



# Coupling a moving-mesh to a fixed grid

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# Contents



- What do we want from the sea-ice model?
  - What is neXtSIM?
  - Why a Lagrangian moving mesh?
- The coupling problem
  - Dynamic mesh and domain decomposition
  - Conservative remapping
- The road ahead

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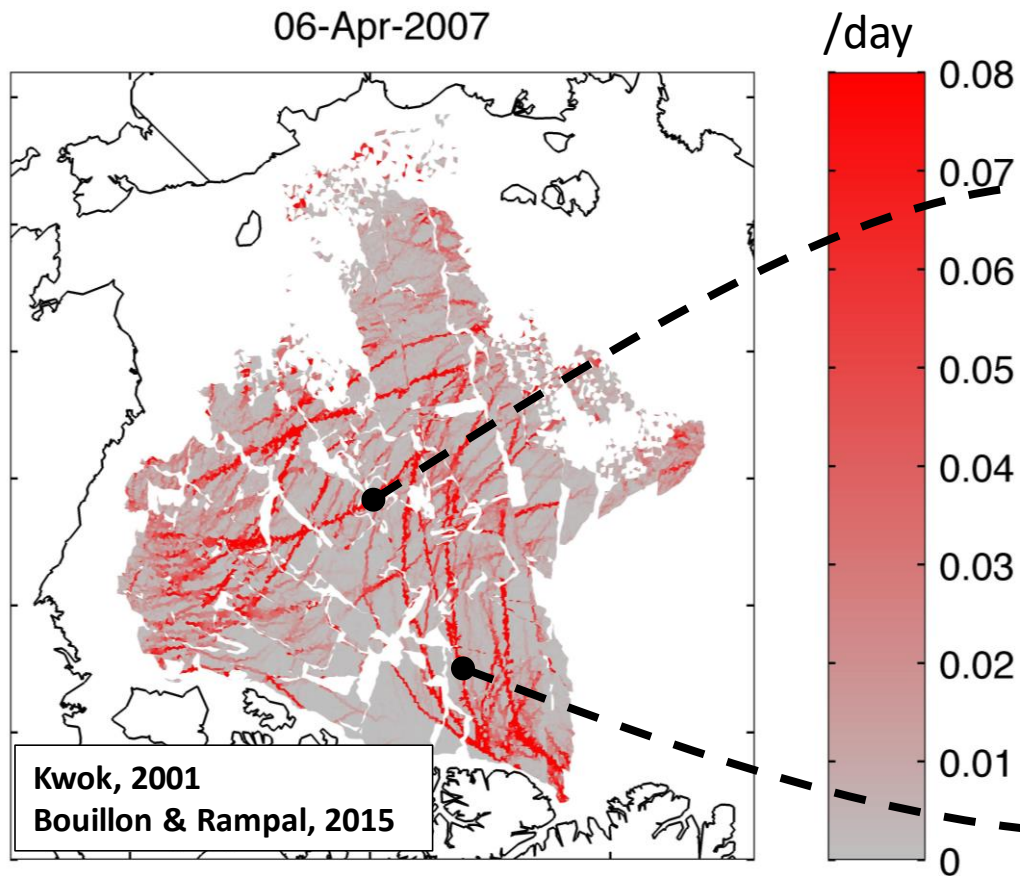
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# Pack-ice is a fracturing solid



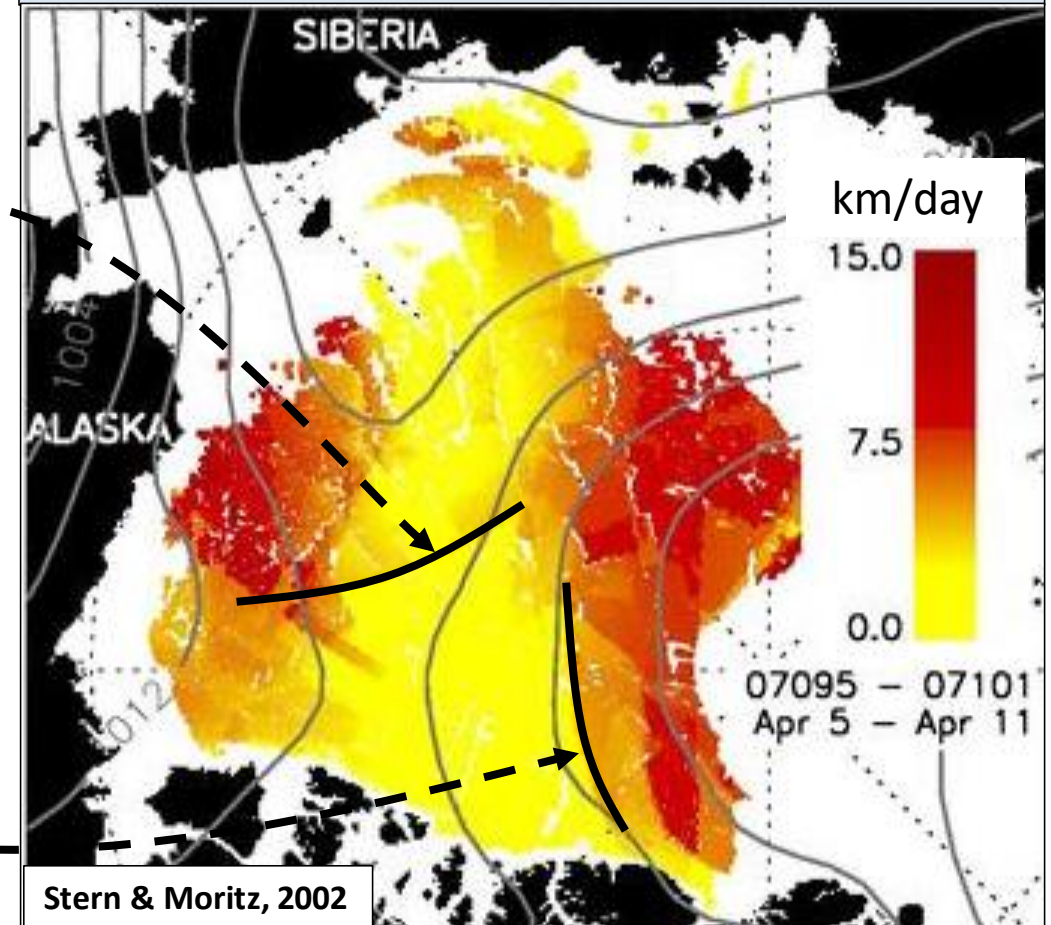
*“LKF: Heterogeneous and intermittent”*

sea ice deformation rate (Data: SAR - Radarsat)



*“Piecewise rigid motion”*

sea ice drifting speed (Data: SAR - Radarsat)



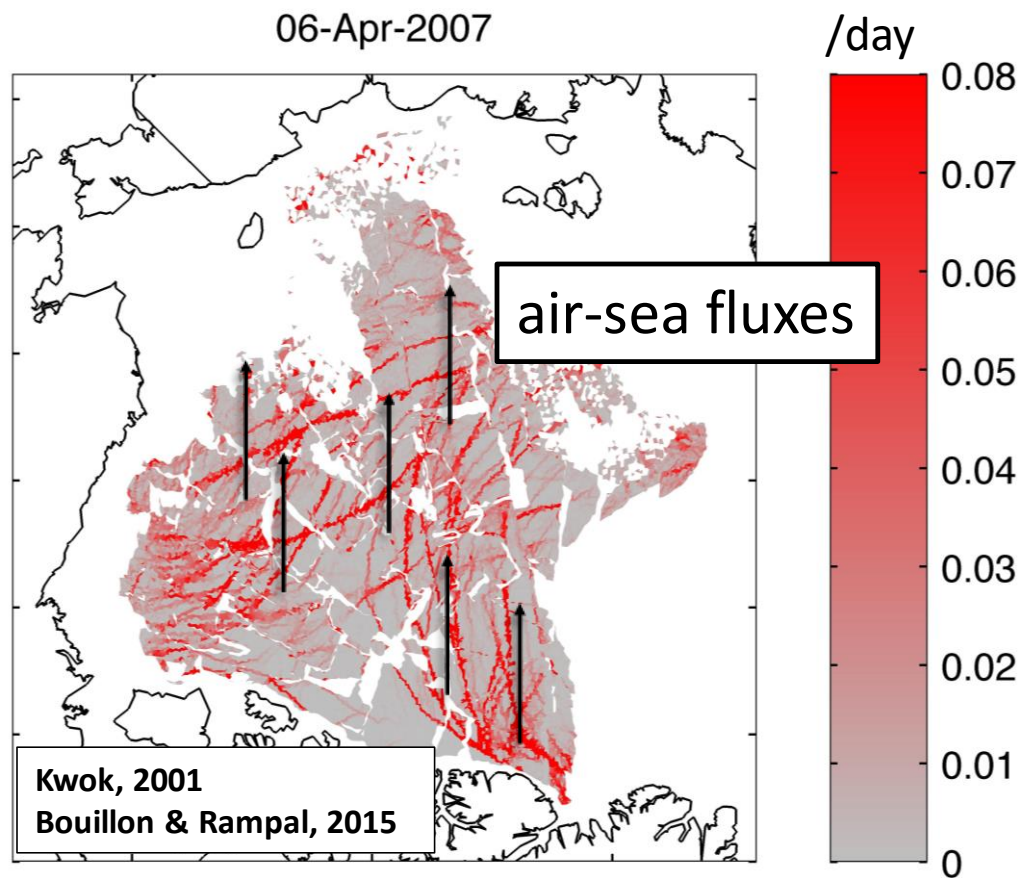


# Pack-ice is a fracturing solid



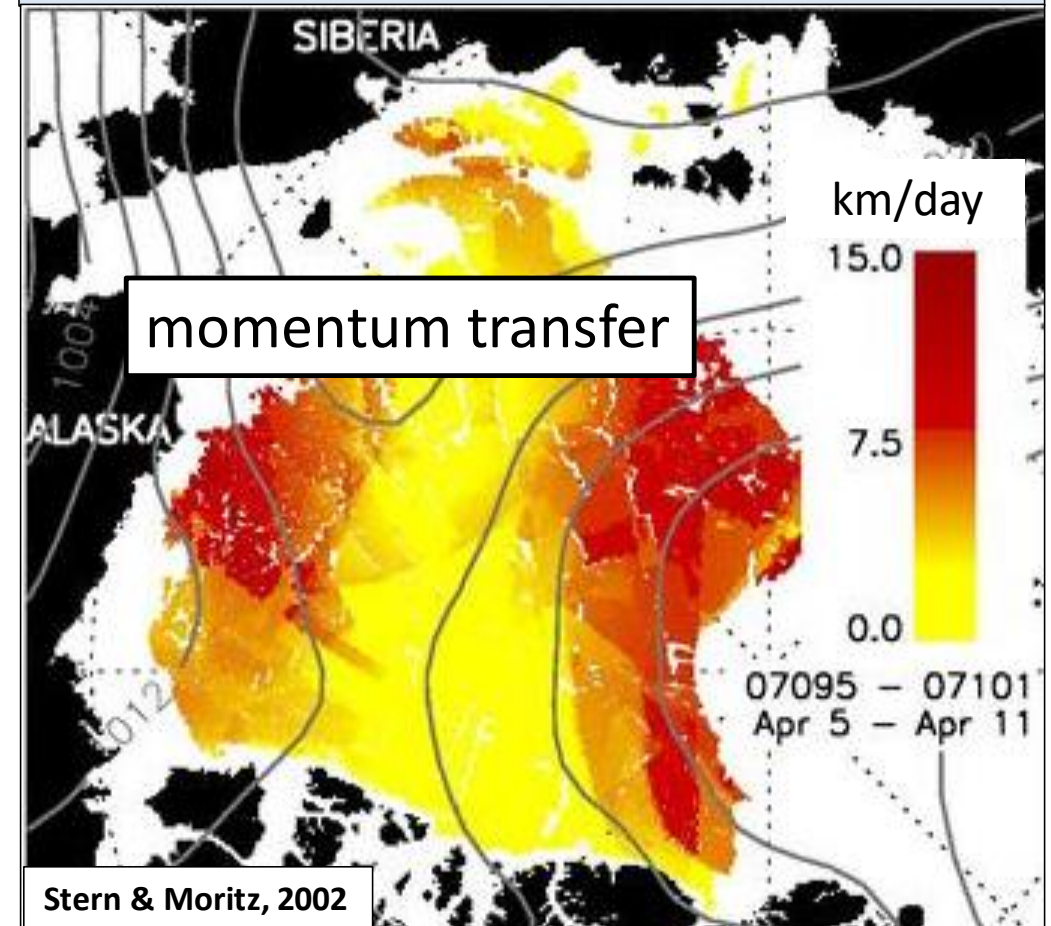
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- Why a Lagrangian moving mesh?

Bouillon and Rampal, 2015  
Rampal et al., 2016  
Samaké et al., 2017  
Dansereau et al., 2017  
Rampal et al., 2019

Maxwell-elasto-brittle rheology

- Long-range elastic interaction
- Memory of ice damage

Lagrangian moving mesh

- Finite-Element discretisation
- Adaptive remeshing

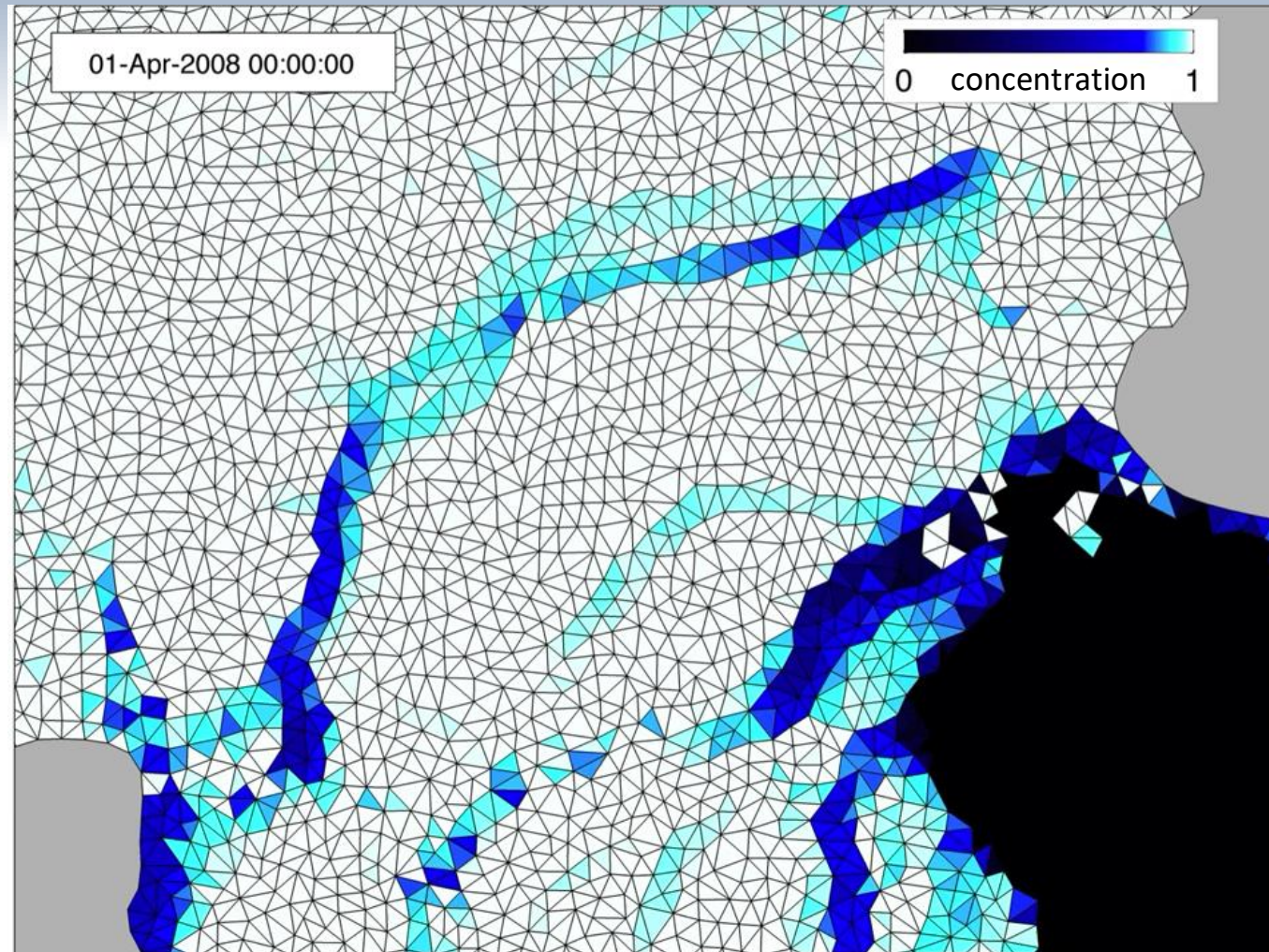
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  1. Localisation
  2. Localisation
  3. Localisation
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# Localisation is neXtSIM's key feature



5th Workshop on Coupling Technologies for  
Earth System Models (CW2020)



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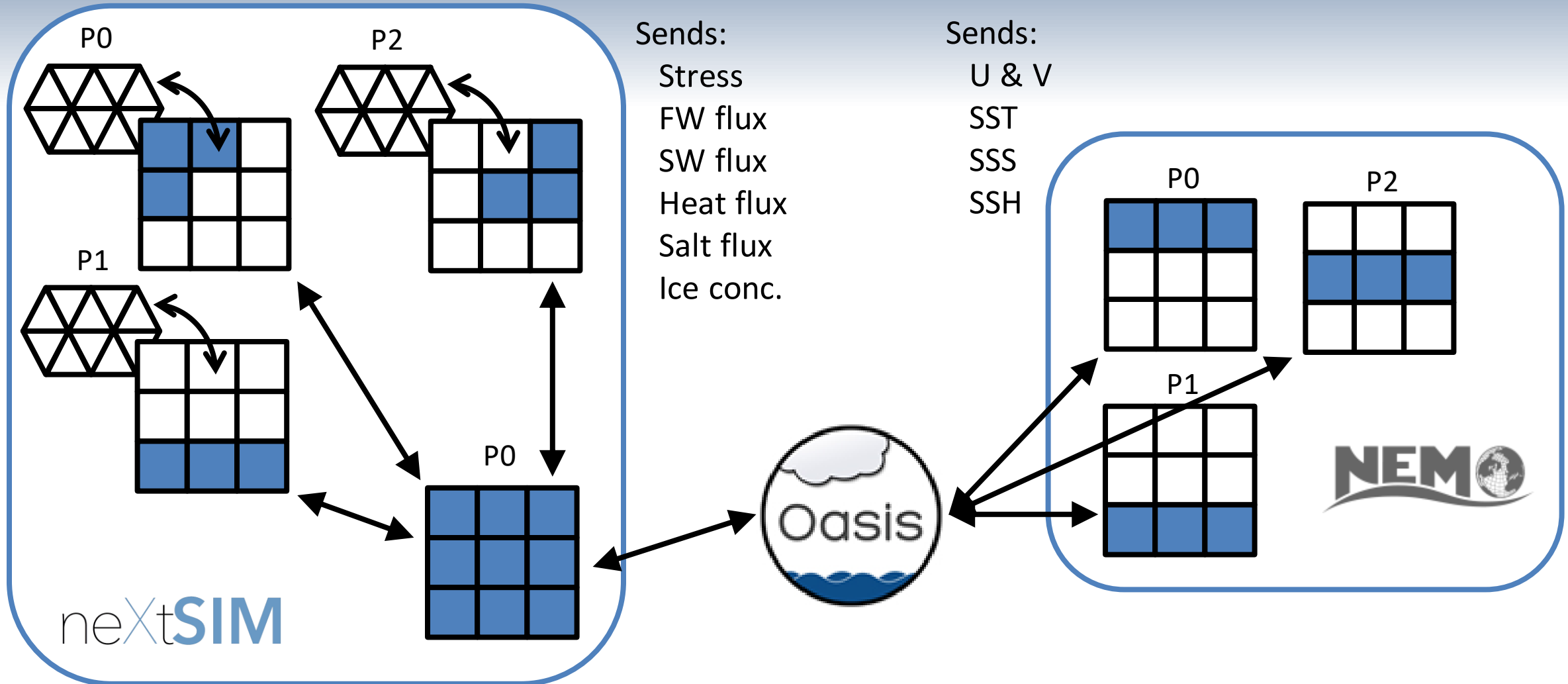
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# Coupling moving mesh is hard



- When the mesh is too deformed we remesh:
  1. Gather all fields to the root processor
  2. Generate new mesh and domain decomposition
  3. Scatter the new fields to the compute nodes
- **Mesh and domain decomposition are dynamic**
- Coupler should recompute weights and communication paths ... but nobody does that!

# Solution: Coupling exchange grid



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# Need conservative remapping

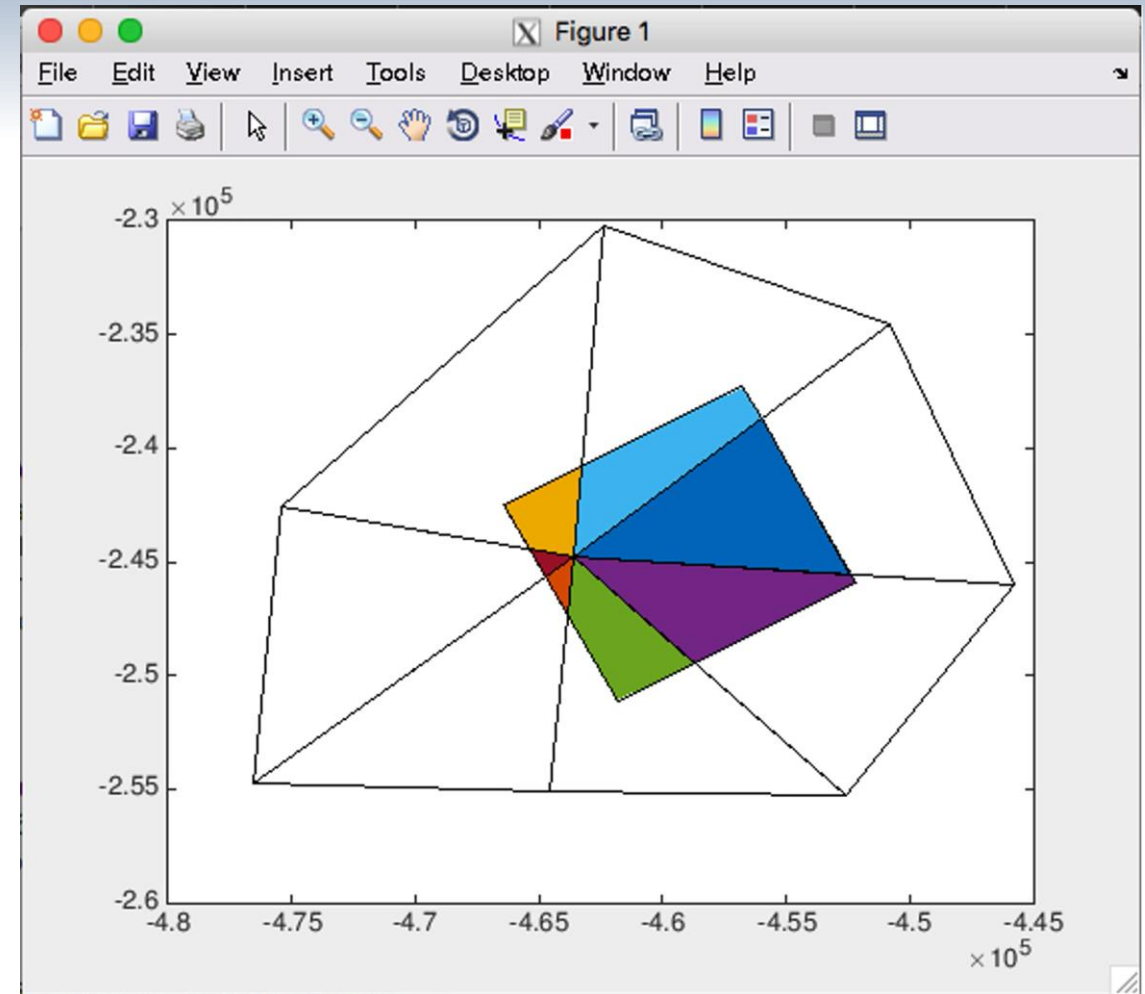


- Fluxes between ice and ocean must be conserved!
- Use weighted averages of overlapping areas of grid cells and triangles
- Interpolation weights are calculated on the root when remeshing
- Interpolation is done in parallel

# Conservative remapping algorithm



- For each grid cell find the triangle covering its centre point (quadtree).
- Do three checks (recursive):
  1. Check & record which vertexes are inside the cell  
=> If inside: Call self for surrounding triangles
  2. Check & record which of the grid cell corners are inside the triangle
  3. Look for & record intersections between the triangle and cell  
=> If intersecting: Call self for other triangle
- We now know all corner and intersection points => also know all areas.



# Conservative remapping algorithm



- For each grid cell find the triangle covering its centre point (quadtree).

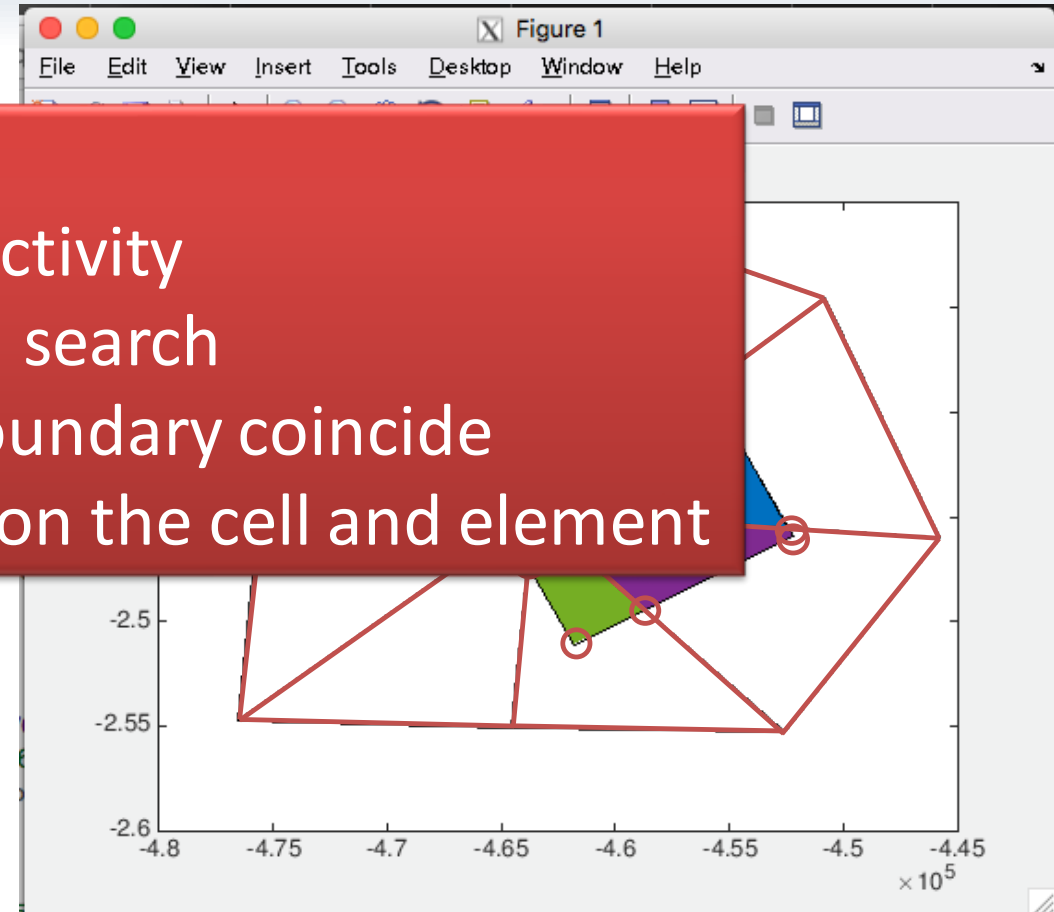
- Do three checks (recursive):

1. Check if point is inside triangle  
=> If yes, done
2. Check if point is on triangle boundary  
=> If yes, done
3. Look for other triangles  
=> If intersecting, can search for other triangle

- We now know all corner and intersection points => also know all areas.

“Easy” because:

- We know mesh connectivity
- We have a quick (tree) search
- Mesh and grid land boundary coincide
- All fields are constant on the cell and element



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# What's the future for a Lagrangian mesh?



## Future remeshing

- Remeshing on the root is a bottle neck.
- All remeshing and interpolation should be done in parallel
- This requires a complete re-write of the remeshing algorithm

**Thank you!**

## Future coupling

- Doing coupling through the root is a bottle neck
- For parallel coupling we need either:
  - A new coupler which can reorganise communication paths at runtime
  - A new remeshing scheme with static domain splitting
- We need to do all interpolation (including weight calculation) in parallel