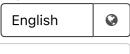
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(https://stanford.edu/~shervine/teaching/cs-229/cheatsheet-unsupervised-learning#cs-229---machine-learning)CS 229 - Machine Learning (teaching/cs-229)



Supervised Learning

Unsupervised Learning

Deep Learning

Tips and tricks

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(https://stanford.edu/~shervine/teaching/cs-229/cheatsheetunsupervised-learning#intro) Introduction to Unsupervised Learning

- \Box **Motivation** The goal of unsupervised learning is to find hidden patterns in unlabeled data $\{x^{(1)},...,x^{(m)}\}.$
- \Box **Jensen's inequality** Let f be a convex function and X a random variable. We have the following inequality:

$$E[f(X)]\geqslant f(E[X])$$

[https://stanford.edu/~shervine/teaching/cs-229/cheatsheetunsupervised-learning#clustering) Clustering

Expectation-Maximization

 \Box Latent variables — Latent variables are hidden/unobserved variables that make estimation problems difficult, and are often denoted z. Here are the most common settings where there are latent variables:

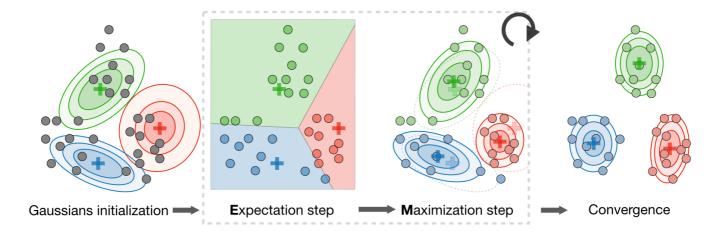
Setting	Latent variable z	x z	Comments
Mixture of k Gaussians	$\operatorname{Multinomial}(\phi)$	$\mathcal{N}(\mu_j, \Sigma_j)$	$\mu_j \in \mathbb{R}^n, \phi \in \mathbb{R}^k$
Factor analysis	$\mathcal{N}(0,I)$	$\mathcal{N}(\mu+\Lambda z,\psi)$	$\mu_j \in \mathbb{R}^n$

- □ **Algorithm** The Expectation-Maximization (EM) algorithm gives an efficient method at estimating the parameter θ through maximum likelihood estimation by repeatedly constructing a lower-bound on the likelihood (E-step) and optimizing that lower bound (M-step) as follows:
 - E-step: Evaluate the posterior probability $Q_i(z^{(i)})$ that each data point $x^{(i)}$ came from a particular cluster $z^{(i)}$ as follows:

$$oxed{Q_i(z^{(i)}) = P(z^{(i)}|x^{(i)}; heta)}$$

• M-step: Use the posterior probabilities $Q_i(z^{(i)})$ as cluster specific weights on data points $x^{(i)}$ to separately re-estimate each cluster model as follows:

$$oxed{ heta_i = rgmax \ \sum_i \int_{z^{(i)}} Q_i(z^{(i)}) \log\left(rac{P(x^{(i)}, z^{(i)}; heta)}{Q_i(z^{(i)})}
ight) dz^{(i)}}$$



k-means clustering

We note $c^{(i)}$ the cluster of data point i and μ_j the center of cluster j.

 \square Algorithm — After randomly initializing the cluster centroids $\mu_1, \mu_2, ..., \mu_k \in \mathbb{R}^n$, the k-means algorithm repeats the following step until convergence:

$$c^{(i)} = \arg\min_{j} ||x^{(i)} - \mu_{j}||^{2} \quad \text{and} \quad \boxed{\sum_{i=1}^{m} 1_{\{c^{(i)} = j\}} x^{(i)}}$$

$$\sum_{i=1}^{m} 1_{\{c^{(i)} = j\}}$$
 Means initialization \rightarrow Cluster assignment \rightarrow Means update \rightarrow Convergence

☐ **Distortion function** — In order to see if the algorithm converges, we look at the distortion function defined as follows:

$$oxed{J(c,\mu) = \sum_{i=1}^m ||x^{(i)} - \mu_{c^{(i)}}||^2}$$

Hierarchical clustering

☐ **Algorithm** — It is a clustering algorithm with an agglomerative hierarchical approach that build nested clusters in a successive manner.

☐ **Types** — There are different sorts of hierarchical clustering algorithms that aims at optimizing different objective functions, which is summed up in the table below:

Ward linkage	Average linkage	Complete linkage
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Clustering assessment metrics

In an unsupervised learning setting, it is often hard to assess the performance of a model since we don't have the ground truth labels as was the case in the supervised learning setting.

 \Box Silhouette coefficient — By noting a and b the mean distance between a sample and all other points in the same class, and between a sample and all other points in the next nearest cluster, the silhouette coefficient s for a single sample is defined as follows:

$$\boxed{s = \frac{b-a}{\max(a,b)}}$$

 \Box Calinski-Harabaz index — By noting k the number of clusters, B_k and W_k the between and within-clustering dispersion matrices respectively defined as

$$B_k = \sum_{j=1}^k n_{c^{(i)}} (\mu_{c^{(i)}} - \mu) (\mu_{c^{(i)}} - \mu)^T, \qquad W_k = \sum_{i=1}^m (x^{(i)} - \mu_{c^{(i)}}) (x^{(i)} - \mu_{c^{(i)}})^T$$

the Calinski-Harabaz index s(k) indicates how well a clustering model defines its clusters, such that the higher the score, the more dense and well separated the clusters are. It is defined as follows:

$$oxed{s(k) = rac{ ext{Tr}(B_k)}{ ext{Tr}(W_k)} imes rac{N-k}{k-1}}$$

[https://stanford.edu/~shervine/teaching/cs-229/cheatsheetunsupervised-learning#dimension-reduction) Dimension reduction

Principal component analysis

It is a dimension reduction technique that finds the variance maximizing directions onto which to project the data.

 \square **Eigenvalue, eigenvector** — Given a matrix $A \in \mathbb{R}^{n \times n}$, λ is said to be an eigenvalue of A if there exists a vector $z \in \mathbb{R}^n \setminus \{0\}$, called eigenvector, such that we have:

$$Az=\lambda z$$

 \square Spectral theorem — Let $A\in\mathbb{R}^{n\times n}$. If A is symmetric, then A is diagonalizable by a real orthogonal matrix $U\in\mathbb{R}^{n\times n}$. By noting $\Lambda=\mathrm{diag}(\lambda_1,...,\lambda_n)$, we have:

$$oxed{\exists \Lambda ext{ diagonal}, \quad A = U \Lambda U^T}$$

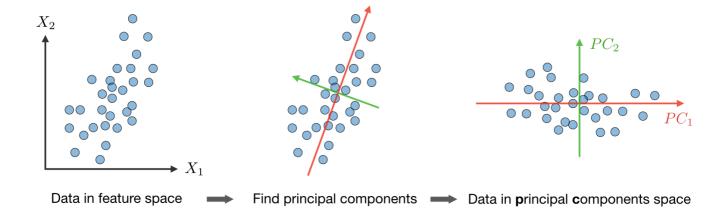
Remark: the eigenvector associated with the largest eigenvalue is called principal eigenvector of matrix A.

- \Box **Algorithm** The Principal Component Analysis (PCA) procedure is a dimension reduction technique that projects the data on k dimensions by maximizing the variance of the data as follows:
 - Step 1: Normalize the data to have a mean of 0 and standard deviation of 1.

$$oxed{x_j^{(i)} \leftarrow rac{x_j^{(i)} - \mu_j}{\sigma_j}} \quad ext{where} \quad oxed{\mu_j = rac{1}{m} \sum_{i=1}^m x_j^{(i)}} \quad ext{and} \quad oxed{\sigma_j^2 = rac{1}{m} \sum_{i=1}^m (x_j^{(i)} - \mu_j)^2}$$

- Step 2: Compute $\Sigma=rac{1}{m}\sum_{i=1}^m x^{(i)} x^{(i)}^T\in\mathbb{R}^{n imes n}$, which is symmetric with real eigenvalues.
- Step 3: Compute $u_1, ..., u_k \in \mathbb{R}^n$ the k orthogonal principal eigenvectors of Σ , i.e. the orthogonal eigenvectors of the k largest eigenvalues.
- Step 4: Project the data on $\operatorname{span}_{\mathbb{R}}(u_1,...,u_k)$.

This procedure maximizes the variance among all k-dimensional spaces.



Independent component analysis

It is a technique meant to find the underlying generating sources.

 \square **Assumptions** — We assume that our data x has been generated by the n-dimensional source vector $s=(s_1,...,s_n)$, where s_i are independent random variables, via a mixing and non-singular matrix A as follows:

$$x = As$$

The goal is to find the unmixing matrix $W = A^{-1}$.

- \Box Bell and Sejnowski ICA algorithm This algorithm finds the unmixing matrix W by following the steps below:
 - Write the probability of $x=As=W^{-1}s$ as:

$$p(x) = \prod_{i=1}^n p_s(w_i^T x) \cdot |W|$$

• Write the log likelihood given our training data $\{x^{(i)}, i \in [\![1,m]\!]\}$ and by noting g the sigmoid function as:

$$l(W) = \sum_{i=1}^m \left(\sum_{j=1}^n \log\left(g'(w_j^T x^{(i)})
ight) + \log|W|
ight)$$

Therefore, the stochastic gradient ascent learning rule is such that for each training example $x^{(i)}$, we update W as follows:

$$W \longleftarrow W + \alpha \begin{pmatrix} \begin{pmatrix} 1 - 2g(w_1^Tx^{(i)}) \\ 1 - 2g(w_2^Tx^{(i)}) \\ \vdots \\ 1 - 2g(w_n^Tx^{(i)}) \end{pmatrix} x^{(i)^T} + (W^T)^{-1} \end{pmatrix}$$





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