

TD: Principal Component Analysis

Exercises 1 to 3 should be addressed in priority by students in tracks ISI, MMIS and IF.

Exercise 1

We study economic indicators of 6 countries in 1991. Table 1 gives the measures of 6 economic indicators in 12 countries in 1991.

Table 1: World economic data in 1991

	GNB per capita	Inflation	Unemployment	Foreign exch.	Population	Area
South Africa	2810	14.7	0.0	6.3	36.8	1.22
Algeria	1540	50.0	24.3	4.2	26.1	2.38
Germany	24130	3.5	5.1	23.5	81.0	0.35
Saudi Arabia	7328	4.4	0.0	22.1	14.8	2.15
Brazil	2400	440.8	4.8	10.5	153.0	8.51
Egypt	620	19.8	17.5	-5.9	56.1	1.00
USA	21890	4.2	6.7	-73.4	255.0	9.36
Ethiopia	110	35.7	0.0	-0.6	54.6	1.22
Finland	25800	4.1	7.7	2.2	5.0	0.33
France	21030	3.2	9.4	-10.1	57.2	0.55
Koweit	14000	3.3	0.0	20.0	1.3	0.02
Tunisia	1350	8.2	15.0	-0.9	8.6	0.16

Interpret the results performed by a normalized PCA applied on this table. We give the eigenvalues of the variance/covariance matrix in Table 2. Principal components representation are given in Figure 1.

Table 2: Eigenvalues of the cov. matrix

	1	2	3	4	5	6
lambda	2.665	1.504	1.159	0.530	0.08	0.062
cumul. proportion	0.444	0.695	0.888	0.976	0.99	1.000

Exercise 2

We are interested by the dataset `cars04` with some car models in 2004. Each car is described by 11 variables listed in table~3.

The aim of this exercise is to summarize and to interpret the data `cars04` using PCA by the following call

```
> cars04.pca <- prcomp(cars04, scale=TRUE)
> summary(cars04.pca)
```

Importance of components:

	PC1	PC2	PC3	PC4	PC5	PC6	PC7
Standard deviation	2.6655	1.3726	0.92181	0.59751	0.52482	0.44491	0.37486
Proportion of Variance	0.6459	0.1713	0.07725	0.03246	0.02504	0.01799	0.01277
Cumulative Proportion	0.6459	0.8171	0.89439	0.92685	0.95189	0.96988	0.98266

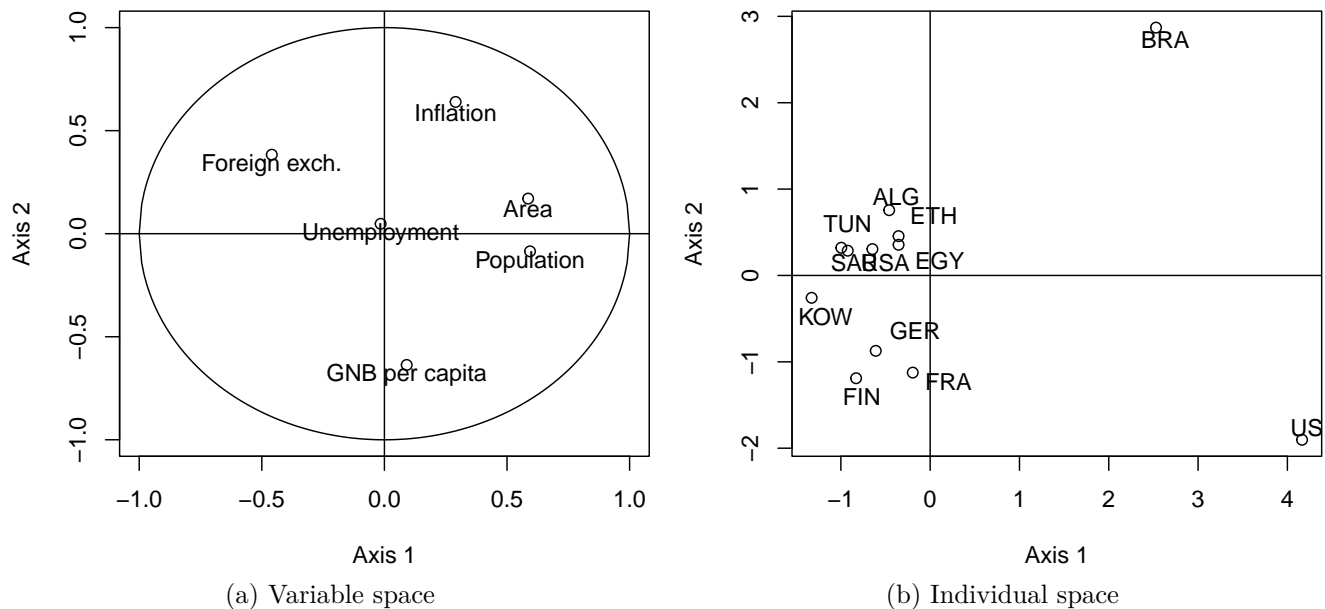


Figure 1: Principal component representation in the first plane of the variable and of the sample spaces.

Variable	Meaning
Retail	Builder recommended price(US\$)
Dealer	Seller price (US\$)
Engine	Motor capacity (liters)
Cylinders	Number of cylinders in the motor
Horsepower	Engine power
CityMPG	Consumption in city (Miles or gallon; proportional to km/liter)
HighwayMPG	Consumption on roadway (Miles or gallon)
Weight	Weight (pounds)
Wheelbase	Distance between front and rear wheels (inches)
Length	Length (inches)
Width	Width (inches)

Table 3: Variable list for cars04

	PC8	PC9	PC10	PC11
Standard deviation	0.29434	0.25766	0.19229	0.02811
Proportion of Variance	0.00788	0.00604	0.00336	0.00007
Cumulative Proportion	0.99053	0.99657	0.99993	1.00000

1. Using previous R traces, what does `scale=TRUE` mean?
2. Does the representation in the first two principal components give a good idea of dataset variations?

Principal components are linear combinations of the 11 variables. The coefficients of the first 2 principal components on these 11 variables are

```
> cars04.pca$rotation[,1:2]
```

	PC1	PC2
Retail	-0.2637504	-0.468508698
Dealer	-0.2623186	-0.470146585
Engine	-0.3470805	0.015347186
Cylinders	-0.3341888	-0.078032011
Horsepower	-0.3186023	-0.292213476
CityMPG	0.3104817	0.003365936
HighwayMPG	0.3065886	0.010964460

Weight	-0.3363294	0.167463572
Wheelbase	-0.2662100	0.418177107
Length	-0.2567902	0.408411381
Width	-0.2960546	0.312891350

3. Can you give an interpretation of each of these new variables?

On Figure 2, the projection on the first two principal components of some cars models is plotted.

4. Interpret each quadrant of the Figure.

5. Can you describe which kind of car Audi RS 6, Ford Expedition 4.6 XLT and Nissan Sentra 1.8 are?

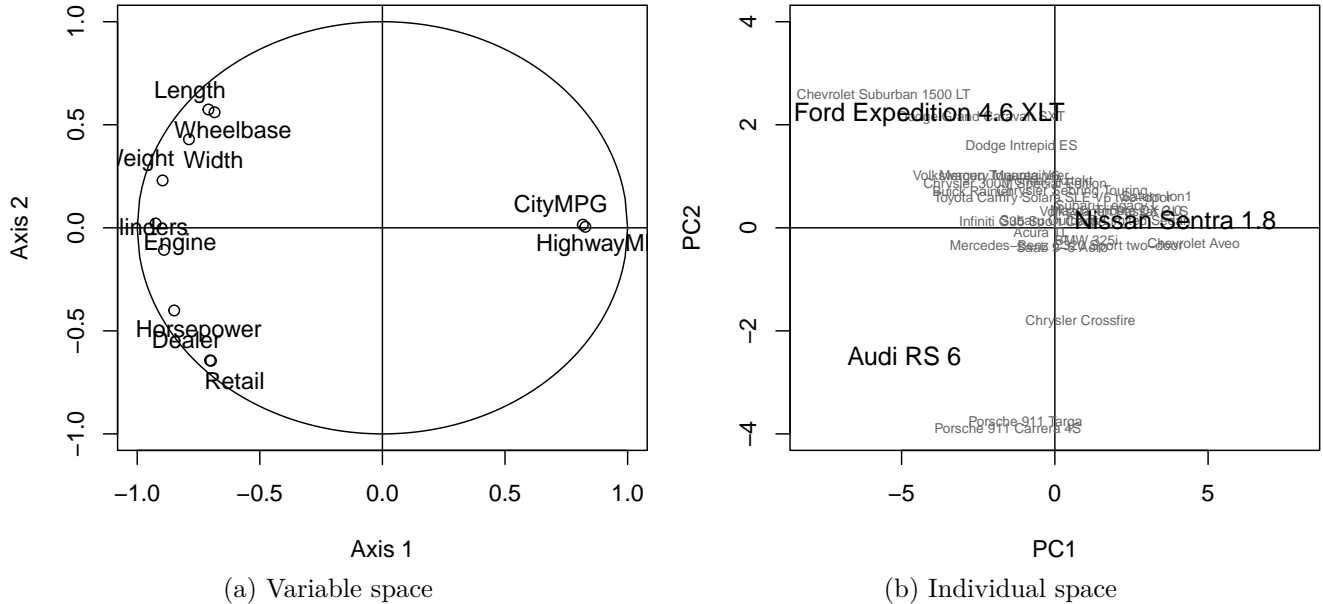


Figure 2: Principal component representation in the first plane of the variable and of the sample spaces.

Exercise 3

Correspondence Analysis (CA) is an adaptation of PCA to study couples of qualitative variables. Let consider a couple of qualitative variables (X, Y) observed on n samples. The observations are denoted $((x_1, y_1), \dots, (x_n, y_n))$. Two PCAs will be performed.

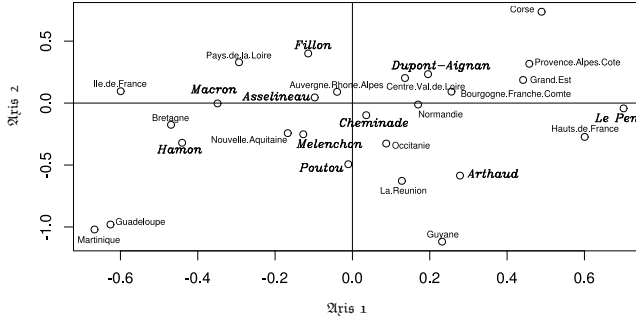
- The first PCA considers the labels i of X as individuals. Each individual is described by conditional frequencies $f(Y = 1|X = i), \dots, f(Y = L|X = i)$ of values j of the variable Y given $X = i$.
- The second PCA considers the labels j of Y as individuals. Each individual is now characterized by conditional frequencies $f(X = 1|Y = j), \dots, f(X = K|Y = j)$.

The interpretations of these two PCAs can be done as usual. The advantage of CA is its ability to represent both PCAs on the same graph. It allows to associate the values i of X with values j of Y using inner product between these two vectors.

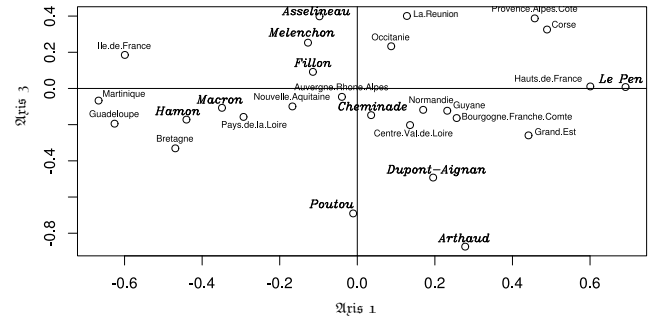
- If the inner product is positive, it means that $(X = i, Y = j)$ is more frequent in the population than it would be under independence between X and Y .
- If the value is negative, it means that we would expect more couples $(X = i, Y = j)$ under independence property.

We propose to apply CA on results recorded after the first turn of presidential election in France in 2017. X represent the candidates and Y the overseas departments. Interpret the CA results.

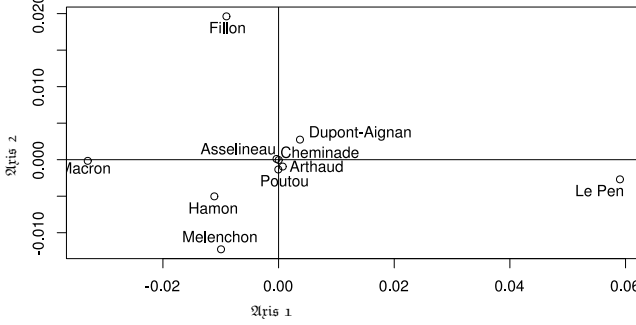
N.B. Candidate Lassalle was removed because he obtained quite small percentages of votes but with a very high relative variability.



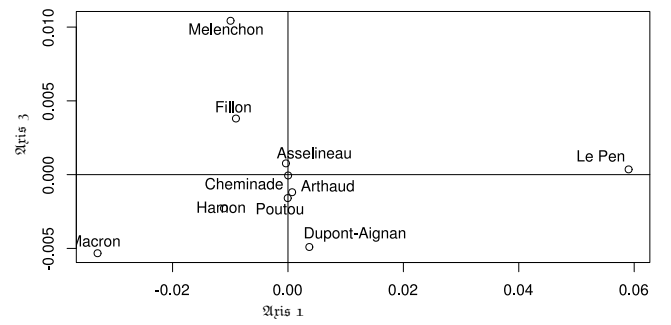
(a) PCA on samples: Departments and candidates (axes 1 and 2)



(b) PCA on samples: Departments and candidates (axes 1 and 3)



(c) PCA on candidates considered as variables (axes 1 and 2)



(d) PCA on candidates considered as variables (axes 1 and 3)

Figure 3: Principal axes of the two PCA

Exercise 4

1. Prove Proposition 1.

Proposition 1. Let $x'_i = x_i - \bar{x}_i$ (for $i = 1, \dots, n$) be some centred sample in dimension p with covariance matrix Σ . Then the canonical inertia of these points $\frac{1}{n} \sum_{i=1}^n \|x'_i\|^2$ is $\text{tr}(\Sigma)$.

Let Π some orthogonal projection (with the canonical dot product). Then the inertia of the projected points is $\text{tr}(\Sigma\Pi)$.

2. As a bonus, prove its Corollaries.

Corollary 1. As a consequence, for standardized samples, $\frac{1}{n} \sum_{i=1}^n \|x'_i\|^2 = p$.

Corollary 2. The projected inertia on the sum of two orthogonal subspaces is the sum of the projected inertia on each subspace.

Hint: for any $a \in \mathbb{R}$, $a = \text{tr}(a)$.

Exercise 5

1. Prove Proposition 2.

Proposition 2. We use the notations in Proposition 1.

Let a_1 some vector with norm 1 such that $\Sigma a_1 = \lambda_1 a_1$, λ_1 being (one of) the highest eigenvalue of Σ . Then the projected inertia on the line $D_1 = \text{Span}(a_1)$ is maximal over projected inertia on all other possible lines.

Moreover, the projected inertia on D_1 is λ_1 .

Hints:

- Use the results from multiple linear regression to prove that for any matrix X with linearly independent columns $X^{(1)}, \dots, X^{(p)}$, the matrix of the orthogonal projection on $\text{Span}\left(\left\{X^{(1)}, \dots, X^{(p)}\right\}\right)$ is $X(X^T X)^{-1}X^T$ (or admit this result if it does not seem obvious).
- Write the maximization problem as

$$\max_{a, \|a\|=1} \text{tr}(\Sigma a a^T).$$

- Introduce a Lagrange multiplier ξ and cancel the gradient of

$$(a, \xi) \rightarrow a^T \Sigma a - \xi(a^T a - 1).$$