

# T4Train:

## Rapid Prototyping of ML-Driven Interactive Applications

### Unit 1

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# Unit 1: Introductions

- Introduce yourself
  - Background, research interests
- What you hope to get out of this course
- One fun fact about yourself!
- Downloads and Installations (CHI WiFi is SLOW! ;)
  - Arduino
  - T4Train
  - Anaconda3-2022.10



# Unit 1: Discussion Agenda

- Overview of Interactive Sensing
  - Types of Sensors
  - Common Sensor Interfaces
  - Signal Processing
    - Filtering, conditioning, and cleanup
  - Featurization
    - Binning, FFT
  - Classical ML Techniques
- Brainstorming an Application
- Installing Software for Workshop



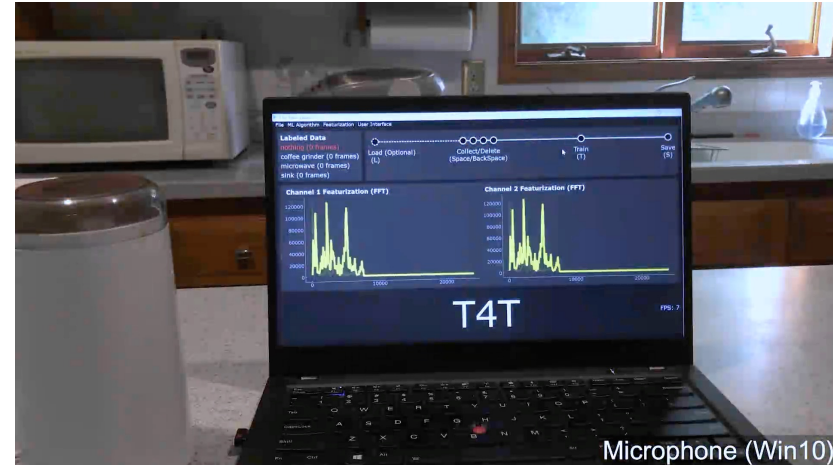
# Unit 2: Workshop Agenda

- Connecting a Sensor
- Visualizing the Data
- Training a Model
- Triggering an Action



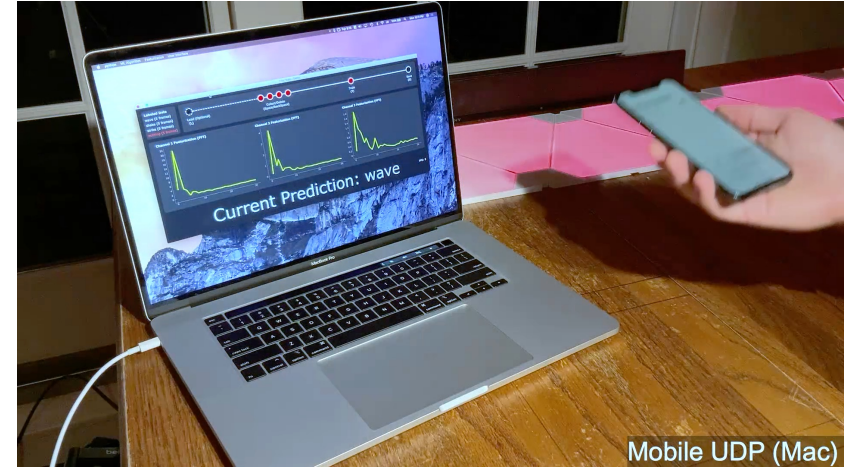
# Why do Interactive Sensing?

- Demonstrating interfaces that are responsive in realtime is an important part of technical HCI
- Provides a high-level view of the capabilities of a system



# What is Interactive Sensing?

- Connecting a Sensor
- Visualizing the Data
- Training a Model
- Triggering an Action



Mobile UDP (Mac)

# Fast prototyping of Interactive ML

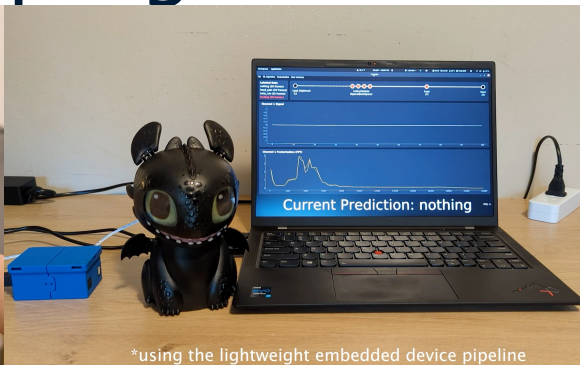
- What could we do if we had a tool that could quickly prototype interactive ML?
- Test different sensors, signal processing approaches, ML models
- Quickly generate useful applications



# Fast prototyping of Interactive ML



Coffee Machine

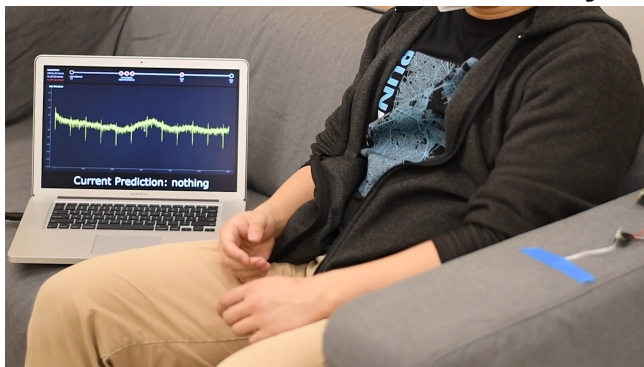


\*using the lightweight embedded device pipeline

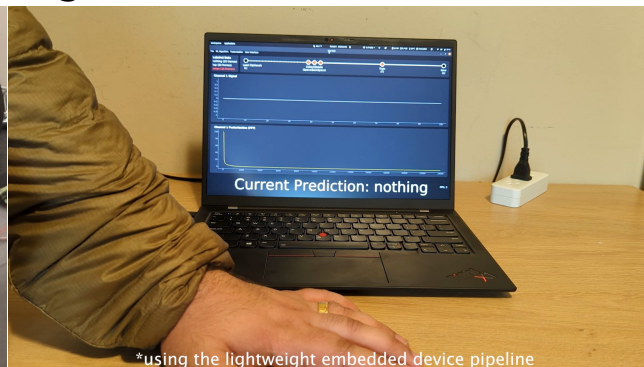
Toy Dragon



Active Speaker



Fabric Couch



\*using the lightweight embedded device pipeline

Fabric Jacket



# Overview of Interactive Sensing

## 6 Step Process:

1. Identify a potential signal
2. Design/select a sensor
3. Digitize the signal
4. Visualize the signal for human interpretation
5. Use signal processing and ML for computer interpretation
6. Perform an action based on ML predictions

# Types of Sensors

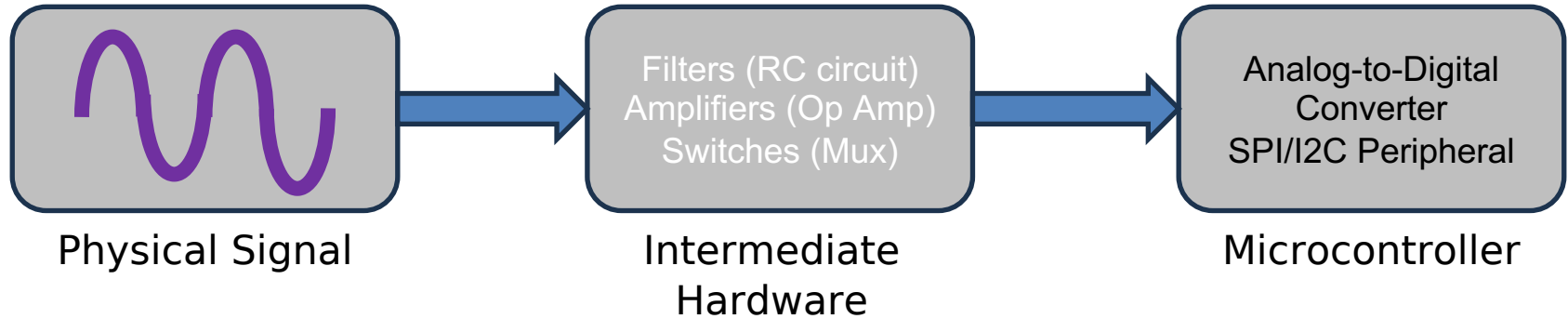
- Optical
  - Cameras
  - Depth Sensor
  - LiDAR
- IMU/Inertial
  - Accelerometer
  - Magnetometer
  - Geophone
- Acoustic
  - Microphone
  - Ultrasonic Rangefinder
- What else? Discuss



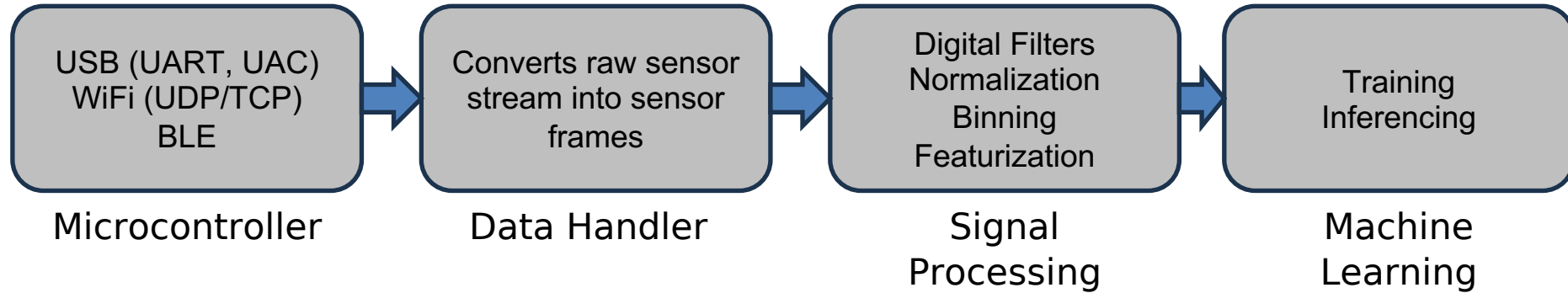
# Common Sensor Interfaces

- USB
  - **Serial/UART**
  - **Universal Audio Class**
  - Universal Video Class
- WiFi TCP/UDP
  - Large bandwidth capabilities, comes at the cost of power
- Bluetooth/BLE
  - Constrained bandwidth, great for low power
  - Unintuitive data transfer structure
  - BLE UART is great for sensor data
- Anything else?

# Signal Lifecycle (Sensor Side)

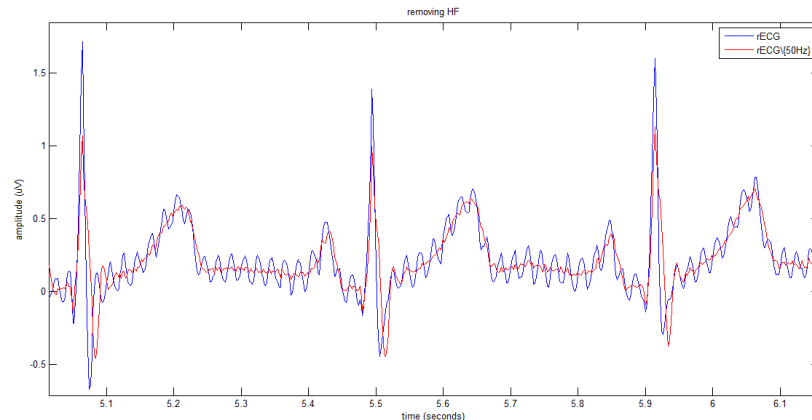


# Signal Lifecycle (Computer Side)



# Signal Processing

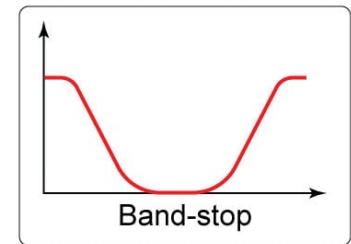
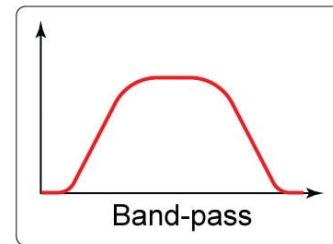
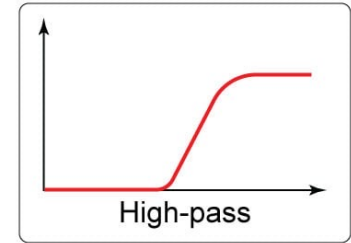
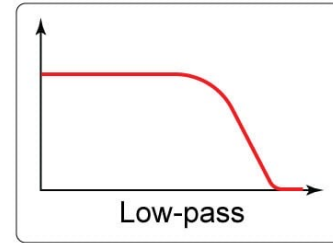
- Why do we need signal processing?
  - Signals are usually imperfect
  - Can have many noise sources
  - Signal we want might be “buried” in sensor data



Sensor data is corrupted by 50Hz line noise, but with filtering and smoothing can be recovered

# Noise Rejection Filtering

- Applying digital filters is an efficient way to remove unwanted noise in sensor data
- In previous example, a band-stop filter at 50Hz was applied to remove only 50Hz noise
- There are a few different kinds of filters, but generally:
  - Low-pass to reject high frequencies
  - High-pass to reject low frequencies
  - Band-pass to reject some low, some high
  - Band-stop to reject specific frequencies

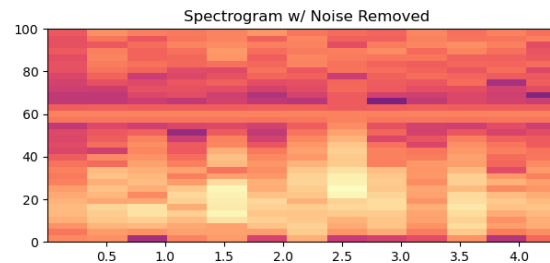
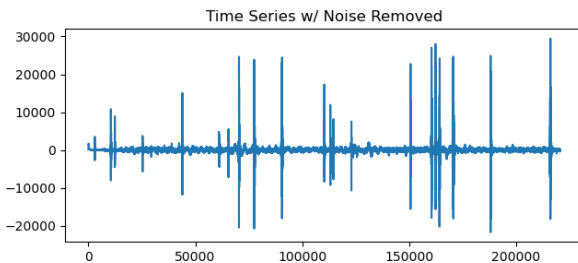
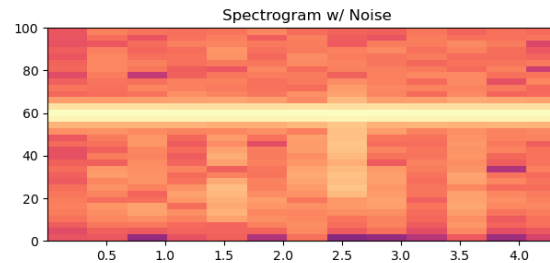
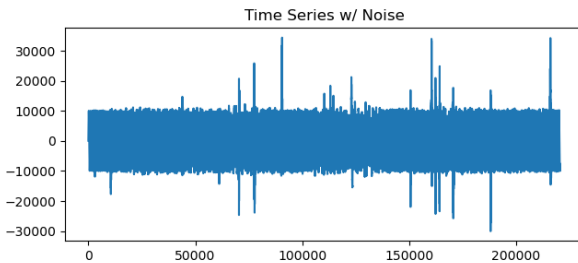
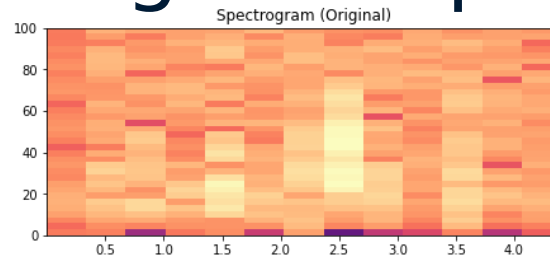
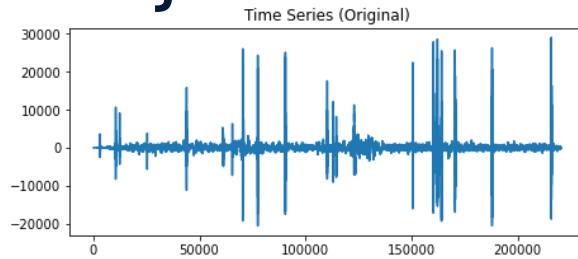


# Noise Rejection Filtering Example

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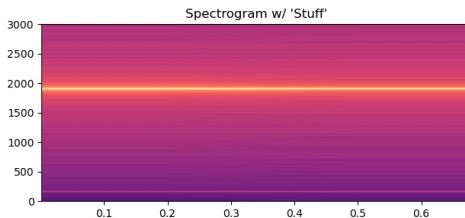
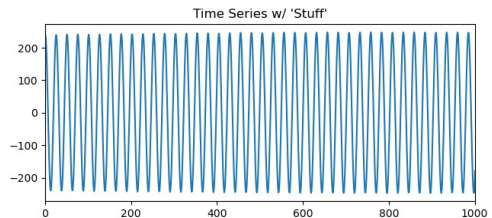
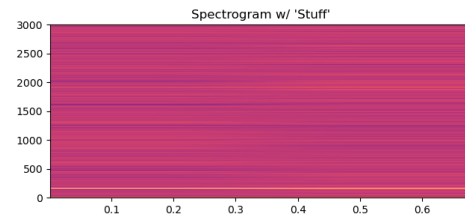
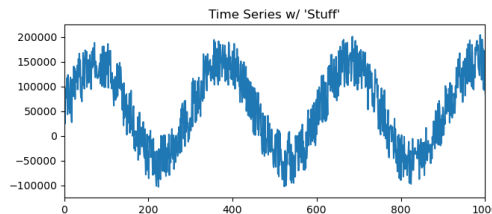
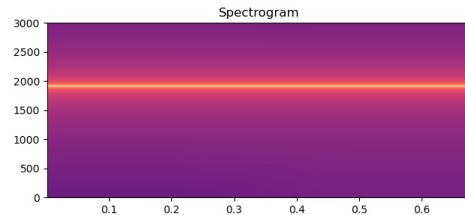
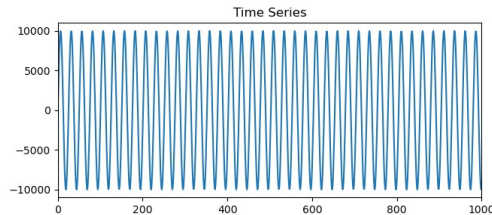


# Noise Rejection Filtering Example



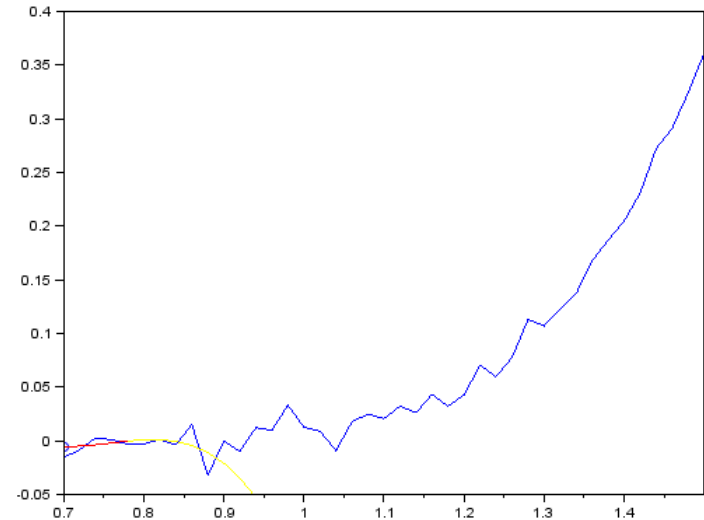
# Signal Extraction Filtering

- You can also use digital filters to extract valuable signal buried in the sensor data
- For example, if we know our signal is in a certain frequency range, a band-pass filter can reject all but our desired signal



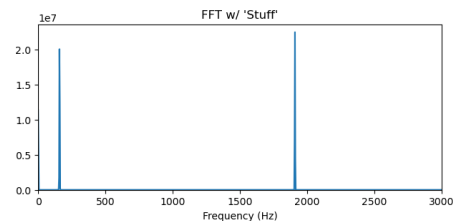
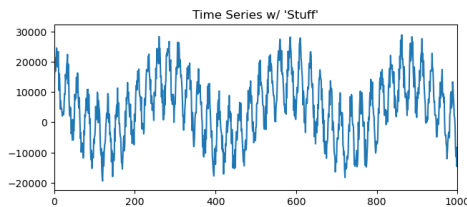
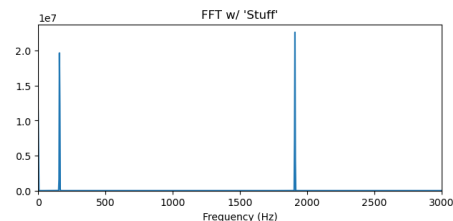
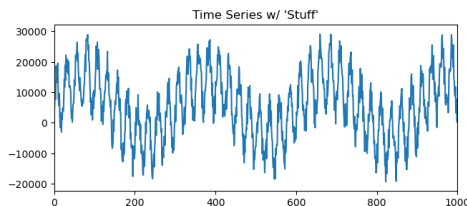
# Signal Conditioning and Smoothing

- Filters can be used to smooth
  - SavGol Filter
  - Kalman Filter
- Sometimes it may be easier to smooth with sliding window methods
- Few different ways:
  - Median Filter
  - Moving Average
  - Moving Maximum
  - Moving Minimum



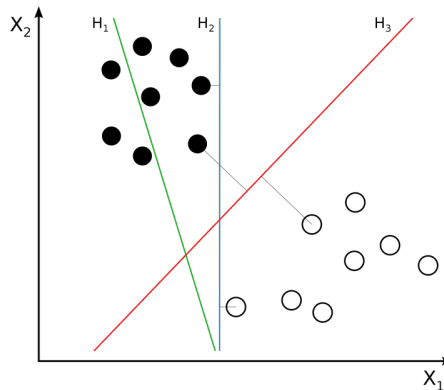
# Featurization

- Why do we need featurization?
- For many time-series sensor data, it is difficult to represent it consistently for classical ML



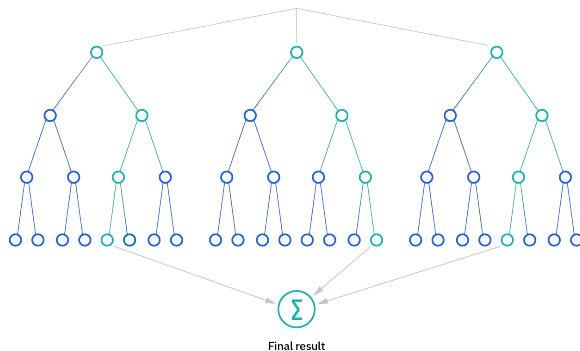
# Classical ML Techniques

- T4Train utilizes classical ML approaches:
  - Can generally train “on the fly”
  - Fast for realtime inferencing
  - Does not require GPU



Support Vector Machines

Random Forests



# Jupyter Notebook Example

- Sound Classification

# T4Train Hello World

- Microphone Demo
- Nano 33 Sense Accelerometer Demo



# Brainstorming an Application

- Pair in groups of 3-4



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