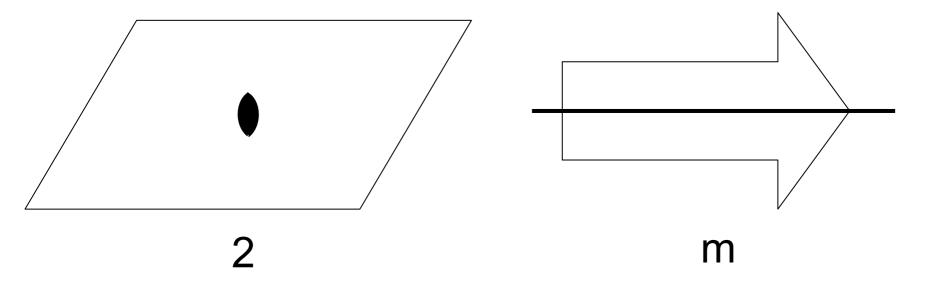


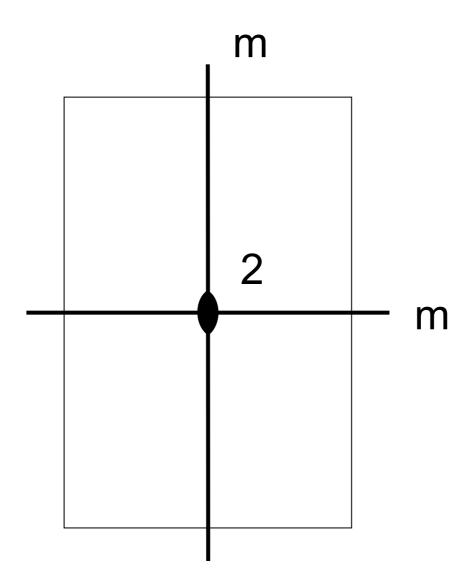
Symmetry, space groups, reciprocal space

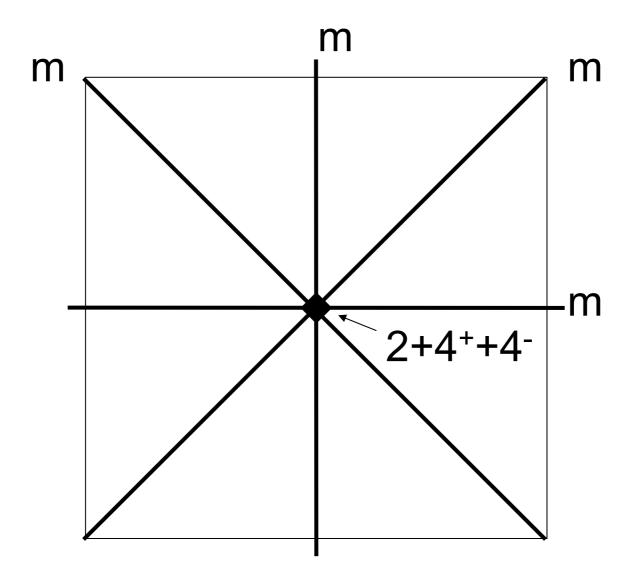
P.G. Radaelli ISIS Facility - RAL

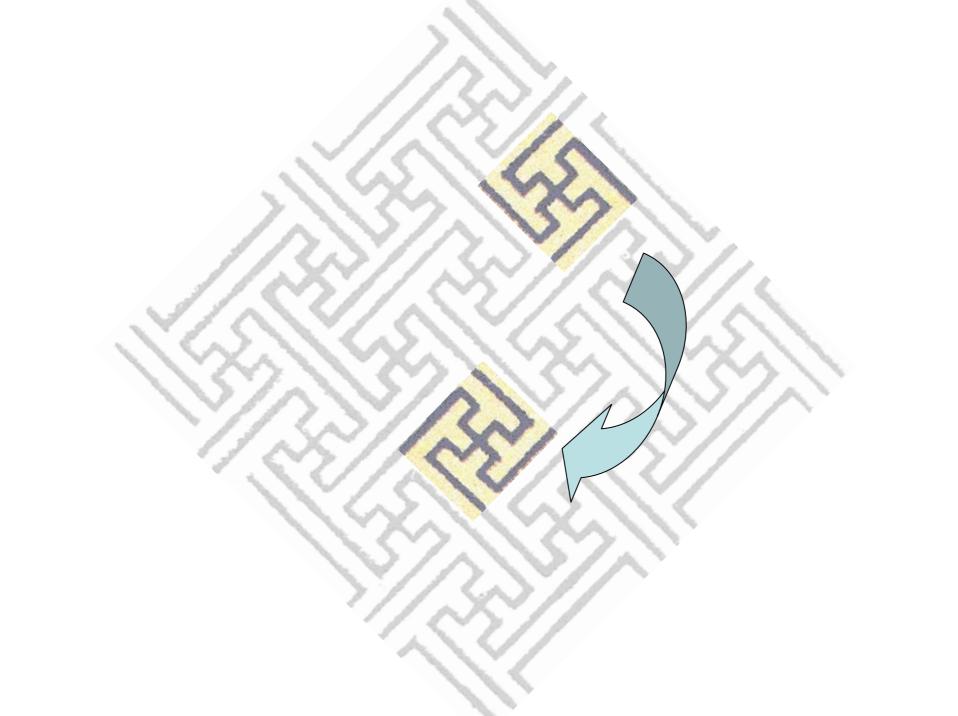
ftp://ftp.nd.rl.ac.uk/scratch/UCL Teaching 2007/





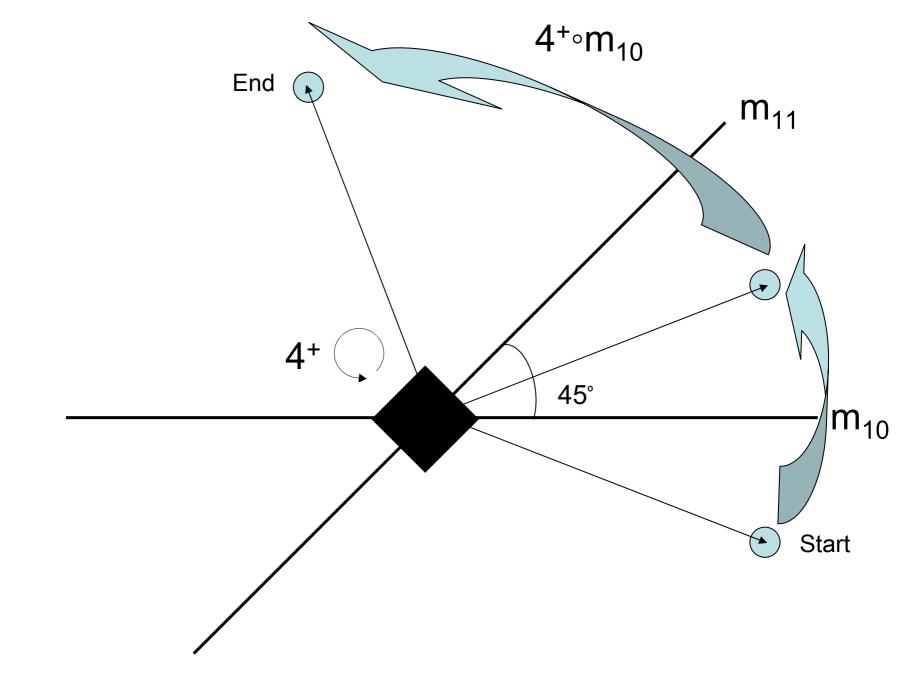






Parallelogram and arrow groups

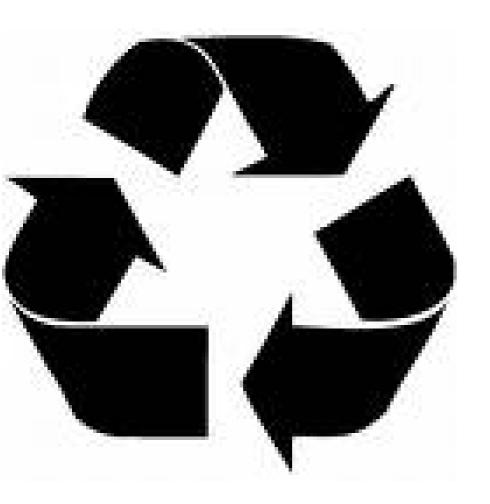
	E	2 or m
E	E	2 or m
2 or m	2 or m	E



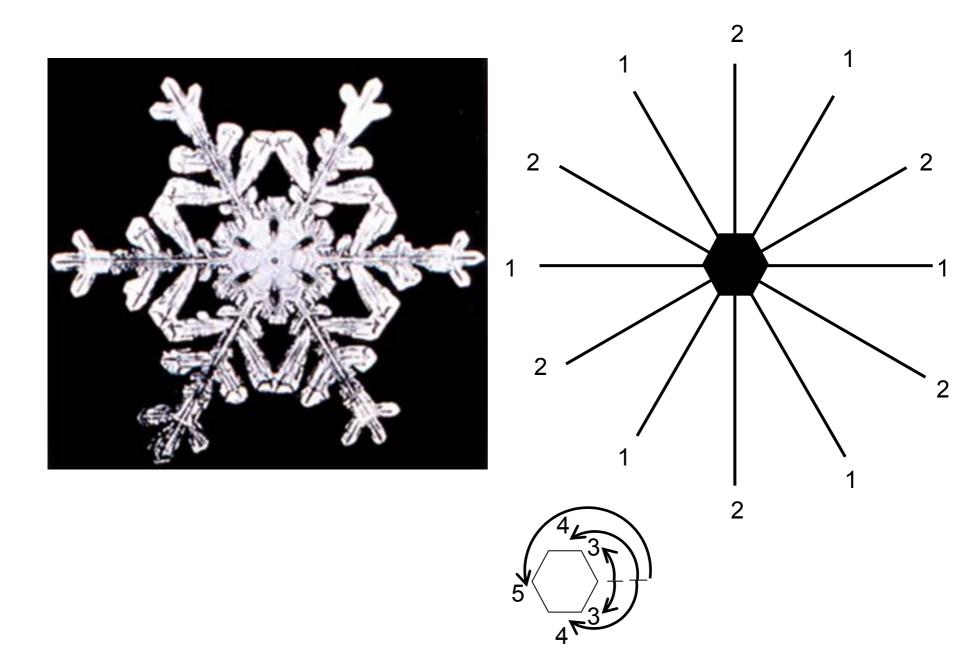
Graph Symmetry (conjugation)

$$g \cdot [h] = [g \circ h \circ g^{-1}]$$



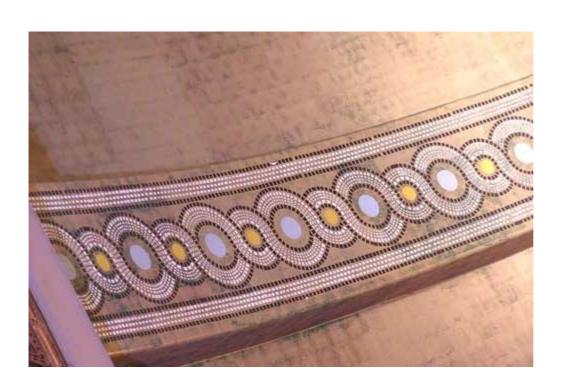




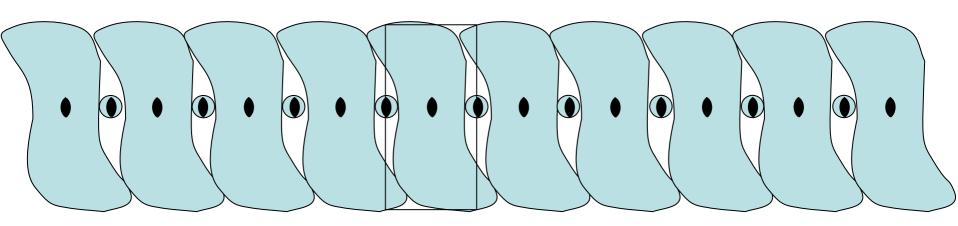


6				•
6	a	1	Hexagon Hexagon (d)	(hki) (ihk) (kih) $(\bar{h}\bar{k}i)$ $(\bar{i}h\bar{k})$ $(\bar{k}i\bar{h})$
6 <i>mm</i>				
12	С	1	Dihexagon $Truncated\ hexagon\ (f)$	$\begin{array}{ccc} (hki) & (ihk) & (kih) \\ (\overline{h}ki) & (\overline{i}\overline{h}\overline{k}) & (\overline{k}\overline{i}h) \\ (\overline{k}\overline{h}\overline{i}) & (\overline{i}\overline{k}\overline{h}) & (\overline{h}\overline{i}\overline{k}) \\ (khi) & (ikh) & (hik) \end{array}$
6	b	.m.	Hexagon Hexagon (e)	$egin{array}{ccc} (10\overline{1}) & (\overline{1}10) & (0\overline{1}1) \\ (\overline{1}01) & (1\overline{1}0) & (01\overline{1}) \\ \end{array}$
6	а	m	Hexagon Hexagon (d)	$\begin{array}{ccc} (11\bar{2}) & (\bar{2}11) & (1\bar{2}1) \\ (\bar{1}\bar{1}2) & (2\bar{1}\bar{1}) & (\bar{1}2\bar{1}) \end{array}$



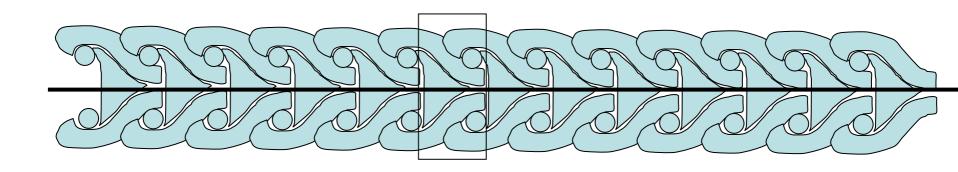




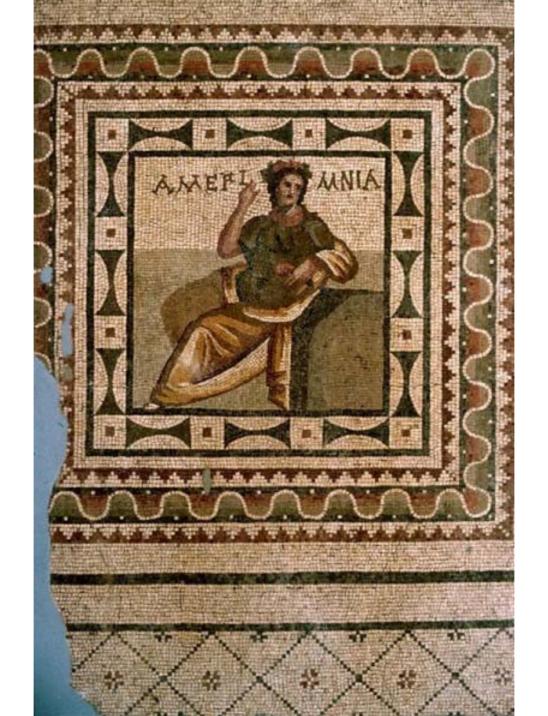


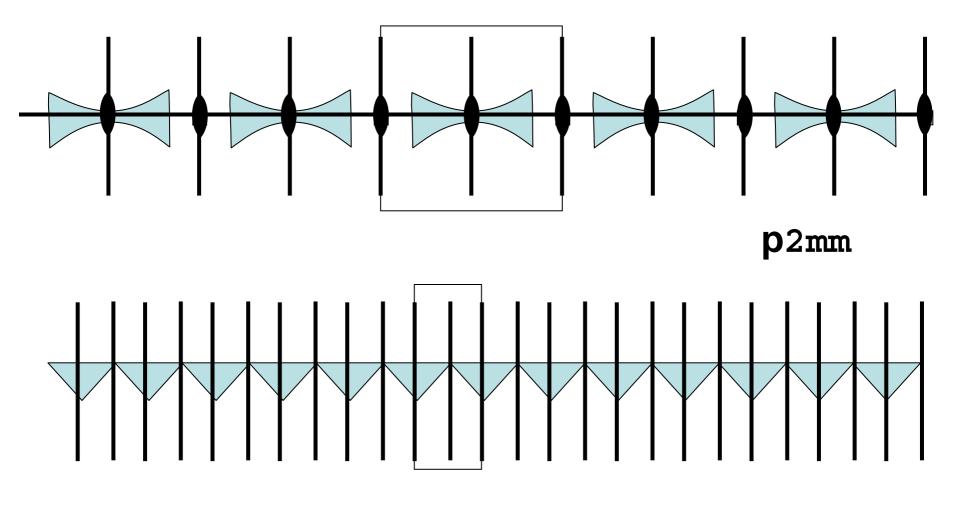
p211



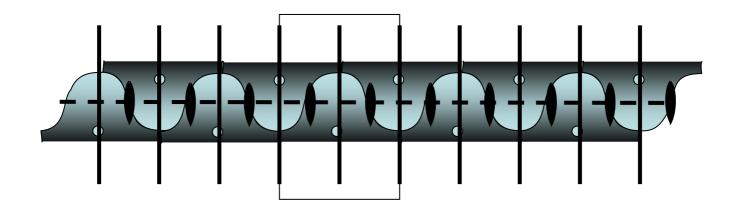


p11m

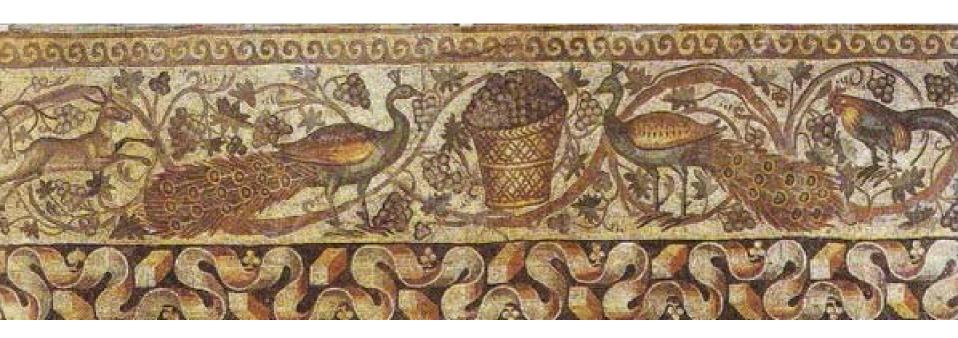




p1m1

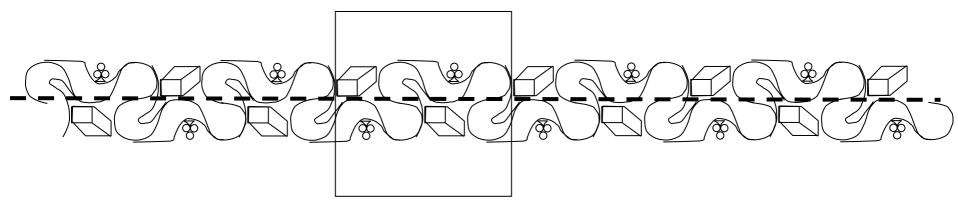


p2mg

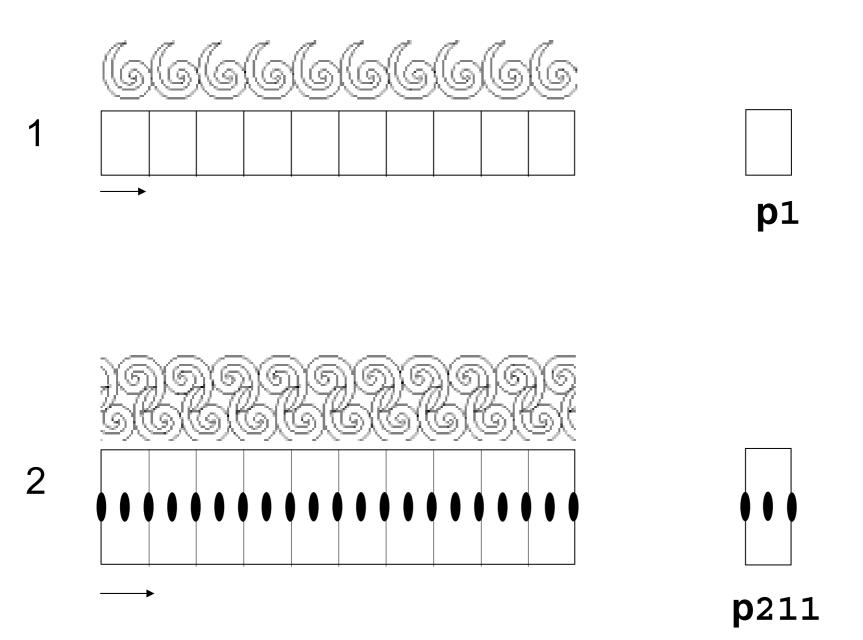


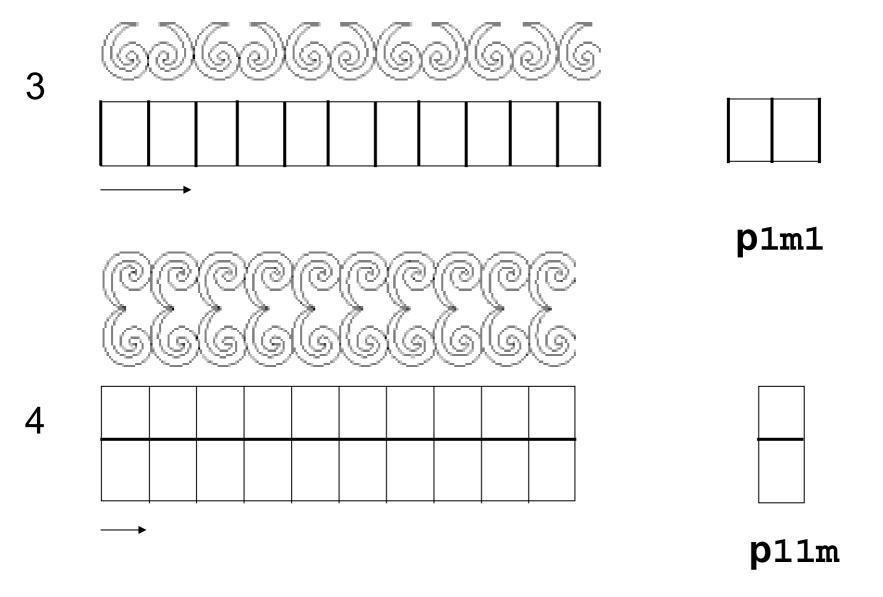
55555555

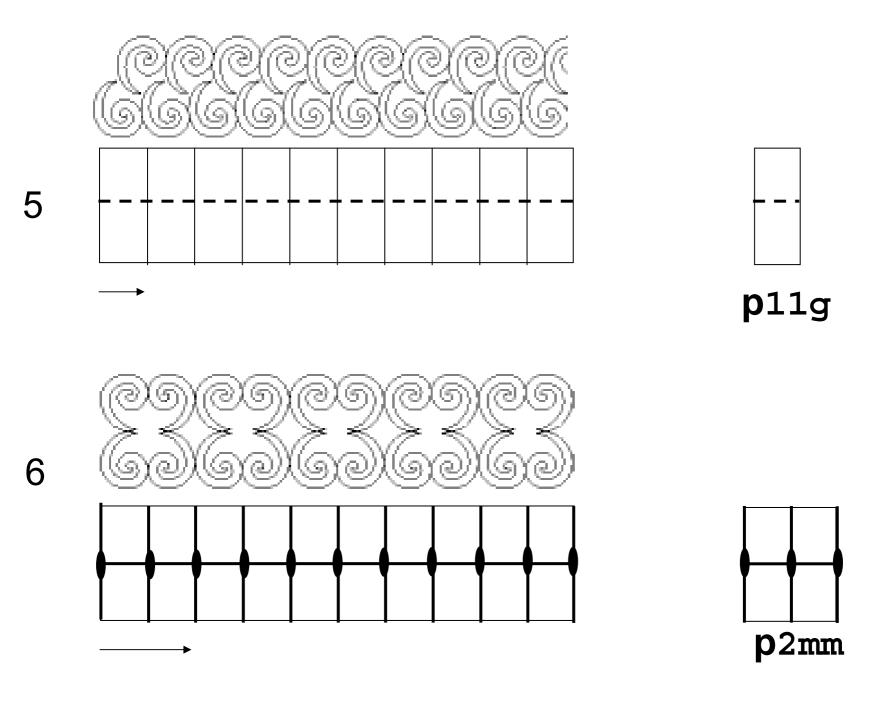
p1

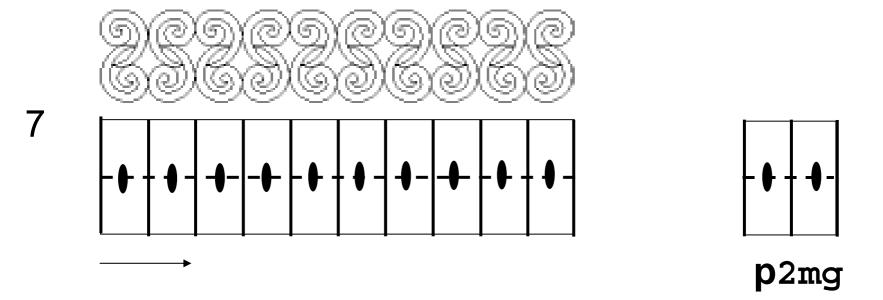


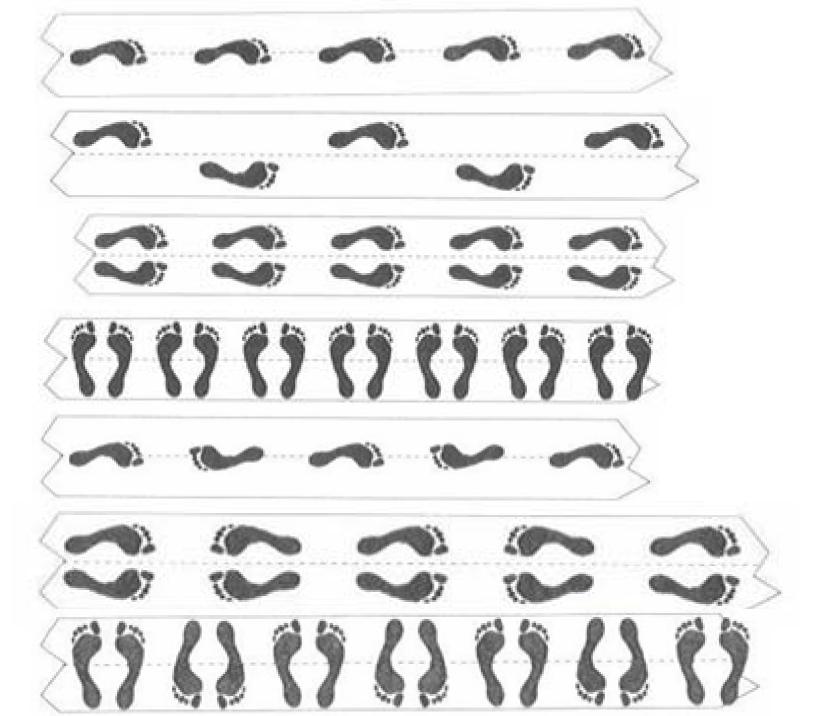
p11g



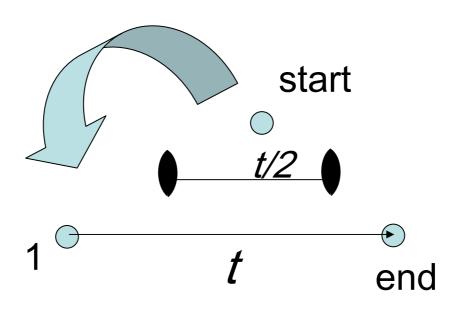


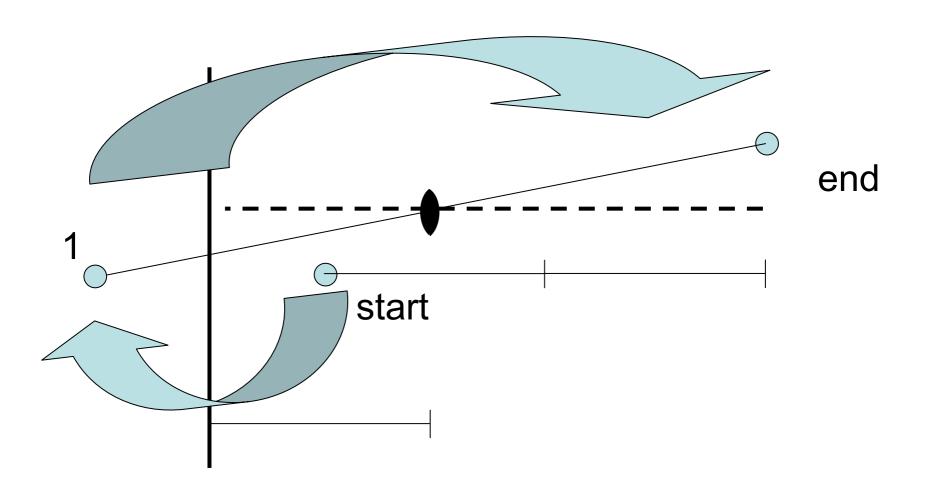




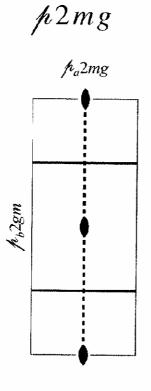


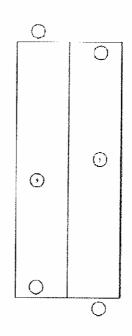
$t \circ 2$





Patterson symmetry /2mm





Origin at 21g

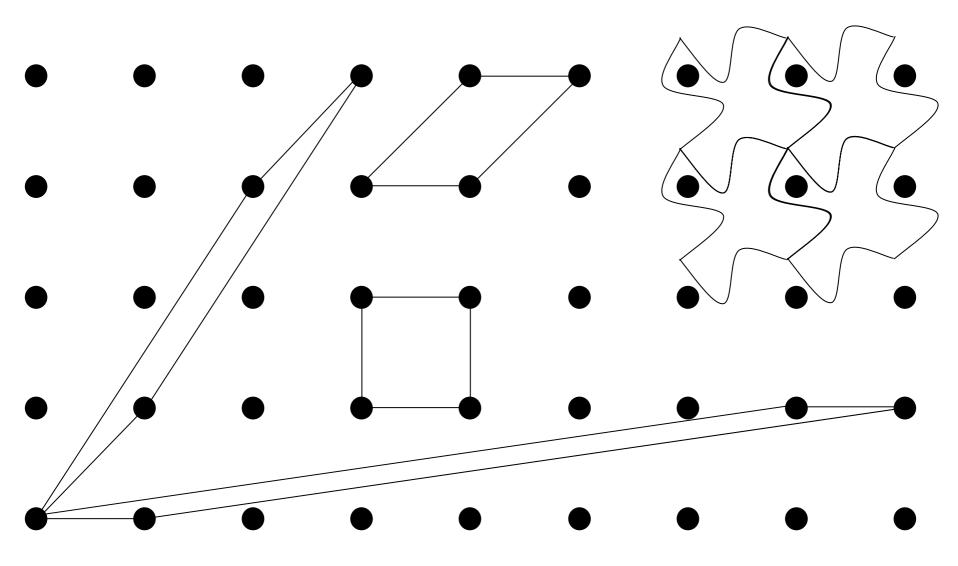
Asymmetric unit $0 \le x \le \frac{1}{4}$

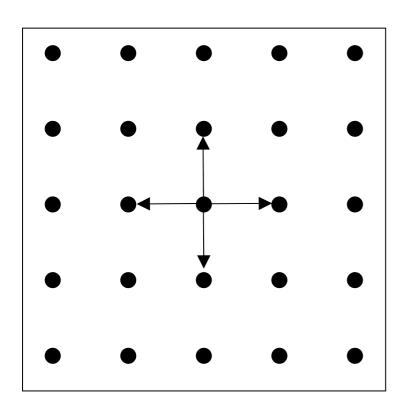
Symmetry operations

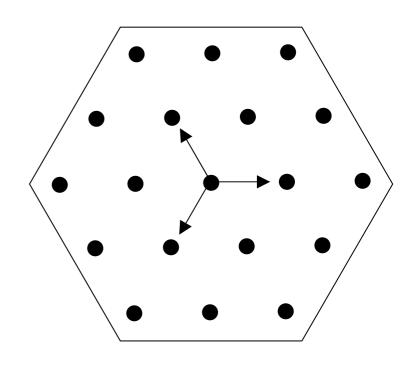
(1) 1

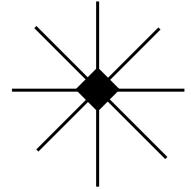
(2) 2 0,0 (3) $m_{\frac{1}{4}},y$ (4) $g_{x},0$

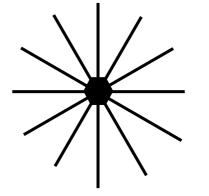
Generators selected (1); t(1); (2); (3)

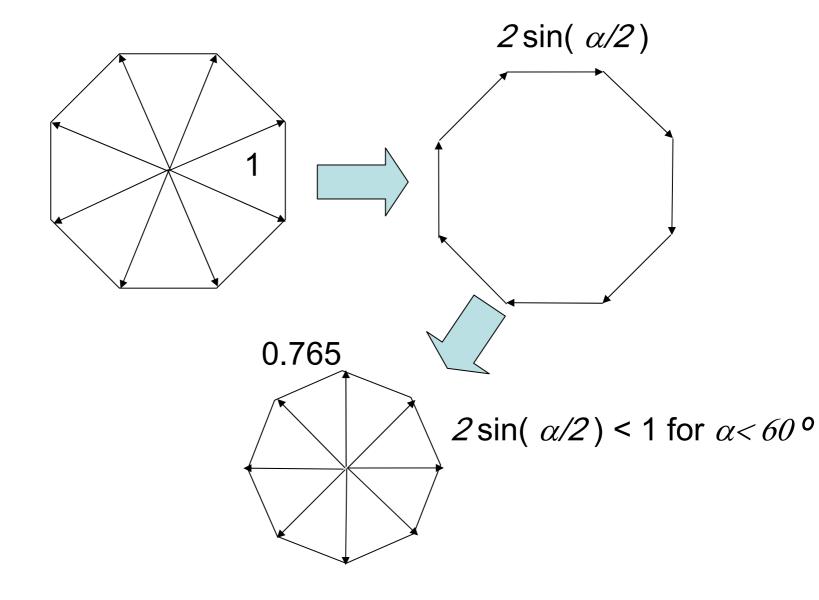


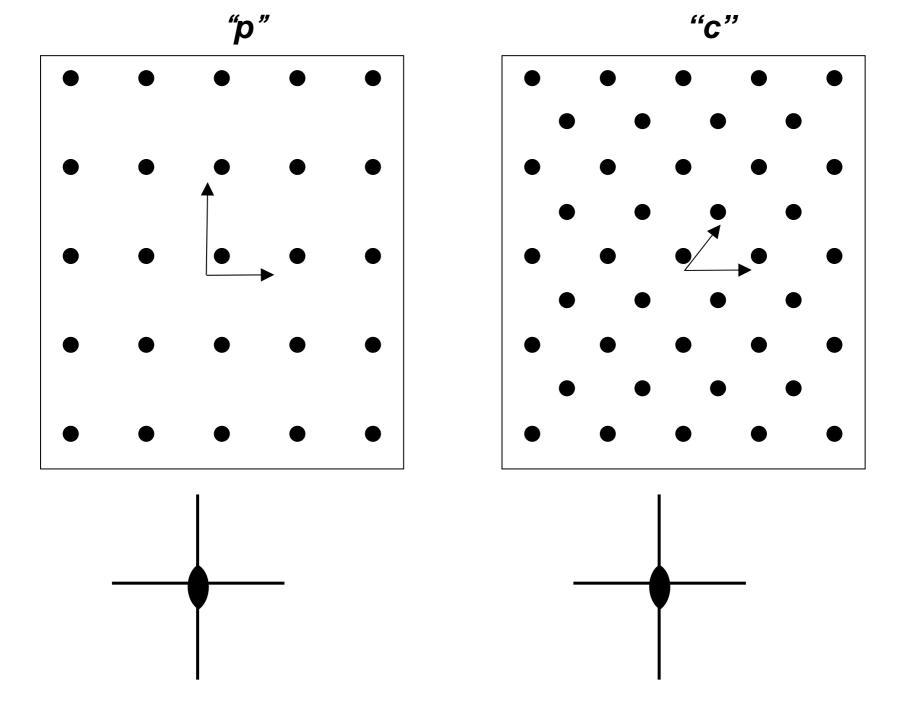


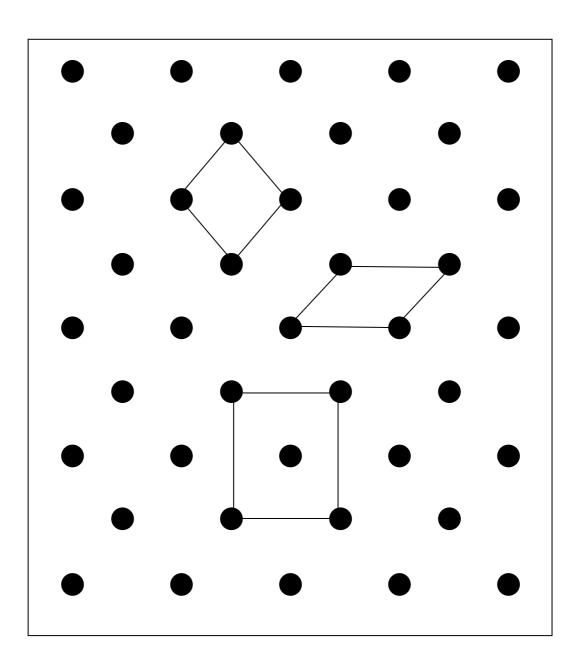




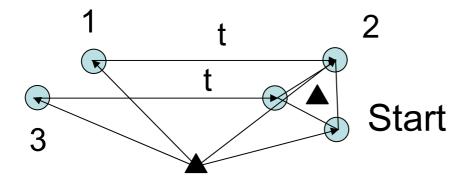


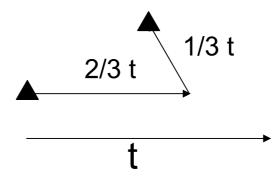


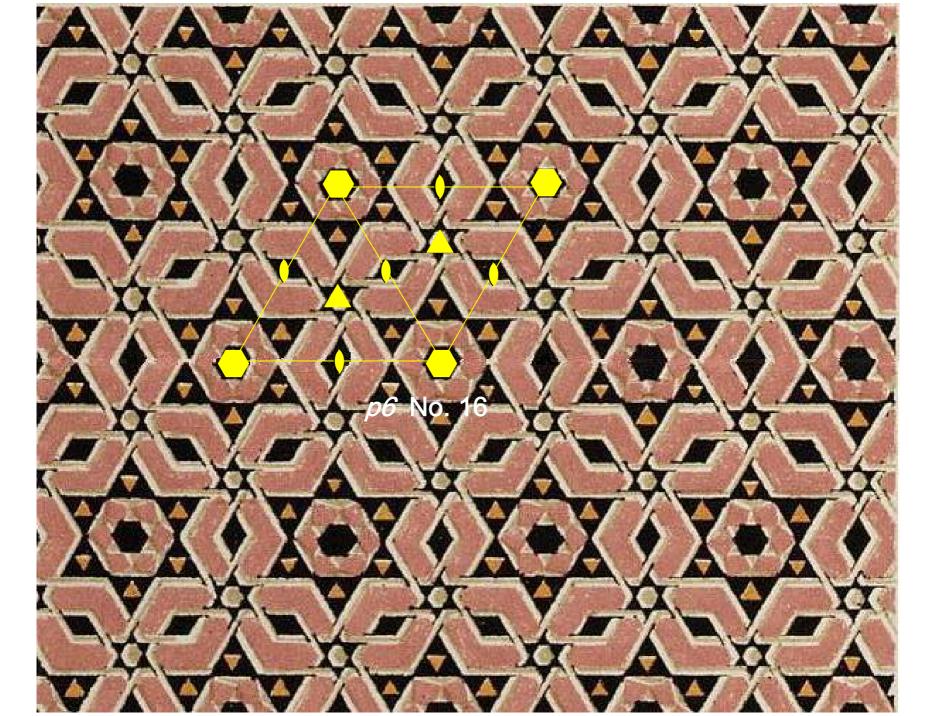


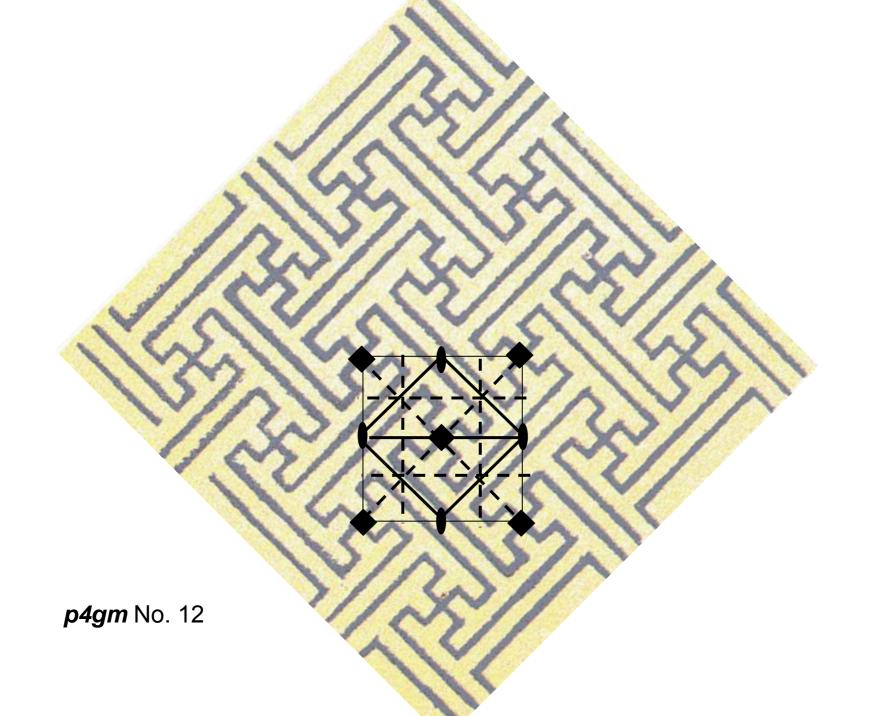


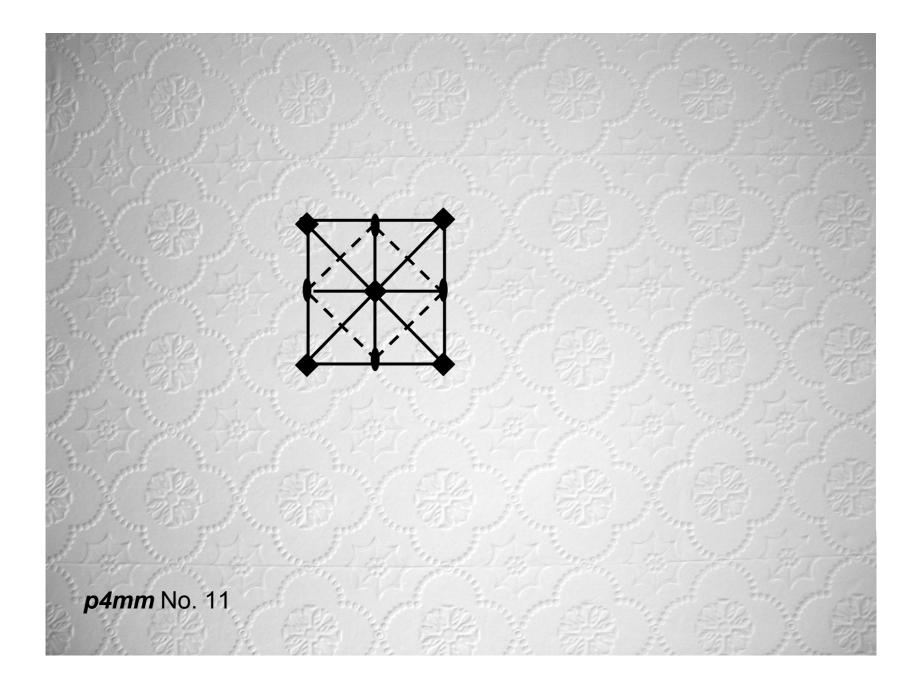
Geometrical construction for [to3]













p31m

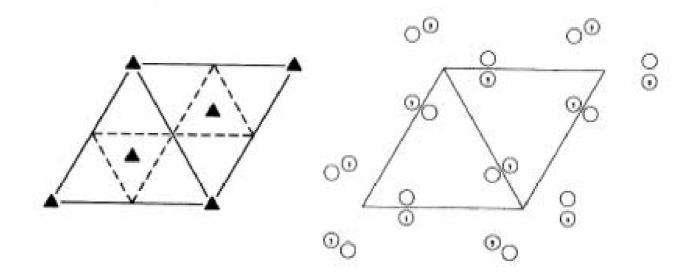
3m

Hexagonal

No. 15

p31m

Patterson symmetry p6mm



Origin at 31m

Asymmetric unit

$$0 \le x \le \frac{2}{3}$$
; $0 \le y \le \frac{1}{3}$; $x \le (1+y)/2$; $y \le \min(1-x,x)$

Vertices:

Symmetry operations

(1) 1

- (3) 3- 0,0 (6) m 0,y

- (4) $m \times x$
- (2) 3^+ 0,0 (5) m x,0

Generators selected (1); t(1,0); t(0,1); (2); (4)

Positions

Multiplicity, Wyckoff letter, Coordinates

Site symmetry

(1)
$$x, y$$

(2)
$$\hat{y}, x - y$$

(3)
$$\bar{x} + y_i \bar{x}$$

(4)
$$y_i x$$

(5)
$$x - y, \bar{y}$$

(6)
$$\bar{x}, \bar{x} + y$$

$$\hat{X}, \hat{X}$$

1; 2; 3

$$1 \ a \ 3.m$$

Maximal non-isomorphic subgroups

Ha none

IIb
$$[3]h31m(a'=3a,b'=3b)(p3m1,14)$$

Maximal isomorphic subgroups of lowest index

He [4]
$$p31m(a'=2a,b'=2b)$$
 (15)

Minimal non-isomorphic supergroups

Reflection conditions

General:

no conditions

Special: no extra conditions

Generic roto-translation Cartesian Coordinates

$$\begin{bmatrix} x_2 \\ y_2 \\ z_2 \end{bmatrix} = \begin{bmatrix} t_x \\ t_y \\ t_z \end{bmatrix} + \mathbf{R} \begin{bmatrix} x_1 \\ y_1 \\ z_1 \end{bmatrix}$$
 (5.5)

Rotations around coordinate axes Cartesian Coordinates

$$\mathbf{R}_{x} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & \cos \theta & -\sin \theta \\ 0 & \sin \theta & \cos \theta \end{bmatrix}$$

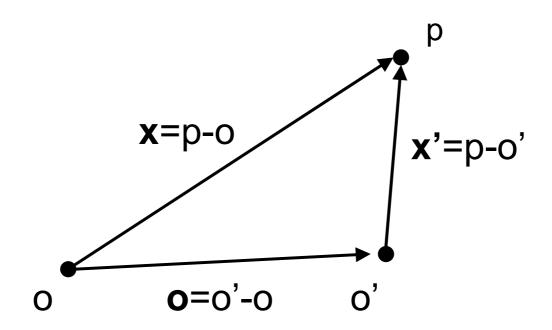
$$\mathbf{R}_{y} = \begin{bmatrix} \cos \theta & 0 & \sin \theta \\ 0 & 1 & 0 \\ -\sin \theta & 0 & \cos \theta \end{bmatrix}$$

$$\mathbf{R}_{z} = \begin{bmatrix} \cos \theta & -\sin \theta & 0 \\ \sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Rotations around generic axis Cartesian Coordinates

$$\mathcal{M}(\hat{\mathbf{v}}, \theta) = \begin{bmatrix} \cos \theta + (1 - \cos \theta)x^2 & (1 - \cos \theta)xy - (\sin \theta)z & (1 - \cos \theta)xz + (\sin \theta)y \\ (1 - \cos \theta)yx + (\sin \theta)z & \cos \theta + (1 - \cos \theta)y^2 & (1 - \cos \theta)yz - (\sin \theta)x \\ (1 - \cos \theta)zx - (\sin \theta)y & (1 - \cos \theta)zy + (\sin \theta)x & \cos \theta + (1 - \cos \theta)z^2 \end{bmatrix}$$
(5.8)

Coordinate systems on an affine space



$$x'=x-o$$

Basis vector transformations (covariant)

$$\begin{aligned} [\mathbf{a}_1', \mathbf{a}_2', \mathbf{a}_3'] &= [\mathbf{a}_1, \mathbf{a}_2, \mathbf{a}_3] \mathbf{P} \\ &= [\mathbf{a}_1, \mathbf{a}_2, \mathbf{a}_3] \begin{bmatrix} P_{11} & P_{12} & P_{13} \\ P_{21} & P_{22} & P_{23} \\ P_{31} & P_{32} & P_{33} \end{bmatrix} \end{aligned}$$

Component transformations (contravariant)

$$\begin{bmatrix} v'^{1} \\ v'^{2} \\ v'^{3} \end{bmatrix} = \mathbf{Q} \begin{bmatrix} v^{1} \\ v^{2} \\ v^{3} \end{bmatrix}$$

$$= \begin{bmatrix} Q_{11} & Q_{12} & Q_{13} \\ Q_{21} & Q_{22} & Q_{23} \\ Q_{31} & Q_{32} & Q_{33} \end{bmatrix} \begin{bmatrix} v^{1} \\ v^{2} \\ v^{3} \end{bmatrix}$$

$$\mathbf{v} = \mathbf{a}_{i} v^{i} = \mathbf{a}'_{j} v'^{j} = \mathbf{a}_{i} P_{j}^{i} Q_{k}^{j} v^{k}$$

$$(5.18)$$

$$P_j^i Q_k^j = \delta_k^i \to \mathbf{Q} = \mathbf{P}^{-1} \tag{5.19}$$

Coordinate transformations

$$x'=x-0$$

$$x'^{i} = Q_{j}^{i}x^{j} - o'^{i} = Q_{j}^{i}(x^{j} - o^{j})$$

$$x^{i} = (Q^{-1})^{i}_{j}(x'^{j} + o'^{j}) = (Q^{-1})^{i}_{j}x'^{j} + o^{j}$$

Dual basis

$$\mathbf{b}^{i} = 2\pi \mathbf{a}_{k} (G^{-1})^{ki}$$

$$\mathbf{a}_{i} \cdot \mathbf{b}^{j} = \mathbf{a}_{i} \cdot \mathbf{a}_{k} (G^{-1})^{kj} = G_{ik} (G^{-1})^{kj} = 2\pi \delta_{i}^{j}$$

$$\mathbf{q} = q_{i} \mathbf{b}^{i}$$

$$\mathbf{q} \cdot \mathbf{v} = 2\pi q_{i} v^{i}$$
(5.34)

Dual basis in 3D

$$\mathbf{b}_{1} = 2\pi \frac{\mathbf{a}_{2} \times \mathbf{a}_{3}}{\mathbf{a}_{1} \cdot (\mathbf{a}_{2} \times \mathbf{a}_{3})}$$

$$\mathbf{b}_{2} = 2\pi \frac{\mathbf{a}_{3} \times \mathbf{a}_{1}}{\mathbf{a}_{1} \cdot (\mathbf{a}_{2} \times \mathbf{a}_{3})}$$

$$\mathbf{b}_{3} = 2\pi \frac{\mathbf{a}_{1} \times \mathbf{a}_{2}}{\mathbf{a}_{1} \cdot (\mathbf{a}_{2} \times \mathbf{a}_{3})}$$

$$q_{i} = \frac{1}{2\pi} \mathbf{q} \cdot \mathbf{a}_{i}$$

Reciprocal Lattice

$$o + h_i \mathbf{b}^i$$
;
 $h_i = h, k, l = \text{integers}$

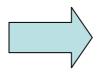
Reciprocal Lattice Alternative definition

$$o + \mathbf{q}$$
; such that

$$\mathbf{q} \cdot \mathbf{v} = 2\pi n$$

For every symmetry translation vector **v**

$$q_i = \frac{1}{2\pi} \mathbf{q} \cdot \mathbf{a}_i$$
 q_i are integers



The reverse is not always true!

$$\mathbf{q} \cdot \mathbf{v} = 2\pi q_i v^i$$

is an integral multiple of 2π only if all the v^i are integers, which is not the case for conventional centred bases.

Primitive RL

$$o + h_i \mathbf{b}^i$$
;
 $h_i = h, k, l = \text{integers}$

Where **b**ⁱ is a *dual primitive basis*.

$$o + \mathbf{q}$$
; such that

$$\mathbf{q} \cdot \mathbf{v} = 2\pi n$$

Conventional RL

Will have "extra" q vectors for which.

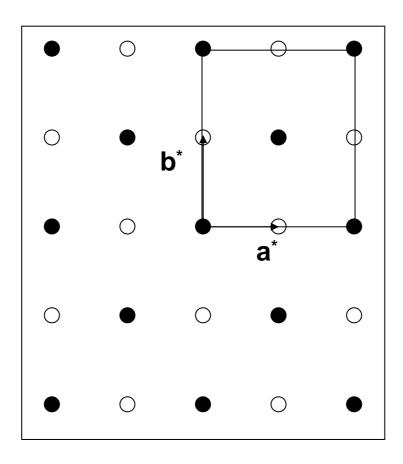
$$\mathbf{q} \cdot \mathbf{v}_c \neq 2\pi n$$

These **q** vectors are said to be <u>extinct by</u> <u>centering</u>. Conversely

$$\mathbf{q} \cdot \mathbf{v}_c = 2\pi n$$

is said to be a reflection condition.

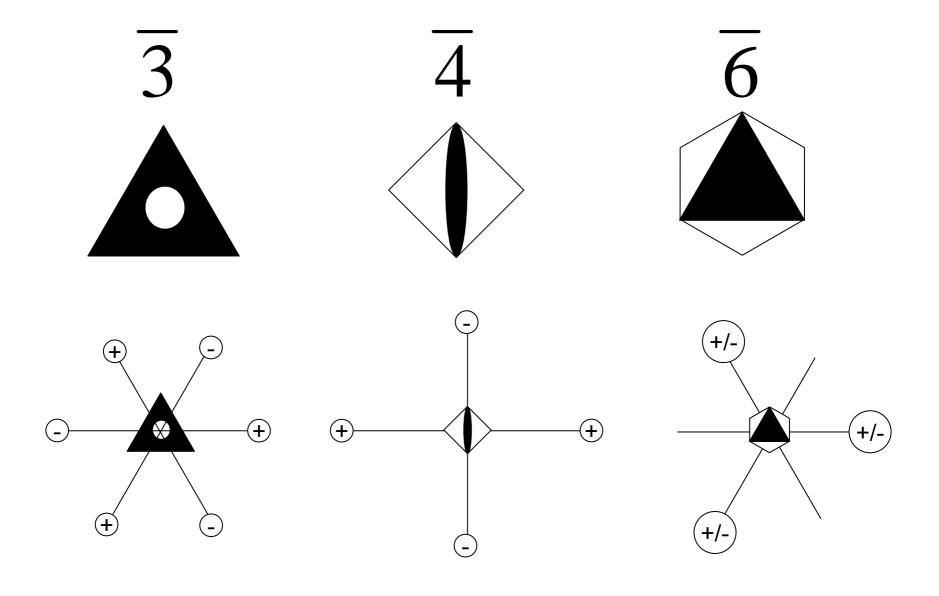
I even or odd



$$2\pi \frac{1}{2}(h+k)$$

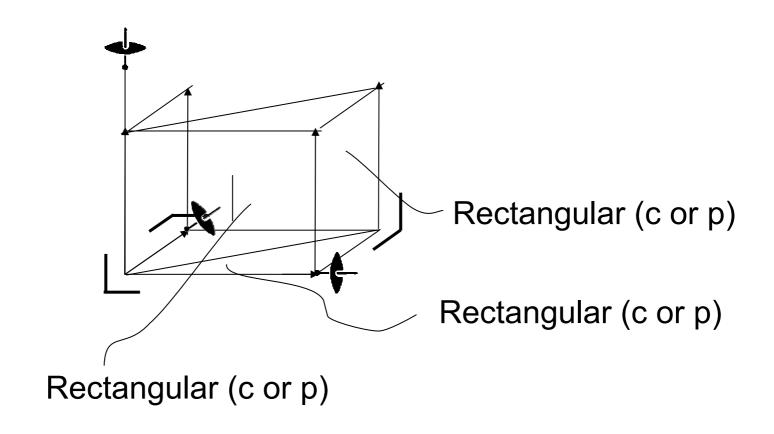
"C" centered cell

Roto-inversion operators

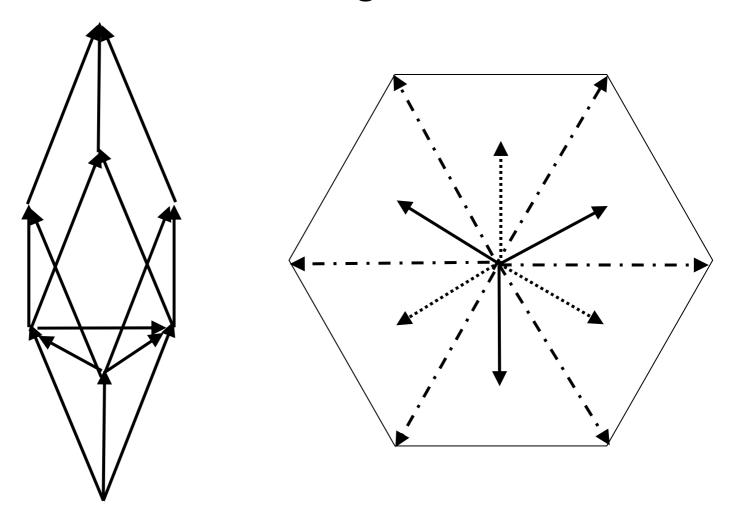


Monoclinic system (2/m) Rectangular (c or p) Oblique Rectangular (c or p)

Orthorhombic system (mmm)



R- centered trigonal lattice



Cubic lattices

