

16-18 January 2023 Toulouse

NEMO: Adaptations for High Performance Computing

Italo Epicoco (CMCC)
NEMO-HPC Working Group





NEMO-HPC WG participants





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NEMO Development strategy: Adaptations for High Performance Computing

Current HPC limitations in NEMO

- Lack of a per-thread parallelism
- High memory access limits a full exploitation of the computational resources
- Lack of a GPU-based implementation
- HPC optimizations and code transformations often clash with readability/maintainability
- Many optimizations have been introduced in recent years, but still need to be consolidated and improved.





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Priorities for 2023-2027

- Consolidating the recent optimizations (Extended halo, Tiling, memory footprint, loop bounds, ...)
- Enhance the single node performance through
 - 3D tiling to better exploit cache memory
 - Exploit the mixed precision approach to increase the arithmetic intensity and reduce the memory footprint
 - Make use of an even wider halo (3 or more points) where needed
- Develop a per-thread parallelism
- Develop GPU-oriented parallelism
- Make use of DSL (PSyclone) approach to
 - Automatically apply HPC transformations without changing the developer interface (i.e., loop-fusion)
 - Generate OpenMP/OpenACC version of the code



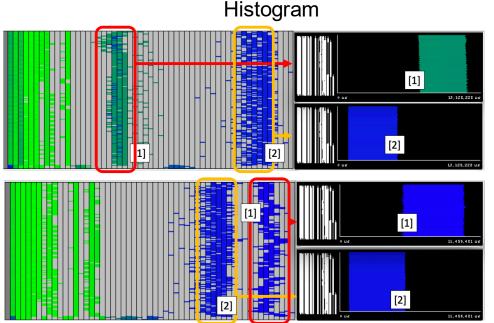


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NEMO Performance Analysis: Extended halo

- ✓ ORCA12-like configuration from BENCH TEST case
- ✓ best domain decomposition: 1536 (48 x 32) cores (32 nodes on MN4)
- ✓ MPI subdomains 94 x 103 grid points

Timeline of Useful duration 13,128s 13,128s



elapsed time with extra halo is ~13% lower

- halo 2 have larger computational blocks
- second part of the iteration
 [1] have smaller blocks of computation in the exp 1
 - computational time of the first part of iteration [2] decreases moving from halo 1 to halo 2



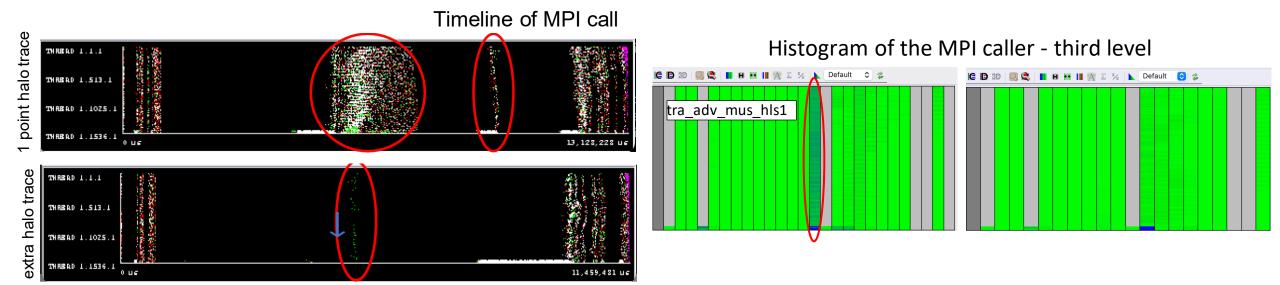




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NEMO Performance Analysis: Extended halo

- The MPI calls are drastically reduced with extra halo, especially in the central part of the iteration
- communication time reduced ~3x for lbc_lnk and ~2.7x for lbc_nfd with extra-halo







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NEMO Performance Analysis: Communications; LoopFusion

MPI3: neighbour collectives

Timeline of MPI call Table of MPI call 443.33 326.67 119 Average Maximum 336 Minimum 330 224 112 15,680 91,776 110 326.67 326.67 112 59.75 110 Maximum 336 112 110 224 30.96 47.01 529,059 us duration of the single iteration in extra halo + MPI3 trace 0.19 0.97

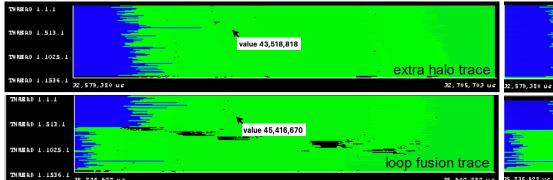
- ✓ The execution with the point-to-point communications was a little bit faster
- higher MPI message size due to MPI Ineighbor alltoallv
- the number of MPI calls has been reduced globally

no much benefit from the use of MPI3

- ✓ few routine fused:
 - dyn_ldf_lf: iso-level harmonic operator
 - tra_adv_fct_lf: FCT advection scheme
- ✓ big improve not expected:
 - no difference in terms of duration
 - no difference in MPI calls
 - but...
 - a little increase in instructions
 - a little improve in cache misses

LoopFusion

Zoom on the timeline of Useful Instruction



Zoom on L3 Cache misses



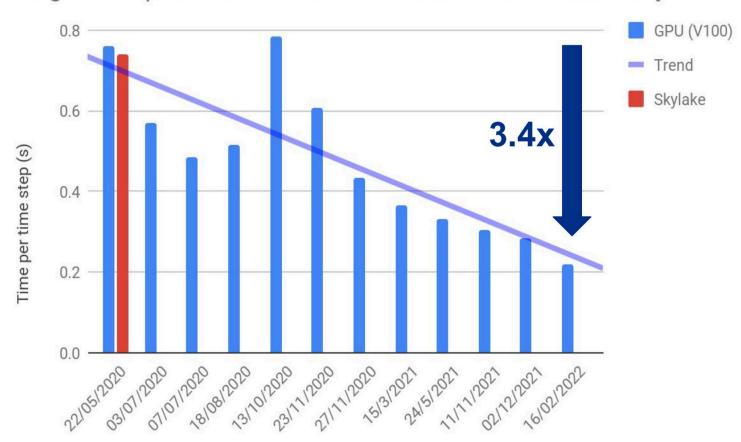




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GPU Performance of PSyclone-processed NEMO

Single GPU performance of ORCA1 NEMO-OCE since May 2020



- 250 source files
- 87K lines of code
- Adds 4.3K OpenACC directives
- Some manual tweaks still required



Using 4.0.2 of NEMO & G08 configuration provided by MO.





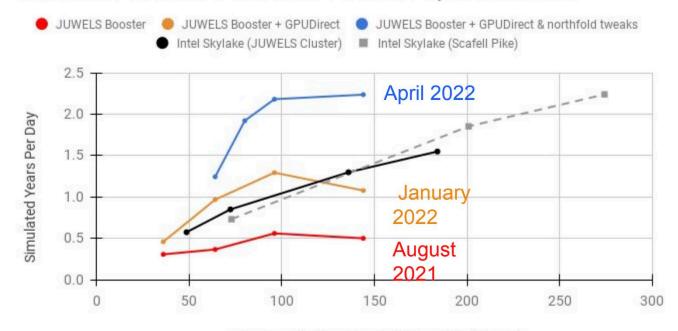
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Multi-GPU Performance of PSyclone-processed NEMO

Large-scale resources accessed through ESiWACE2

Run on up to **192 GPUs** on **Marconi** (V100) and JUWELS Booster (A100)

Evolution of NEMO ORCA12 GPU+MPI performance



Number of GPUs (CPU sockets for Intel Skylake)







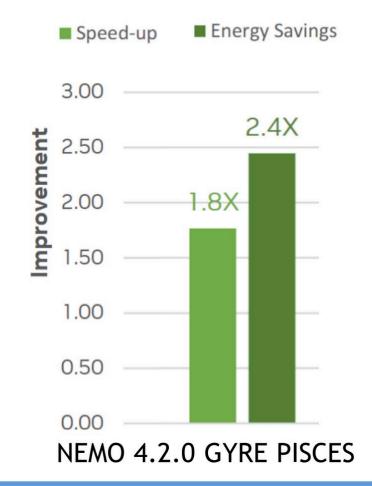


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NEMO Performance on NVIDIA Grace

NEMO Projections of Speed-up and Energy Savings

- Configurations for comparisons:
 - 2 x AMD EPYC 7763, 64 Zen 3 cores each, 128 cores total
 - 2 x NVIDIA Grace Arm, 74 cores each, 144 cores total
- Runtimes projected from actual results
 - 2 x AMD: runtime = 130 sec (actual); BW = 328 GB/s
 - Graviton3: runtime = 215 sec (actual); BW = 260 GB/s
 - 2 x Grace: runtime = 74 sec (projected); BW = 760 GB/s
- Speedup projection based on GV3 runtime:
 - GV3-based = 215 sec / (760 GB/s / 260 GB/s) = 74 sec
 - AMD-based = 130 sec / (760 GB/s / 328 GB/s) = 56 sec
 - Grace speedup vs. AMD = 1 / (74 sec / 130) sec = 1.8x







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Plans for the next future

- Mixed precision
 - Generalization of the AutoRPE tool + automation of parsing tool that can be integrated into the continuous Integration pipeline used in the NEMO GitLab.
 - Integration of mixed-precision version of NEMO4.0 on an ORCA12 grid with IFS-NEMO (Destination Earth framework)
 - Mixed-Precision version of NEMO4.2 implemented in the NEMO (ORCA36) component of the Ocean Twin (EDITO project)
 - Explore half-precision
- GPU porting
 - To explore the porting of some modules in NEMO to GPUs, targeting MN5, LUMI, Leonardo





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Plans for the next future

- Improvements to tiling performance
 - Vertical tiling
 - Removal of halo calculations
 - Implement OpenMP-compatible solution for tiling overlap issue
- Scope OpenMP parallelisation of tiling
- Extend the tiling approach to other NEMO modules TOP/MEDUSA
- Applying PSyclone to NEMO 4.2 & GOSI9
- Apply BSC mixed precision tool to NEMO 4.2 & GOSI9







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Plans for the next future

- Integration of PSyclone DSL into the NEMO compilation chain (strong collaboration with STFC and MetOffice)
 - Enhancement of PSyclone with new transformations tailored for NEMO (e.g. loop fusion)
 - Performance evaluation of the OpenMP OpenACC version of NEMO produced by PSyclone and developing of eventual improvemets for the automatic code parallelization
- Evaluation of AutoRPE tool for obtaining a mixed precision configuration of NEMO at CMCC (strong collaboration with BSC)
 - Preliminary investigation of mixed precision based on Stocastichal Arithmetic by means of CADNA library
- Development of performance monitoring service for NEMO (collaboration with BSC)











This project has received funding from the European Union's Horizon 2020 research and innovation programme under grant agreement N°824084

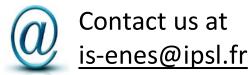


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