

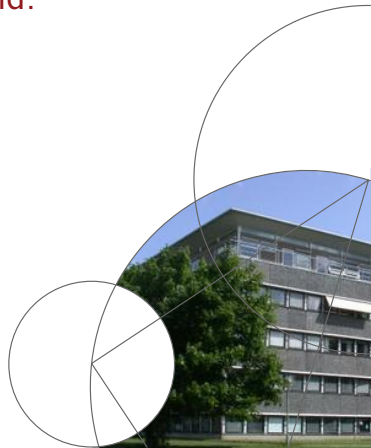


Department of Mathematical Sciences



De Finetti's theorem and beyond: Extreme point models revisited

Steffen Lauritzen



Overview

- 1 Statistical models
- 2 de Finetti and Hewitt–Savage theorems
- 3 Sufficient and summarizing statistics
- 4 Binary arrays
- 5 Repetitive structures
- 6 Random graphs



Statistical models



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For example, a model could be a functional relationship $y = f(x)$ which is 'fitted' to data (\tilde{x}, \tilde{y}) with 'error' $\epsilon = \tilde{y} - f(\tilde{x})$.



de Finetti and Hewitt–Savage theorems



Exchangeability

Definition

An infinite sequence X_1, \dots, X_n, \dots of random variables is said to be **exchangeable** if for all $n = 2, 3, \dots$,

$$X_1, \dots, X_n \stackrel{\mathcal{D}}{=} X_{\sigma(1)}, \dots, X_{\sigma(n)} \text{ for all } \sigma \in S(n),$$

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$$p(1, 1, 0, 0, 0, 1, 1, 0) = p(1, 0, 1, 0, 1, 0, 0, 1).$$



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For example, for a binary sequence, we may have:

$$p(1, 1, 0, 0, 0, 1, 1, 0) = p(1, 0, 1, 0, 1, 0, 0, 1).$$

If X_1, \dots, X_n, \dots are independent and identically distributed, they are exchangeable, but not conversely.



de Finetti's Theorem

Theorem (de Finetti (1931))

A binary sequence is exchangeable iff there exists a distribution function F on $[0, 1]$ such that for all n

$$p(x_1, \dots, x_n) = \int_0^1 \theta^{t_n} (1 - \theta)^{n - t_n} dF(\theta),$$

where $t_n = \sum_{i=1}^n x_i$.



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and $P(X_1 = x_1, \dots, X_n = x_n \mid Y = \theta) = \theta^{t_n} (1 - \theta)^{n - t_n}$.



The Hewitt–Savage theorem

Theorem (Hewitt and Savage (1955))

Let X_1, \dots, X_n, \dots be exchangeable random variables with values in \mathcal{X} . Then there is a probability μ on $\mathbb{P}(\mathcal{X})$ such that

$$P(X_1 \in A_1, \dots, X_n \in A_n) = \int Q(A_1) \cdots Q(A_n) \mu(dQ),$$

Further, μ is the distribution of the empirical measure:

$$M(A) = \lim_{n \rightarrow \infty} M_n(A) = \lim_{n \rightarrow \infty} \frac{1}{n} \sum_{i=1}^n \chi_A(X_i), \quad M \sim \mu.$$

and $Q^{\otimes \infty}$ is obtained by conditioning on M :

$$P(X_1 \in A_1, \dots, X_n \in A_n \mid M = Q) = Q(A_1) \cdots Q(A_n).$$



Contrasting model types

Simplest Bayesian model:

Subjective *exchangeable* distribution P representing Your expectation for behaviour of X_1, \dots, X_n, \dots



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Simplest frequentist model:

There is an unknown distribution Q , so that X_1, \dots, X_n, \dots are independent and identically distributed with distribution Q , $Q(A)$ being *defined as the limiting proportion* of X 's in A .



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The empirical measure M_n (\bar{X}_n in the binary case) is *sufficient* for the unknown parameter Q .



A convexity perspective

If P_0 and P_1 are both exchangeable (finitely or infinitely):

$$P_i(X_1 \in A_1, \dots, X_n \in A_n) = P_i(X_{\pi(1)} \in A_1, \dots, X_{\pi(n)} \in A_n), i = 0, 1$$

this also holds for any convex combination

$$P_\alpha = \alpha P_0 + (1 - \alpha) P_1, 0 \leq \alpha \leq 1.$$



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$$P_\alpha = \alpha P_0 + (1 - \alpha) P_1, 0 \leq \alpha \leq 1.$$

Thus, *the set of exchangeable measures is convex*. A point P of a convex set \mathcal{P} is an *extreme point* if

$$P = (P_1 + P_2)/2 \text{ and } P, P_1, P_2 \in \mathcal{P} \text{ implies } P = P_1 = P_2.$$



Integral representation

Any point in a compact convex set can be represented as a barycenter (centre of gravity) of a measure concentrated on the extreme points.



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expresses an arbitrary exchangeable P as *barycenter* of a *unique* measure μ concentrated on the *extreme exchangeable distributions*, which correspond to i.i.d.r.v.



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A compact and convex set, where the representing measure μ is uniquely determined by P is a *simplex*.



Extreme points and asymptotic behaviour

Consider the following σ -fields:

The *tail* σ -field of events that do not depend on the first finite number of coordinates:

$$\mathcal{T} = \bigcap_{n=1}^{\infty} \sigma\{X_n, X_{n+1}, \dots\}.$$



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The *sufficient* σ -field \mathcal{M} , generated by the limiting empirical measure M_{∞} . It clearly holds that

$$\mathcal{M} \subseteq \mathcal{T} \subseteq \mathcal{E}.$$

If P is exchangeable all three σ -fields coincide as measure algebras (Olshen, 1971).



Characterizing extreme points

Theorem

An exchangeable distribution is an extreme point if and only if it has trivial tail, i.e. \mathcal{T} only contains sets of probability one or zero:

$$A \in \mathcal{T} \implies P(A) \in \{0, 1\}.$$



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Same statement would be true if \mathcal{T} were replaced by \mathcal{M} or \mathcal{E} .



Sufficient and summarizing statistics



Exchangeability and summarizing statistics

For binary variables, X_1, \dots, X_n, \dots is exchangeable if and only if for all n

$$P(X_1 = x_1, \dots, X_n = x_n) = \phi_n(\sum_i x_i).$$

Because $S(n)$ *acts transitively on binary n -vectors with fixed sum*, i.e. if x and y are two such vectors, there is a permutation which sends x into y .



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So, in the binary case, *exchangeability is equivalent to $t_n = \sum_i x_i$ being sufficient and*

$$p(x_1, \dots, x_n \mid t_n) = \binom{n}{t_n}^{-1}.$$

In general, the basic sufficient statistic is the *empirical measure* M_n .



Summarizing statistics

Following Freedman (1962) we say that $t(x)$ is **summarizing** a distribution p if for some ϕ

$$p(x) = \phi(t(x)).$$

Note that *if $t(x)$ is summarizing, it is sufficient* for any family of distributions that it summarizes.



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$$p(x) = \phi(t(x)).$$

Note that *if $t(x)$ is summarizing, it is sufficient* for any family of distributions that it summarizes. In addition it holds that

$$p(x \mid t) \text{ is uniform on } \{x : t(x) = t\}$$

Exchangeability is equivalent to $t_n = \sum_i x_i$ summarizing the distribution of X_1, \dots, X_n .



Geometric distribution

Let X_1, X_2, \dots , be i.i.d. with a geometric distribution so

$$p(x_i) = (1 - \theta)\theta^{x_i}, \quad x = 0, 1, 2, \dots$$

Then

$$p(x_1, \dots, x_n) = (1 - \theta)^n \theta^{\sum_i x_i}$$

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Question: What is the family of distributions on $\{0, 1, \dots\}$ summarized by $\sum_i x_i$?

Answer: Mixtures of distributions which are conditionally i.i.d. and geometric given the tail.



Uniform distribution

Let X_1, X_2, \dots , be i.i.d. uniform on $]0, \theta]$:

$$p(x_i) = \theta^{-1} \chi_{]0, \theta]}(x_i), \quad 0 < x < \infty.$$

Then

$$p(x_1, \dots, x_n) = \theta^{-n} \chi_{]0, \theta]}(\max_i x_i)$$

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In fact, *any minimal, summarizing sequence of statistics is recursively computable:*

$$t_{n+1}(x_1, \dots, x_n, x_{n+1}) = \phi_n\{t_n(x_1, \dots, x_n), x_{n+1}\}.$$



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This property of minimal sufficient statistics was observed by Fisher (1925), see also Freedman (1962); Lauritzen (1988).



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So the median can never be a minimal sufficient statistic.



Semigroup statistics

If a sequence of statistics $t_n, n = 1, 2, \dots$ are all *symmetric*, i.e.

$$t_n(x_1, \dots, x_n) = t_n(x_{\pi(1)}, \dots, x_{\pi(n)}), \pi \in \mathcal{S}(n)$$

and recursively computable, it must be of the form

$$t_n(x_1, \dots, x_n) = t(x_1) \oplus \dots \oplus t(x_n),$$

where t takes values in an *Abelian semigroup* i.e. \oplus satisfies

$$a \oplus b = b \oplus a, \quad (a \oplus b) \oplus c = a \oplus (b \oplus c).$$

Conversely, any such statistic is recursively computable and symmetric.



Examples

Examples of semigroup statistics are

$$t(x) = x, \quad x \oplus y = x + y,$$

$$t(x) = x, \quad x \oplus y = \max(x, y)$$

and

$$t(x) = \delta_x, \quad \delta_x \oplus \delta_y = \delta_x + \delta_y,$$

where δ_x is the distribution with point mass in x .

These correspond to the sum, the maximum, and the empirical distribution as summarizing statistics.



de Finetti's Theorem for semigroups

Let $t : \mathcal{X} \rightarrow \mathcal{S}$ be a semigroup valued statistic.

The distribution of X_1, \dots, X_n of is summarized by $t_n(x_1, \dots, x_n) = t(x_1) \oplus \dots \oplus t(x_n)$ for all n if and only if X_1, \dots, X_n, \dots are conditionally i.i.d. given the tail \mathcal{T} and

$$P(X_i = x \mid \mathcal{T}) = p(x) = p(x \mid \theta) = c(\theta)^{-1} \rho_\theta \{t(x)\}$$

where ρ_θ is a *character* on the semigroup generated by $t(\mathcal{X})$, i.e. an 'exponential function', satisfying

$$\rho_\theta(u) \rho_\theta(v) = \rho_\theta(u \oplus v), \quad \rho_\theta(u) \geq 0.$$

Shown e.g. in Lauritzen (1988); Ressel (1985).



A non-standard example

For distributions on the integers $\mathcal{X} = 1, 2, \dots$ and $t(x) = x$ with $x \oplus y = xy$ we get

$$\rho_{\theta}(x) = \prod_{\nu \in \Pi} \theta_{\nu}^{n_{\nu}(x)}, \quad \theta = \{\theta_{\nu}, \nu \in \Pi\},$$

where Π are the prime numbers and $n_{\nu}(x)$ the number of times ν divides x .



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where Π are the prime numbers and $n_{\nu}(x)$ the number of times ν divides x .

If X is distributed according to $p(x | \theta)$, the multiplicities $n_{\nu}(X)$ of its prime factors are independent and geometrically distributed with parameter θ_{ν} (Lauritzen, 1988).



Binary arrays



Beyond sequences

Rasch model (Rasch, 1960):

Problem i attempted by person j . There are 'easinesses' $\alpha = (\alpha_i)_{i=1,\dots}$ and 'abilities' $\beta = (\beta_j)_{j=1,\dots}$ so that binary responses X_{ij} are conditionally independent given (α, β) and

$$P(X_{ij} = 1 \mid \alpha, \beta) = 1 - P(X_{ij} = 0 \mid \alpha, \beta) = \frac{\alpha_i \beta_j}{1 + \alpha_i \beta_j}.$$



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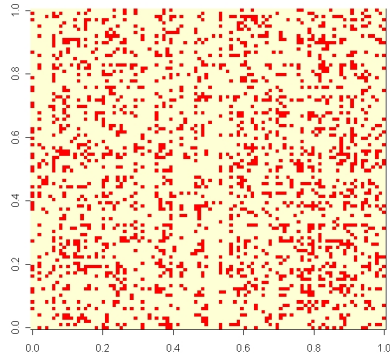
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A *random Rasch matrix* has (α_i) i.i.d. with distribution A and (β_j) i.i.d. B .

Also potential model for *hit of batter i against pitcher j , occurrence of species i on island j* , etc.



Example of random Rasch matrix



Row- and column-exchangeable matrices

A doubly infinite matrix $X = \{X_{ij}\}_{1,1}^{\infty,\infty}$ is said to be

- *row-column exchangeable* (RCE-matrix) if for all m, n , $\pi \in S(m)$, $\rho \in S(n)$

$$\{X_{ij}\}_{1,1}^{m,n} \stackrel{\mathcal{D}}{=} \{X_{\pi(i)\rho(j)}\}_{1,1}^{m,n}.$$

- *weakly exchangeable* (WE-matrix) if for all n and $\pi \in S(n)$

$$\{X_{ij}\}_{1,1}^{n,n} \stackrel{\mathcal{D}}{=} \{X_{\pi(i)\pi(j)}\}_{1,1}^{n,n}.$$



Summarized matrices

A doubly infinite (binary) matrix $X = \{X_{ij}\}_{1,1}^{\infty,\infty}$ is said to be *row-column summarized* (RCS-matrix) if for all m, n

$$p(\{x_{ij}\}_{1,1}^{m,n}) = \phi_{m,n}\{R_1, \dots, R_m; C_1, \dots, C_n\},$$

with $R_i = \sum_j x_{ij}$ and $C_j = \sum_i x_{ij}$ the row- and column sums.



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Note that, in contrast to the case of binary sequences, *RCE-matrices are generally not RCS-matrices and vice versa* because group G_{RC} of row and column permutations does *not* act transitively on matrices with fixed row- and column sums:



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A doubly infinite (binary) matrix $X = \{X_{ij}\}_{1,1}^{\infty,\infty}$ is said to be *row-column summarized* (RCS-matrix) if for all m, n

$$p(\{x_{ij}\}_{1,1}^{m,n}) = \phi_{m,n}\{R_1, \dots, R_m; C_1, \dots, C_n\},$$

with $R_i = \sum_j x_{ij}$ and $C_j = \sum_i x_{ij}$ the row- and column sums.

Note that, in contrast to the case of binary sequences, *RCE-matrices are generally not RCS-matrices and vice versa* because group G_{RC} of row and column permutations does *not* act transitively on matrices with fixed row- and column sums:

If a matrix is both RCE and RCS, it is an *RCES-matrix*.



Convexity formulation

The set of distributions \mathcal{P}_{RCE} is a convex simplex.

In particular, *every* $P \in \mathcal{P}_{RCE}$ has a unique representation as a mixture of extreme points \mathcal{E}_{RCE} , i.e.

$$P(A) = \int_{\mathcal{E}} Q(A) \mu_P(Q).$$

The same holds if RCE is replaced by RCS, RCES, WE, SWE, SWES, etc. In addition, it can be shown that

$$\mathcal{E}_{RCES} = \mathcal{E}_{RCE} \cap \mathcal{P}_{RCS}, \quad \mathcal{E}_{WES} = \mathcal{E}_{WE} \cap \mathcal{P}_{WS},$$

etc.



Features of extreme measures

Aldous (1981): *for any $P \in \mathcal{P}_{RCE}$ the following are equivalent:*

- $P \in \mathcal{E}_{RCE}$
- *The tail σ -field \mathcal{T} is trivial*
- *The corresponding RCE-matrix X is dissociated.*

Here the *tail* \mathcal{T} is $\mathcal{T} = \bigcap_{n=1}^{\infty} \sigma\{X_{ij}, \min(i, j) \geq n\}$ and a matrix is *dissociated* (Silverman, 1976) if for all A_1, A_2, B_1, B_2 with $A_1 \cap A_2 = B_1 \cap B_2 = \emptyset$

$$\{X_{ij}\}_{i \in A_1, j \in B_1} \perp\!\!\!\perp \{X_{ij}\}_{i \in A_2, j \in B_2}.$$



Repetitive structures



Repetitive structure

Let $(\mathcal{I}, <)$ be a *partially ordered and directed* index set, i.e.

$$i \in \mathcal{I} \vee j \in \mathcal{I} \implies \exists k \in \mathcal{I} : i < k, j < k$$

and assume it has a *cofinal* sequence $(i_n)_{n \in \mathbb{N}} \subseteq \mathcal{I}$, i.e.

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$$\forall i \in \mathcal{I} : \exists n \in \mathbb{N} : i < i_n.$$

Further, assume that with every $i \in \mathcal{I}$ we have a *sample space* \mathcal{X}_i and a system P_{ij} for all $i < j$ where P_{ij} is a Markov kernel from \mathcal{X}_j to \mathcal{X}_i that is *consistent*, meaning that if $i < j < k$ it holds that

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We shall term these *Markov projections*. and the combination of the above items is a *repetitive structure*; see also Martin-Löf (1974) and Lauritzen (1988) for details.



Examples

For example, \mathcal{I} could be the set of finite subsets of the integers and for $A \in \mathcal{I}$ let $\mathcal{X}_A = \mathcal{X}^{\otimes A}$ be the product space.

Then let P_{AB} simply be the coordinate projection: for $x_B = (x_\beta)_{\beta \in B}$ let

$$P_{AB}(x_B, \cdot) = \delta_{x_A}$$

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Or — slightly more sophisticated — let $P_{AB}(x_B, \cdot)$ be the random distribution over \mathcal{X}_A obtained by taking a random subsample of size $|A|$ of elements in x_B .



Projective limits

We shall be interested in the *projective limit*

$$\mathcal{X} = \operatorname{proj} \lim_{i \in \mathcal{I}} \mathcal{X}_i$$

which in our case can be identified as the *extreme points* of the set of consistent sequences of probability measures

$$\operatorname{proj} \lim_{i \in \mathcal{I}} \mathcal{X}_i = \{ \mu = (\mu_i)_{i \in \mathcal{I}} \mid \mu_i = P_{ij} \mu_j, i < j \}.$$



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If the Markov projections $P_{ij} = \pi_{ij}$ are coordinate projections, it may be identified with the set of *consistent sequences*

$$\mathcal{X} = \operatorname{proj} \lim_{i \in \mathcal{I}} \mathcal{X}_i = \{ x = (x_i)_{i \in \mathcal{I}} \mid x_i = \pi_{ij}(x_j), i < j \}$$

and then there is a unique system of projections

$\pi_i : \mathcal{X} \mapsto \mathcal{X}_i, i \in \mathcal{I}$ such that $\pi_{ij} \circ \pi_j = \pi_i$ for $i < j$.



Consistency theorem

Theorem (Kolmogorov)

Let $(\mathcal{X}_i, i \in \mathcal{I}, (\pi_{ij})_{i < j})$ be a projective system as above, \mathcal{X} the projective limit, and $\mu = (\mu_i)_{i \in \mathcal{I}}$ a consistent system of probability measures.

Then there is a unique probability measure $\tilde{\mu}$ on \mathcal{X} such that $\mu_i = \pi_i(\mu)$ for all $i \in \mathcal{I}$.



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Clearly, this is only true under regularity conditions (Borel spaces etc.) as the theorem above subsumes the standard version of Kolmogorov's consistency theorem.

We shall not distinguish between the sequence μ and the distribution $\tilde{\mu}$ it defines.



Framework for general de Finetti theorems

Consider now a projective system $((\mathcal{X}_i)_{i \in \mathcal{I}}, (\pi_{ij})_{i < j})$ as above and a similar system of ‘sufficient’ or ‘summarizing’ statistics

$$t_i : \mapsto \mathcal{Y}_i, i \in \mathcal{I}$$

with Markov kernels $Q_i : \mathcal{Y}_i \rightarrow \mathcal{X}_i$ representing *potential conditional distributions* of $X_i = \pi_i(X)$ given $Y_i = t_i(X_i)$.



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Fulfilled for suitable summarizing statistics, not necessarily recursively computable. For example maximal RCE invariants.



de Finetti's theorem

Theorem (Lauritzen (1988))

Let $(\mathcal{X}_i, i \in \mathcal{I}, (\pi_{ij})_{i < j})$ be a projective system as above with \mathcal{X} the projective limit and let $t_i : \mathcal{X}_i \mapsto \mathcal{Y}_i, i \in \mathcal{I}$ a system of statistics with associated consistent Markov kernels Q_i and Q_{ij} as above.



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The set M of systems $\mu = (\mu_i)_{i \in \mathcal{I}}$ of probabilities on \mathcal{Y}_i which are consistent w.r.t. Q_{ij} form a convex simplex.



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Each such system induces a consistent system $\nu = (\nu_i) = (Q_i \mu_i)$ of probability measures on \mathcal{X}_i and thus a probability measure $\tilde{\nu}$ on \mathcal{X} as previously.



de Finetti's theorem – continued

Theorem (Lauritzen (1988))

Q_i are valid conditional distributions for $X_i = \pi_i(X)$ given $Y_i = t_i(X_i)$ w.r.t. $\tilde{\nu}$.



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$$\lim_{j \rightarrow \infty} Q_{ij}(\cdot | Y_j) = \gamma_i(\cdot) \text{ a.s. } \tilde{\nu},$$

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where $\gamma = (\gamma_i)_{i \in \mathcal{I}} \in \mathcal{E}$.

Finally, $\mu \in \mathcal{E}$ if and only if $\gamma = \mu$ almost surely.



Random graphs



Positive definite functions on semigroups

Let $(S, +)$ be an Abelian semigroup with neutral element 0.



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Recall that a *character* is a function $\rho : S \rightarrow \mathbb{R}$ satisfying

$$\rho(s + t) = \rho(s)\rho(t), \quad \rho(0) = 1.$$

The set of characters form itself a semigroup under multiplication. This is the *dual* semigroup (\hat{S}, \cdot) .



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A function $\phi : S \rightarrow \mathbb{R}$ is *positive definite* if and only if

$$\sum_{j,k=1}^n c_j c_k \phi(s_j + s_k) \geq 0, \quad \forall n \in \mathbb{N}, c_j \in \mathbb{R}, s_j \in S;$$



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in other words, a function is positive definite if and only if all matrices of the form $\{m_{jk} = \phi(s_j + s_k)\}$ are positive semidefinite.



Integral representation

We shall be using the following result from Berg et al. (1976).

Theorem (Berg, Christensen, Ressel)

The set of normalized positive definite functions $\mathcal{P}_1^b(S)$ is a simplex with the bounded characters as extreme points. In particular, any $\phi \in \mathcal{P}_1^b(S)$ has a unique representation as barycentre of a probability measure μ on \hat{S} :

$$\phi(s) = \int_{\hat{S}} \rho(s) \, \mathrm{d}\mu(\rho)$$

and the bounded characters \hat{S} form a closed subset of $\mathcal{P}_1^b(S)$.



Graphs

For $A \subseteq \mathbb{N}$, \mathcal{L}_A denotes the set of simple labeled (undirected) graphs with labels in A .



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For $A \subseteq \mathbb{N}$, $G \in \mathcal{L}_A$, and $\sigma \in \mathcal{S}(A)$, the group of permutations of elements of A , we will let G_σ be the graph obtained from G by relabeling its nodes according to σ .



Symmetric random graphs

We consider a probability distribution P on \mathcal{L}_A and say this is *symmetric* or *exchangeable* if and only if

$$P\{G = H\} = P\{G = H_\sigma\}, \quad \forall H \in \mathcal{L}_A, \sigma \in S(A).$$



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It is practical to represent the distribution P through its *Möbius parameters*

$$Z(F) = P(G : F \subseteq G).$$

Clearly, P is symmetric if and only if Z is symmetric, or, equivalently, if there is a function $\phi : \mathcal{U} \rightarrow \mathbb{R}$ such that

$$Z(F) = \phi([F]) \tag{1}$$

or, in other words the map t_A

$$t_A(G) = [G]$$

is summarizing.



Positive definiteness of Möbius transform

We also note that $(\mathcal{U}, +)$ — where $U + V = U \cup V$ is (node disjoint) graph union — is an Abelian semigroup with the empty graph as its neutral element.



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We also note that $(\mathcal{U}, +)$ — where $U + V = U \cup V$ is (node disjoint) graph union — is an Abelian semigroup with the empty graph as its neutral element.

Clearly $\phi(\emptyset) = 1$ and ϕ is bounded. Moreover we have

Lemma

Let G be a symmetric random graph with Möbius parameter Z given as above. Then the function ϕ is bounded and positive definite on $(\mathcal{U}, +)$; in other words, $\phi \in \mathcal{P}_1^b(\mathcal{U})$.



de Finetti's theorem for graphs

Corollary

Let P be the distribution of a random graph with Möbius parameter Z . Then P is symmetric if and only if there is a unique probability measure μ on $\hat{\mathcal{U}}$ such that for all $F \in \mathcal{L}$

$$Z(F) = \int_{\hat{\mathcal{U}}} \rho([F]) \, d\mu(\rho).$$



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Note that symmetric measures corresponding to the pure characters are *dissociated* (Silverman, 1976): if $F = F_1 \cup F_2$ and F_1 and F_2 are disjoint subgraphs of F it holds that

$$Z(F) = \rho([F]) = \rho([F_1])\rho([F_2]) = Z(F_1)Z(F_2)$$

or, in other words, we have for node-disjoint F_1, F_2 :

$$P_\rho(F_1 \cup F_2 \subseteq G) = P_\rho(F_1 \subseteq G)P_\rho(F_2 \subseteq G).$$



Graphons as characters

Theorem

The bounded characters $\hat{\mathcal{U}}$ on $(\mathcal{U}, +)$ are exactly the functions ρ satisfying for $F \in \mathcal{L}_n^$*

$$\rho([F]) = \int_{[0,1]^n} \prod_{ij:i \sim j \in F} W(u_i, u_j) \, du$$

for some measurable, symmetric function

$W : [0, 1]^2 \rightarrow [0, 1]$. The function W is unique up to measure-preserving transformations of the unit interval.



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$W : [0, 1]^2 \rightarrow [0, 1]$. The function W is unique up to measure-preserving transformations of the unit interval.

The equivalence class of functions W is known as a **graphon** (Lovász and Szegedy, 2006) or **limit** of an unlabeled graph. For further details, see Lauritzen (2020).



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Final summary

- de Finetti theorems form a bridge between Fisherian and Bayesian models;
- Unifying concept is a *repetitive structure* that leads to parameter being defined as limit of observables;
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- Still far too few examples that are properly understood.



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