

EXA2CT

INTEL'S EUROPEAN RESEARCH AND INNOVATION CONFERENCE

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EXA2CT

CREATING BREAKTHROUGH INNOVATIVE ALGORITHMS AND NEW PROGRAMMING MODELS, PAVING THE WAY TO EXASCALE FOR LEADERSHIP CLASS CODES.

The EXA2CT project brings together experts at the cutting edge of the development of solvers, related algorithmic techniques, and HPC software architects for programming models and communication.

It will take a revolutionary approach to exascale solvers and programming models, rather than the incremental approach of other projects.

We will produce modular open source proto-applications that demonstrate the algorithms and programming techniques developed in the project, to help bootstrap the creation of genuine exascale codes.





Start from existing, leadership class applications running on Tier-0 systems today and extract knowledge about them to create the appropriate **Proto-Applications**.

Enhanced Numerical Algorithms

Scalable, Pipelined, Robust Numerical Solvers

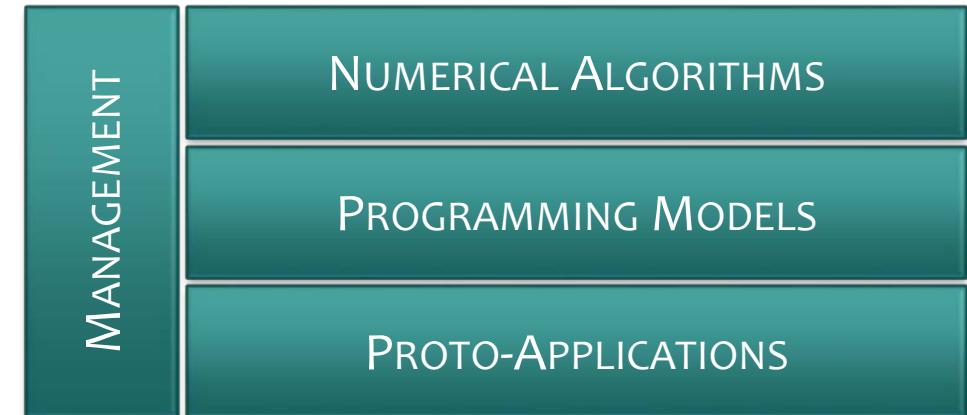
- that scale up to exascale performance
- that survive hardware failures

Enhanced Programming Models

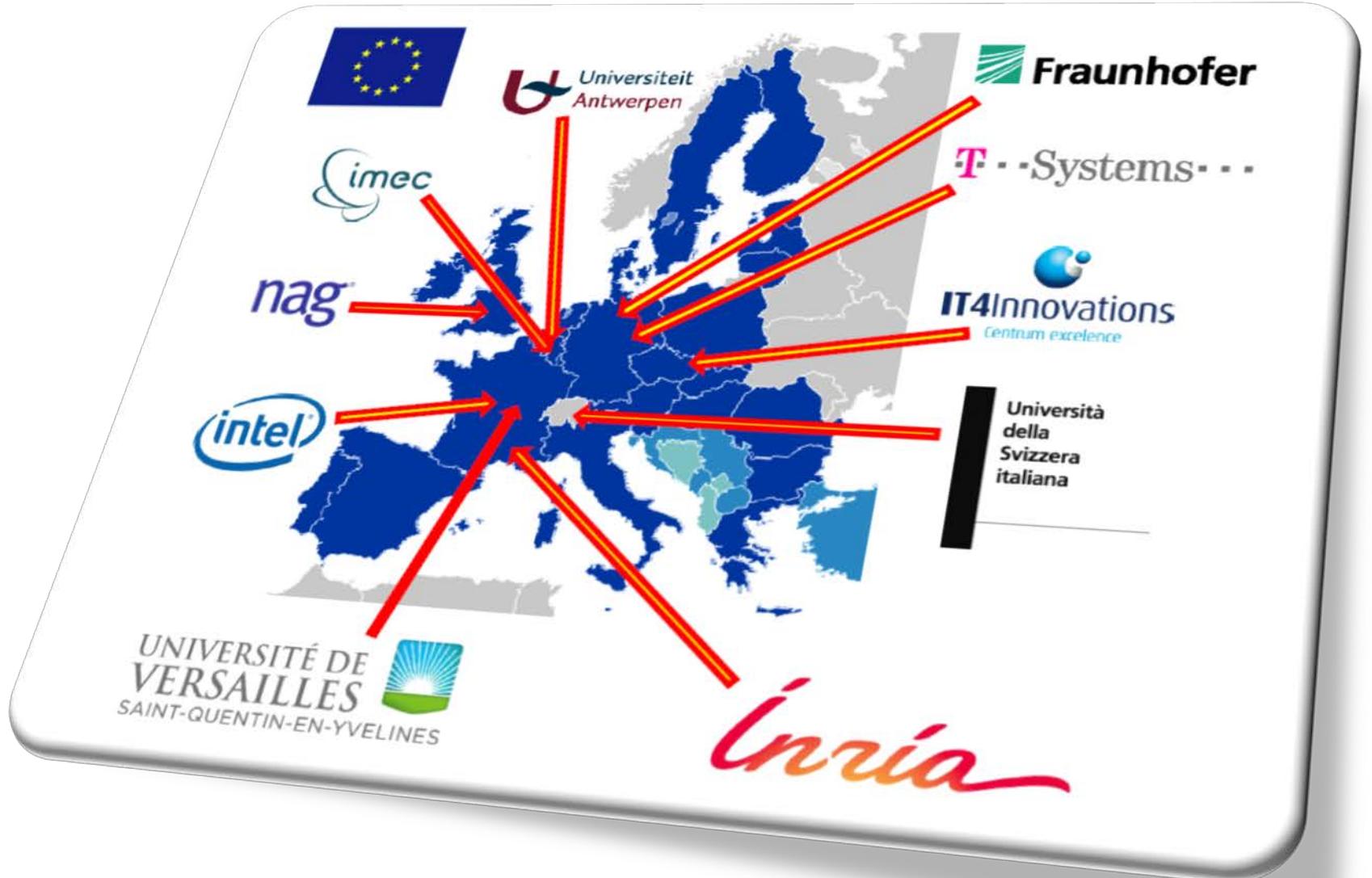
GPI/GASPI, Shark,

Irregular Stencil Code, PATUS

- communication model
- to deal with platform heterogeneity
- to deal with resilience



Partners



Numerical Algorithms

Current linear solvers will not scale well to exascale, because of

- Global communication
- Bandwidth : Insufficient arithmetic intensity
- Lack of Resilience

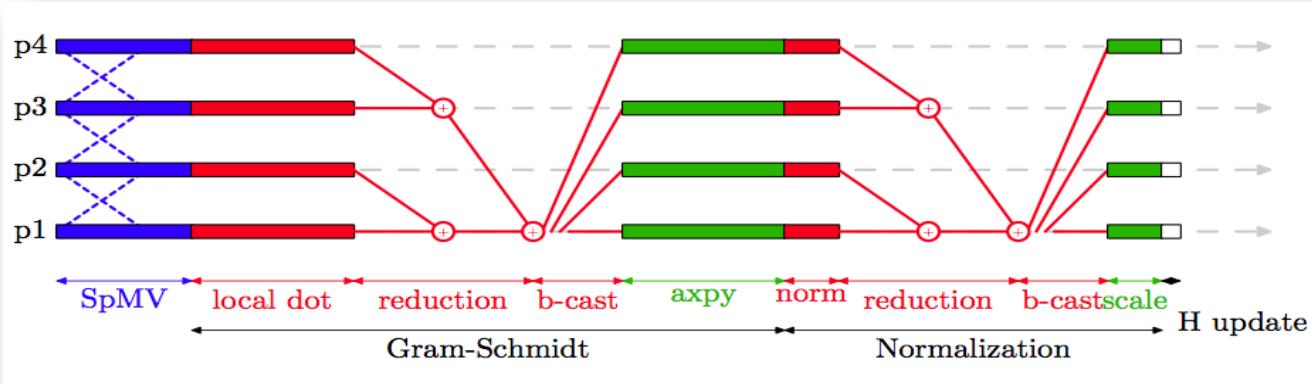
Beyond state of the art

- Extend communication avoiding/hiding
 - Preconditioning, aug'd/blocked/deflated
- Exploit arithmetic intensity using *tasking models* as backend
- Resilience through *interpolation/ABFT*
- Application to *FETI* methods



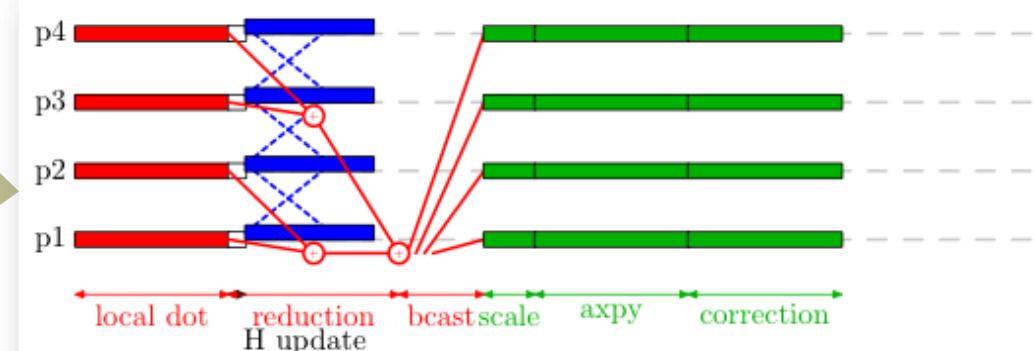
Numerical Algorithms, an example

P. GHYSELS, T.J. ASHBY, K. MEERBERGEN AND W. VANROOSE



Pipelined GMRES overlaps dot-product global communication latency with SpMV

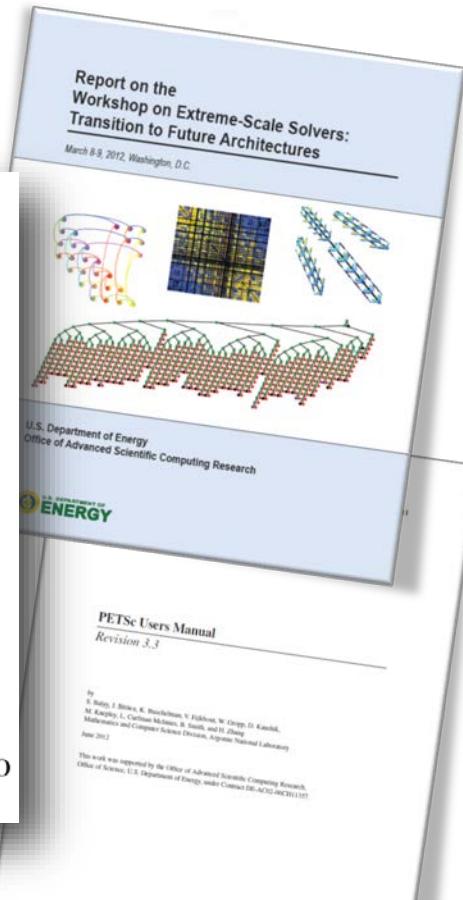
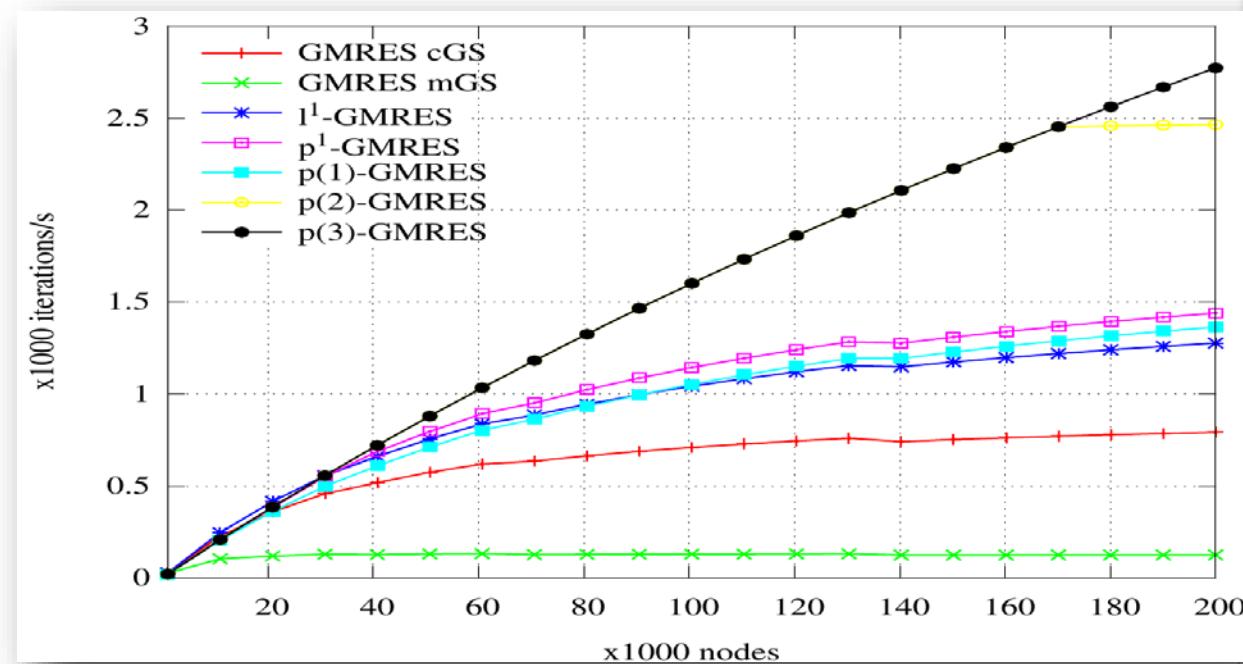
Next generation solvers can hide these latencies and **boost performance** of a wide range applications in complex systems.



Numerical Algorithms, an example

P. GHYSEL, T.J. ASHBY, K. MEERBERGEN AND W. VANROOSE

Pipelined GMRES shows significant speedups compared to standard GMRES for strong scaling experiments



WP1 in a nutshell

- Communication hiding, pipelining global reduction
 - Wim Van Rose, University of Antwerpen
- Communication avoiding, increasing arithmetic intensity using matrix power kernel based on stencil compiler (PATUS)
 - Olaf Schenk, USI
- Resilience by interpolating missing data
 - Luc Giraud and Laura Grigori, INRIA
- FETI benchmarks with coarse operators
 - Tomas Kozubek, IT4Innovations
- Communication avoiding at the level of the preconditioner



WP2 Organization



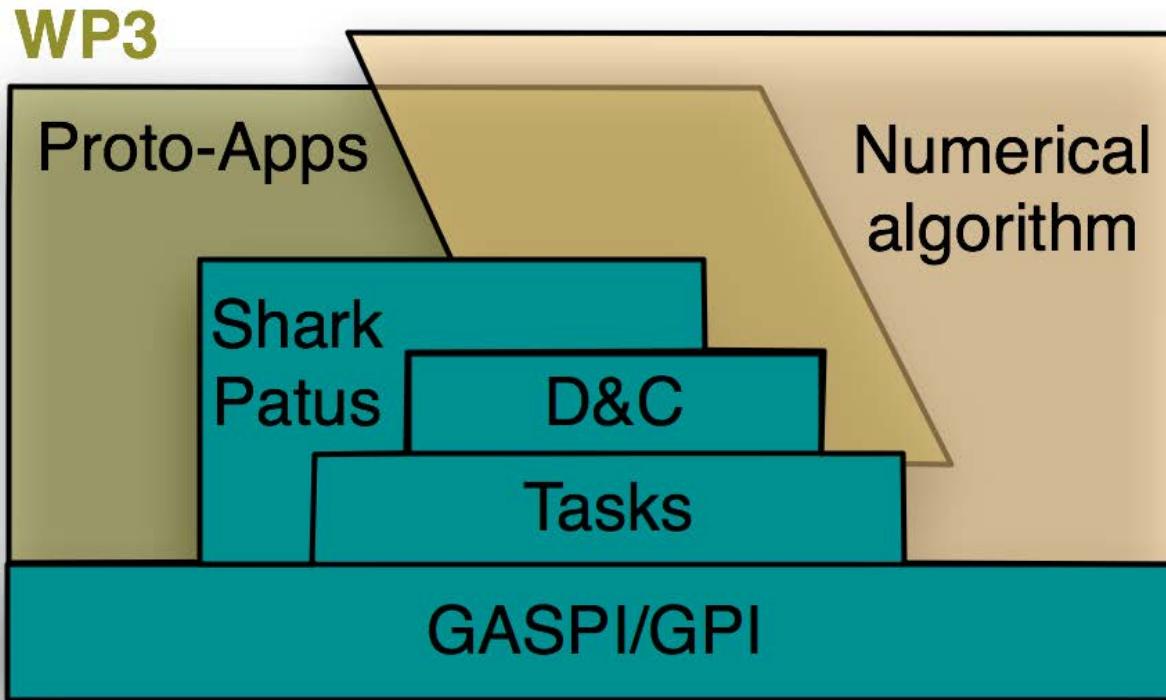
Proto-Applications

Extract representative proto-applications from HPC applications

Enhance Numerical Algorithms

Scalable and robust numerical solvers

WP1



Enhance Programming Models

WP2

Improve efficiency, robustness and scalability of GPI/GASPI , Shark , PATUS and leverage task parallelism

WP2-Programming Models

Current HPC programming models don't scale very well

- MPI, OpenMP, Vectorization
 - ... too complex
- PGAS Languages
 - ... are a partial solution

Beyond State of the Art

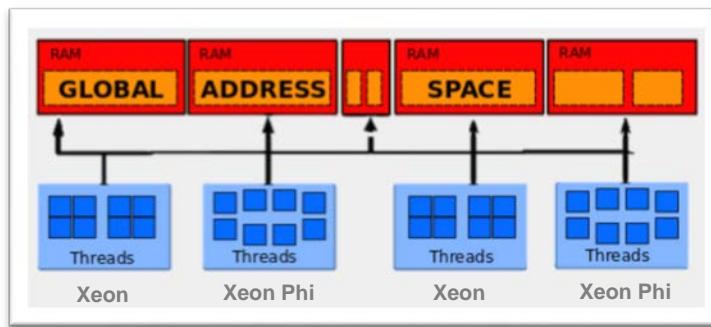
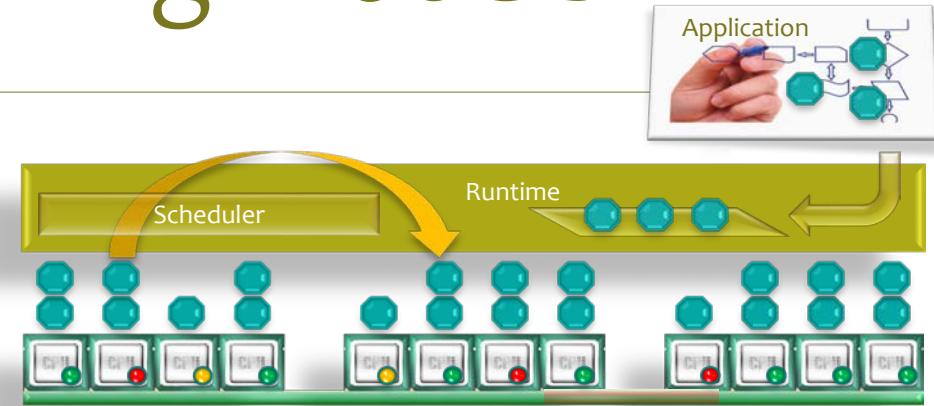
- Extend PGAS with Tasking Models
 - ... starting from GASPI
- High Level Libs : Patus, Shark
- Resilience : Software that survives failures



WP2-Programming Models

Tasks

Formulate your program in terms of **logical tasks**, instead of threads
Threading Building Blocks , Cilk™ Plus, ...



GASPI – a PGAS API

- is not a new language or a language extension, but complements existing languages (*library approach ~ MPI*)
- Support for resilience
 - e.g. time-out mechanisms for all non-local procedures

GASPI + Tasks → extreme scalability

Opportunities : Heterogeneous execution platforms for tasks, task/data migration, task/data resilience, ...



EXA2CT-WP2

Contact



GASPI/GPI

- Christian Simmendinger ¹
- Valeria Bartsch ²
- Mirko Rahn ²

Resilience

- Valeria Bartsch ²
- Mirko Rahn ²

D&C and Task programming

- Eric Petit ³ (WP leader)
- Christian Simmendinger ¹

Shark and Patus

- Roel Wuyts ⁴
- Olaf Shenk ⁵

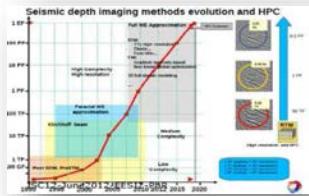
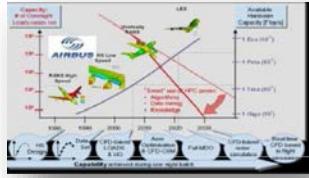
¹ @t-system-sfr.com

² @itwm.fraunhofer.de

³ @prism.uvsq.fr

⁴ @imec.be

Proto-Apps



Sometimes considered identical to
Mini-apps, Proxy-Apps, Skeleton Apps

However proto-apps are not reduced version of real-world applications, they are specifically designed to be :

- demonstrating high scalability for re-factored applications
- encapsulating essential characteristics:
 - New exascale algorithms
 - Advanced parallel implementations



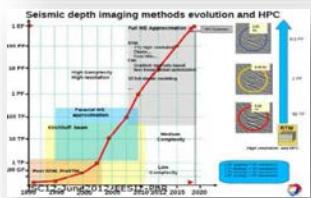
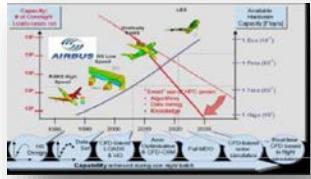
Proto-Apps

Scientific & Industrial Board

- Define the selection of the proto-apps
- Have a say in the definition of the targets
- Are preferred partners in the take-up of the results
- Will get help in translating the proto-app (back) into the reference applications

Reference Application Areas

- Computational Fluid Dynamics for Aerospace, combustion
 - Structural Mechanics Analysis
 - Geophysics
 - Material sciences
 - And others ...

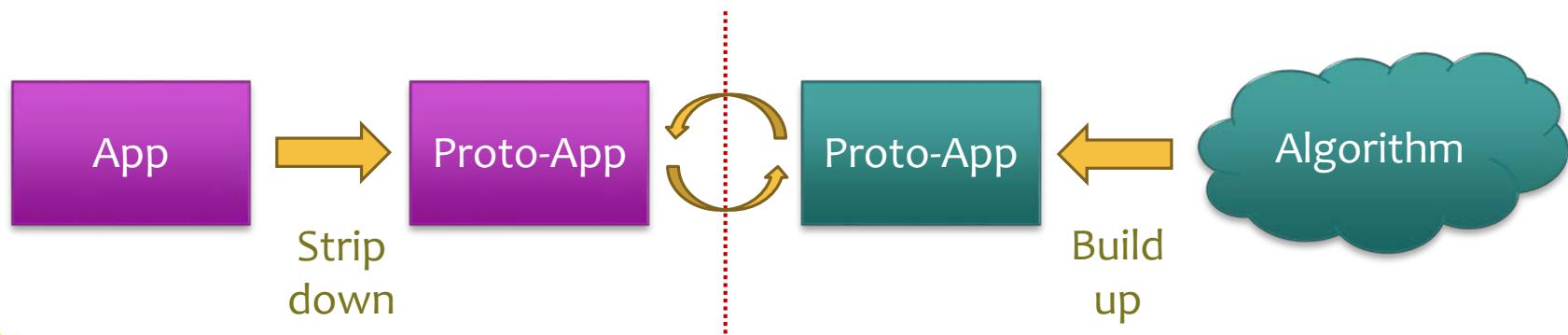


Proto-app development questions

- Discussion with WP1 & WP2: what proto-app description?
 - Numerics-oriented: actually functional (computes)
 - Dataflow-like description (tasks + dependencies)
 - Communication-oriented (profiling-parameterized « sleeps »)

Abstraction

Coupling to implementation



Presently 8 reference applications

Code	Domain
YALES2	CFD combustion
TAU	CFD
SPECFEM3D	Seismology
elsA	CFD
MUPHY	Fields/particles multiphysics
Aeronautics code	CFD
GYSELA	Fusion
Quantum Espresso	Quantum chemistry
Climate	Climate science



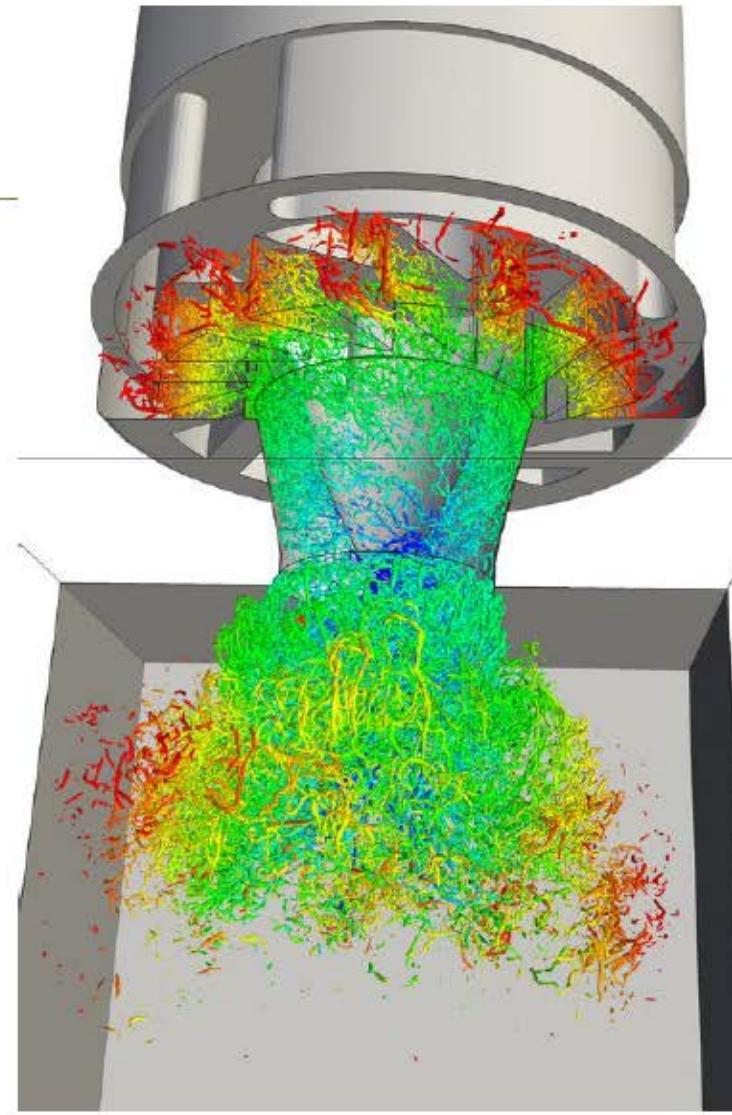
Reference applications features

- Strong scaling is a popular scalability model
 - Time to solution drives most industrial codes
- Some use cases for weak scaling
 - Multi-scale physics (YALES2)
 - Higher resolution (Climate, muphy)
 - More complex physics (elsA)
- Some very precise answers about target problem sizes
 - YALES2
 - TAU
- Most science is done on 1k-10k cores
- I/O is a recurring problem
- Fault tolerance: not a lot of feedback beyond checkpoint/restart



Test Cases

- Getting suitable test cases is crucially important to us
 - Should show good scalability, up to a point
 - Should also show performance issues
 - Should be representative of genuine application usage



YALES2, PRECCINSTA 2.6B test case (V. Moureau)



YALES2 status update

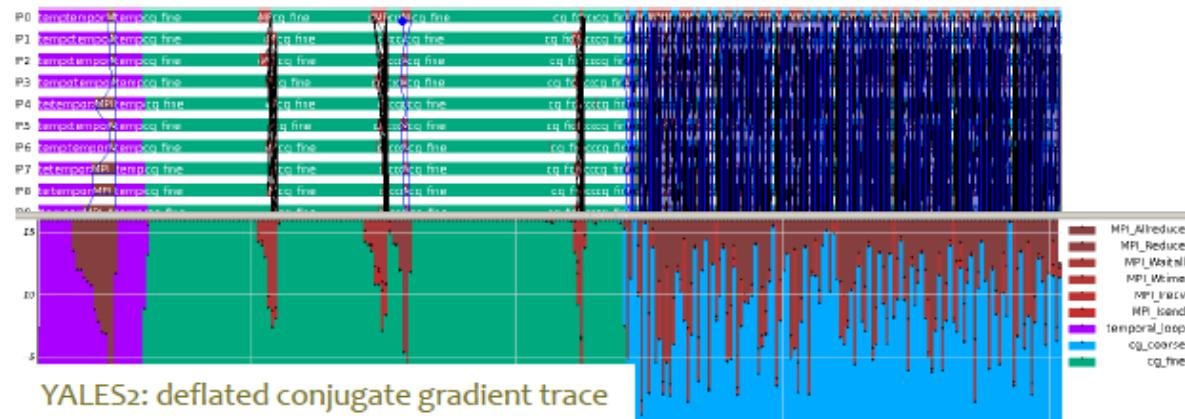


- Questionnaire feedback received
- Two main development cases identified:
 - CFD linear solvers
 - Good scaling up to 16k cores
 - Want to reduce cell count/core, from 100k to 10k: strong scaling
 - Main identified issue: deflated preconditioned CG
 - Reactive code (combustion)
 - Large computational imbalance across MPI domains
 - MPI task scheduler (dynamic load balancing) scaling up to 1k cores
 - Performance issues beyond that



Application Profiling

- Understanding both node-level performance and parallel scalability
 - In-depth, **quantitative** knowledge of application runtime behaviour is vital for building proto-apps
- Detailed analysis greatly facilitated by access to relevant source code
 - Allows targeted instrumentation
 - When not possible, extensive work on code owner's part is to be expected



YALES2: deflated CG

- Conjugate gradient on 2 levels
 - Main grid
 - « Deflated » level (typically 200x coarser than main grid)
- Scalability issues
 - Extremely fine-grained MPI comms, esp. at deflated level
 - Global comms. (sychronizing) for norm and dot product computations



WP3 Roadmap

- NAG
 - Mike Dewar and Chris Goodyer
- Intel Exascale Lab, France
 - Omar Awile, Thomas Guillet, Marie-Christine Sawley
- Prepare the list of reference applications
- Profile and help refactoring reference applications
- Prepare the library of protoapplications for Opensource release



Dissemination

- EPCC workshop with all 6 Exascale EU projects
 - GASPI tutorial
- ISC booth and BOF
- TERATEC, July 1 and 2nd



www.exa2ct.eu



SEARCH

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Home

- ▶ About
- ▶ News and Events
- ▶ Public Documents
- ▶ Private Documents
- ▶ Contact

Picture of some sort (Group photot?)

Numerical simulation is a crucial part of science and industry in Europe. The advancement of simulation as a discipline relies on increasingly compute intensive models that require more computational resources to run. This is the driver for the evolution to exascale. Due to limits in the increase in single processor performance, exascale machines will rely on massive parallelism on and off chip, with a complex hierarchy of resources. The large number of components and the machine complexity introduce severe problems for reliability and programmability. The former of these will require novel fault-aware algorithms and support software. In addition, the scale of the numerical models exacerbates the difficulties by making the use of more complex simulation algorithms necessary, for numerical stability reasons. A key example of this is increased reliance on solvers. Such solvers require global communication, which impacts scalability, and are often used with preconditioners, increasing complexity again. Unless there is a major rethink of the design of solver algorithms, their components and software structure, a large class of important numerical simulations will not scale beyond petascale. This in turn will hold back the development of European science and industry which will fail to reap the benefits from exascale.

The EXA2CT project brings together experts at the cutting edge of the development of solvers, related algorithmic techniques, and HPC software architects for programming models and communication. It will take a revolutionary approach to exascale solvers and programming models, rather than the incremental approach of other projects. We will produce modular open source proto-applications that demonstrate the algorithms and programming techniques developed in the project, to help boot-strap the creation of genuine exascale codes.

News feed Article feed

Map + Logos overview



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