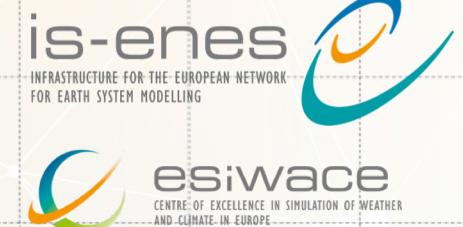
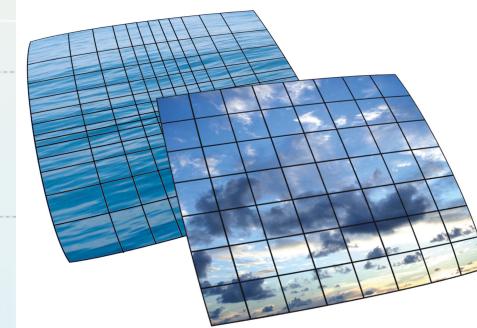




EUROPEAN CENTRE FOR RESEARCH AND ADVANCED TRAINING IN SCIENTIFIC COMPUTING



Latest developments of the OASIS3-MCT coupler for improved performance



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Outline

Historical overview

User community

Latest developments

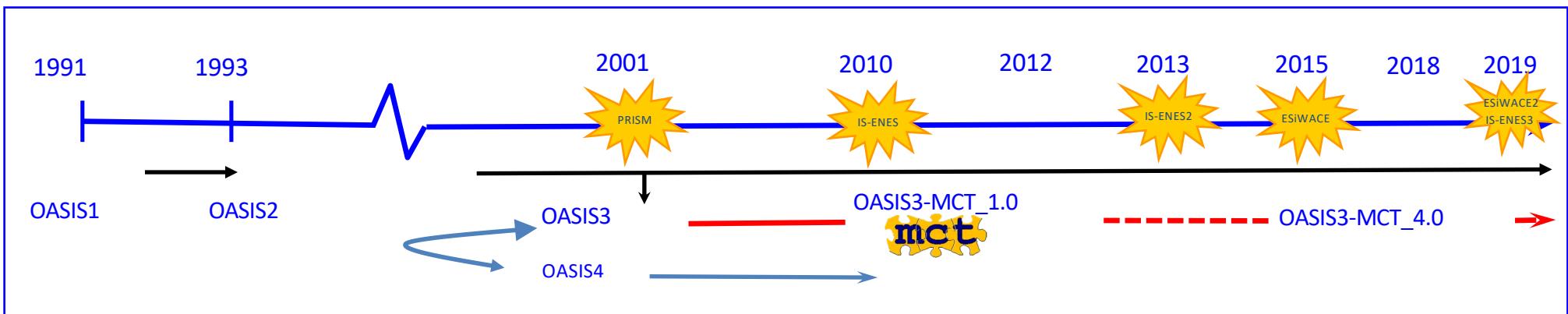
On-going developments

Conclusion

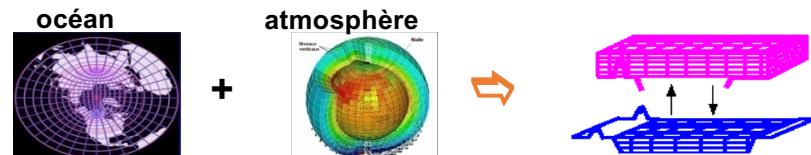


CERFACS

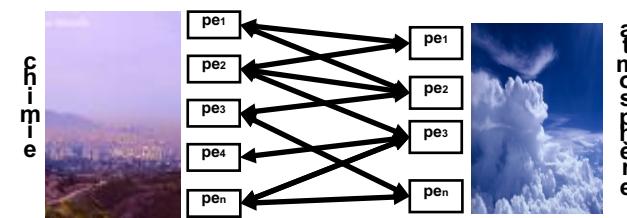
Historical overview



- OASIS1 -> OASIS2 -> OASIS3:
2D ocean-atmosphere coupling
low frequency, low resolution :
→ **Flexibility, 2D interpolations**



- OASIS4 / OASIS3-MCT:
2D/3D coupling of high-resolution parallel components
→ **Parallelism, performance**



- F90 & C, LGPL licence, public domain libraries (MPI, NetCDF, SCRIP, MCT)





User community

2019 survey

67 climate
modelling
groups around
the world use
OASIS3-MCT ...



....
to assemble
more than
80 coupled
applications
!!

OASIS3-MCT is used in 5 of the 7 European ESMs participating to CMIP6



OASIS3-MCT_4 .0 (June 2018 release)

- Bundle fields
- Activation of « nointerp » for identical grids – impact on IS-ENES2 benchmarks
- New more performant algorithms for the global CONSERV operation
- Upgrade to 2.10beta1 MCT library : reduces by O(10) – O(100) MCT router initialization cost
- Debugging of the coupling initialisation
- Optimisation of the communication using the mapping weights
- Hybrid MPI+OpenMP parallelisation of the SCRIP library



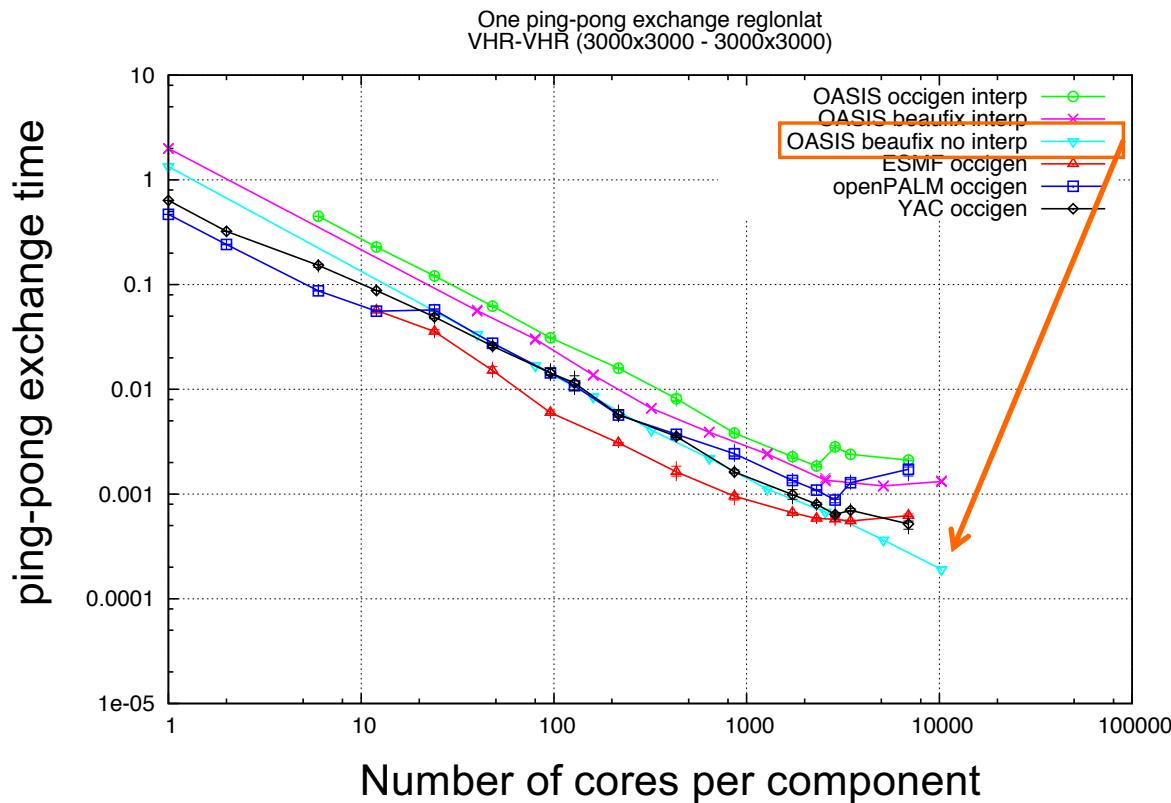
Latest developments

Since June 2018(trunk version):

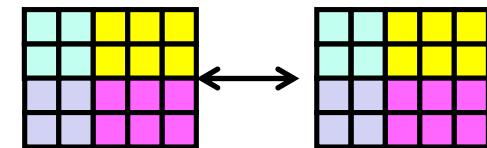
- Fractional masks for the global conservation operation CONSERV
- New options in global CONSERV to conserve fields with average value close to zero
- « True » area normalisation in conservative remapping
- Possibility to deactivate the “additional nearest-neighbour” option (BILINEARNF, BICUBICNF, DISTWGTNF, and GAUSWGTNF)
- Bugfix for local distance calculation in GAUSWGT interpolation
- More systematic test of NetCDF returned error code



"nointerp" : bypass matrix-vector multiplication for identical grids



IS-ENES2 benchmark VHR:
ping-pong exchange between
3000x3000 regular lat-lon grids
same decomposition





New algorithms for the global CONSERV operation

Different algorithms with different trade-offs between performance and reproduciblity

- *gather* : field gathered and summed on master process: costly but bit-for-bit reproducibility
- *lsum8*: local sum by each process, sent to all other processes, then global sum by all: fastest but no bit-for-bit reproducibility
- *lsum16* : as *lsum8* with quadruple precision : 2 x slower than *lsum8* but higher chance of reproducibility
- *ddpdd*: parallel double–double algorithm with single scalar reduction (He & Ding, 2001)
- *reprosum*: fixed point method based on ordered double integer sums (Mirin & Worley, 2012) : bit-for-bit results except in extremely rare cases

cores, mapping	CONSERV unset	CONSERV <i>lsum8</i>	CONSERV <i>lsum16</i>	CONSERV <i>ddpdd</i>	CONSERV <i>reprosum</i>	CONSERV <i>gather</i>
48, <i>src</i>	4.00	8.27	16.78	10.65	17.34	117.72
48, <i>dst</i>	4.39	8.02	16.59	10.42	16.98	142.12
180, <i>src</i>	1.25	2.21	4.59	2.87	4.85	126.91
180, <i>dst</i>	1.56	2.26	4.62	2.92	4.90	130.01

ORCA025 - T799
Cerfacs Lenovo

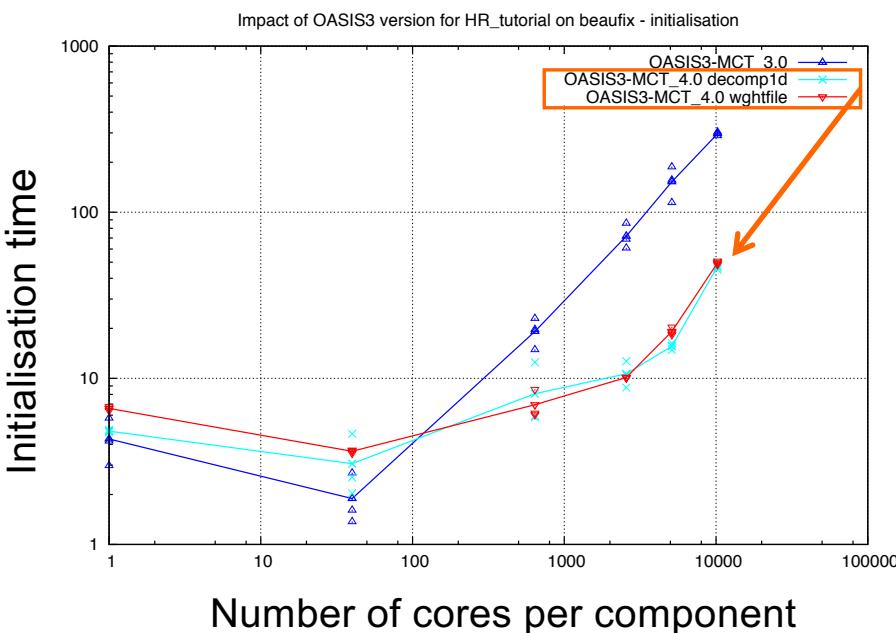
➤ *reprosum* is the new default: bit-for-bit reproducibility (except in extremely rare cases) and 7/26 times faster than *gather* on 48/180 cores



Debugging of the coupling initialisation

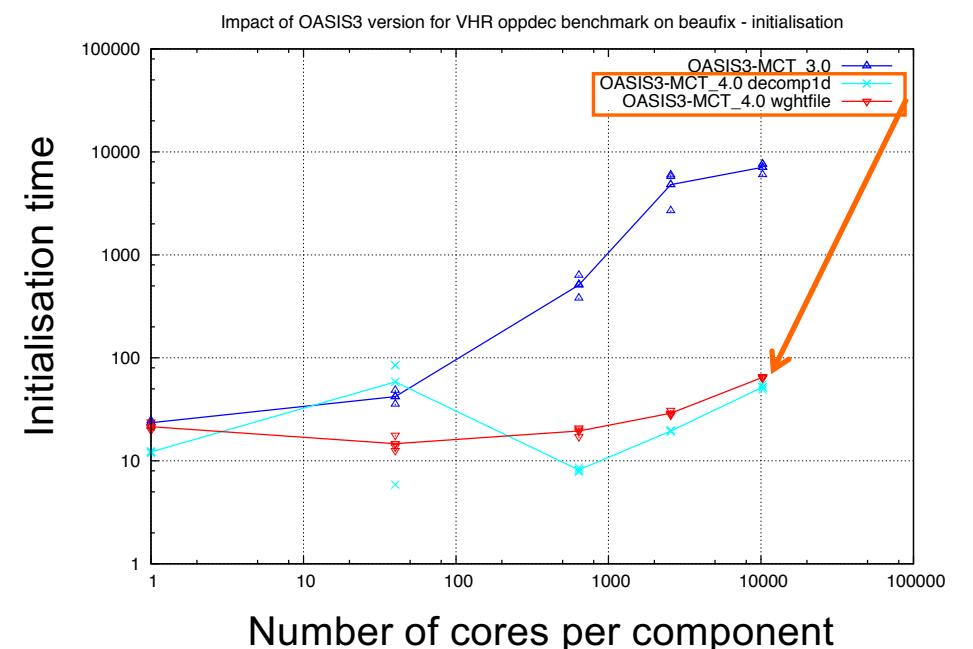
Bugfix: removal of concurrent writing into the OASIS3-MCT debug files at initialization

NEMO ORCA025 grid (1021x1442) –
Gaussian Reduced T799 grid (843 000)



⇒ 82% reduction in init time at 10240 cores

IS-ENES benchmark VHR: 3000x3000
reg lat-lon grids, opposite decompositions



⇒ 99% reduction in init time at 10240 cores



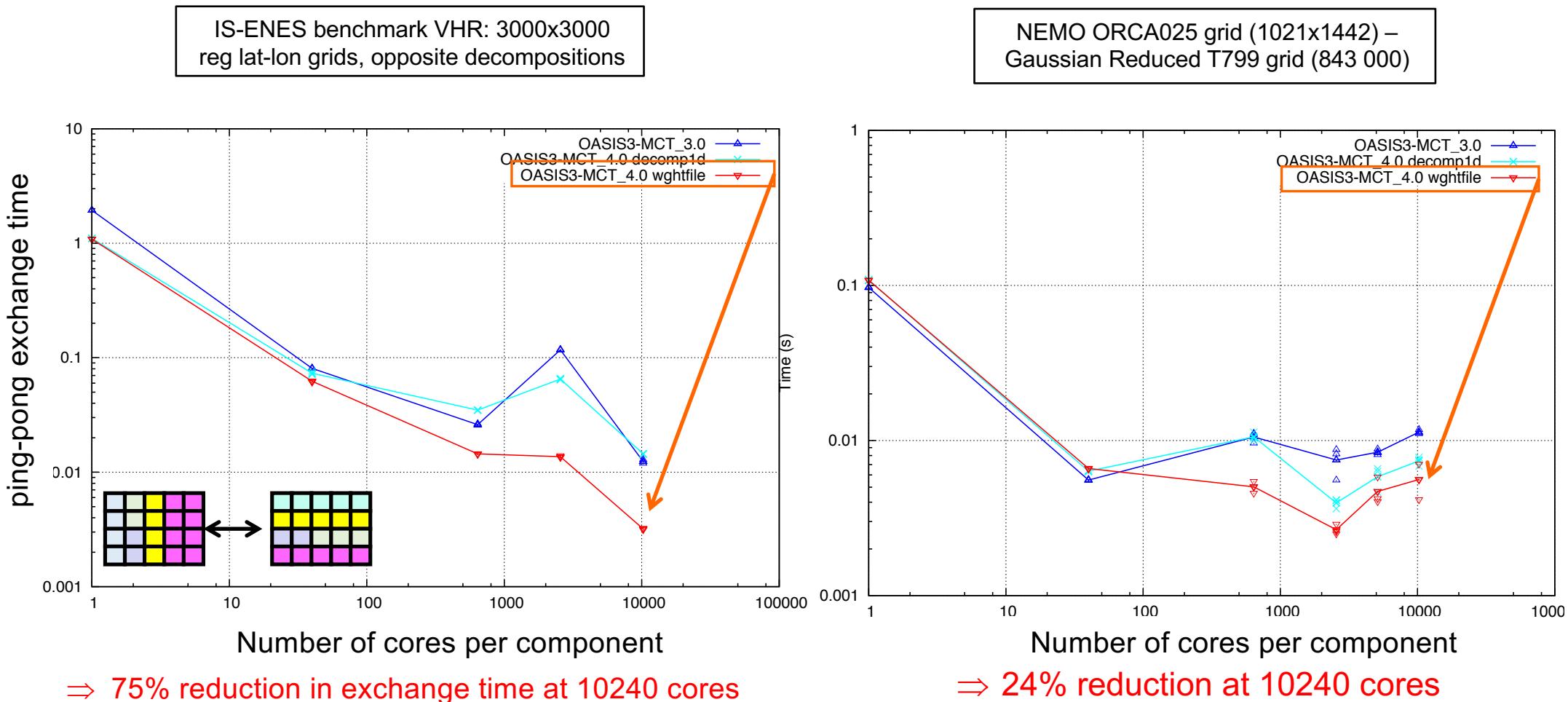
Optimisation of the communication using the mapping weights

Current implementation requires to treat mapping and cross-component communication separately; therefore, a “mapping decomposition” of the target grid on the source tasks is created:

- *decomp_1d* : each target grid point is assigned to a source task in a trivial 1-D way
- *decomp_wghtfile*: a target grid point is associated with the source task that holds the source grid points needed for calculation of its interpolated value:
 - mapping communication reduced (number and size of messages)
 - same cost for sparse matrix multiply
 - same cost communication between source and target

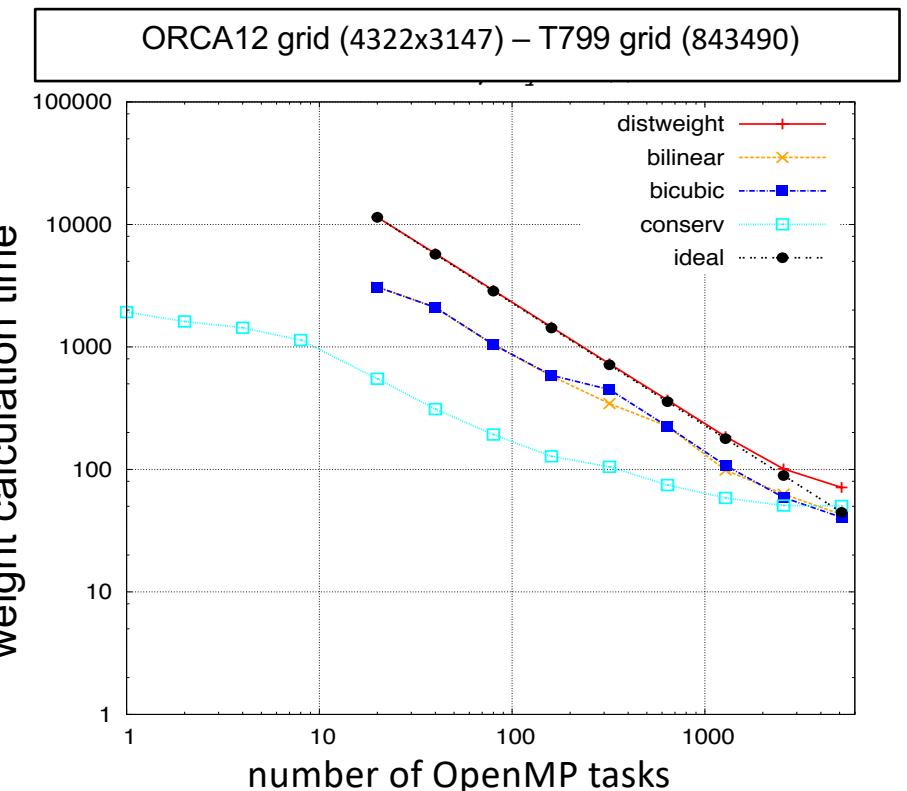
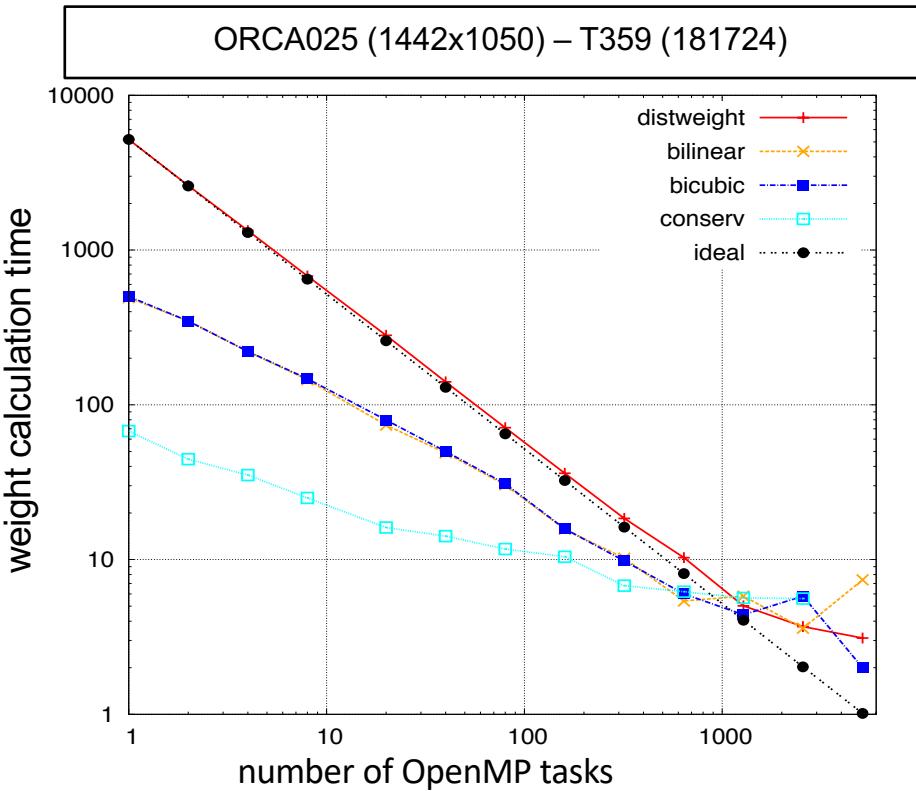


Optimisation of the communication using the mapping weights





Hybrid MPI+OpenMP parallelisation of the SCRIP library



- Almost perfect scalability for nearest-neighbour and bilinear (-> 1280 tasks for HR;-> 2560 tasks for VHR)
- Good scalability for bicubic remapping
- Less scalability for conservative remapping, due to better sequential performance (bin restriction)
- **Reduction in the weight calculation time of O(10)-O(100) at high number of cores**



On-going developments

- Beta version of API for python codes (STFC)
- Additional and improved diagnostics
- Additional pre- and post-processing transformation
- Redesign of the LUCIA load-balancing tool (with BSC)
- Analysis of ESMF, XIOS, YAC, ATLAS, MOAB-TempestRemap interpolation library
- Replacement of SCRIP with one of the above
 - OASIS3-MCT_5.0, 12/2021
- Support of grids with mask evolving with time (?)



Analysis of SCRIP library

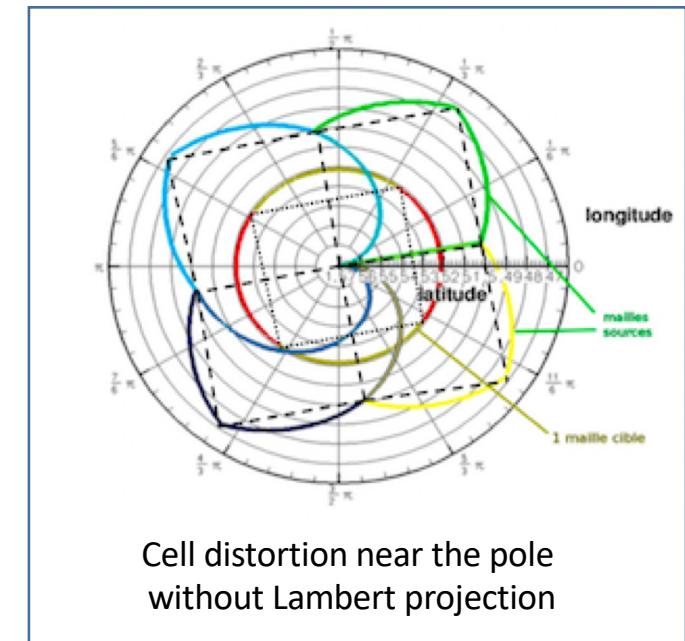
Detailed analysis of the quality of the SCRIP library

(CERFACS tech reports: Jonville & Valcke 2019, Valcke & Piacentini 2019)

- 4 grid types : lon-lat, logically-rectangular, icosahedral, Gaussian-reduced
- Two normalisation options : FRACAREA (intersected area) and DESTAREA (full area)
- Impact of Lambert equivalent azimuthal projection

For lon-lat, logically-rectangular, icosahedral grids:

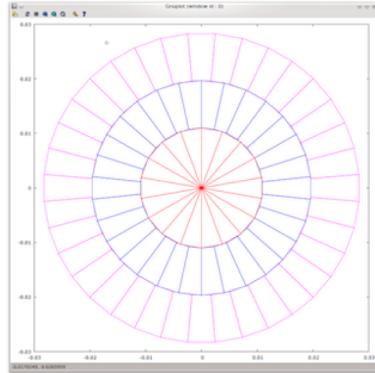
- FRACAREA OK for all grids with and without Lambert projection
- DESTAREA OK for all grids but
 - log.rect <-> lon-lat: only if Lambert projection is activated
 - icos -> log.rect: only if Lambert projection is not activated
 - log.rect -> icos: Lambert projection does not change the results



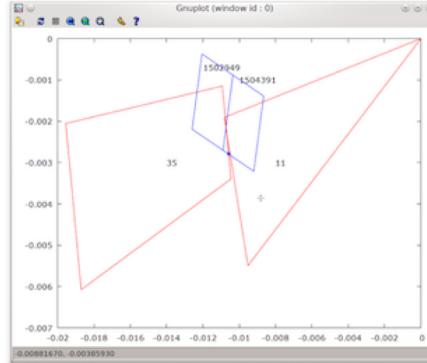


Analysis of SCRIP interpolation library

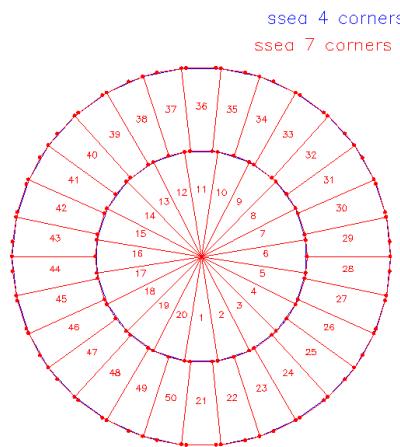
Detailed analysis of the SCRIP remapping quality for the Gaussian-reduced grid :



Gaussian-Reduced cells defined with 4 vertices : corners of a cell do not necessarily match the corners of a neighbour cell



Gaussian-Reduced cells defined with 4 vertices (in red) in Lambert space : the grid cells do not completely cover the globe



Gaussian-Reduced cells defined with 7 vertices: corners of a cell match corners of a neighbour cell

For Gaussian-reduced grids:

- FRACAREA OK without Lambert projection (4-corner and 7-corner grid)
- DESTAREA not OK: significant error with & without Lambert projection (4-corner and 7-corner grid)



Analysis of other interpolation libraries: on-going ...

ESMF:

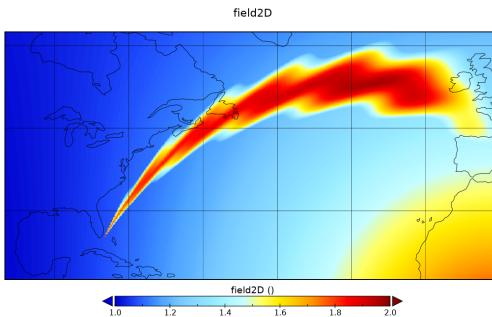
- Very good candidate: complete, efficient, very good user support
- Still some issues with ORCA grid on the North-fold

ATLAS (ECMWF) (CERFACS Tech Rep, Piacentini 2020) :

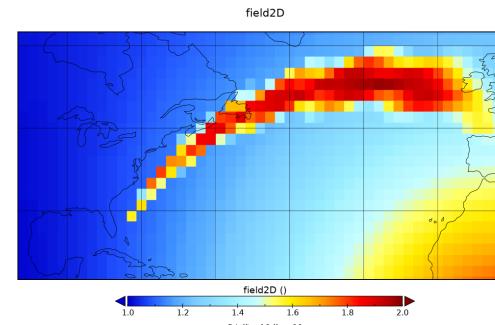
- Appealing, provides a useful portable toolkit for the best usage of new heterogeneous architectures
- But cannot be used in OASIS3-MCT **on the short term** (no handling of masked values, no conservative regrid, low support for geometries and representations from existing models, ...)

XIOS (IPSL):

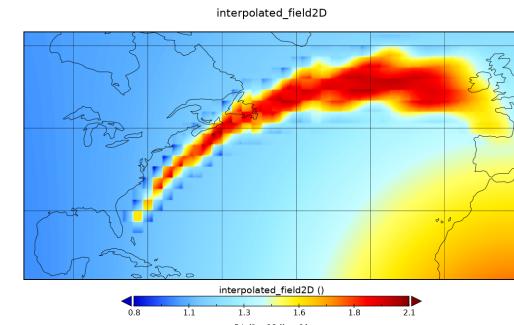
- Very interesting 2nd O conservative regrid (no need to provide field gradient, Kritsikis 2015)



Analytical field on ORCA025



Analytical field on 2° reg lat-lon



Interpolated field from 2° reg lat-lon to ORCA025



Conclusions

- OASIS is still there and lively
- Large and always growing community
- Active developments and user support (IS-ENES3 and ESiWACE2 funding)
- Needs some reshape of its interpolation library (OASIS3-MCT_5.0 December 2021)
- Next challenges:
 - use of MCT : good enough for next big coupled systems?
 - support of dynamic grids, recalculation of regridding weights during the simulation



THE CONSORTIUM

Coordinated by CNRS-IPSL, the IS-ENES3 project gathers 22 partners in 11 countries



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