INSTITUTO SUPERIOR DE ENGENHARIA DE LISBOA LICENCIATURA EM ENGENHARIA INFORMÁTICA E DE COMPUTADORES MESTRADO EM ENGENHARIA INFORMÁTICA E DE COMPUTADORES IMAGE PROCESSING AND BIOMETRICS

2nd semester, 2017/2018

Mid-term exam April, 27; 3:30 pm Available time: 1:30

You can consult your class notes, with 2 A4 pages.

Explain, in detail, all your answers. Write down all the hand calculations that you carry out.

1. The monochrome image *I* with 16 gray levels was decomposed into bitplanes. The binary images corresponding to the Most Significant Bitplane (MSB) and to the Least Significant Bitplane (LSB) are

$$I_{MSB} = \left[\begin{array}{ccccc} 1 & 1 & 1 & 1 & 1 \\ 1 & 0 & 1 & 0 & 1 \\ 0 & 1 & 0 & 1 & 0 \end{array} \right] \qquad \text{and} \qquad I_{LSB} = \left[\begin{array}{ccccc} 1 & 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 1 \\ 0 & 1 & 0 & 1 & 0 \end{array} \right].$$

- (a) $\{1.0\}$ Under these settings, regarding image I, state: the total number of distinct bitplanes that compose the image; the spatial resolution; the total number of bits that the image occupies; the minimum value for its energy.
- (b) $\{1.0\}$ Assume that I has average intensity $m_I = 8$. Consider that image I_2 is computed from I, by setting its LSB bitplane, I_{LSB} to zero. Compute the average intensity of the I_2 image.
- 2. The monochrome images I_1 and I_2 , with depth n=4 bit/pixel, are defined as

$$I_1 = \left[egin{array}{ccccc} 10 & 1 & 10 & 1 \\ 5 & 1 & 1 & 5 \\ 4 & 1 & 1 & 4 \end{array}
ight] \qquad ext{and} \qquad I_2 = \left[egin{array}{ccccc} 12 & 10 & 8 & 7 & 6 \\ 12 & 10 & 8 & 7 & 6 \\ 12 & 10 & 8 & 7 & 6 \end{array}
ight].$$

- (a) {1.5} Draw the histogram of each image. Which one of these images has higher brightness? Which one has higher contrast? Show the brightness and contrast indicators that you have considered.
- (b) $\{1.5\}$ Let $I_3 = NOT[I_1]$ and $I_4 = 2 \times I_2 5$. Show the I_3 and I_4 images, as well as their corresponding histograms.
- (c) $\{1.5\}$ Sketch the intensity transformation T_1 that yields the negative version of I_1 . Explain how the lookup table that performs this transformation is composed. Show the image that results from applying T_1 to I_1 .
- (d) $\{1.5\}$ Sketch the intensity transformation T_2 that performs histogram equalization on I_1 . Show the image that results from applying T_2 to I_1 .
- 3. The following questions address Digital Image Processing (DIP) techniques.
 - (i) $\{1.5\}$ The monochrome images I_1 and I_2 shown in the figure below have the properties reported in the table. Suppose you want to mix both images, yielding image I_3 . State, with all the details, how one should proceed in order to compute the I_3 image.

	I_1	I_2
Spatial Resolution	512×512	256×256
Depth Resolution	8 bit/pixel	16 bit/pixel







- (ii) {1.5} State two examples of DIP problems, such that one has to resort to spatial or frequency filtering techniques, given that the use of intensity transformations is not enough/adequate.
- (iii) {1.5} On a given software module of a monochrome digital camera, we want to add the brightness control capability. This feature consists of detecting if the image under acquisition has excessive high brightness or excessive low brightness. The goal is to prevent the user from taken a picture which is not of good quality. State, in detail, how would you proceed to implement this capability.
- (iv) {1.5} On the following algorithm, the linear_spatial_filtering function performs linear spatial filtering, with the masks defined by parameters a and b.

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Input: Monochrome image f[m,n], Mask a, Mask b, Boolean flag.
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Output: Monochrome image g[m,n].

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1. f1 = linear_spatial_filtering( f, a ).
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- 2. f2 = linear_spatial_filtering(f, b).
- 3. if (flag==1)
- 4. g = abs(f1) + abs(f2).
- 5. else
- 6. g = f1 f2.

State the type of operation/technique that this algorithm performs as well as the relationship between the f[m, n] and the g[m, n] images, with:

(1)
$$a = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$
 , $b = \begin{bmatrix} 0 & 1 & 0 \\ 1 & -4 & 1 \\ 0 & 1 & 0 \end{bmatrix}$ and flag=0.

(2)
$$a = \begin{bmatrix} 1 & 0 & -1 \\ 2 & 0 & -2 \\ 1 & 0 & -1 \end{bmatrix}$$
 , $b = \begin{bmatrix} 1 & 2 & 1 \\ 0 & 0 & 0 \\ -1 & -2 & -1 \end{bmatrix}$ and flag=1.

$$\text{4. The } f[m,n] \text{ image has spectrum } F[u,v] = \left[\begin{array}{cccc} 15 & 2-j & 5 & 2+j \\ -1 & -2-j & -3 & -2+j \\ -5 & -2-j & 1 & -2+j \\ -1 & -2-j & -3 & -2+j \end{array} \right].$$

- (a) $\{1.5\}$ State the average intensity value and the spatial resolution of f[m, n].
- (b) $\{1.5\}$ Compute |F[u,v]| and $\arg[F[u,v]]$, on the centered format.
- 5. The following questions address image filtering techniques.
 - (a) {1.5} On a given digital image processing problem, one wonders regarding the choice of spatial filtering techniques or frequency filtering techniques. State the advantages and disadvantages of frequency filtering techniques, as compared to spatial filtering. Show one example of a case, in which we should chose a spatial filtering technique. Show another example, in which we should chose a frequency filtering technique.
 - (b) {1.5} Show as an image sketch, the frequency response of the following filters:
 - (1) Ideal high-pass filter, with cutoff frequency $D_o = 40$, for 256×256 images;
 - (2) Filter that removes the image DC component, while keeping all the other frequency components, for 512×512 images;
 - (3) Band-Reject Filter, for the bandwidth between $D_a = 30$ and $D_b = 50$, for 1024×512 images.