

Efficient Ensemble Data Assimilation For Earth System Models with the Parallel Data Assimilation Framework (PDAF)

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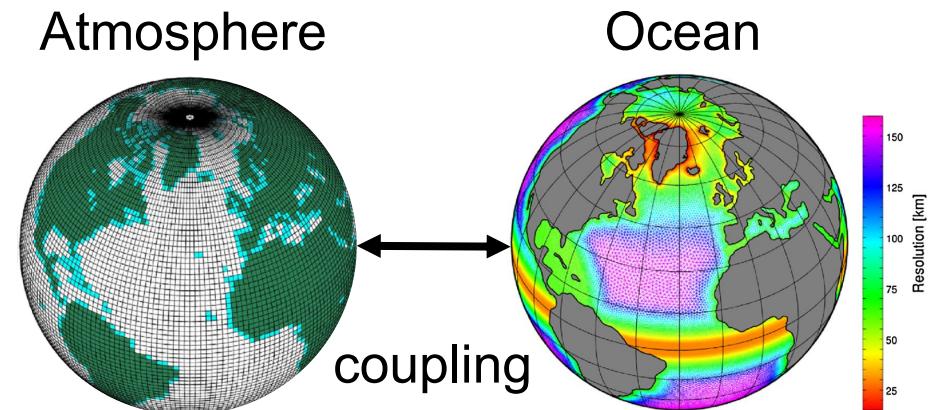
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- Coupled Data Assimilation
- PDAF – Parallel Data Assimilation Framework
- Combining coupled model and PDAF
- Example: AWI Climate Model (ECHAM6 & FESOM)

Coupled Models and Coupled Data Assimilation

Coupled models

- Several interconnected compartments, like
 - Atmosphere and ocean
 - Ocean physics and biogeochemistry (carbon, plankton, etc.)
 - Atmosphere, Land surface, subsurface



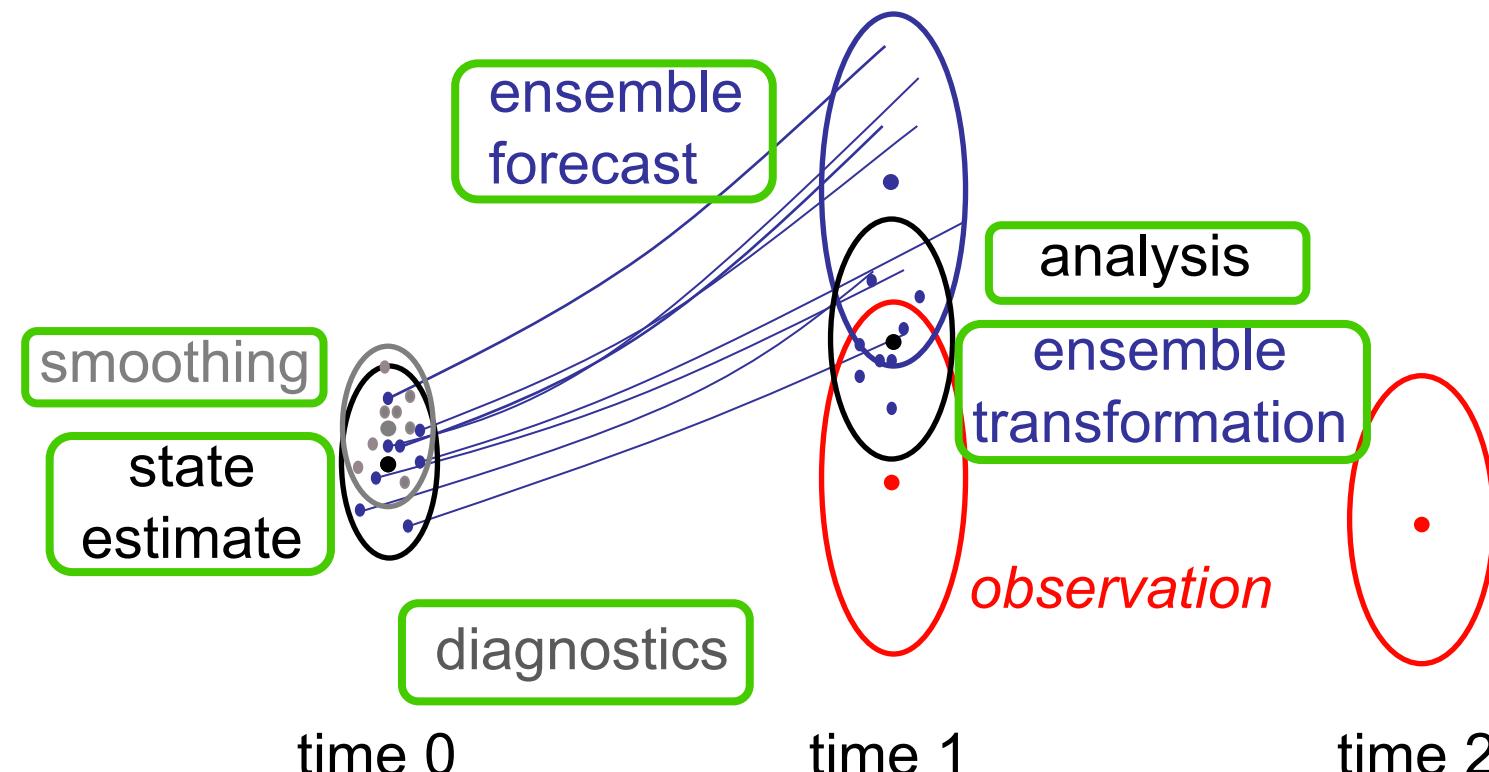
Coupled data assimilation

- Assimilation into coupled models
 - **Weakly coupled:** separate assimilation in the compartments
 - **Strongly coupled:** joint assimilation of the compartments
 - Use cross-covariances between fields in compartments
 - Plus various “in between” possibilities ...

Ensemble Data Assimilation

Ensemble Kalman Filters & Particle Filters

- Use ensembles to represent state and uncertainty
- Propagate ensemble using numerical model
- Use observations to update ensemble
- EnKFs are current ‘work horse’



PDAF provides methods for each of the steps

PDAF - Parallel Data Assimilation Framework

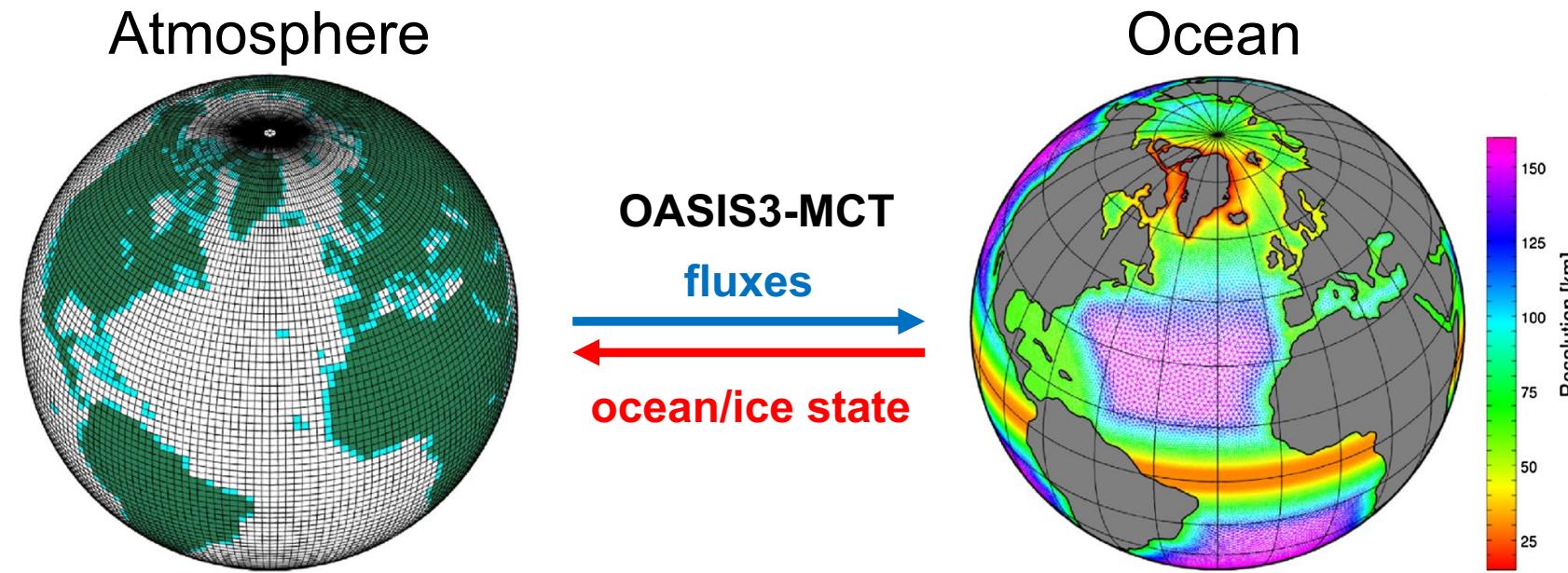
- a program library for ensemble data assimilation
- provides support for parallel ensemble forecasts
- provides filters and smoothers - fully-implemented & parallelized
(EnKF, LETKF, LESTKF, NETF, PF ... easy to add more)
- easily useable with (probably) any numerical model
(coupled to e.g. NEMO, MITgcm, FESOM, HBM, MPI-ESM, SCHISM/ESMF)
- run from laptops to supercomputers (Fortran, MPI & OpenMP)
- Usable for real assimilation applications and to study assimilation methods
- ~470 registered users; community contributions

Open source:
Code, documentation, and tutorial available at

<http://pdaf.awi.de>

Combining coupled model and PDAF

Example for assimilation into coupled model: AWI-CM



Atmosphere

- ECHAM6
- JSBACH land

Coupler library

OASIS3-MCT

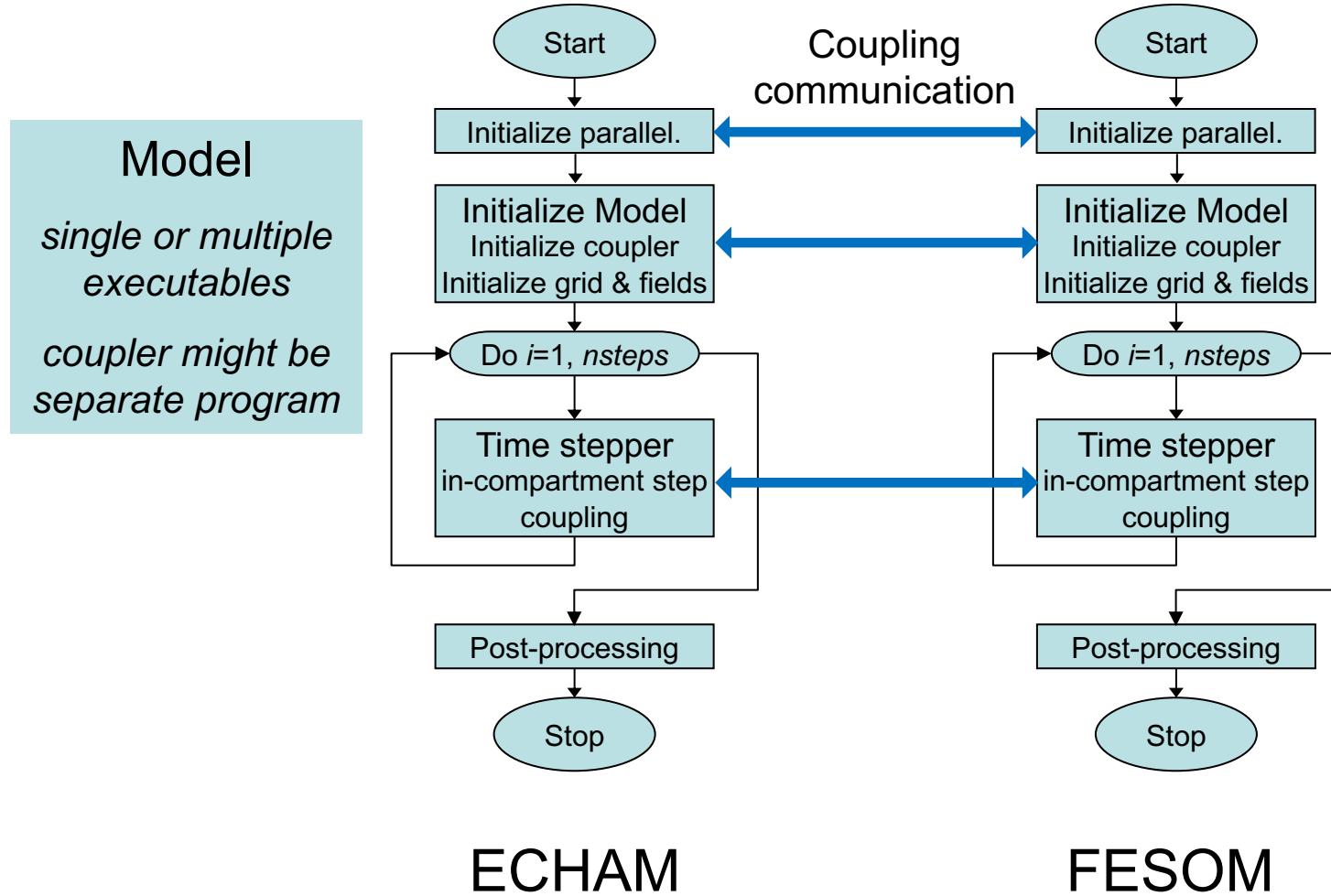
Ocean

- FESOM
- includes sea ice

Two separate executables for atmosphere and ocean

Goal: Develop data assimilation methodology for cross-domain assimilation (“strongly-coupled”)

Augmenting a Model for Data Assimilation

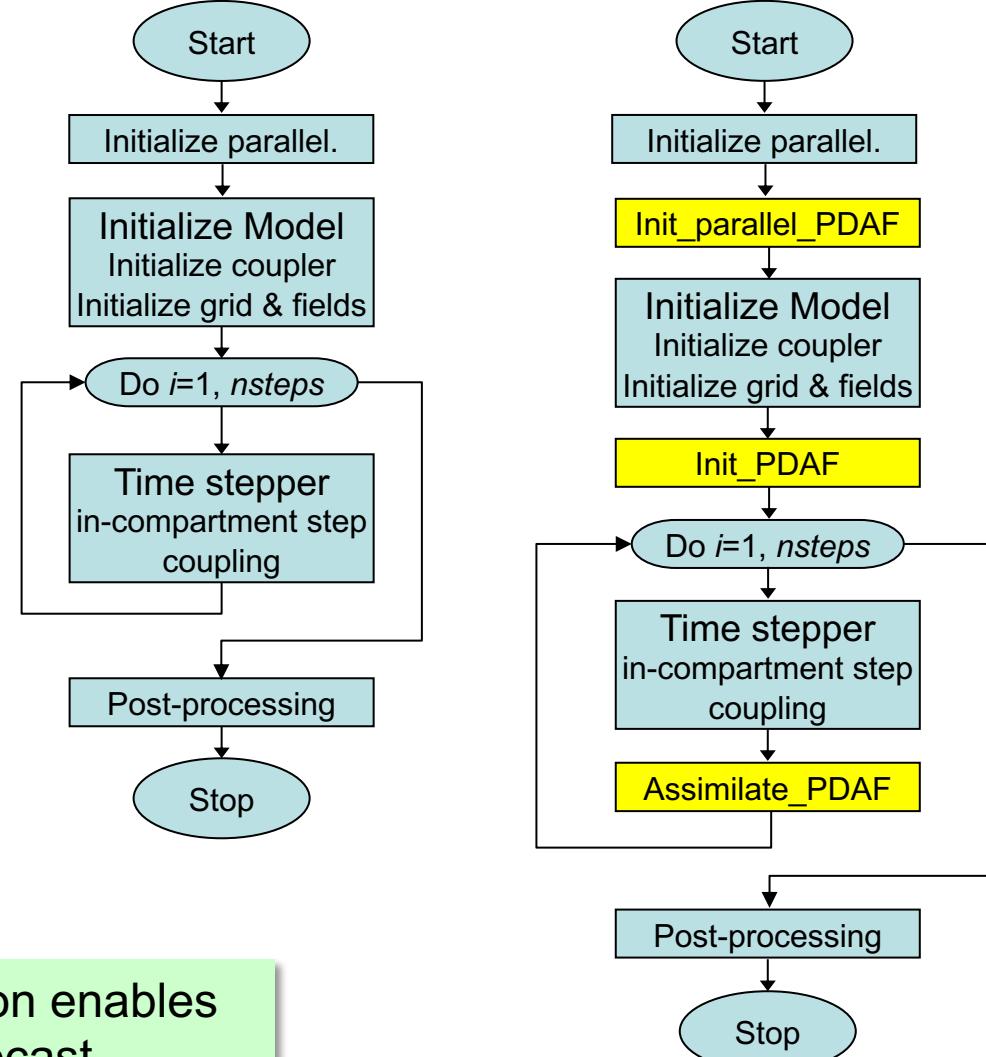


Augmenting a Model for Data Assimilation

Model
single or multiple executables
coupler might be separate program

Augment both
ECHAM & FESOM

revised parallelization enables ensemble forecast



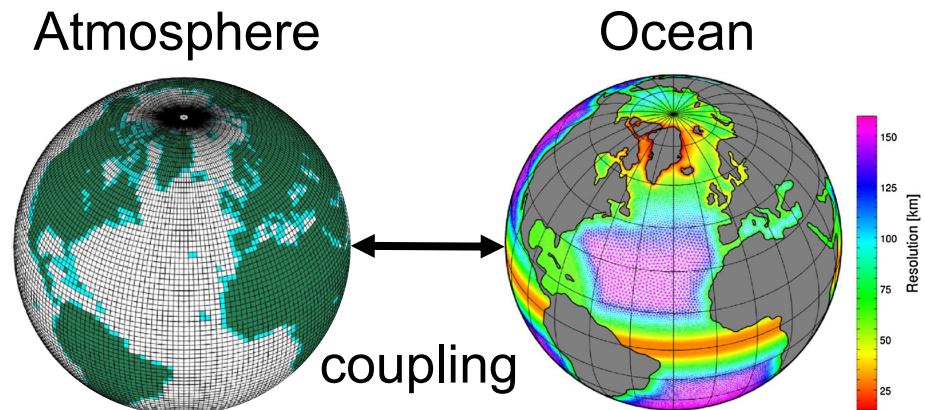
Extension for data assimilation

plus:
Possible model-specific adaption
e.g. in NEMO or ECHAM: treat leap-frog time stepping

Requirements on the Coupler

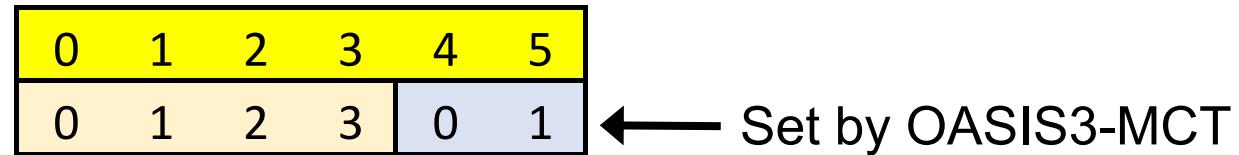
- Coupling to PDAF bypasses model coupler
 - Provides direct access to model fields and mesh information
 - Should be compatible with any coupler

- Coupler has to support ensemble integrations
 - Run several model instances concurrently
 - Example OASIS3-MCT (version in AWI-CM)
 - uses MPI_COMM_WORLD → need to be replaced
 - Current version allows to specify ‘*commworld*’



MPI Process setup

Communicators for AWI-CM (single model instance)



Color legend:

MPI_COMM_WORLD
COMM_FESOM
COMM_ECHAM

MPI Processes – setup for ensemble run

Communicators for AWI-CM (single model instance)

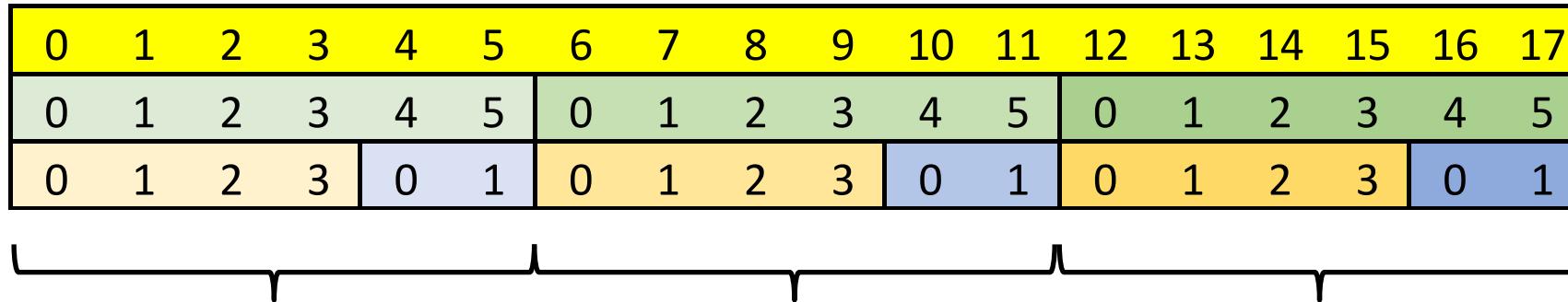
0	1	2	3	4	5
0	1	2	3	0	1

Color legend:

MPI_COMM_WORLD	COMM_CPLMOD
COMM_FESOM	COMM_COUPLE
COMM_ECHAM	COMM_FILTER

Communicators for ensemble run (ensemble size 3)

0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17
0	1	2	3	4	5	0	1	2	3	4	5	0	1	2	3	4	5
0	1	2	3	0	1	0	1	2	3	0	1	0	1	2	3	0	1



← Set by PDAF
← Set by OASIS3

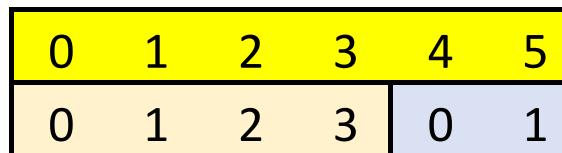
Realization 1

Realization 2

Realization 3

MPI Processes – typical setup for assimilation

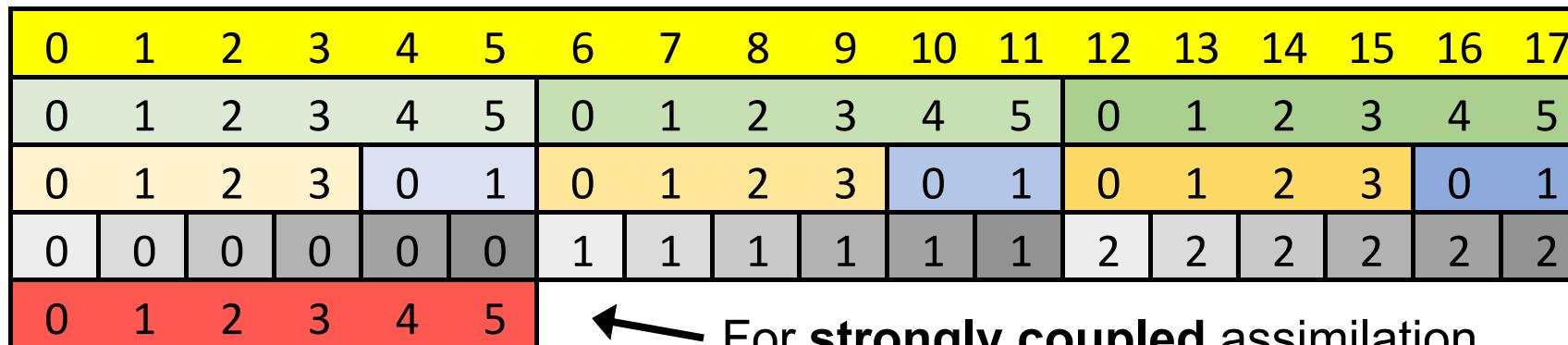
Communicators for AWI-CM (single model instance)



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Communicators for ensemble run (ensemble size 3)

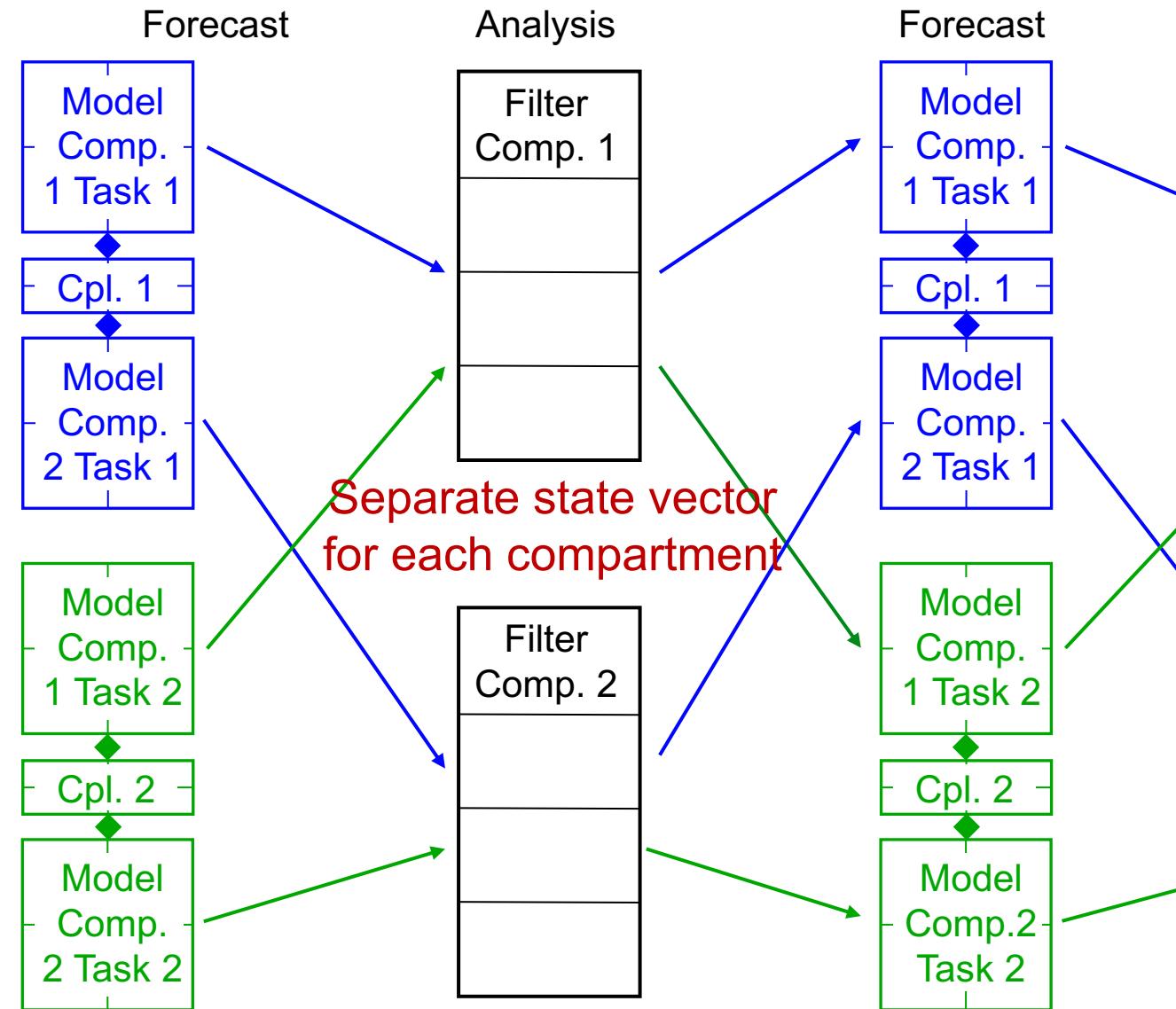


- ← Set by PDAF
- ← Set by OASIS3
- ← Set by PDAF

← For **strongly coupled** assimilation
(ECHAM and FESOM combined)

← For **weakly coupled** assimilation
(separate ECHAM and FESOM)

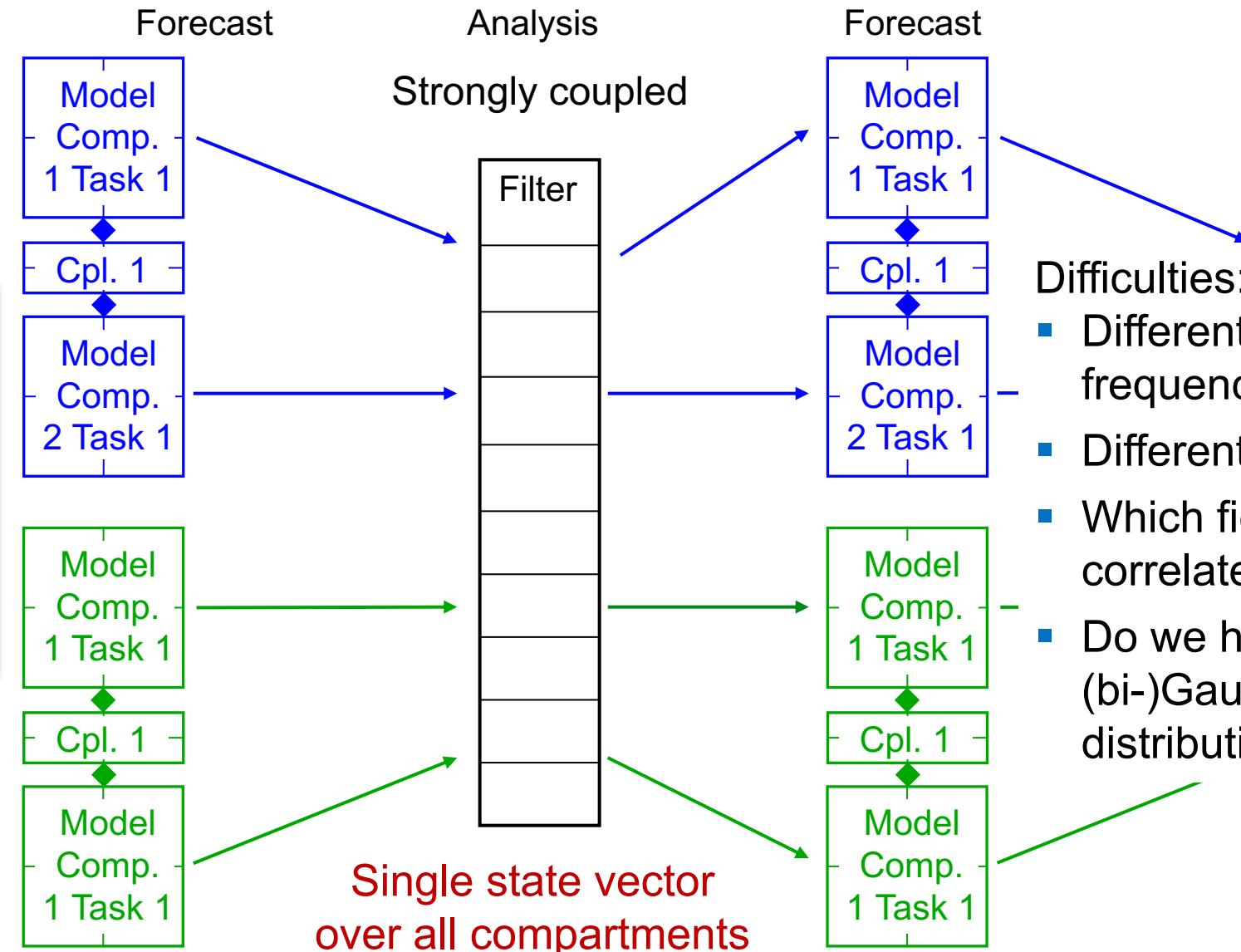
2 compartment system – weakly coupled DA



- Simpler setup than strongly coupled
- Different DA methods possible
- Different timing of DA possible
- But:
Fields in different compartments can be inconsistent

2 compartment system – strongly coupled DA

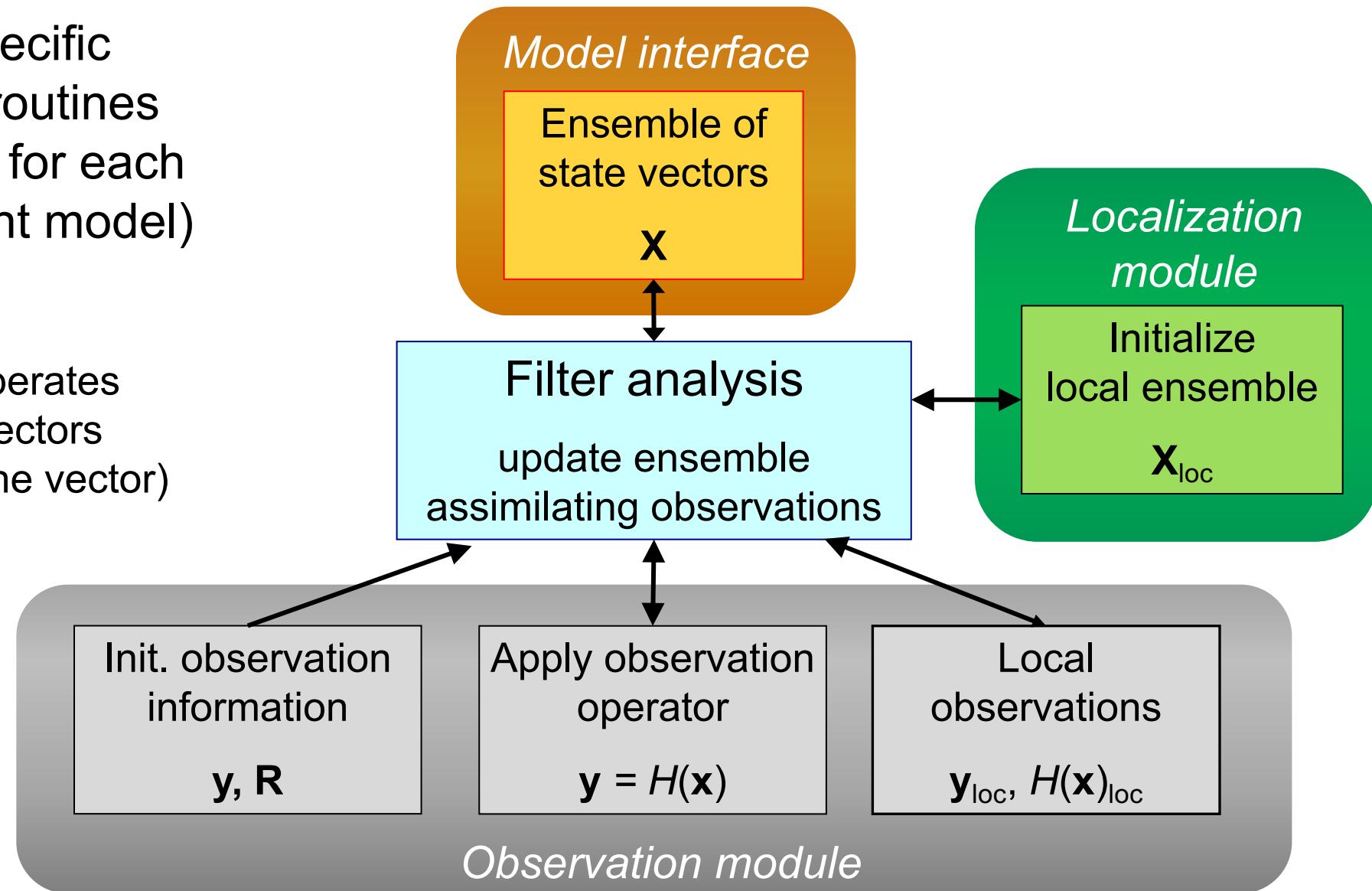
Switch between
weakly coupled
and
strongly coupled
assimilation
by change in
MPI configuration



Implementing the Ensemble Filter Analysis Step

case-specific
call-back routines
(implement for each
compartment model)

Analysis operates
on state vectors
(all fields in one vector)



Numerical results

Data Assimilation Experiments

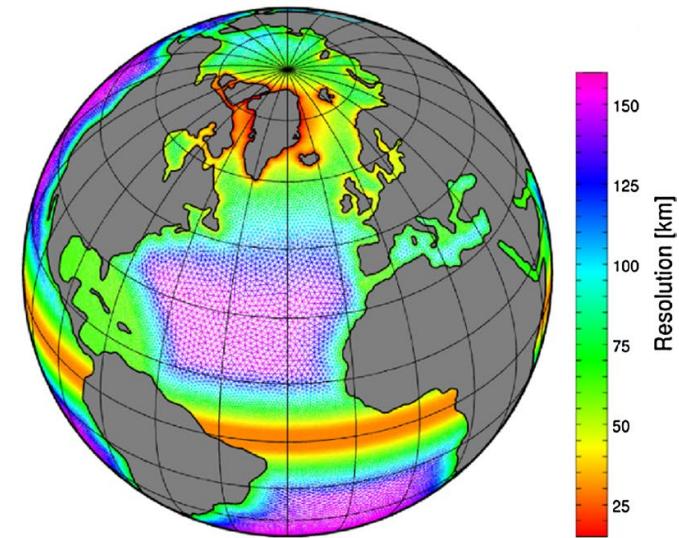
Model setup

- Global model
- ECHAM6: T63L47
- FESOM: resolution 30-160km

Data assimilation experiments

- Observations
 - Satellite Sea surface temperature
 - Temperature and salinity profiles (EN4)
- Updated:
 - ocean (SSH, T, S, u, v, w)
 - atmosphere (T, surf. P, vorticity, divergence, humidity, wind velocity)
- Assimilation method: Ensemble Kalman Filter (LESTKF)
- Ensemble size: 46
- Simulation period: year 2016, daily assimilation update
- Run time: ~4h, fully parallelized using 12,000 processor cores

FESOM mesh resolution



Online and Offline Coupling - Efficiency

Offline-coupling is simple to implement
but can be very inefficient

Example:

Timing from atmosphere-ocean
coupled model (AWI-CM)
with daily analysis step:

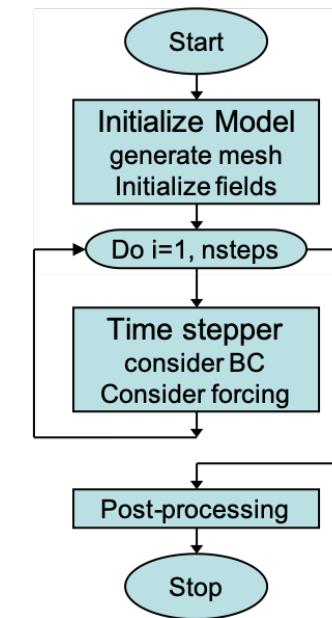
Model startup: 95 s

Integrate 1 day: 33 s

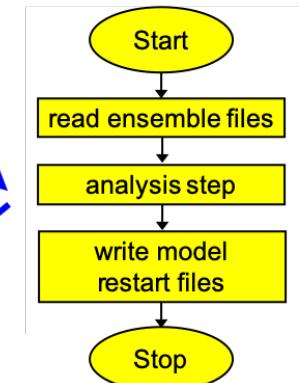
Model postprocessing: 14 s

Analysis step: 1 s

Model



Assimilation program



Online and Offline Coupling - Efficiency

Offline-coupling is simple to implement
but can be very inefficient

Example:

Timing from atmosphere-ocean
coupled model (AWI-CM)
with daily analysis step:

Model startup:

95 s

Integrate 1 day:

33 s

overhead

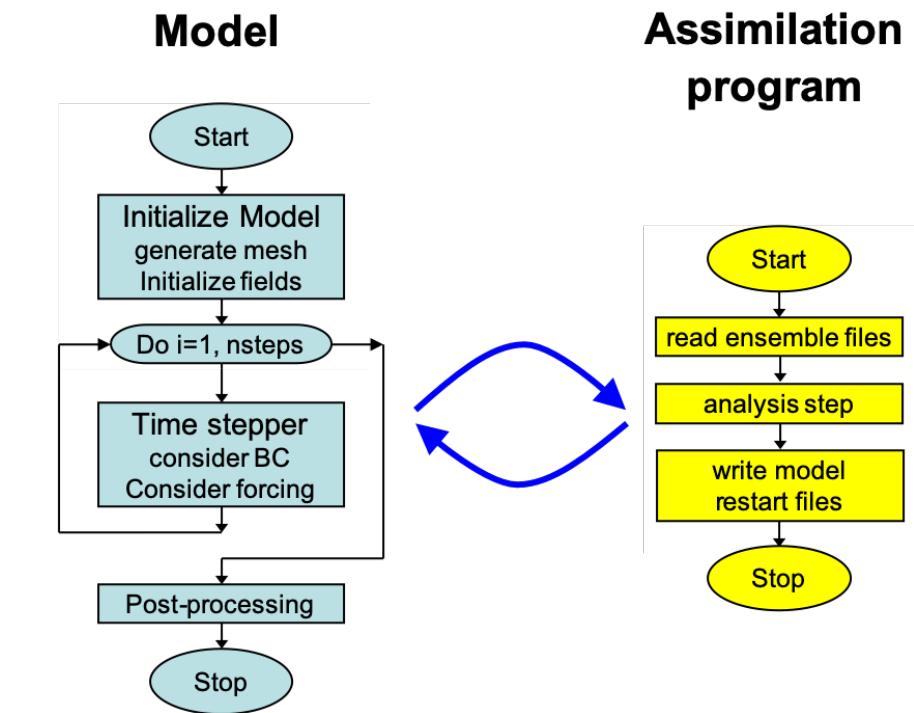
Model postprocessing:

14 s

Analysis step: 1 s

Restarting this model is ~3.5 times
more expensive than integrating 1 day

→ avoid this for data assimilation



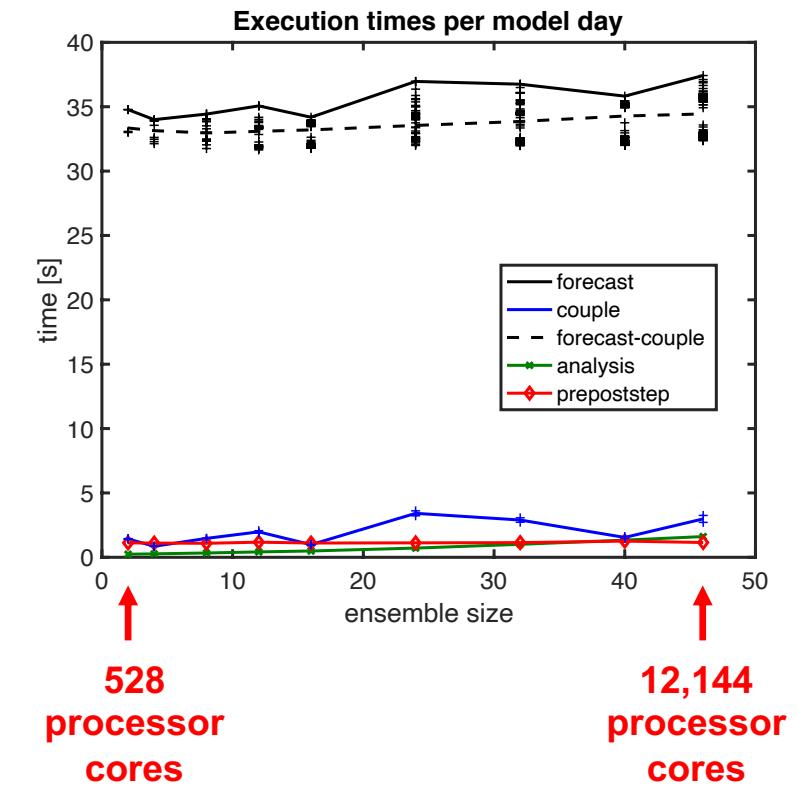
Execution times (weakly-coupled, DA only into ocean)

MPI-tasks (each model instance)

- ECHAM: 72
- FESOM: 192
- Vary ensemble size
- Increasing integration time with growing ensemble size (11%; more parallel communication; worse placement)
- some variability in integration time over ensemble tasks

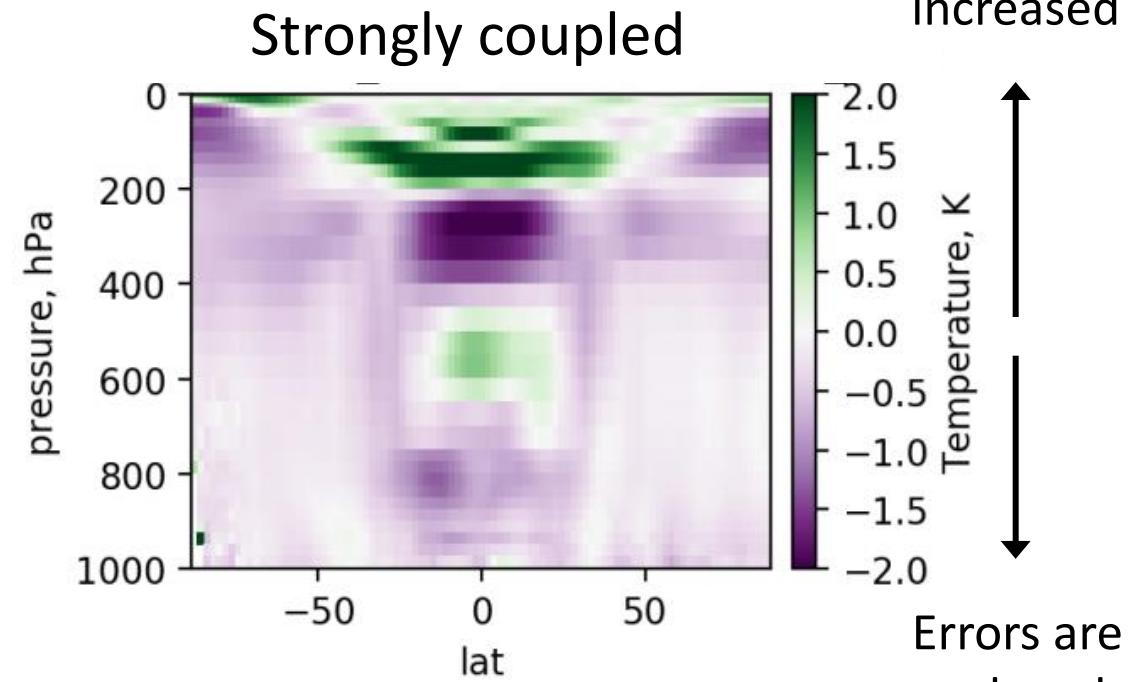
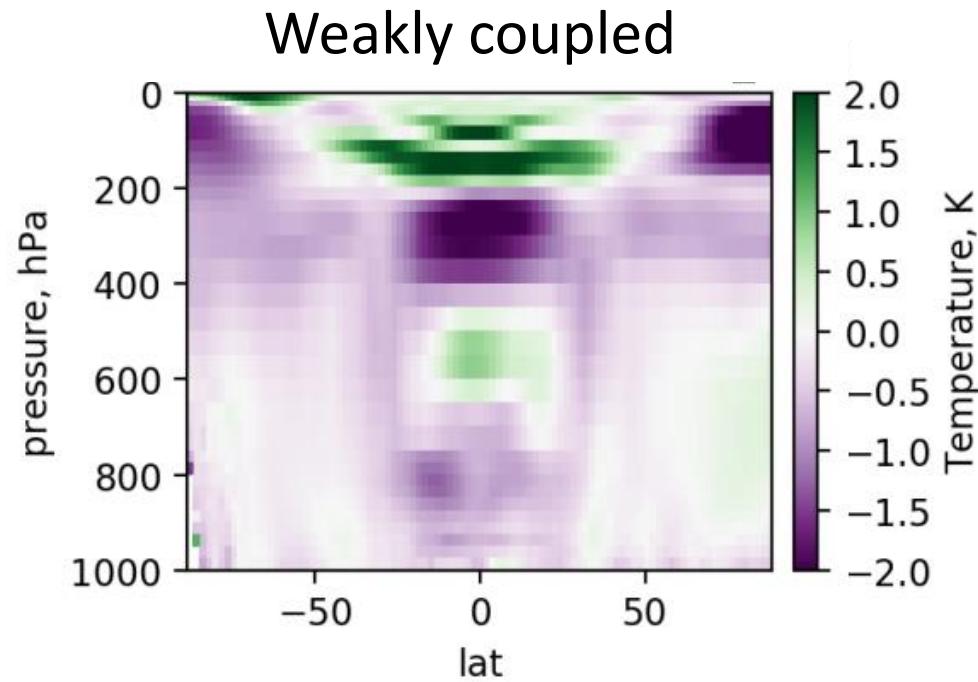
Important factors for good performance

- Need optimal distribution of programs over compute nodes/racks (here set up as ocean/atmosphere pairs)
- Avoid conflicts in IO (Best performance when each AWI-CM task runs in separate directory)



Strongly and weakly coupled DA

Difference of RMS errors: Assimilation – Free run (zonal averages)



Errors are increased

Errors are reduced

- Coupled DA of sea surface temperature
 - Effect throughout the atmosphere
 - Strongly coupled: reduced errors in Arctic troposphere compared to weakly
 - (currently analyzing results in detail)

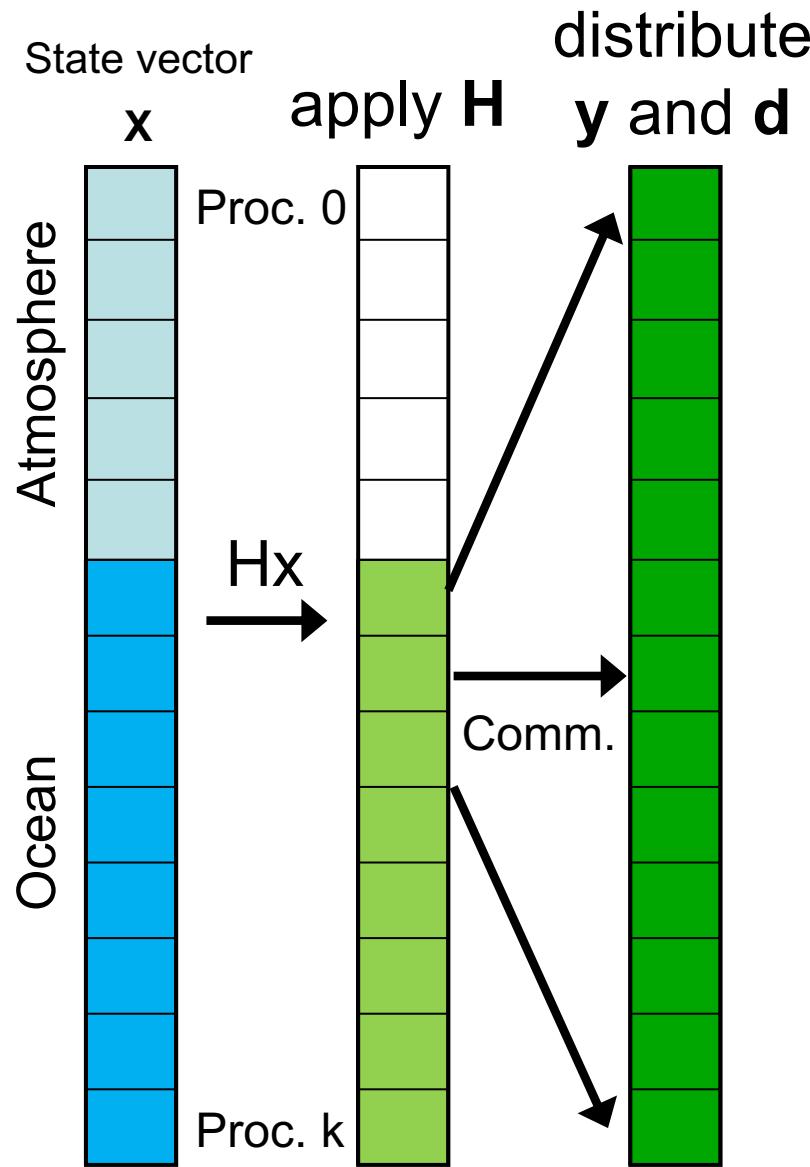
Summary

- Efficient assimilative coupled model
 - by combining of coupled model with PDAF (“online-coupling”)
 - bypass the model coupler
 - avoid excessive file IO
 - avoid model restarts
- Resulting model is run like original model
 - with more processes and additional options
- Strongly coupled DA can be easily implemented
 - Making it efficient is the real issue
- PDAF is open source (<http://pdaf.awi.de>)

References

- <http://pdaf.awi.de>
- Nerger, L., Hiller, W. (2013). Software for Ensemble-based Data Assimilation Systems - Implementation Strategies and Scalability. *Computers and Geosciences*, 55, 110-118. [doi:10.1016/j.cageo.2012.03.026](https://doi.org/10.1016/j.cageo.2012.03.026)
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- Mu, L., Nerger, L., Tang, Q., Losa, S. N., Sidorenko, D., Wang, Q., Semmler, T., Zampieri, L., Losch, M., Goessling, H. F. (2020) Towards a data assimilation system for seamless sea ice prediction based o the AWI climate model. *Journal of Advances in Modeling Earth Systems*, 12, e2019MS001937 [doi:10.1029/2019MS001937](https://doi.org/10.1029/2019MS001937)

Strongly coupled: Parallelization of analysis step



We need innovation: $\mathbf{d} = \mathbf{H}\mathbf{x} - \mathbf{y}$

Observation operator H links different compartments

1. Compute part of \mathbf{d} on process ‘owning’ the observation
2. Communicate \mathbf{d} to processes for which observation is within localization radius

In PDAF:

achieved by changing the communicator for the filter processes (i.e. getting a joint state vector decomposed over the processes)