectively, and `logdist` is a function handle taking one input and returning the log prior density.

If the starting value is `NaN`, then the currently assigned parameter value (from the model object) is used. The constants `-Inf` and `Inf` can be used for the lower and upper bounds, respectively. Use the `logdist` package to set up the log-prior function handles.

```
50 E = struct();
51
52 E.chi = {NaN, 0.5, 0.95, logdist.normal(0.85,0.025)};
53 E.xiw = {NaN, 30, 1000, logdist.normal(60,50)};
```

```

54 E.xip = {NaN, 30, 1000, logdist.normal(300,50)};
55 E.rhor = {NaN, 0.10, 0.95, logdist.beta(0.85,0.05)};
56 E.kappap = {NaN, 1.5, 10, logdist.normal(3.5,1)};
57 E.kappan = {NaN, 0, 1, logdist.normal(0,0.2)};
58
59 E.std_Ep = {0.01, 0.001, 0.10, logdist.invgamma(0.01,Inf)};
60 E.std_Ew = {0.01, 0.001, 0.10, logdist.invgamma(0.01,Inf)};
61 E.std_Ea = {0.001, 0.0001, 0.01, logdist.invgamma(0.001,Inf)};
62 E.std_Er = {0.005, 0.001, 0.10, logdist.invgamma(0.005,Inf)};
63 E.corr_Er__Ep = {0, -0.9, 0.9, logdist.normal(0,0.5)};
64
65 disp(E);

```

```

      chi: {NaN} [0.5000] [0.9500] [[function_handle]]
      xiw: {NaN} [30] [1000] [[function_handle]]
      xip: {NaN} [30] [1000] [[function_handle]]
      rhor: {NaN} [0.1000] [0.9500] [[function_handle]]
    kappap: {NaN} [1.5000] [10] [[function_handle]]
    kappan: {NaN} [0] [1] [[function_handle]]
    std_Ep: {[0.0100] [1.0000e-03] [0.1000] [[function_handle]]}
    std_Ew: {[0.0100] [1.0000e-03] [0.1000] [[function_handle]]}
    std_Ea: {[1.0000e-03] [1.0000e-04] [0.0100] [[function_handle]]}
    std_Er: {[0.0050] [1.0000e-03] [0.1000] [[function_handle]]}
    corr_Er__Ep: {[0] [-0.9000] [0.9000] [[function_handle]]}

```

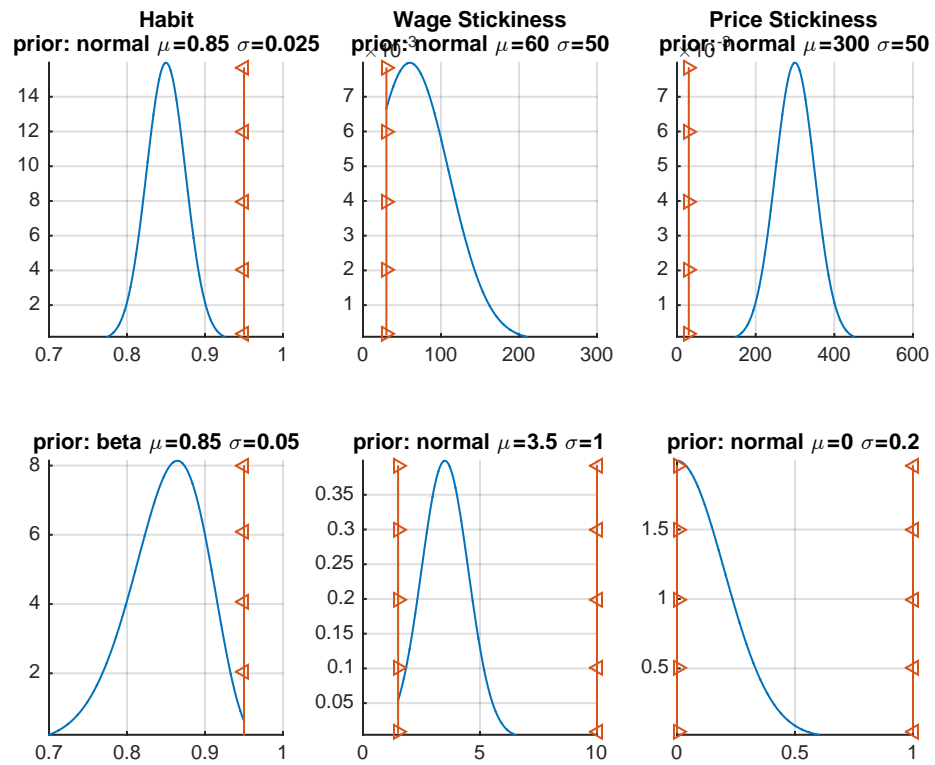
4 Visualise Prior Distributions

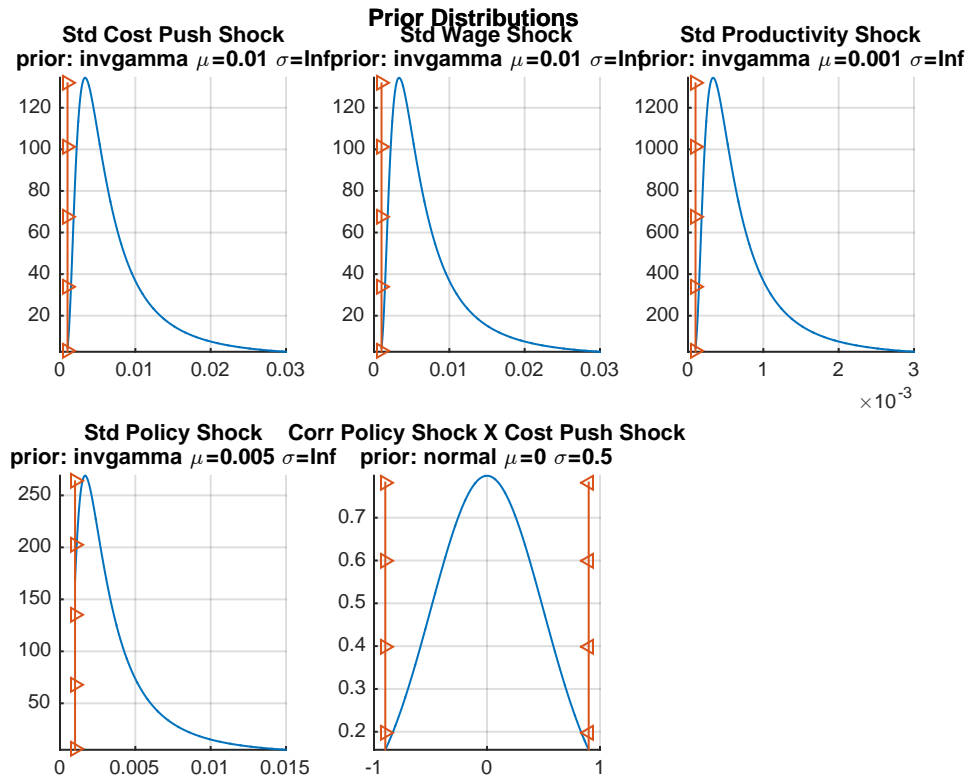
The function `plotpp` plots the prior distributions (this function can also plot the priors together with posteriors obtained from a posterior simulator – see below). To control the appearance and graphics properties of the various plots included in the graphs, use either the options `'figure='`, `'axes='` 1, `'title='` 2, `'plotprior='`, `'plotinit='`, `'plotmode='`, `'plotposter='`, `'plotbounds='`, or alternatively the standard Matlab function set with the graphics handles returned in the struct `h`.

```

78 c = autocaption(m,E,'$descript$');
79
80 [pr,po,h] = plotpp(E,[],[], ...
81   ... 'axes',{'fontsize',8}, ... 1
82   ... 'title',{'fontsize',8}, ... 2
83   'subplot',[2,3],'caption=',c); %#ok<ASGLU>
84
85 ftitle(h.figure,'Prior Distributions');

```





5 Maximise Posterior Distribution to Locate Its Mode

The main output arguments are the following (these remain the same whatever the set-up of the estimation):

- `est` – Struct with point estimates.
- `pos` – Initialised posterior simulator object. The object `pos` will be used later in this file to run a posterior simulator.
- `c` – Covariance matrix of the parameter estimates based on the asymptotical hessian of the posterior density at its mode.
- `H` – Cell array 1-by-2: H1 is the hessian of the objective function returned by the Optim Tbx (should be close to `c`); H2 is a diagonal matrix with the contributions of the priors to the total hessian.
- `mest` – Model object with the new estimated parameters.

- v – Estimate of the common variance factor (only with the option 'relative=' true, which is the default setting); all the std dev of all shocks are multiplied automatically by the square root of this number.
- δ – Estimates of the deterministic trend parameters estimated by concentrating them out of the likelihood function.

```

107 filterOpt = { ...
108     'outoflik',{'Short_','Infl_','Growth_','Wage_'}, ...
109     'relative',true, ...
110 };
111
112 optimSet = { ...
113     'maxFunEvals',10000, ...
114     'maxIter',100, ...
115 };
116
117 tic();
118 [est,pos,C,H,mest,v,~,~,delta,Pdelta] = ...
119     estimate(m,d,startHist:endHist,E, ...
120     'filter=',filterOpt,'optimSet=',optimSet);
121 toc();

```

Iter	F-count	f(x)	Max constraint	Line search steplength	Directional derivative	First-order optimality	Procedure
0	12	409.27	0				
1	26	390.185	0	0.25	-138	2.58e+04	
2	39	354.693	0	0.5	-43.3	9.24e+03	
3	52	340.247	-0.00075	0.5	-46.9	4.91e+03	
4	66	336.371	-0.0005625	0.25	-20.9	1.57e+04	
5	84	335.998	-0.0005537	0.0156	-44.2	7.07e+03	
6	101	335.576	-0.0009188	0.0312	-30.9	3.65e+03	
7	115	329.15	-0.0007087	0.25	-19.2	5.64e+03	
8	129	328.624	-0.001072	0.25	-14.8	1.01e+04	
9	143	326.323	-0.0008043	0.25	-16.8	5.56e+03	
10	158	324.633	-0.0007126	0.125	-10.4	9.42e+03	
11	174	324.243	-0.000703	0.0625	-4.7	5.82e+03	
12	188	323.447	-0.0005273	0.25	-13.3	5.52e+03	
13	203	322.677	-0.0004613	0.125	-5.3	4.86e+03	
14	217	320.276	-0.000346	0.25	-11.7	4e+03	
15	233	320.08	-0.0005059	0.0625	-5.13	4.49e+03	
16	247	319.128	-0.0003794	0.25	-4.68	3.25e+03	
17	262	318.654	-0.000332	0.125	-10	980	
18	277	318.643	-0.0003855	0.125	-1.19	2.91e+03	

19	292	318.179	-0.0003373	0.125	-2.68	6.17e+03	
20	306	318.1	-0.000253	0.25	-0.792	2.5e+03	
21	321	317.927	-0.0002503	0.125	-2.79	2.59e+03	
22	338	317.878	-0.0002831	0.0312	-2.76	2.18e+03	
23	352	317.791	-0.0002123	0.25	-1.48	1.58e+03	
24	366	317.723	-0.0002294	0.25	-1.33	538	
25	378	317.699	-0.0002119	1	-0.312	273	
26	390	317.69	-0.0002191	1	-0.119	45	
27	402	317.658	-0.0002297	1	-0.0784	495	
28	414	317.561	-0.0002496	1	-0.0643	1.32e+03	
29	426	317.349	-0.0002774	1	-0.0549	2.32e+03	
30	438	316.927	-0.0003074	1	-0.0491	3.31e+03	
31	450	316.282	-0.0003143	1	-0.0434	3.87e+03	
32	462	315.62	-0.0002653	1	-0.0371	3.24e+03	
33	474	315.353	-0.0001911	1	-0.0296	1e+03	
34	486	315.315	-0.000177	1	-1.02	306	
35	498	315.308	-0.000178	1	-0.00774	49.6	
36	510	315.308	-0.0001775	1	-0.00163	9.08	
37	522	315.307	-0.0001776	1	-0.000959	17.6	Hessian modified
38	534	315.307	-0.0001775	1	-0.000741	11	Hessian modified
39	546	315.307	-0.0001775	1	-0.00104	9.08	Hessian modified
40	558	315.306	-0.0001772	1	-0.00224	35.9	Hessian modified
41	570	315.304	-0.0001767	1	-0.00316	101	Hessian modified
42	582	315.3	-0.0001758	1	-0.00433	183	
43	594	315.288	-0.0001744	1	-0.00509	309	
44	606	315.266	-0.0001728	1	-0.00528	401	
45	618	315.238	-0.0001723	1	-0.0052	345	
46	630	315.223	-0.0001736	1	-0.00488	157	
47	642	315.219	-0.0001747	1	-0.00397	31.2	
48	654	315.219	-0.0001748	1	-0.000724	2.07	
49	666	315.219	-0.0001748	1	-5.99e-05	0.222	Hessian modified

Local minimum possible. Constraints satisfied.

fmincon stopped because the predicted change in the objective function is less than the selected value of the function tolerance and constraints are satisfied to within the default value of the constraint tolerance.

No active inequalities.

Elapsed time is 15.425097 seconds.

6 Print Some Estimation Results

```
125 disp('Point estimates');
126 est
127
128 disp('Common variance factor');
129 v
130
131 disp('Out-of-lik parameters');
132 delta
133
134 disp('Parameters in the estimated model object');
135 disp('Std deviations adjusted for the common variance factor');
136 get(mest,'parameters')
```

Point estimates

est =

chi: 0.9138
xiw: 133.8447
xip: 264.6905
rhor: 0.8587
kappap: 2.9459
kappan: 0.3419
std_Ep: 0.0041
std_Ew: 0.0024
std_Ea: 0.0014
std_Er: 0.0012

corr_Er__Ep: -0.1108

Common variance factor

v =

0.6255

Out-of-lik parameters

delta =

Short_: -3.9012
Infl_: -0.3539
Growth_: 0.0078
Wage_: -1.9244

Parameters in the estimated model object

Std deviations adjusted for the common variance factor

ans =

alpha: 1.0074
beta: 0.9962
gamma: 0.6000
delta: 0.0300
k: 10
pi: 1.0062


```

eta: 6
psi: 0.2500
chi: 0.9138
xiw: 133.8447
xip: 264.6905
rhoa: 0.9000
rhor: 0.8587
kappap: 2.9459
kappan: 0.3419
Short_: -3.9012
Infl_: -0.3539
Growth_: 0.0078
Wage_: -1.9244
std_Mp: 0
std_Mw: 0
std_Ey: 0.0079
std_Ep: 0.0032
std_Ea: 0.0011
std_Er: 9.2918e-04
std_Ew: 0.0019
corr_Ep__Er: -0.1108

```

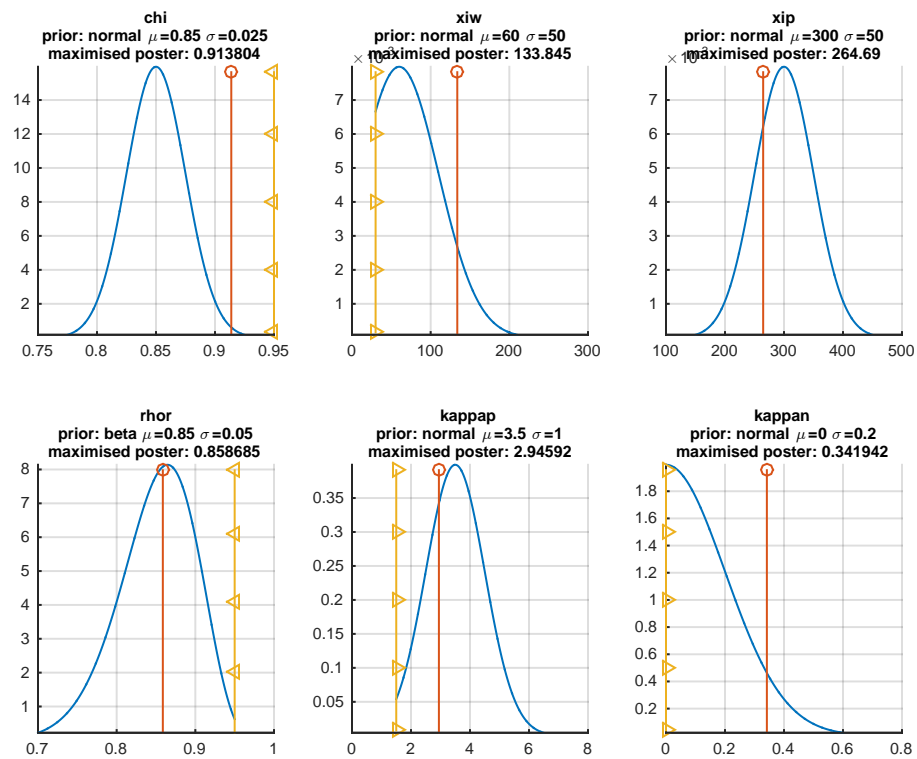
7 Visualise Prior Distributions and Posterior Modes

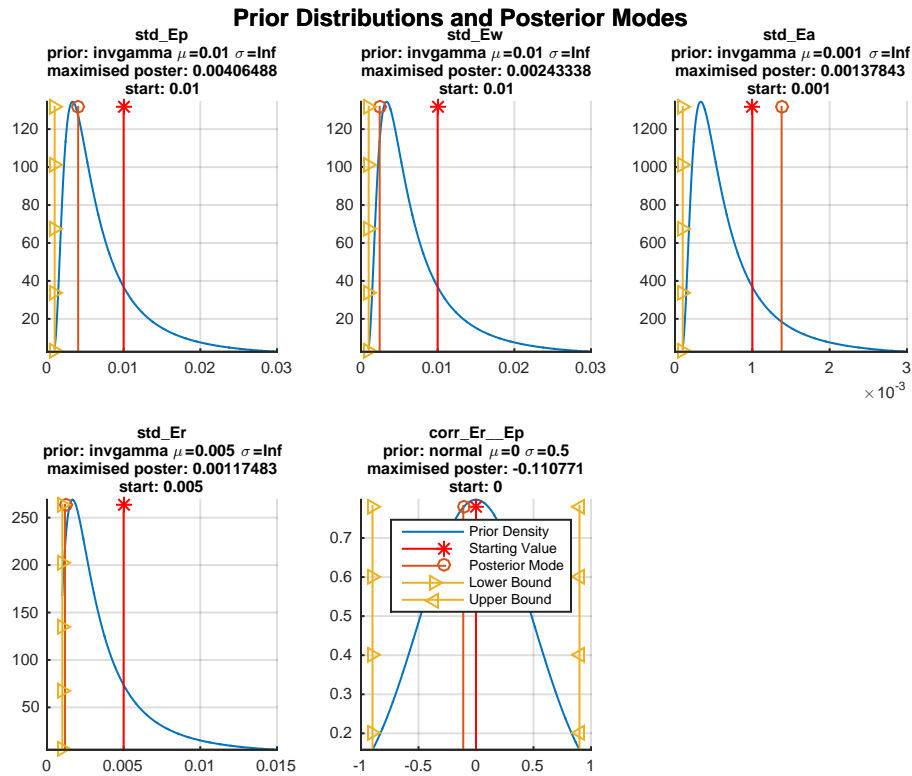
Use the function `plotpp` again supplying now the struct `est` with the estimated posterior modes as the second input argument. The posterior modes are added as stem graphs, and the estimated values are included in the graph titles.

```

145 [pr,po,h] = plotpp(E,est,[], ...
146     'title',{'fontsize=',8}, ...
147     'axes',{'fontsize=',8}, ...
148     'plotInit',{'color=', 'red', 'marker=', '*'}, ...
149     'subplot',[2,3]); %#ok<ASGLU>
150
151 ftitle(h,'Prior Distributions and Posterior Modes');
152 legend('Prior Density','Starting Value','Posterior Mode', ...
153     'Lower Bound','Upper Bound');

```





8 User Supplied Optimisation Routine

Uncomment the block of code below in order to get it executed.

Set up the `estimate` command with a user-supplied optimisation routine. Re-use the Optim Tbx's functions to illustrate the implementation details. Feel free though to use any kind of third-party solver.

Proceed in two steps:

1. Write a `mymin` m-file to organise the input and output arguments as required by the `estimate` function. Note also that an extra input argument with the settings will be passed in.
2. Call the `estimate` function and pass in a function handle to `mymin` through the option `'solver'`. Because the same routine is effectively used as before, the results ought to be identical (although the execution might be somewhat slower).

```

174 %{
175 % edit mymin.m;
176
177 tic();
178 [est1,pos1,C1,H1,mest1,v1,ans,ans,delta1,Pdelta1] = ...
179     estimate(m,d,startHist:endHist,E, ...
180     'filter=',filterOpt, ...
181     'solver=',@mymin); %#ok<NOANS,ASGLU>
182 toc();
183
184 dbfun(@(x,y) [x,y,y-x],est,est1)
185 %}

```

9 Covariance Matrix of Parameter Estimates

Compute the std deviations of the parameter estimates by taking the square roots of the diagonal entries in the Hessian returned by the optimisation routine.

```

193 plist = fieldnames(E);
194
195 std = sqrt(diag(inv(H{1})));
196
197 disp('Std deviations of parameter estimates');
198 [char(plist), num2str(std,': %-g') ]

```

```

Std deviations of parameter estimates
ans =
chi      : 0.0189469
xiw      : 39.9031
xip      : 48.452
rhorr    : 0.0295335
kappap   : 1.1377
kappan   : 0.089874
std_Ep   : 0.00056756
std_Ew   : 0.000405932
std_Ea   : 0.000306453
std_Er   : 0.000183524
corr_Er__Ep: 0.148394

```

10 Examine Neighbourhood Around Optimum

The function `neighbourhood` evaluates the posterior density (accessible through the poster object `pos`) at a number of points around the optimum for each parameter. In the code below, each parameter estimate is examined within the range of $\pm 5\%$ of the posterior mode (i.e., $0.95 : 1.05$ times the value of the estimate).

The `plotneigh` function then plots graphs depicting the local behaviour of both the overall objective function (minus log posterior density) and the data likelihood (minus log likelihood). Note that the likelihood curve is shifted up or down by an arbitrary constant to make it fit in the graph.

The option `'linkaxes'` makes the y-axes identical in all graphs to help compare the curvature of the posterior density around the individual parameter estimates. This indicates the degree of identification.

```

218 n = neighbourhood(mest,pos,0.95:0.005:1.05, ...
219     'progress=',true,'plot=',false)
220
221 plotneigh(n,'linkaxes=',true,'subplot=',[2,3], ...
222     'plotobj',{'linewidth=',2}, ...
223     'plotest',{'marker=', 'o', 'linewidth=',2}, ...
224     'plotbounds',{'lineStyle','--','lineWidth',2});

```

```
[--IRIS model.neighbourhood progress-----]
```

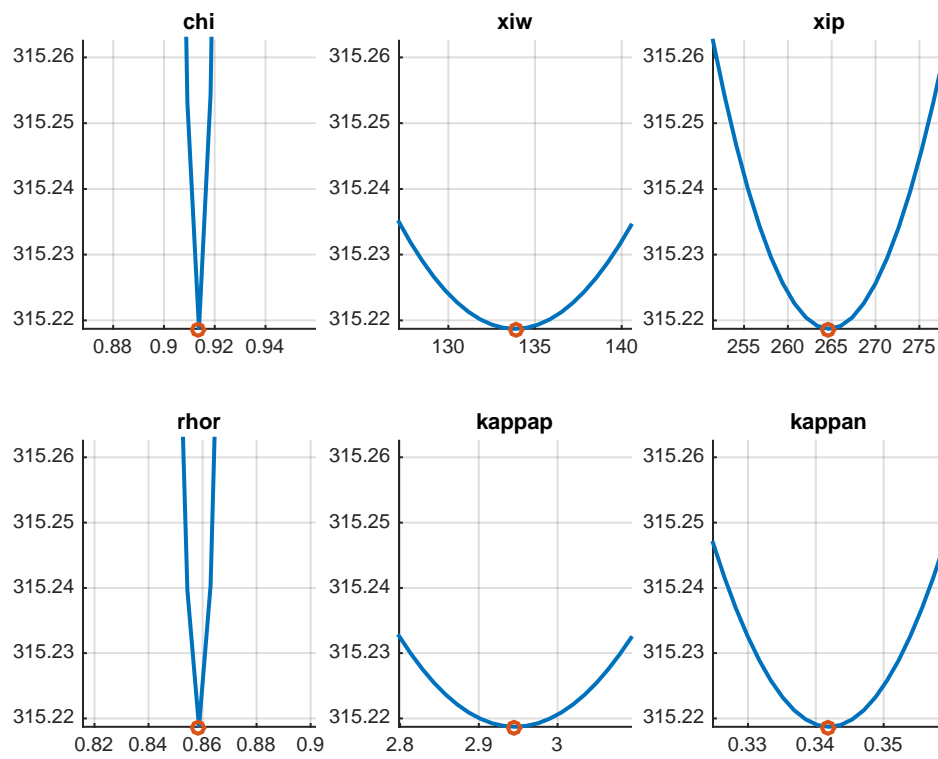
```
[*****]
```

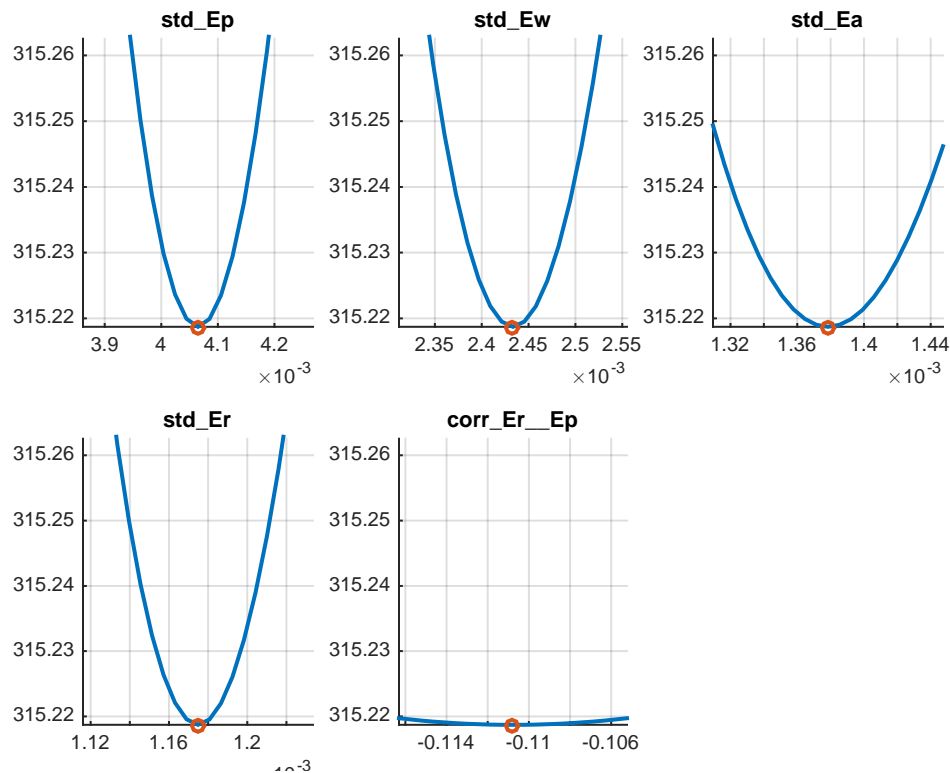
```
n =
```

```

      chi: {1x3 cell}
      xiw: {[21x1 double] [21x2 double] [133.8447 315.2187 30 1000]}
      xip: {[21x1 double] [21x2 double] [264.6905 315.2187 30 1000]}
      rhor: {1x3 cell}
      kappap: {[21x1 double] [21x2 double] [2.9459 315.2187 1.5000 10]}
      kappan: {[21x1 double] [21x2 double] [0.3419 315.2187 0 1]}
      std_Ep: {[21x1 double] [21x2 double] [1x4 double]}
      std_Ew: {[21x1 double] [21x2 double] [1x4 double]}
      std_Ea: {[21x1 double] [21x2 double] [1x4 double]}
      std_Er: {[21x1 double] [21x2 double] [1x4 double]}
      corr_Er__Ep: {[21x1 double] [21x2 double] [1x4 double]}

```





11 Run Metropolis Random Walk Posterior Simulator

Run 5,000 draws from the posterior distribution using an adaptive version of the random-walk Metropolis algorithm. The number of draws, $N=1000$, should be obviously much larger in practice (such as 100,000 or 1,000,000). Use then the function `stats` to calculate some statistics of the simulated parameter chains – by default, the simulated chains, their means, std errors, high probability density intervals, and the marginal data density are returned. Feel free to change the list of requested characteristics; see `help` on `poster/stats` for details.

The output argument `ar` monitors the evolution of the acceptance ratio. The default target acceptance ratio is 0.234 (can be modified using the option `'targetAR'` in `arwm`), the covariance of the proposal distribution is gradually adapted to achieve this target.

```

242 N = 1000
243
244 tic;
245 [theta,logpost,ar] = arwm(pos,N, ...
246     'progress=',true,'adaptScale=',2,'adaptProposalCov=',1,'burnin=',0.20);

```

```

247 toc;
248
249 disp('Final acceptance ratio');
250 ar(end)
251
252 s = stats(pos,theta,logpost)

```

```

N =
    1000
[--IRIS poster.arwm progress-----]
[*****]
Elapsed time is 22.843962 seconds.
Final acceptance ratio
ans =
    0.2390
s =
    chain: [1x1 struct]
    mean: [1x1 struct]
    std: [1x1 struct]
    hist: [1x1 struct]
    mdd: -343.3406

```

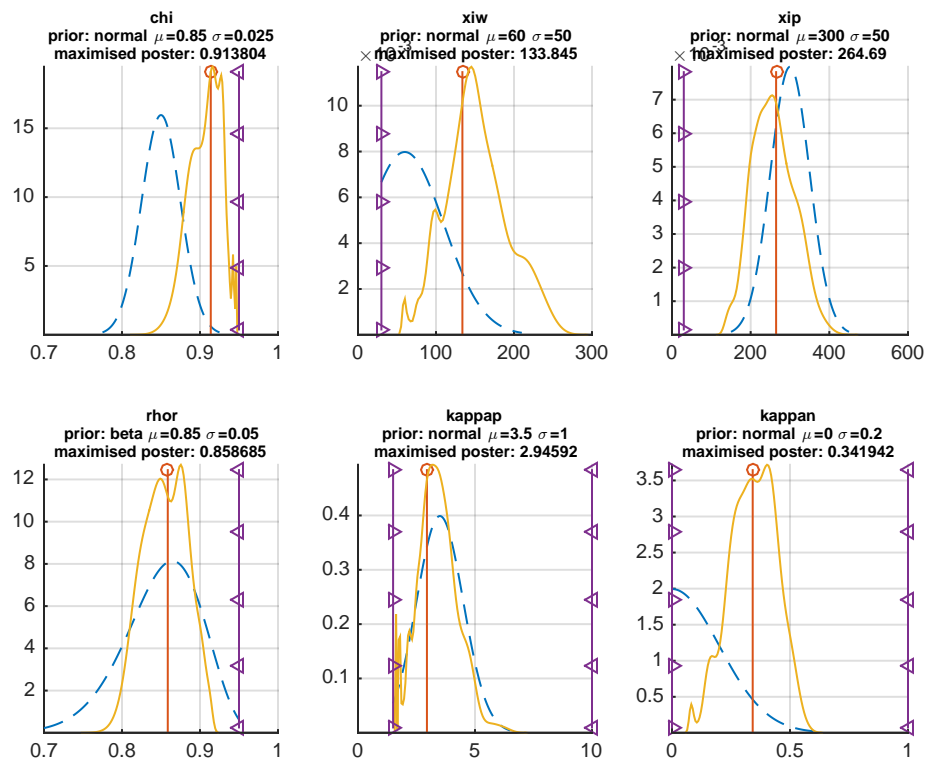
12 Visualise Priors and Posteriors

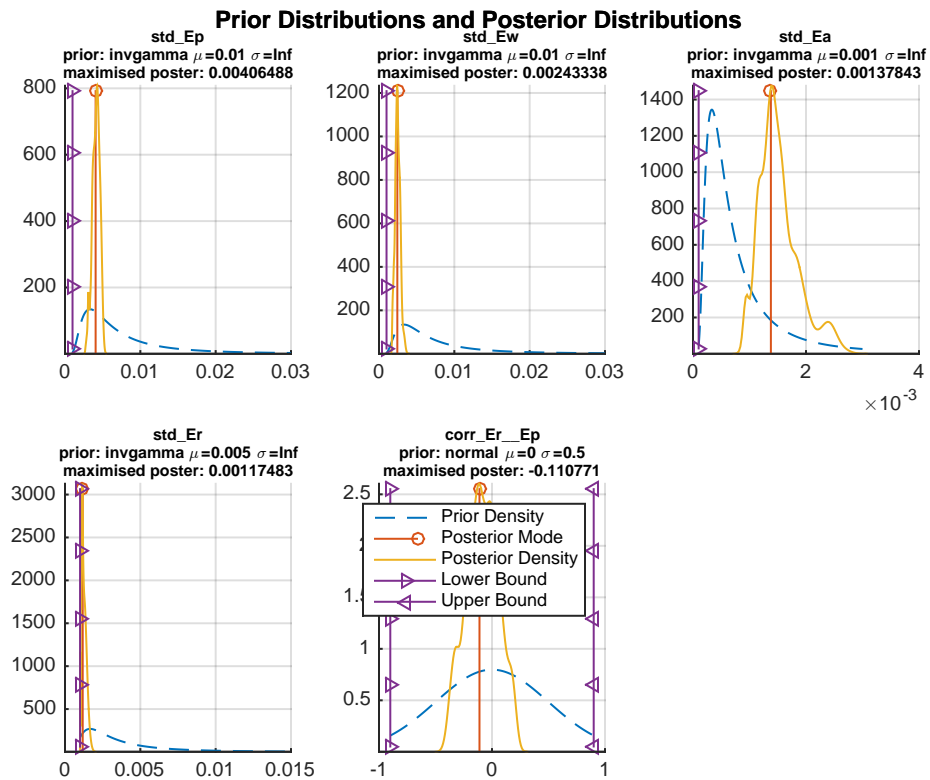
Because the number of draws from the posterior distribution is very low, $N=1000$, the posterior graphs are far from being smooth, and may visibly change if another posterior chain is generated.

```

260 [pr,po,h] = plotpp(E,est,theta, ...
261     'plotprior',{'linestyle','--'}, ...
262     'title',{'fontsize',8}, ...
263     'subplot',[2,3]);
264
265 ftitle(h.figure,'Prior Distributions and Posterior Distributions');
266
267 legend('Prior Density','Posterior Mode','Posterior Density', ...
268     'Lower Bound','Upper Bound');

```



13 Save Model Object with Estimated Parameters

```
272 save estimate_params.mat mest pos E theta logpost;
```

14 Help on IRIS Functions Used in This File

Use either `help` to display help in the command window, or `idoc` to display help in an HTML browser window.

```
help model/estimate
help model/neighbourhood
help poster/arwm
help poster/stats
help grfun/plotpp
help logdist
help logdist.normal
```

```
help logdist.lognormal
help logdist.beta
help logdist.gamma
help logdist.invgamma
help logdist.uniform
```