

# Graph Mining and Community Detection

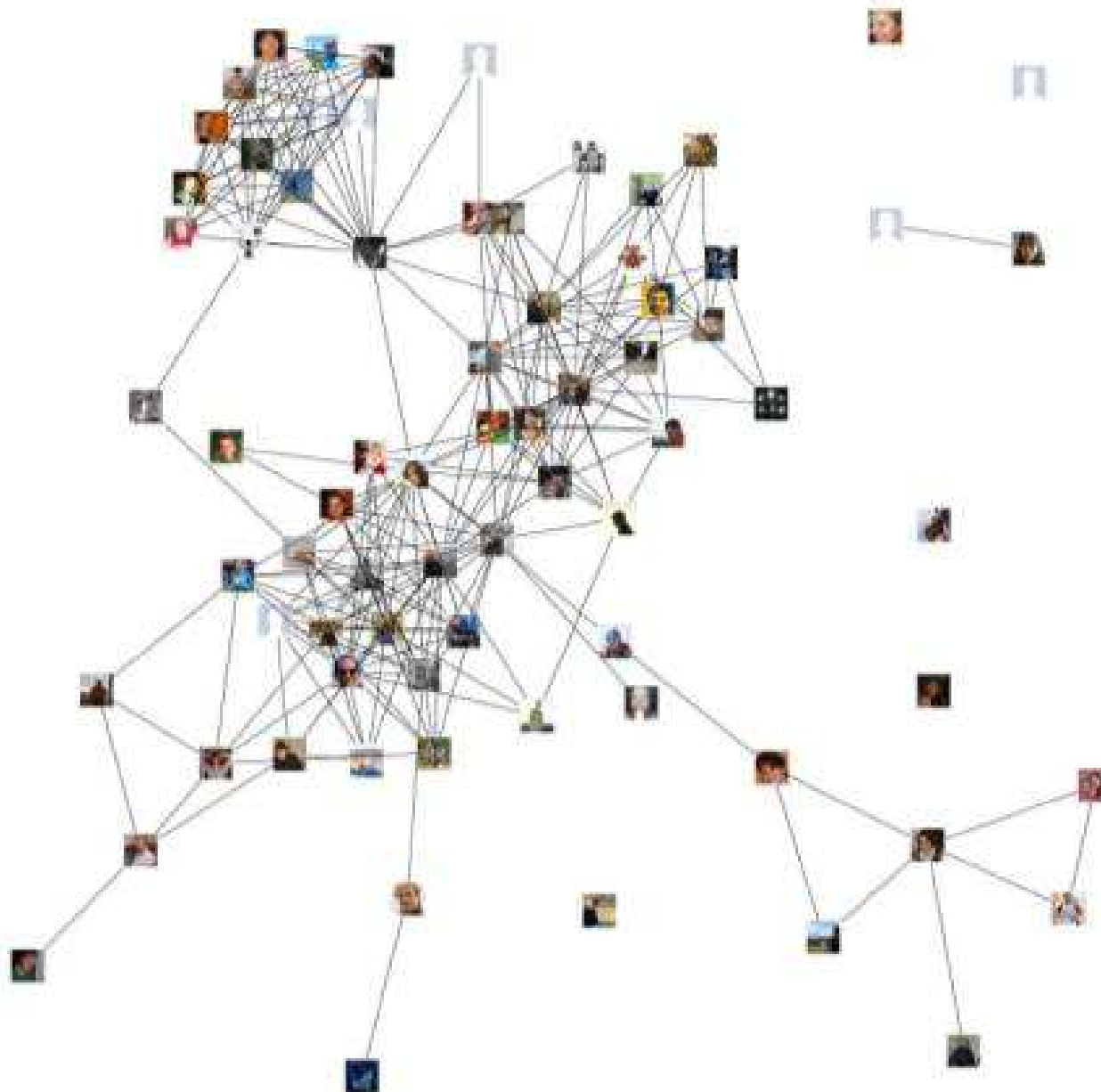
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Jean-Baptiste Durand

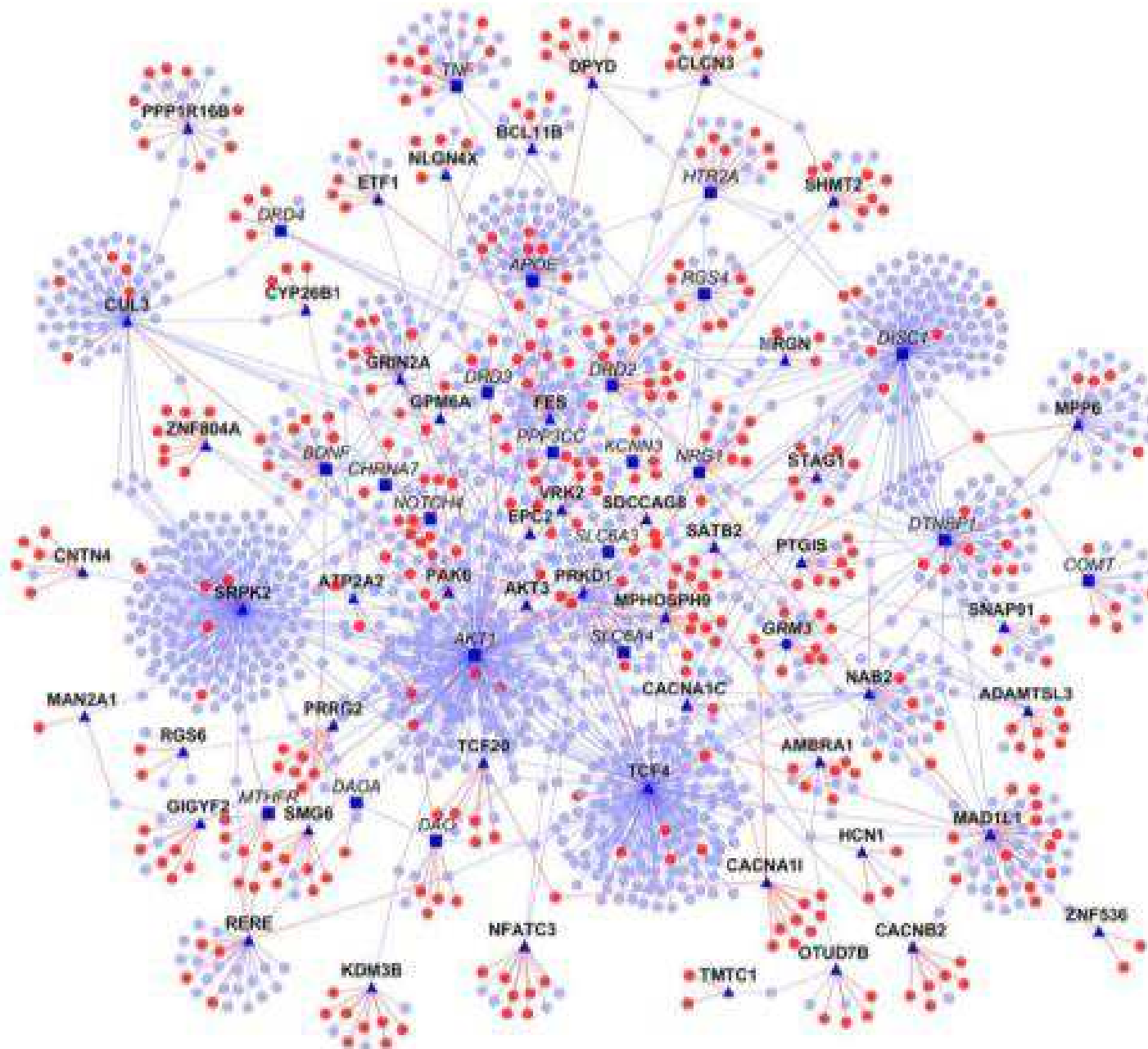
Credits: Charlotte Laclau

Community detection  $\equiv$  clustering of graph vertices

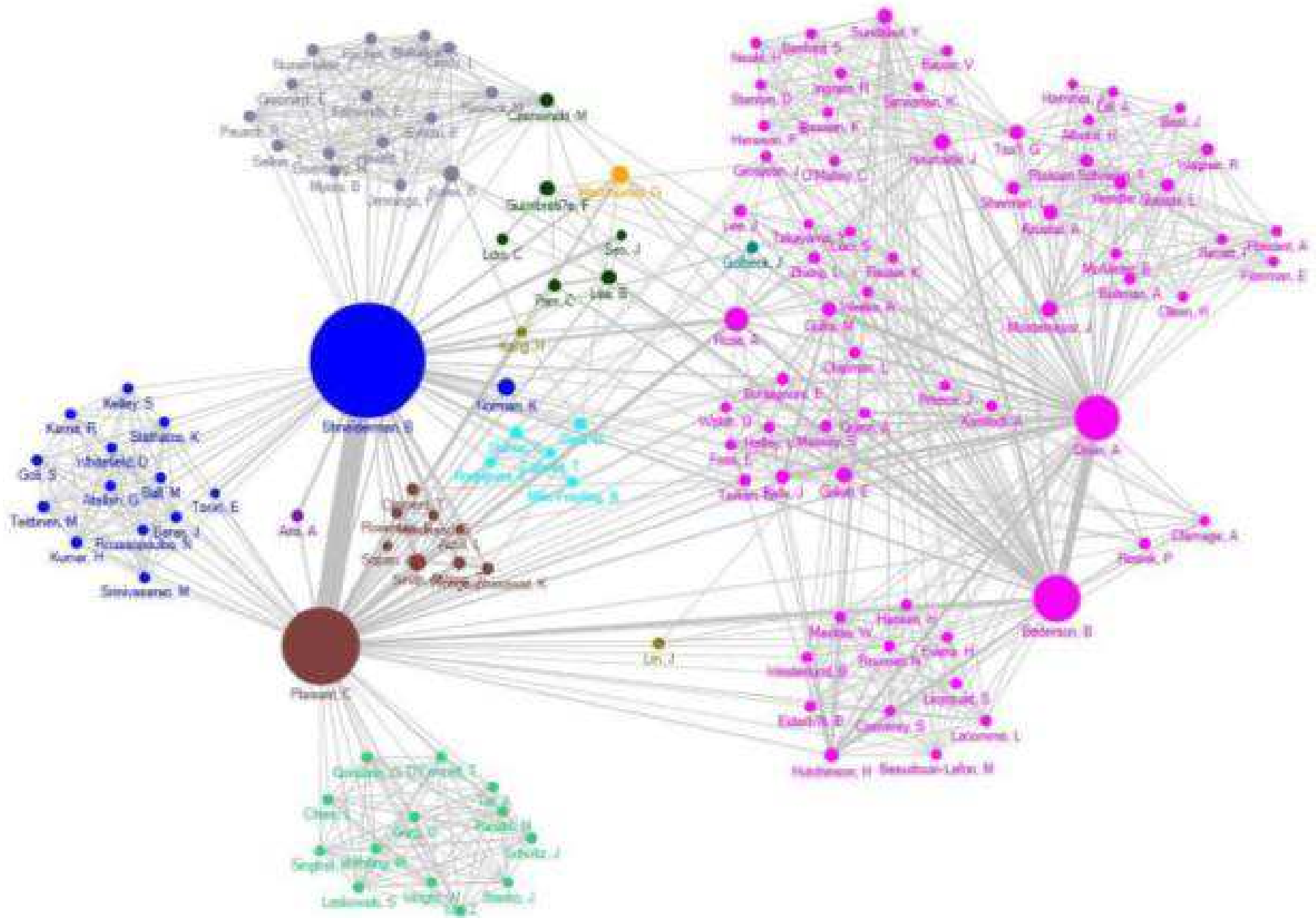
## Example 1 : Facebook network



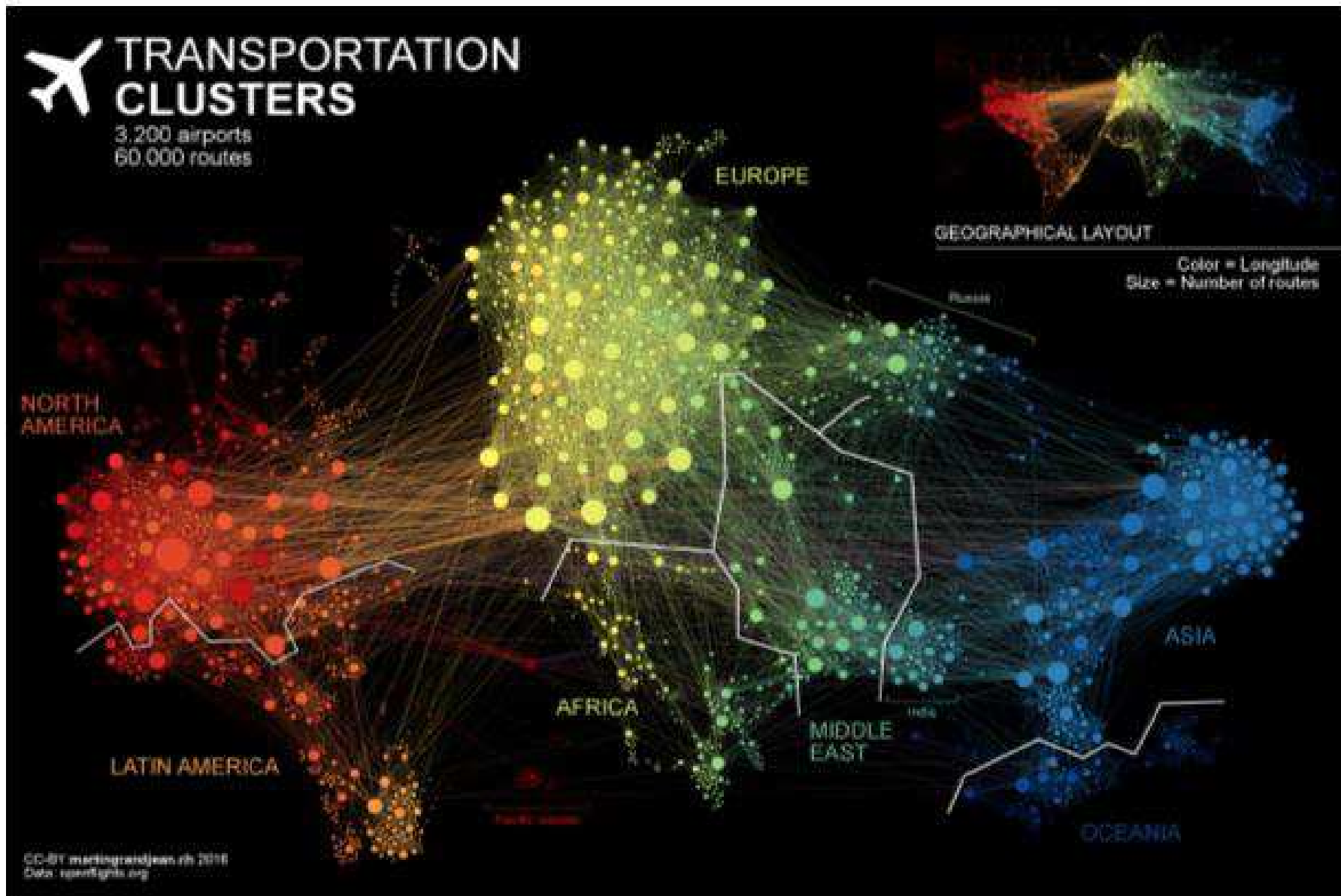
## Example 2: protein-protein interaction network



## Example 3: co-authors network

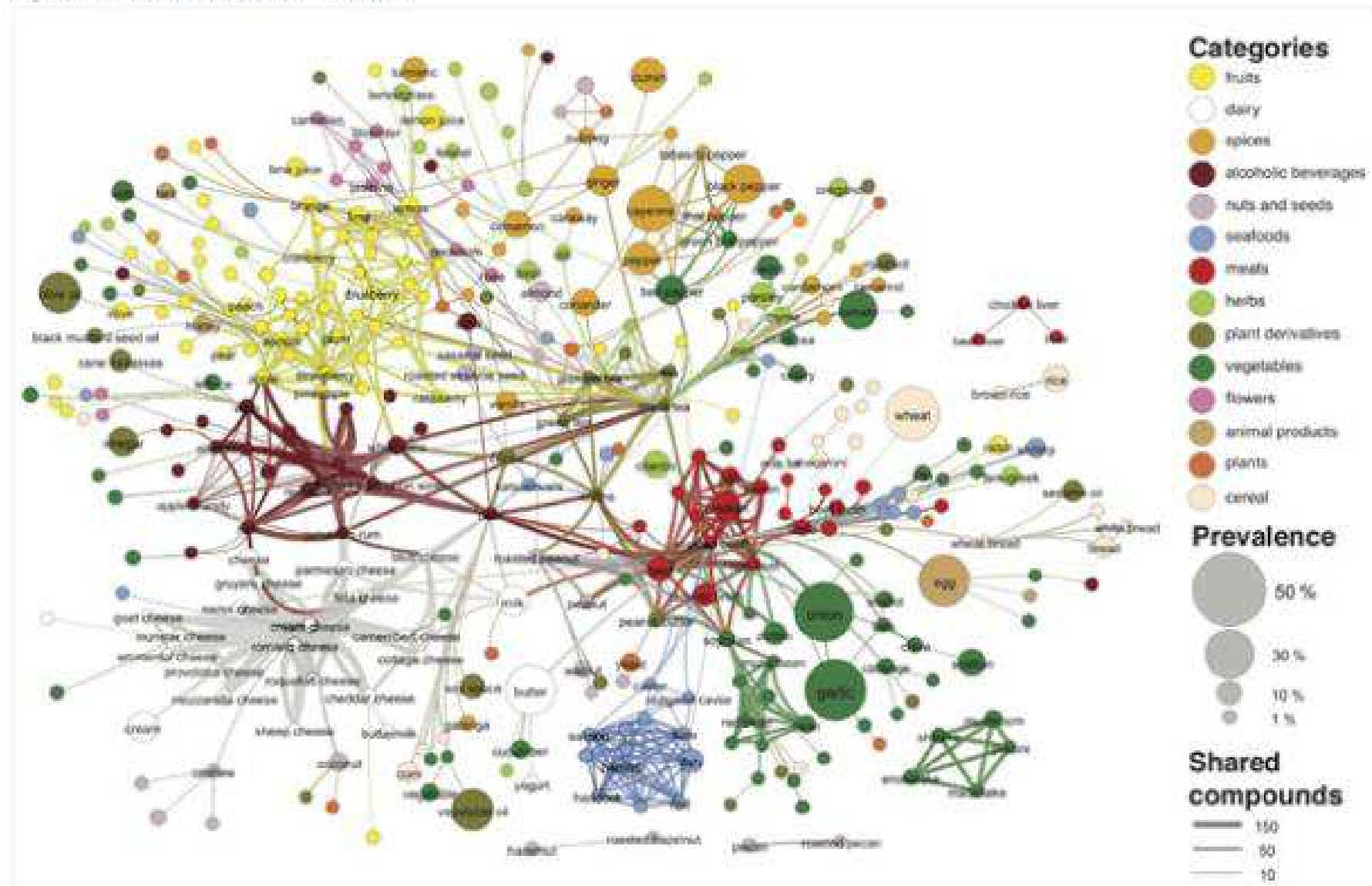


## Example 4: International Airport Traffic



# Example 5: The Flavor Network

Figure 2: The backbone of the flavor network.



Which ingredients would go well together?

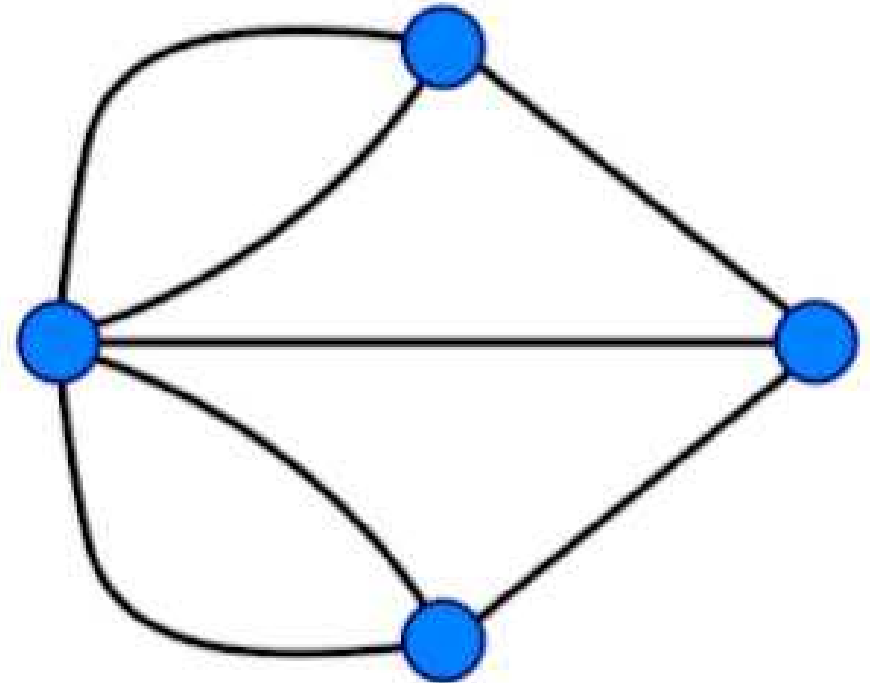
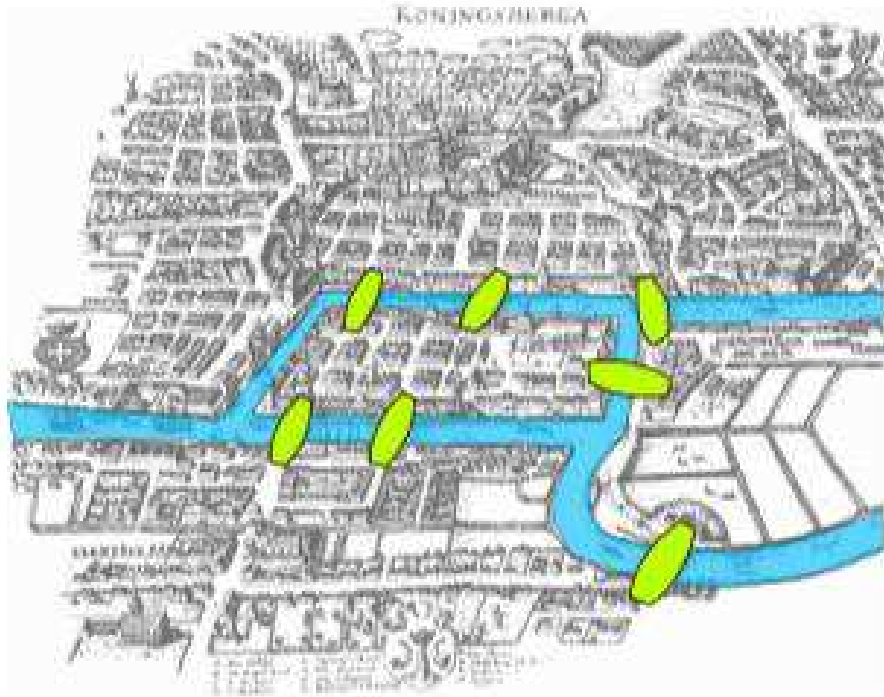
# Graphs Basics

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# The Graph theory starts

**Context** : The town of Königsberg is built around two islands connected by a bridge, and there exists 6 other bridges to connect these two islands.

**Question** How to walk through the city that would cross each bridge once and only once ?



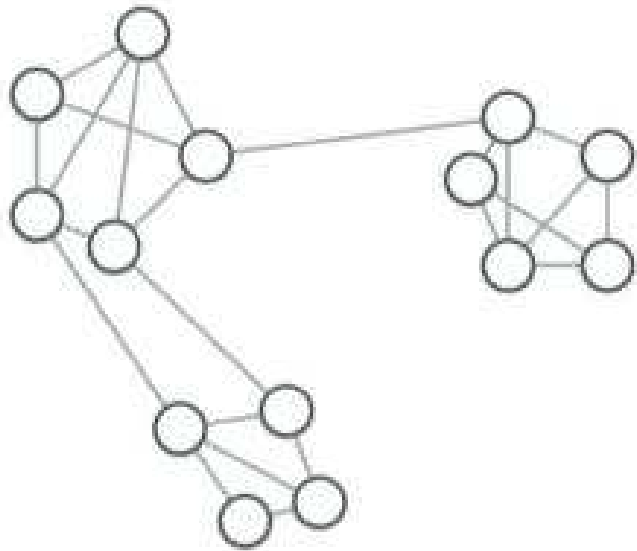


# The Graph Theory Paradigms

A graph is denoted by  $G = (V, E)$ , where

- $V$  is the finite set of **vertices** (nodes)
- $E$  is the finite set of **edges** (arcs)

example:  $\{a, b\}$  is the edge connecting vertices  $a$  and  $b$



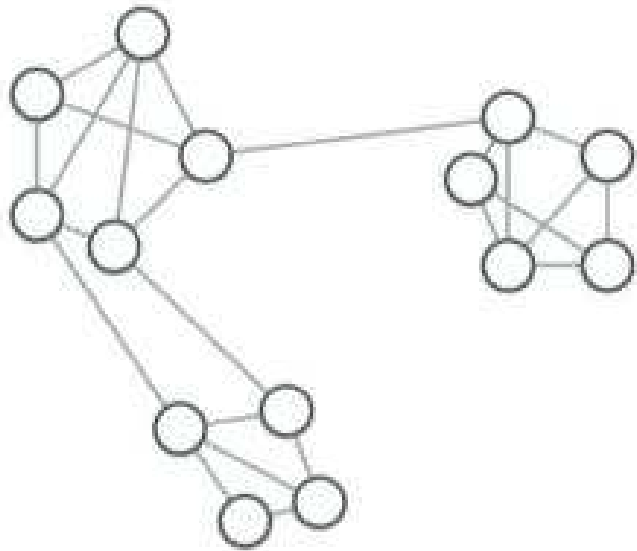
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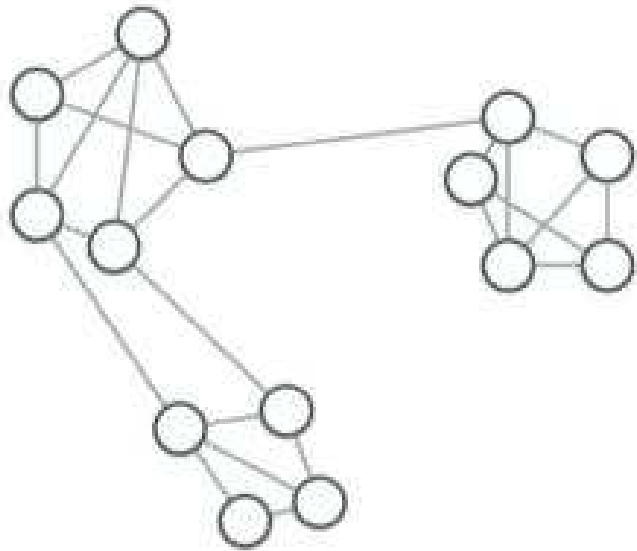
$$|V| = 14 \text{ and } |E| = 23$$

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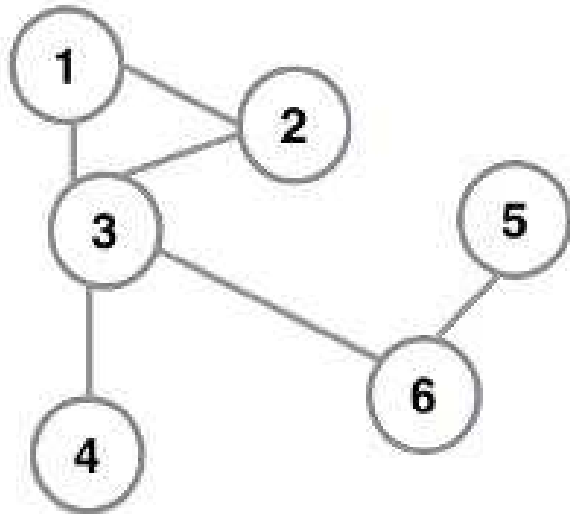


- What is the number of nodes?
- How many edges do we have here?  
 $|V| = 14$  and  $|E| = 23$
- $|V| = n$  is called the order of the graph  $G$
- $|E| = m$  is called the size of the graph  $G$
- If  $|E| = n(n - 1)/2$ , the graph is complete.

# The Adjacency Matrix

A graph can be represented by an **adjacency matrix**, that indicates the connexion between the nodes.

The adjacency matrix is a 2D array of size  $n \times n$  where  $n$  is the number of vertices in a graph.



where

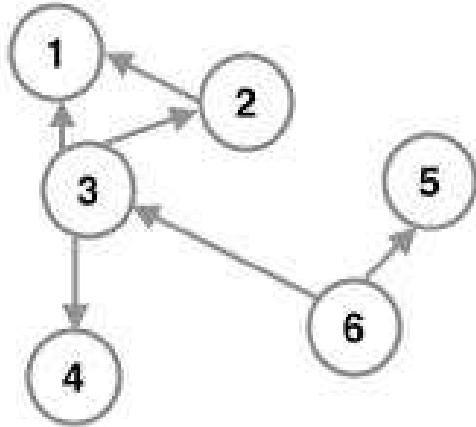
$$A = \begin{bmatrix} 0 & 1 & 1 & 0 & 0 & 0 \\ 1 & 0 & 1 & 0 & 0 & 0 \\ 1 & 1 & 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 & 1 & 0 \end{bmatrix}$$

$$a_{ij} = \begin{cases} 1 & \text{if } v_i \text{ and } v_j \text{ are connected} \\ 0 & \text{otherwise.} \end{cases}$$

NB: in this case the adjacency matrix is symmetric

# Other Types of Graphs

## Directed graphs

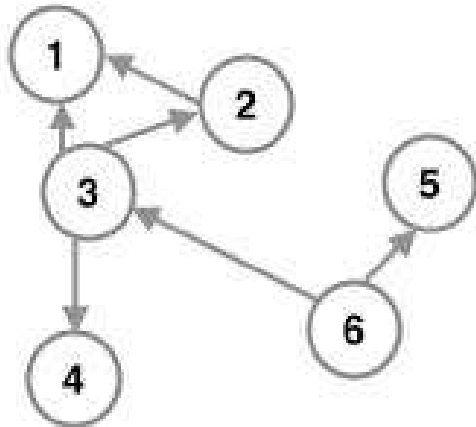


*NB: A is no more symmetric*

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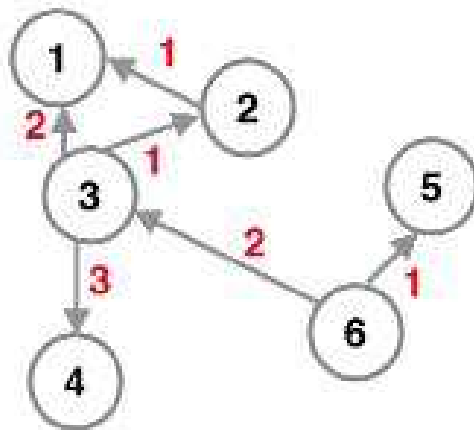
## Directed graphs



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## Weighted graphs

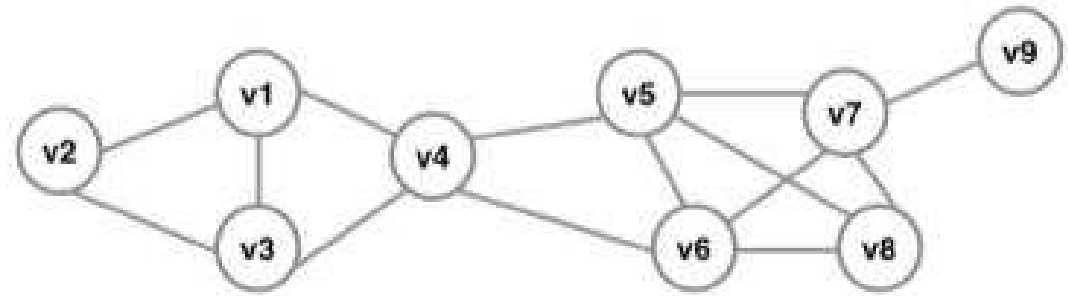


$$A = \begin{bmatrix} 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 \\ 2 & 1 & 0 & 3 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 2 & 0 & 1 & 0 \end{bmatrix}$$

$$a^{ij} = \omega(v^i, v^j) \rightarrow A = W = (w^{ij}) = (\omega(v, v))$$

# Key Notions : Definitions and Properties (1)

Consider the following  
labeled graph  $G = (V, E)$ ,  
where  $|V| = 9$  and  $|E| = 14$



**Path** : succession of vertices and edges that allow to go from one vertex to another. A path  $P = (V(P), E(P))$  is a subgraph such that

$$V(P) = \{v^{i_0}, \dots, v^{i_k}\} \text{ and } E(P) = \{\{v^{i_0}, v^{i_1}\}, \{v^{i_1}, v^{i_2}\}, \dots, \{v^{i_{k-1}}, v^{i_k}\}\}.$$

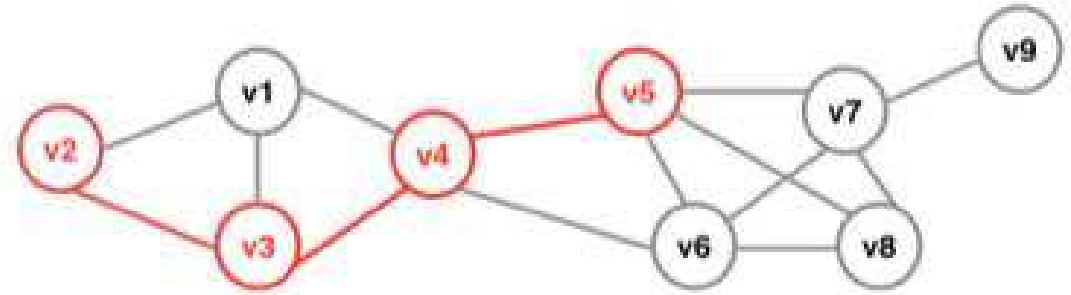
**Geodesic distance  $\delta_{ij}$**  : number of edges of the shortest path between two vertices.

Ex: from  $v_2$  to  $v_5$  several paths are possible, and there exists a shortest path where  $\delta_{ij} = 3$ .

**Connected graph** : iff  $\forall u, v$ , there is at least one path connecting  $v$  and  $u$ . Is the graph presented above connected?

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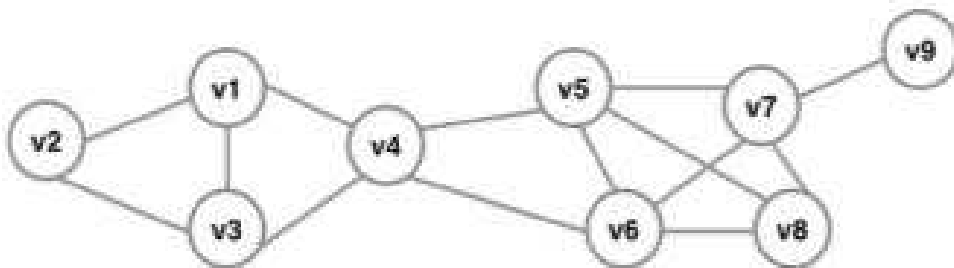
**Connected graph** : iff  $\forall u, v$ , there is at least one path connecting  $v$  and  $u$ . Is the graph presented above connected?



## Key Notions : Definitions and Properties (2)

**Density of a graph** : ratio between the number of edges observed (size)  $|E|$  and the maximum number of possible edges.

$$Density = \frac{|E|}{|V| \frac{|V|-1}{2}}$$



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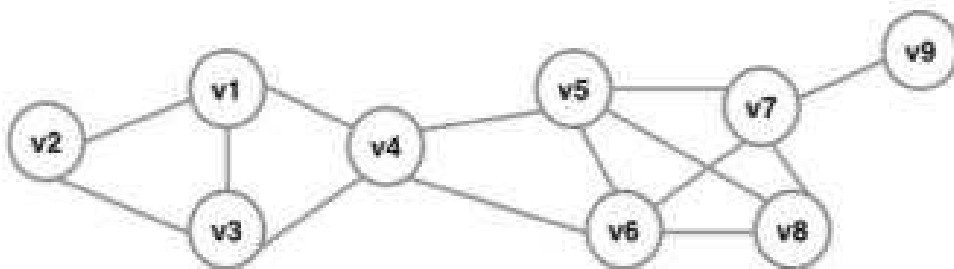
$$Density = \frac{|E|}{\frac{|V|(|V|-1)}{2}}$$

**Diameter of a graph** : The greatest geodesic distance possible between 2 vertices in the graph

**Neighborhood  $N_i$  of a node**:  $v_i$  is a subgraph of  $G$  induced by all vertices adjacent to  $v_i$ . Ex :  $N_3 = \{2, 1, 4\}$ .

**Connection strengths between two vertices**: can be evaluated from the importance of overlap between their neighborhoods. The higher the recovery, the stronger the link.

$$overlap(v_i, v_j) = \frac{|N^i \cap N^j|}{|N^i \cup N^j| - 2}$$



TO DO

1. Diameter of this graph ?
2. Strength between  $v_1$  and  $v_4$ ?  $v_5$  and  $v_4$ ? Conclusion?

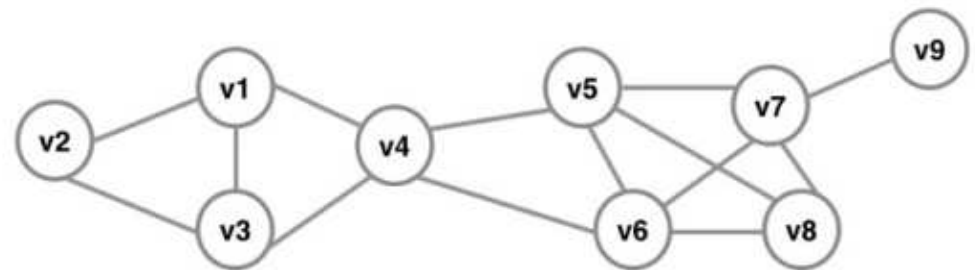
## Key Notions : Definitions and Properties (3)

**Degree centrality of a node (in terms of neighborhood)** : number of edges associated with it (number of adjacent neighbors) absolute  $C_D(v_i)$  or relative  $C_D^0(v_i)$ .

$$C_D(v_i) = d_i = \sum_j A_{ij}$$

$$C_D^0(v_i) = \frac{C_D(v_i)}{n-1}$$

Ex :  $C_D(v_3) = 3, C_D^0(v_3) : 3/8$



**Average centrality** : average distance from a given node to all the other ones.

$$C_{avg}(v_i) = \frac{1}{n-1} \sum_{j \neq i} \delta_{ij}$$

**Closeness centrality** : inverse of the average degree.

$$C_C(v_i) = \frac{1}{C_{avg}(v_i)}$$

# Community Detection

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## What is a community ?

**Community (social)** : group of people who have special ties because they have particular affinities, or have similar characteristics, or share interests.

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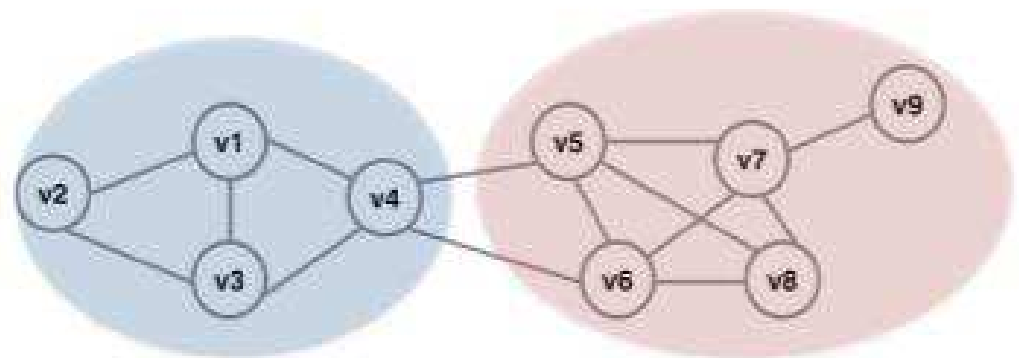
**Community (graph)** : a set nodes that are strongly linked to each other, and weakly linked with nodes outside the community.

→ implies that it must exist at least a path between two nodes of a community, and this path must be internal to the community.

**Clustering**: in the clustering framework, a community is a cluster of nodes in a graph → **there are no ground-truth labels available !**

## Challenges :

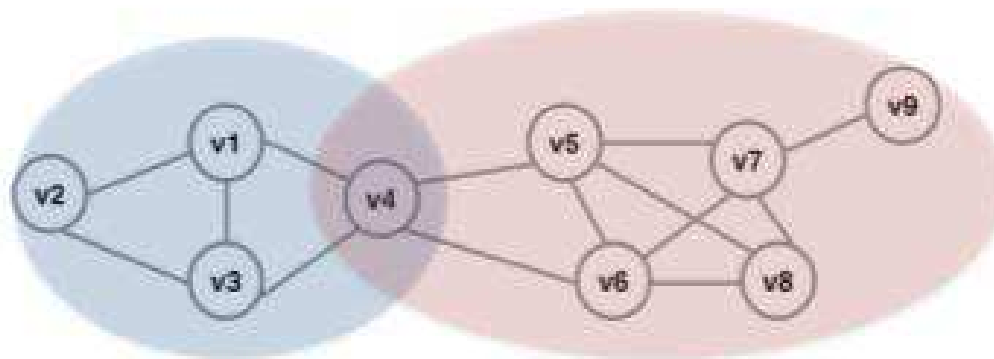
1. Define a community?
2. How many communities?
3. Evaluate the quality?



## Disjoint communities vs. overlapping communities

Just like in clustering, the partition can be crisp (disjoint communities) or fuzzy (overlapping communities).

Membership in a community is not necessarily unambiguous!



Ex: node  $v_4$  belongs to both communities, acting as an interface between both. In this case, we perceive the notion of centrality and influence.

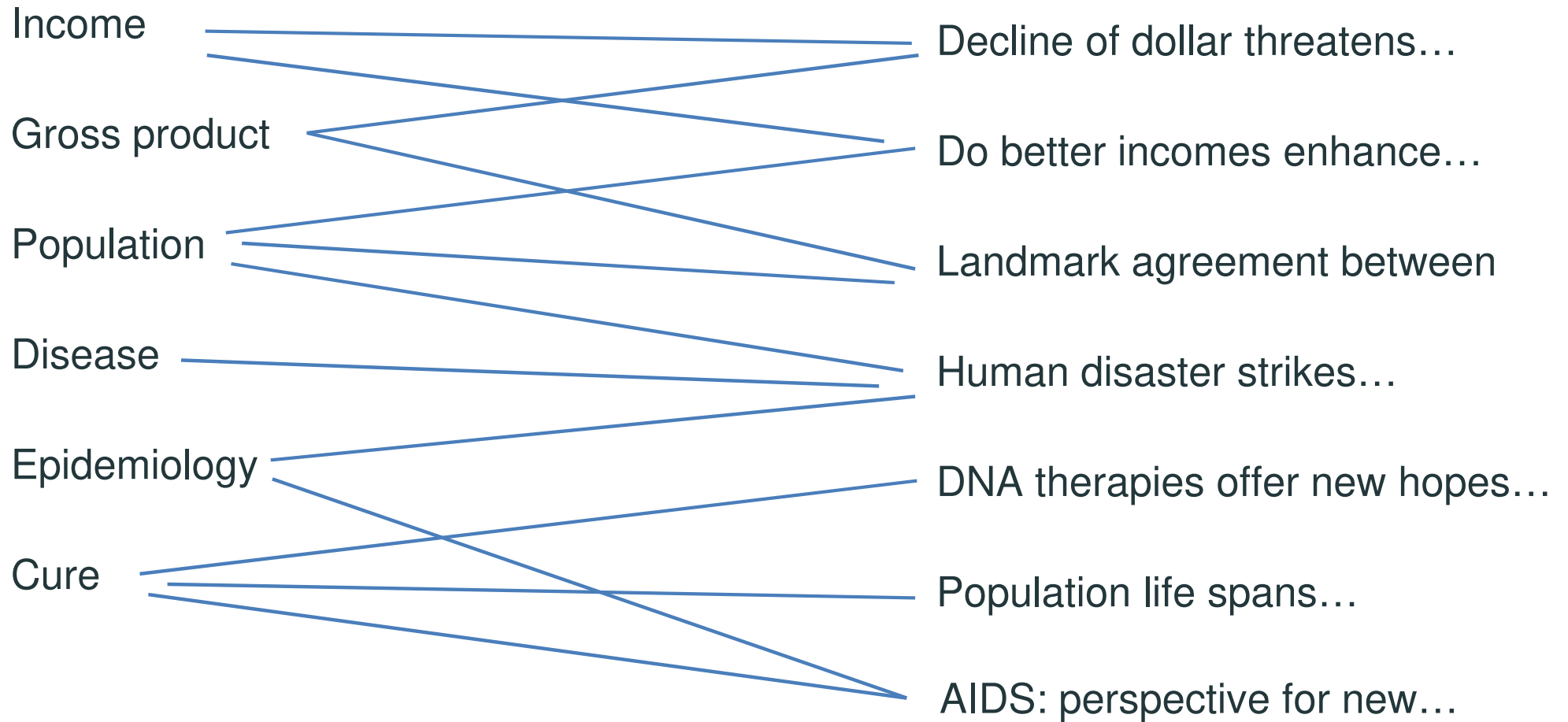
For the rest of the course, we focus only on disjoint communities.

# Possible applications to document analysis





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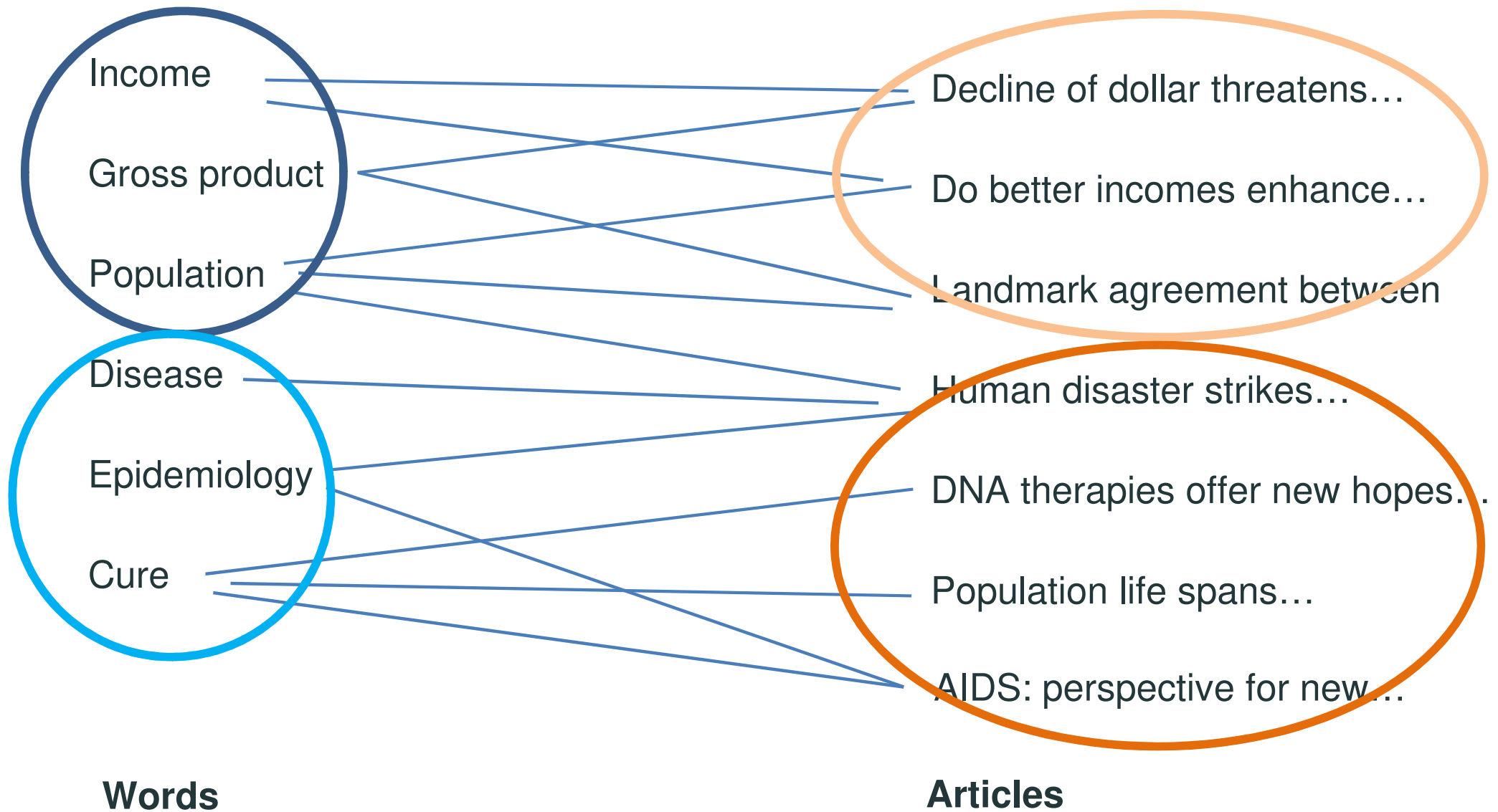


**Words**

**Articles**

Clustering of documents sharing the same words / topics (of topic / words present in the same documents)

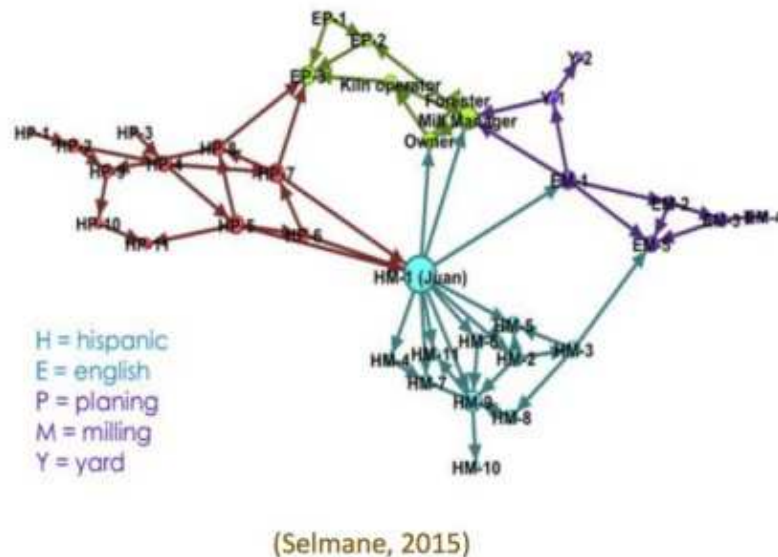
# Possible applications to document analysis



Clustering of documents sharing the same words / topics (of topic / words present in the same documents)

# Interest of community detection - an example

## The example of the sawmill network (Michael and Massey, 1997)



The employees were from different ethnic groups ( $E$ ,  $H$ ), and assigned to different tasks ( $P$ ,  $M$ ,  $Y$ ).

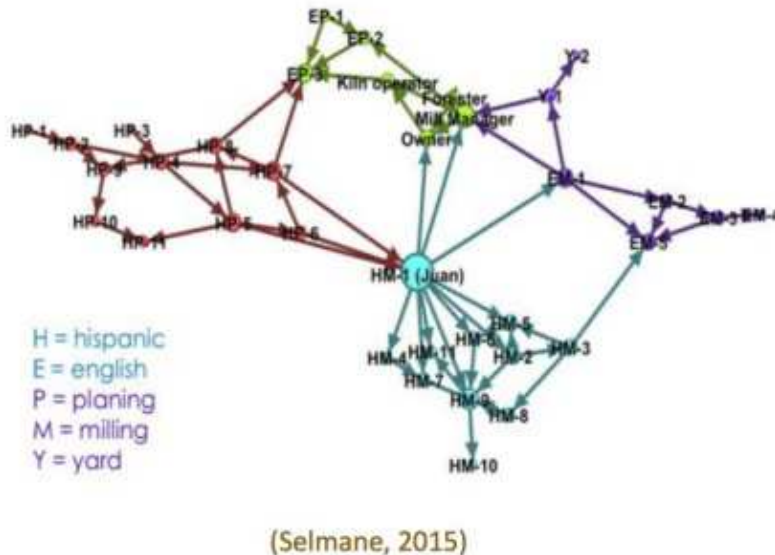
When a change of organization was proposed, strong opposition emerged.



A communications map, based on the frequency of discussions between employees was produced.

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When a change of organization was proposed, strong opposition emerged.



A communications map, based on the frequency of discussions between employees was produced.

Juan was playing a central role in the network. To make the changes, they persuaded him first, and then the acceptance just spread to others later.

# Modularity [Newman and Girvan]

**Modularity** is a frequently used quality function.

**Idea:** a random graph is not expected to have a community structure

→ compare the actual density of edges in a subgraph and a random subgraph

**Modularity:** difference between the number of connections observed and the theoretical number (expected) obtained if the connections were distributed randomly<sup>(1)</sup> between the nodes. For a given community  $k$

$$Q(k) = \sum_{i,j \in k} A_{ij} - \frac{d_i d_j}{2m},$$

where  $m$  is the number of observed connections,  $d_i$  and  $d_j$  are the centrality degrees of vertices  $v_i$  and  $v_j$ , respectively.

Modularity of the network  
after the partitioning into  $K$   
clusters

$$Q = \frac{1}{2m} \sum_{k=1}^K \sum_{i,j \in k} \left( A_{ij} - \frac{d_i d_j}{2m} \right)$$

→ The greater the modularity, the better the partition

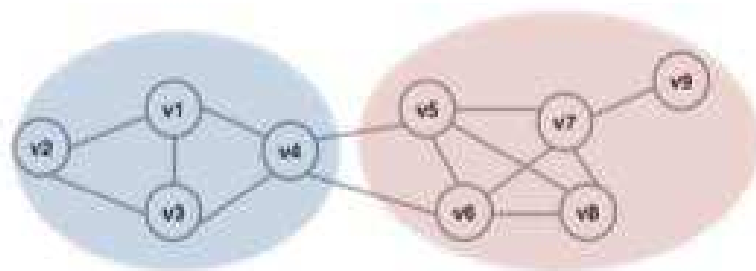
# Modularity - the matrix formulation

One can write the modularity as follows

$$Q = \frac{1}{2m} \text{Tr}(S^T B S),$$

where

- $S$  is a  $(n \times K)$  indicator matrix associating each node to one of the community
- $B$  is the  $(n \times n)$  modularity matrix, i.e.  $B_{ij} = A_{ij} - \frac{d_i d_j}{2m}$ .



$$S = \begin{bmatrix} 1 & 0 \\ 1 & 0 \\ 1 & 0 \\ 1 & 0 \\ 0 & 1 \\ 0 & 1 \\ 0 & 1 \\ 0 & 1 \\ 0 & 1 \end{bmatrix}$$

$$Q \approx 0.35$$

The modularity can be used to compare partitions obtained with different algorithms and/or to detect the number of communities.

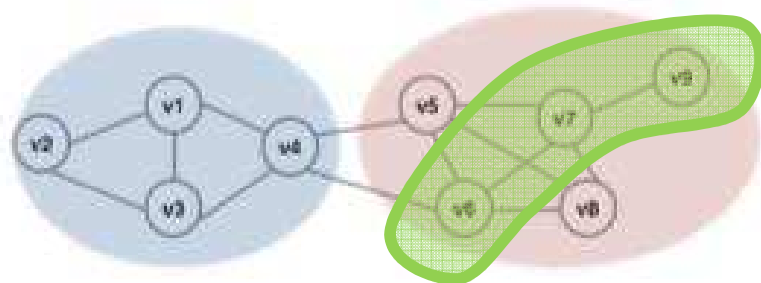
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$$Q \approx 0.06$$

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Graphs Basics

Community Detection

Agglomerative Hierarchical Algorithms

Divisive Hierarchical Algorithms - Betweenness

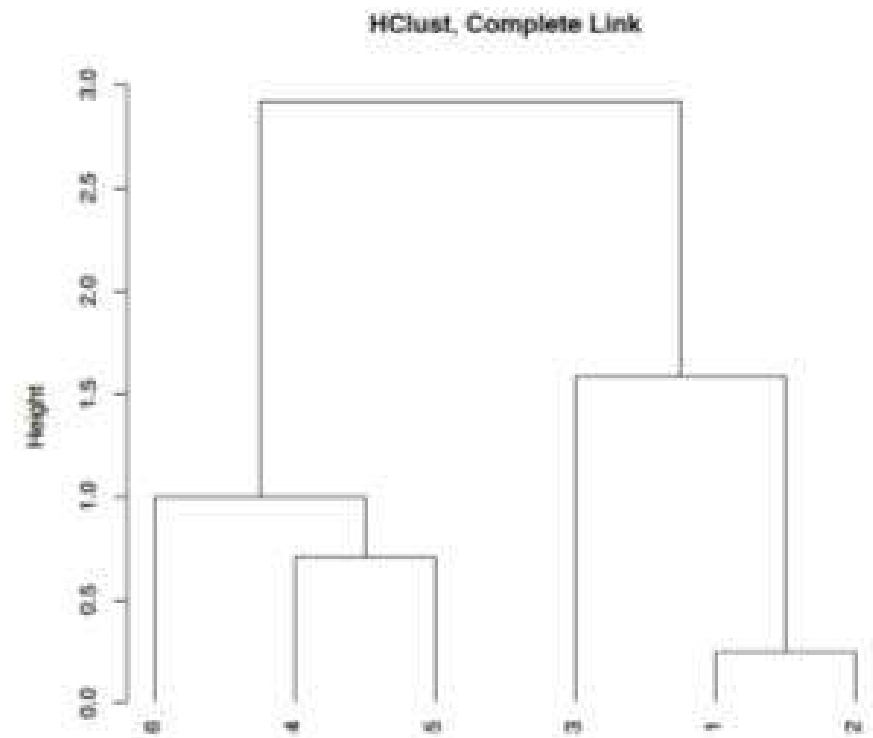
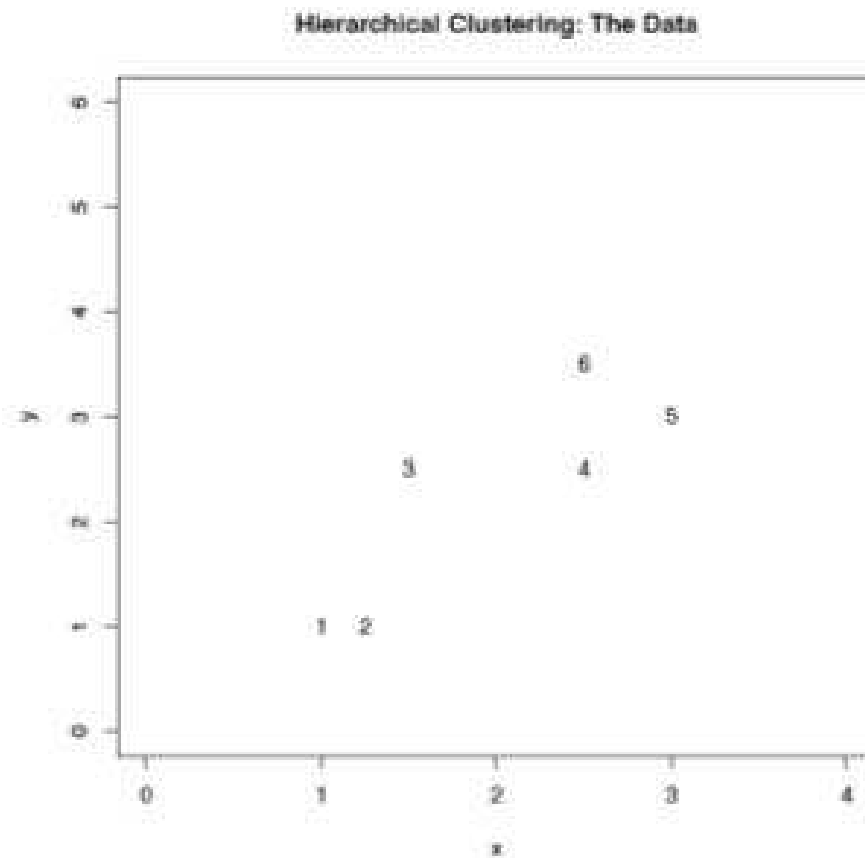
The Louvain algorithm

Spectral Community Detection



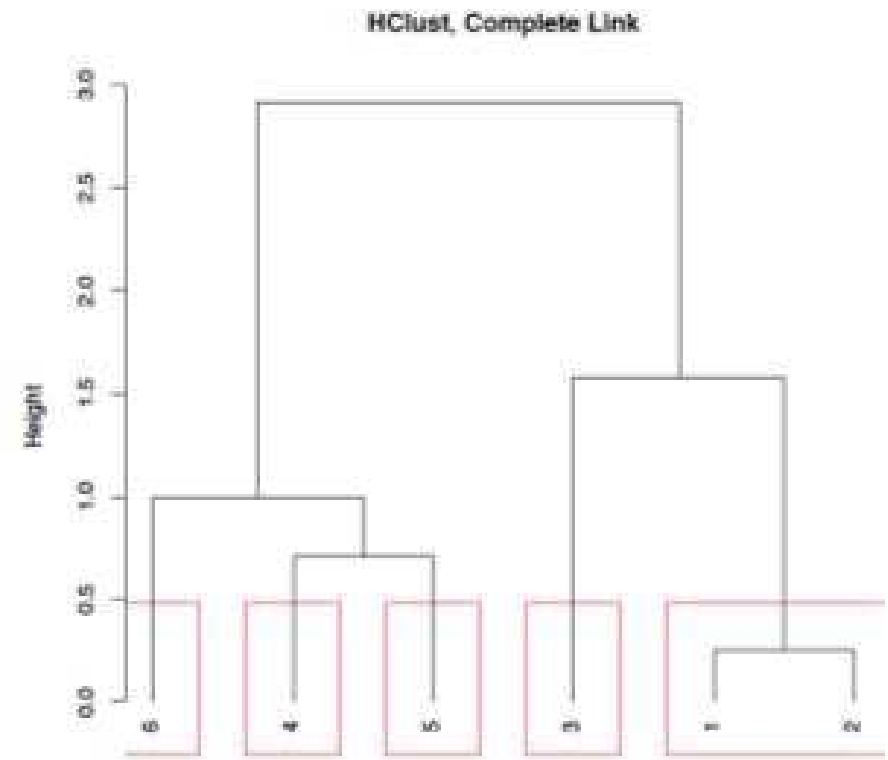
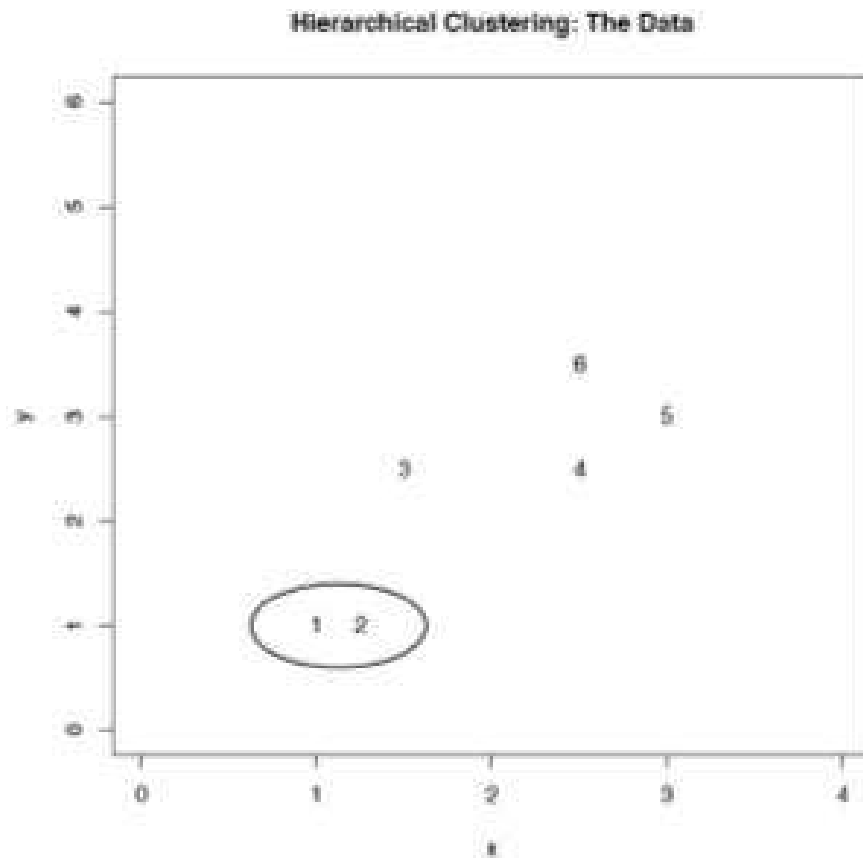
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At the starting point, the  $n$  objects to cluster are their own classes, then at each stage we merge the two most similar clusters.



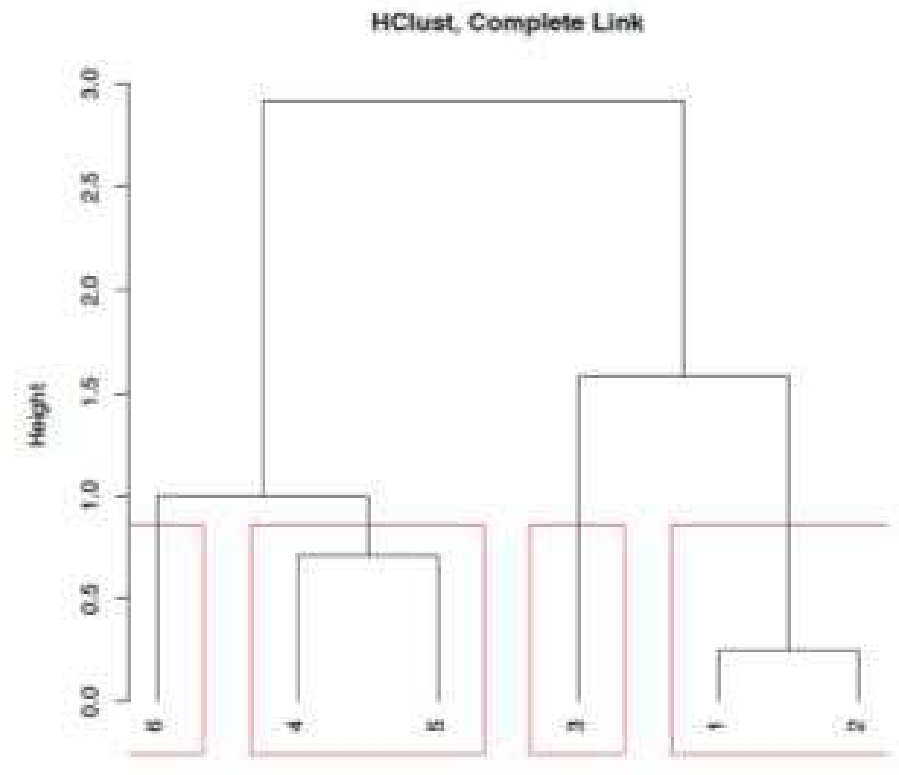
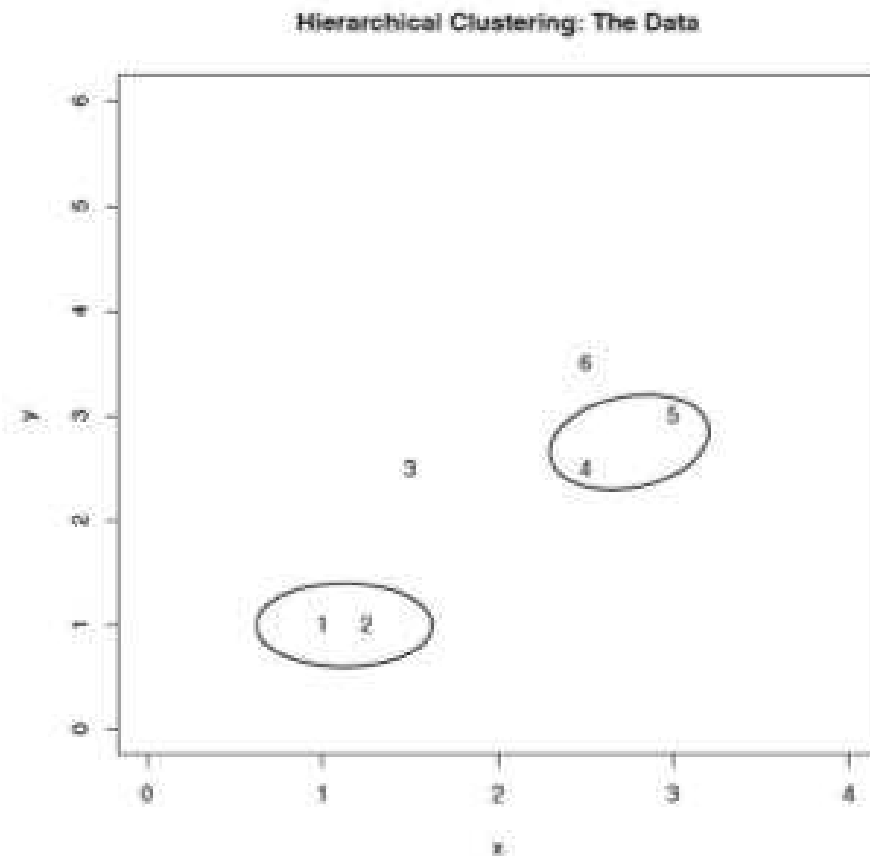
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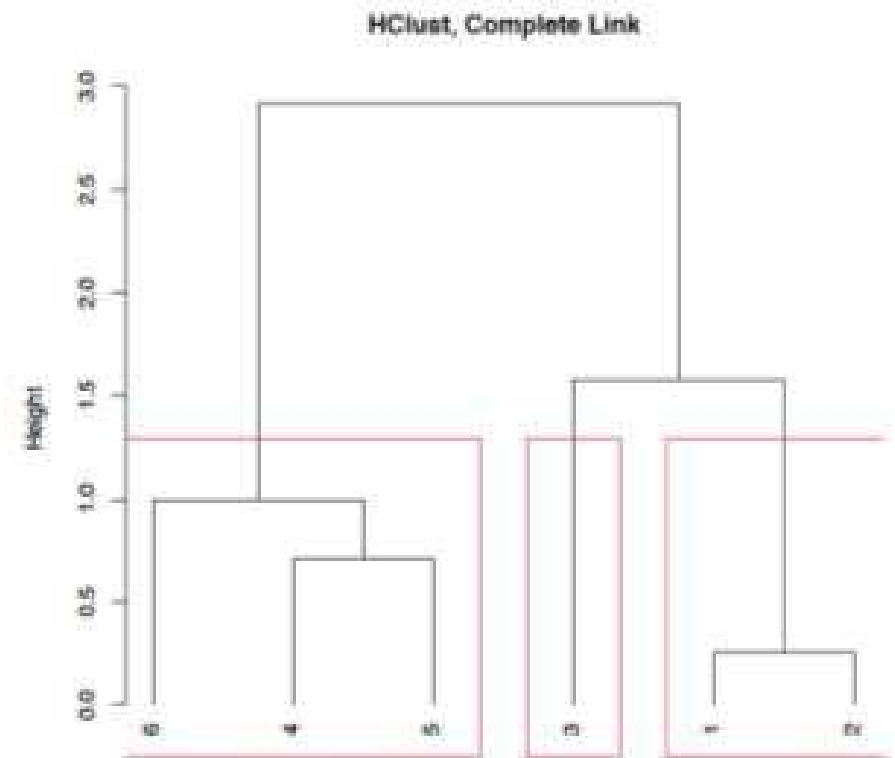
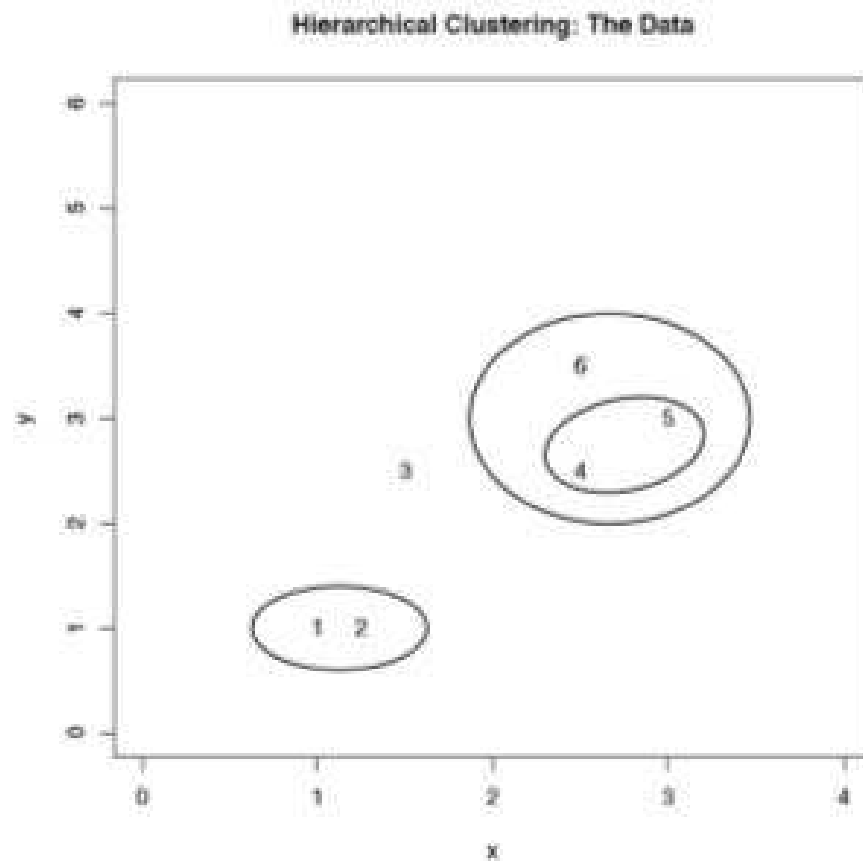
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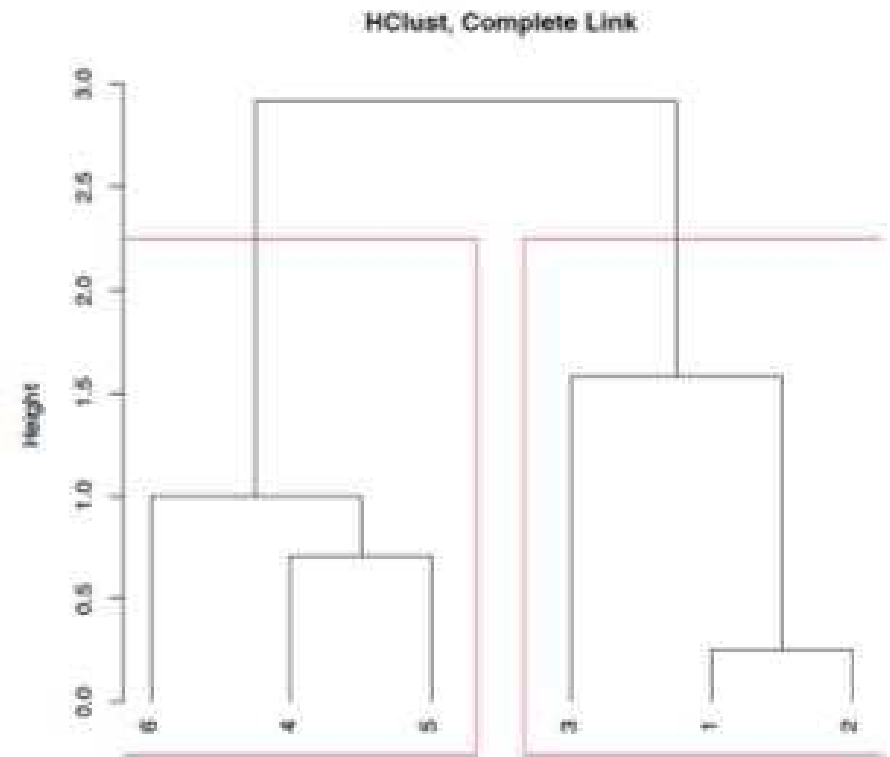
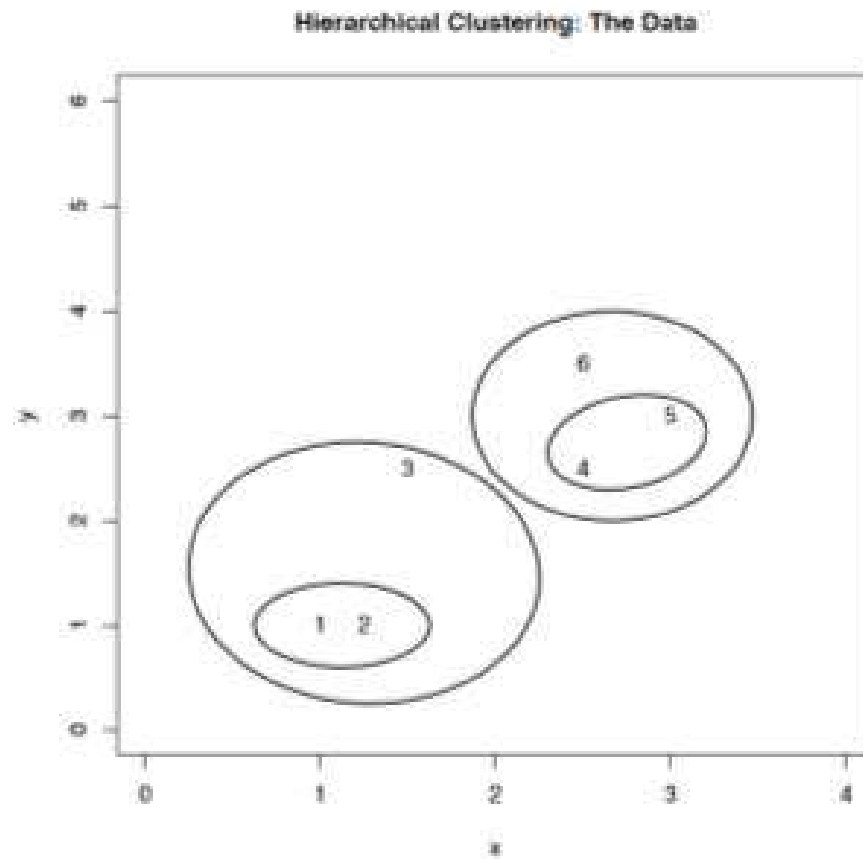
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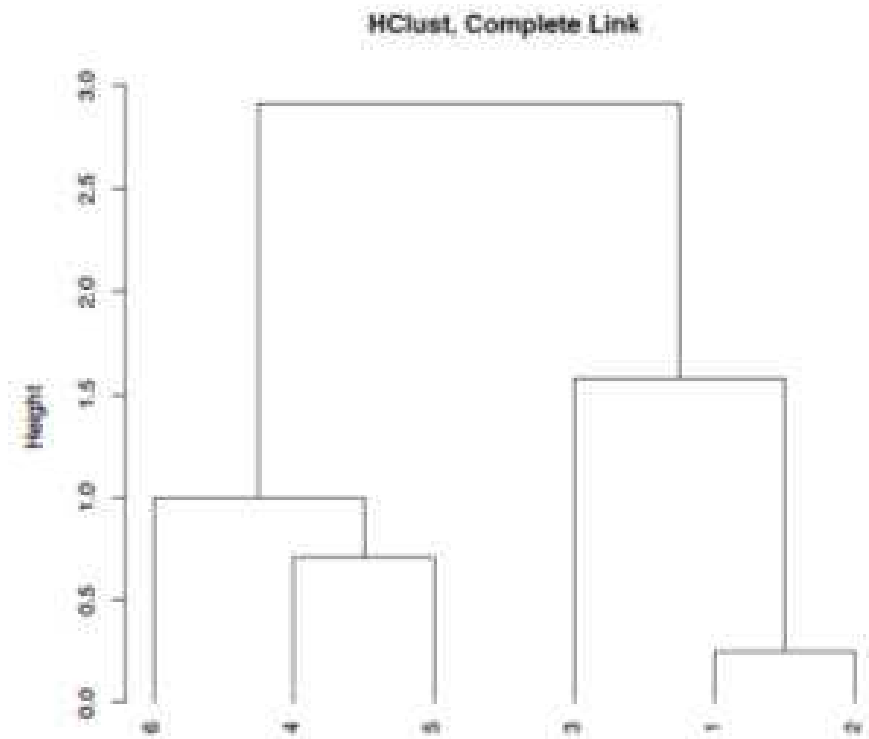
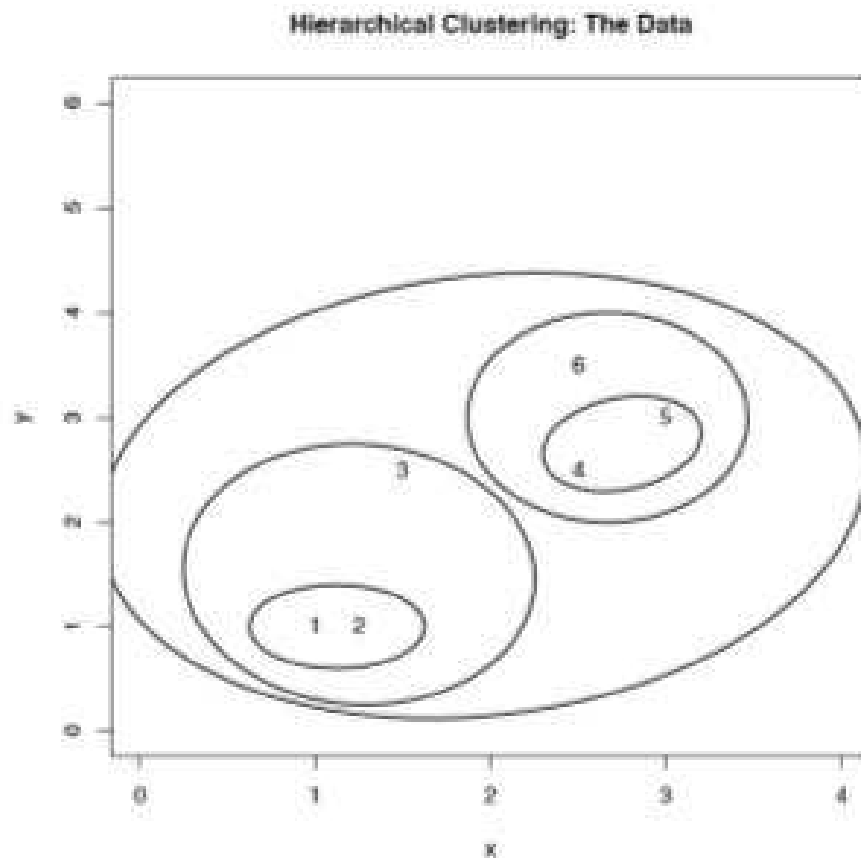
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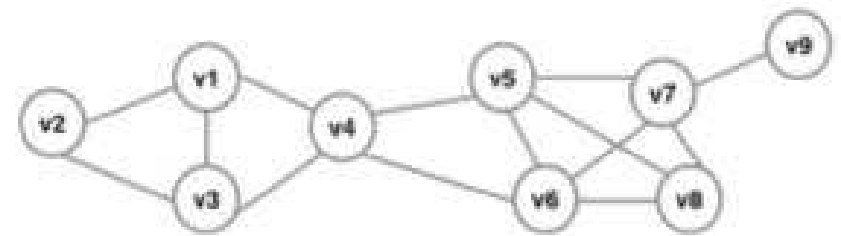
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# Agglomerative Hierarchical Algorithms - the distance / similarity measures

**Similarity:** in graph theory, the similarity is defined in terms of neighbourhood. Two nodes are close if there is a high overlapping between their neighborhoods.

Example of indices / distance



- The Jaccard index

$$Jaccard(v_i, v_j) = \frac{|N^i \cap N^j|}{|N^i \cup N^j|}$$

$$0 \leq Jaccard(v^i, v^j) \leq 1$$

- Cosine similarity

$$Cosine(v_i, v_j) = \frac{|N^i \cap N^j|}{\sqrt{|N^i|} \sqrt{|N^j|}}$$

$$0 \leq Cosine(v^i, v^j) \leq 1$$

- $Jaccard(v^4, v^5) = ?$
- $Cosine(v^4, v^5) = ?$
- $overlap(v^4, v^5) = 1/5$

N.B. Dissimilarity: any decreasing function of sim.

# Agglomerative Hierarchical Algorithms - the link choice

For a given dissimilarity measure  $dis$  between two nodes, several dissimilarities between clusters  $D$  exist:

- the single linkage :

$$D(A, B) = \min\{dis(x, y) : x \in A, y \in B\}$$

- the complete linkage :

$$D(A, B) = \max\{dis(x, y) : x \in A, y \in B\}$$

- the average linkage :

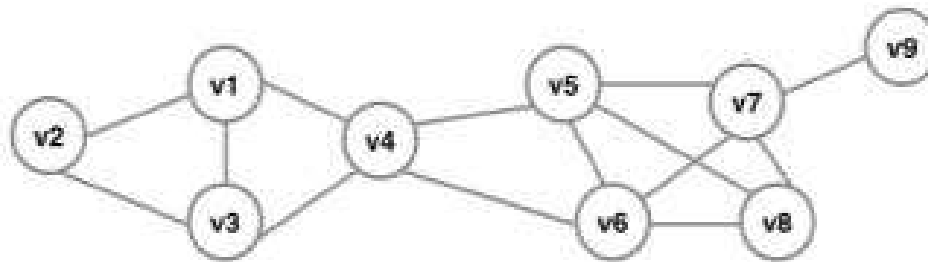
$$D(A, B) = \frac{1}{|A| \cdot |B|} \sum_{x \in A} \sum_{y \in B} dis(x, y)$$

Two main phases:

1. Initialisation of the algorithm: compute the pairwise distances between each pair of nodes
2. Iterations over the following steps :
  - Group 2 elements (nodes or groups) based on the chosen  $dis$
  - Update the pairwise distance matrix between groups

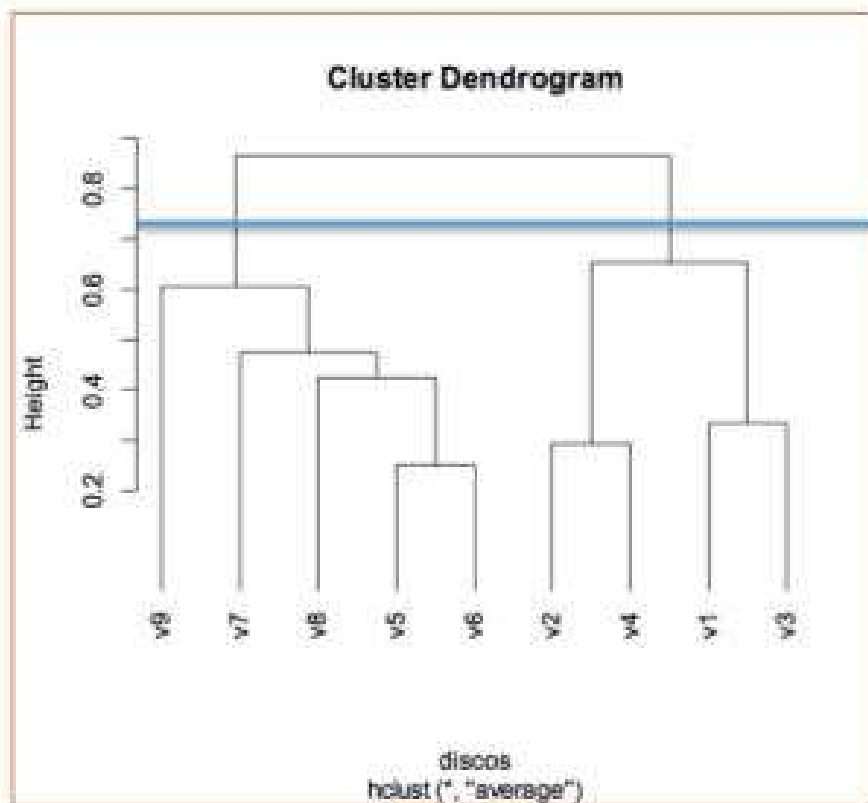


# Example



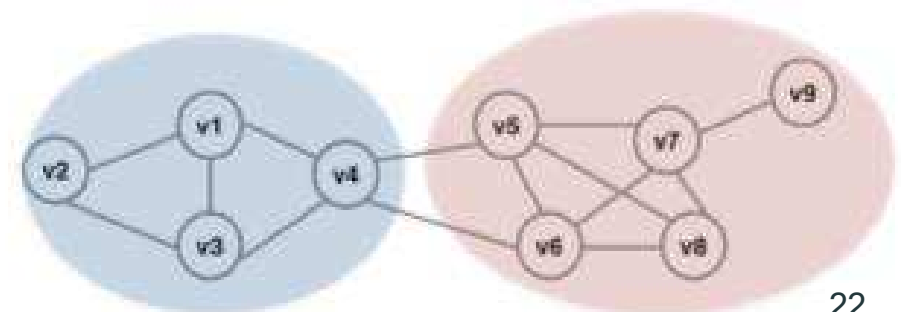
	v1	v2	v3	v4	v5	v6	v7	v8	v9
v1	1	0.408	0.667	0.289	0.289	0.289	0.000	0.000	0.000
v2	0.408	1	0.408	0.707	0.000	0.000	0.000	0.000	0.000
v3	0.667	0.408	1	0.289	0.289	0.289	0.000	0.000	0.000
v4	0.289	0.707	0.289	1	0.250	0.250	0.500	0.577	0.000
v5	0.289	0.000	0.289	0.250	1	0.750	0.500	0.577	0.500
v6	0.289	0.000	0.289	0.250	0.750	1	0.500	0.577	0.500
v7	0.000	0.000	0.000	0.500	0.500	0.500	1	0.577	0.000
v8	0.000	0.000	0.000	0.577	0.577	0.577	0.577	1	0.577
v9	0.000	0.000	0.000	0.000	0.500	0.500	0.000	0.577	1

Similarity matrix: cosine



Dissimilarity matrix: 1-cosine

TO DO: write the first two iterations of the agglomerative algorithms for the given graph with the average linkage



[Graphs Basics](#)

[Community Detection](#)

[Agglomerative Hierarchical Algorithms](#)

[Divisive Hierarchical Algorithms - Betweenness](#)

[The Louvain algorithm](#)

[Spectral Community Detection](#)

# Edge betweenness

Idea : find the connecting edges to find the communities

**Edge betweenness:** indicates the frequency with which it is borrowed when one considers the shortest path between each pair of nodes.

The higher the value, the higher the connection is important because it establishes a bridge between groups of vertices.

$$eb(e) = \sum_i \sum_{j>i} \frac{\sigma_{ij}^e(e)}{\sigma_{ij}}$$

where

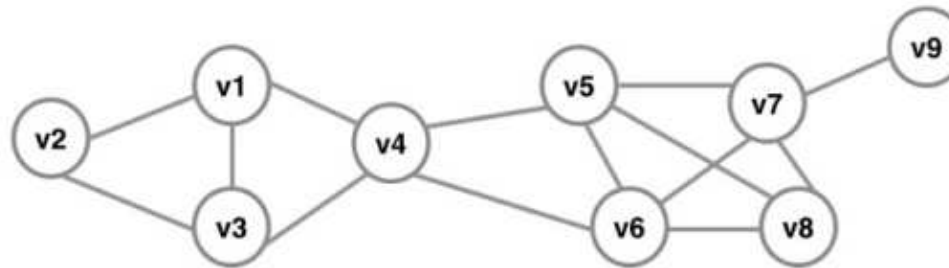
- $\sigma_{ij}^e(e)$  is number of shortest paths between nodes  $v^i$  and  $v^j$  going through  $e$ .
- $\sigma_{ij}$  is the number of shortest paths between nodes  $v^i$  and  $v^j$

# Edge betweenness

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- number of shortest paths between nodes  $v^i$  and  $v^k$  going through  $e$ .
- number of shortest paths between nodes  $v^i$  and  $v^k$
- for  $(v^i, v^k) = (v^2, v^9)$  and  $e = (v^4, v^6)$
- for  $(v^i, v^k) = (v^1, v^9)$  and  $e = (v^1, v^4)$

# Divisive algorithm [Newman and Girvan]

**Principle:** divide the graph by finding and "removing" edges connecting communities, *i.e.* edges on the maximum of shortest paths between these communities (max edge betweenness).

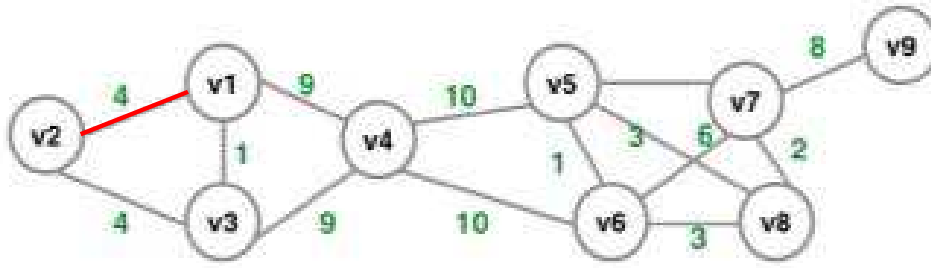
## Recursive Algorithm:

1. Compute the edge betweenness for all edges of the running graph
2. Remove the edge with the maximum  $eb$ 
  - if the removing partitions the graph then divide the graph into groups and compute the  $eb$  of the subgraphs
  - else update the  $eb$  for the graph.

Stopping criteria : graph = singleton or quality criteria (e.g. modularity)

Complexity edge betweenness on a graph can be computed in  $\mathcal{O}(nm)$  for unweighted graphs and in  $\mathcal{O}(nm + n^2 \log n)$  for weighted ones.

# Example



Computation of  $eb(e[1, 2]) = 4$  ?

$$eb(e) = \sum_i \sum_{j>i} \frac{\sigma_{ij}(e)}{\sigma_{ij}}$$

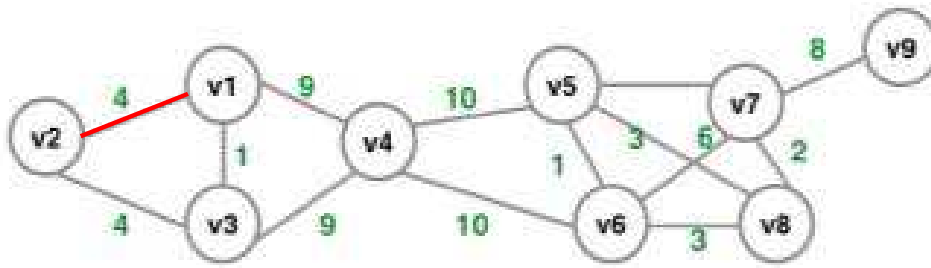
$$1 \longrightarrow (2, 3, \dots) : \frac{1}{1} + \frac{0}{1} + \frac{0}{1} + \dots = 1$$

$$2 \longrightarrow (3, 4, \dots) : 0 + \frac{1}{2} \times 6 = 3$$

$$3 \longrightarrow (4, 5, \dots) : 0$$

$$\dots : 0$$

# Example



Computation of  $eb(e[1, 2]) = 4$  ?

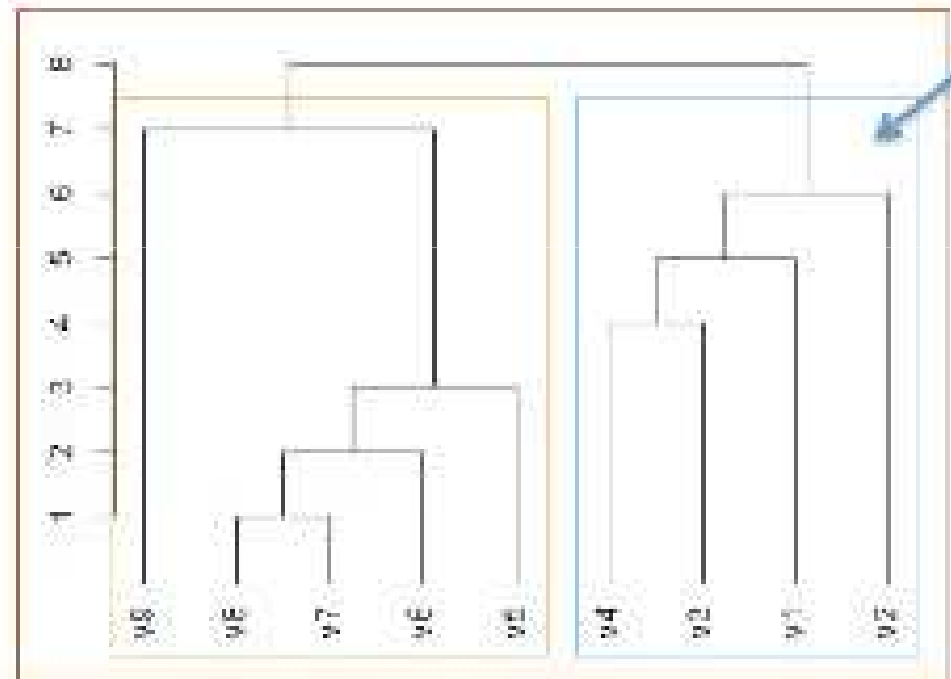
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Sequence of deleted edges

[Graphs Basics](#)

[Community Detection](#)

[Agglomerative Hierarchical Algorithms](#)

[Divisive Hierarchical Algorithms - Betweenness](#)

[The Louvain algorithm](#)

[Spectral Community Detection](#)



**Modularity** is a metric that quantifies the quality of an assignment of nodes to communities.

How much more densely connected the nodes within a community are compared to how connected they would be, on average, in a suitably defined random network?

$$Q = \frac{1}{2m} \sum_{k=1}^K \sum_{i,j \in k} \left( A_{ij} - \frac{d_i d_j}{2m} \right)$$

Idea: optimizing the modularity, i.e., finding the partitioning of  $G$  into  $K$  communities that maximizes  $\rightarrow$  **NP-hard Problem** !

**Louvain's idea**: relies on the gain in modularity  $\Delta Q$  obtained by moving some node  $i$  into a community  $k$ .

Observed complexity: generally  $O(n \log n)$

# The Louvain Algorithm

**Initialization:** create one community per node.

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## Phase 1: Community assignment

While modularity can be improved: pick a node and compute the change in modularity if it were removed from its current community and put in a connected community.

- If none of these modularity changes are positive, we keep the node in its current community
- If some of the modularity changes are positive, we move the node into the community for which the modularity change is maximum

# Change of Modularity

Phase 1 of the procedure relies on maximising wrt  $c=out$  differences

$$\Delta_{c=in,out} \frac{1}{2m} \left( 2k_{i,c} - \frac{2}{2m} k_i \Sigma_{i,c} \right)$$

where

- $c$ : community ( $i$  leaving *out* and entering *in*)
- $k_{i,c}$ : number of neighbours of  $i$  in  $c$

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Evaluates the change of modularity by removing  $i$  from its community and then by moving it into a neighbouring community.

# The Louvain Algorithm

**Initialization:** create one community per node.

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## Phase 2 : Coarse Graining

Define a new, coarse-grained network where the nodes are the communities discovered during Phase 1.

Edge weight between the nodes representing two communities = the sum of the edge weights between the lower-level nodes of each community.

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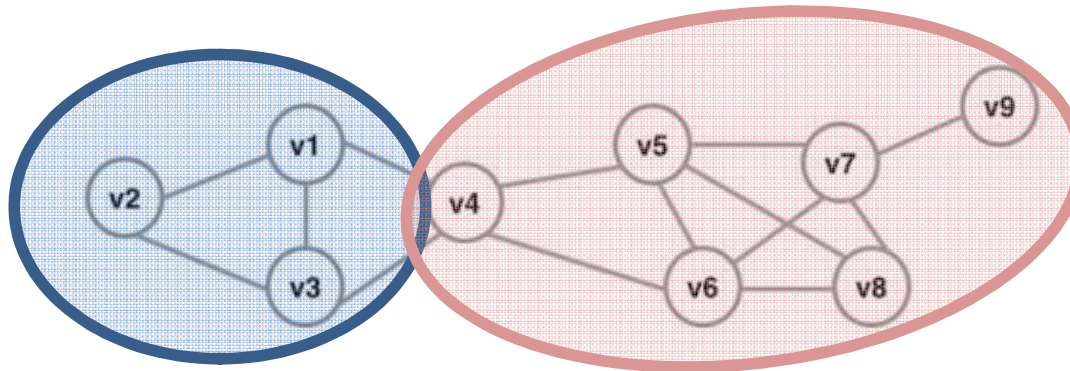
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**Repeat** these two phases until only one community remains.

# The Louvain algorithm: step

**To do:** compute the change in modularity induced by switching the community of  $v_4$ .



$$\Delta_{c=in,out} \frac{1}{2m} \left( 2k_{i,c} - \frac{2}{2m} k_i \Sigma_{i,c} \right)$$

where

- $c$ : community ( $i$  leaving *out* and entering *in*)
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[Graphs Basics](#)

[Community Detection](#)

[Agglomerative Hierarchical Algorithms](#)

[Divisive Hierarchical Algorithms - Betweenness](#)

[The Louvain algorithm](#)

[Spectral Community Detection](#)

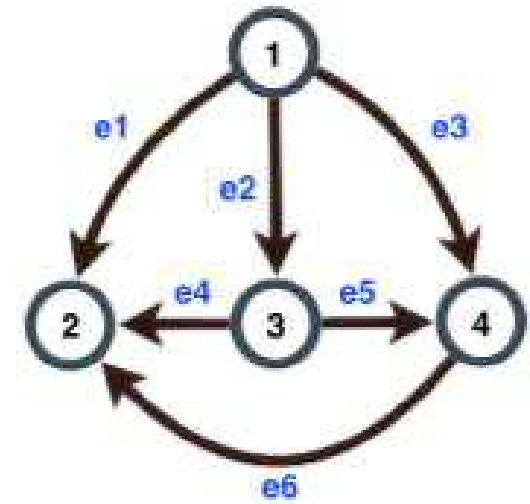
# Graph Laplacian (1)

## Incidence matrix

each row  $\rightarrow$  edge

each column  $\rightarrow$  vertex

$$C = C(G) = \begin{bmatrix} \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots \end{bmatrix}$$



# Graph Laplacian (1)

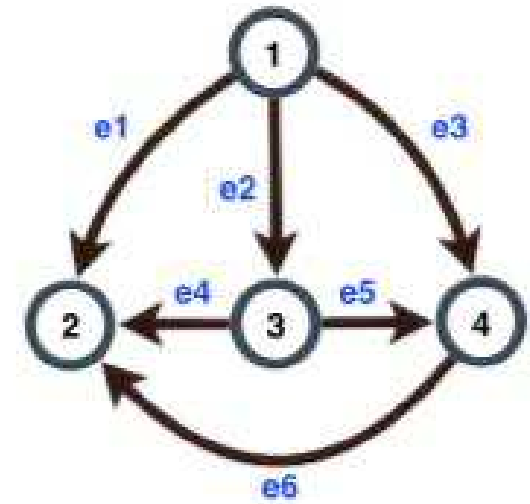
## Incidence matrix

each row  $\rightarrow$  edge

each column  $\rightarrow$  vertex    Example:  $e_1 = e(1, 2)$

$\rightarrow C(1, 1) = 1$  and  $C(1, 2) = -1$

$$C = C(G) = \begin{bmatrix} 1 & -1 & \dots & \dots \\ \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots \end{bmatrix}$$



# Graph Laplacian (1)

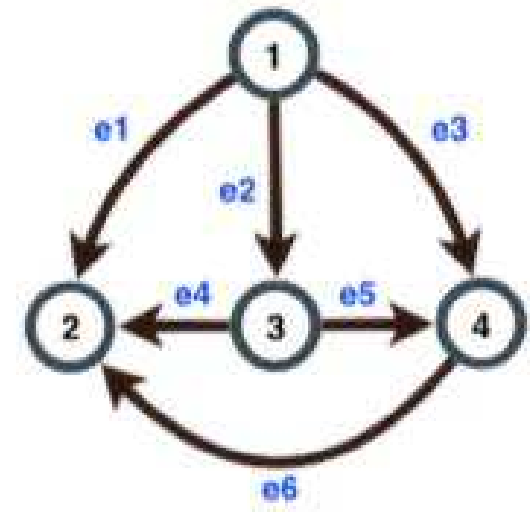
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Graph Laplacian  $L(G) = C^T C$

## Graph Laplacian (2)

Symbolically, one can write  $C$  as a sequence of its  $n$  edges

$$C = \begin{bmatrix} e_1^T \\ e_2^T \\ \cdot \\ \cdot \\ \cdot \\ e_n^T \end{bmatrix}$$

Therefore

$$C^T C = \sum_{\ell=1}^n e_{\ell}^T e_{\ell}$$

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$\text{edge}(i,j) \rightarrow e_{\ell}$ , where  $e_{\ell} = 1$  at the  $i$ -th position and  $-1$  at the  $j$ -th position

Consider  $e_{\ell} e_{\ell}^T$

- Gives a matrix with only 4 elements  $\neq 0$
- Diagonal count incident edges
- Off-diagonal: existence of an edge
- Lost the direction information

What about the sum?

## Graph Laplacian (2)

Symbolically, one can write  $C$  as a sequence of its  $n$  edges

$$C = \begin{bmatrix} e_1^T \\ e_2^T \\ \cdot \\ \cdot \\ \cdot \\ e_n^T \end{bmatrix}$$

Therefore

$$C^T C = \sum_{\ell=1}^n e_{\ell}^T e_{\ell}$$

What about the sum?

**Diagonal** counts the degree of each vertex  
→ diagonal matrix  $D$

**Off-diagonal** marks all the edges  
→ adjacency matrix  $A$

$$C^T C = \sum_{\ell=1}^n e_{\ell}^T e_{\ell} = D - A$$

where  $A$  is the adjacency matrix of the undirected graph

Frequent use of normalised graph Laplacian

$$D^{-\frac{1}{2}} L D^{-\frac{1}{2}}$$

# Graph Laplacian (3)

## Laplace matrix and heat equation on a graph

- $\phi_i$  heat at vertex  $i$ .
- transported heat from  $\phi_i$  to  $\phi_j : \rho(\phi_i - \phi_j)$
- total flux to  $i$ :

$$\frac{d\phi_i}{dt} = -\rho \sum_{j=1}^n A_{ij} (\phi_i - \phi_j)$$

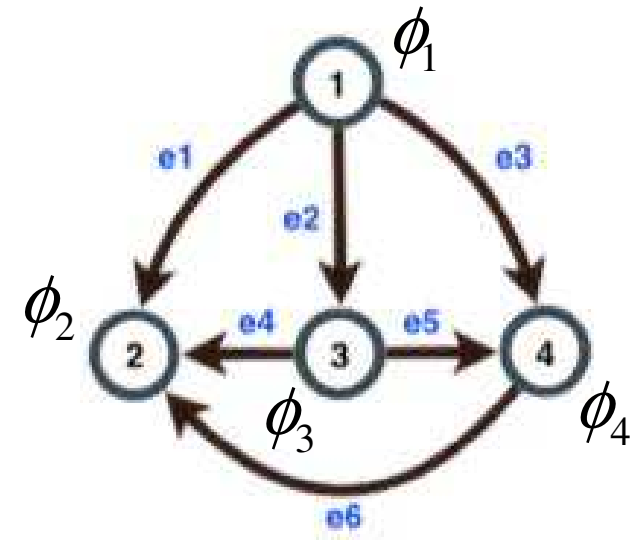
- in matrix / vector notations:

$$\frac{d\phi}{dt} = -\rho L\phi$$

- to be compared with the continuous model

$$\frac{d\phi}{dt} = \rho \nabla^2 \phi$$

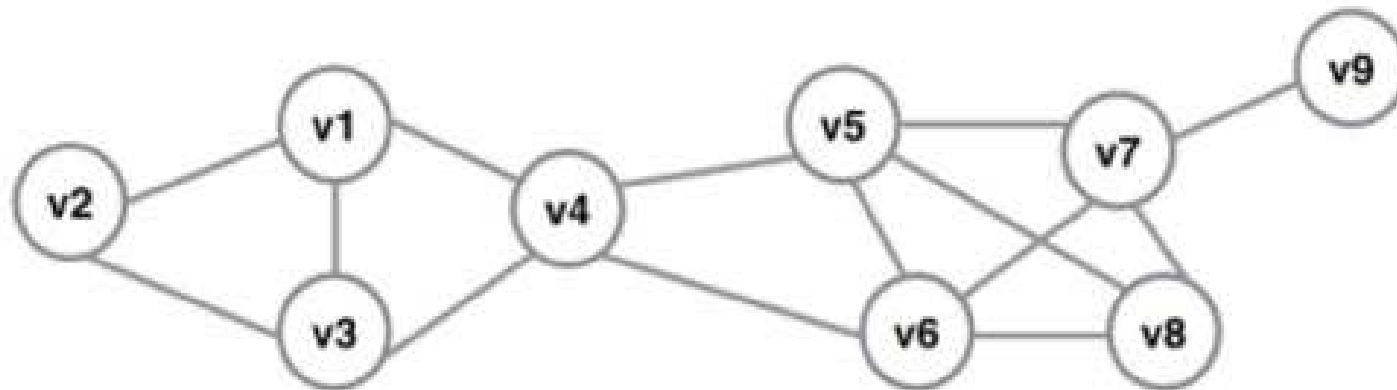
- $-L$  discrete Laplace operator





# Example

Compute the Laplacian matrix of the following example



## Properties of the Graph Laplacian

1.  $L(G)$  symmetric
2.  $L(G)$  has real-valued, non-negative eigenvalues  
and real-valued, orthogonal eigenvectors
3.  $G$  has  $K$  connected components iif

$$\lambda^1 = \lambda^2 = \dots = \lambda^K = 0 \quad (\text{Fiedler, 1973})$$

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$$\lambda^1 = \lambda^2 = \dots = \lambda^K = 0 \quad (\text{Fiedler, 1973})$$

Recall: let  $(\lambda_i, \vec{q}_i)$  be an eigenpair of  $L(G)$

$$\Rightarrow L(G)\vec{q}^i = \lambda^i \vec{q}^i$$

Can also be written in a matrix form

$$\Rightarrow L(G)Q = Q\Lambda,$$

where the columns of  $Q$  are the eigenvectors and  $\Lambda$  is a diagonal matrix whose diagonal elements are the eigenvalues

Convention:  $\lambda^n \geq \lambda^{n-1} \geq \dots \geq \lambda^1$

Let consider a graph  $G$  with a partition into two communities (+ or -)

- Let  $V_+$  be the set of vertices in +
- Let  $V_-$  be the set of vertices in -
- Let  $\vec{x}$  be a vector containing the community information

Then the number of cut edges is  $\frac{1}{4} \vec{x}^T L(G) \vec{x}$

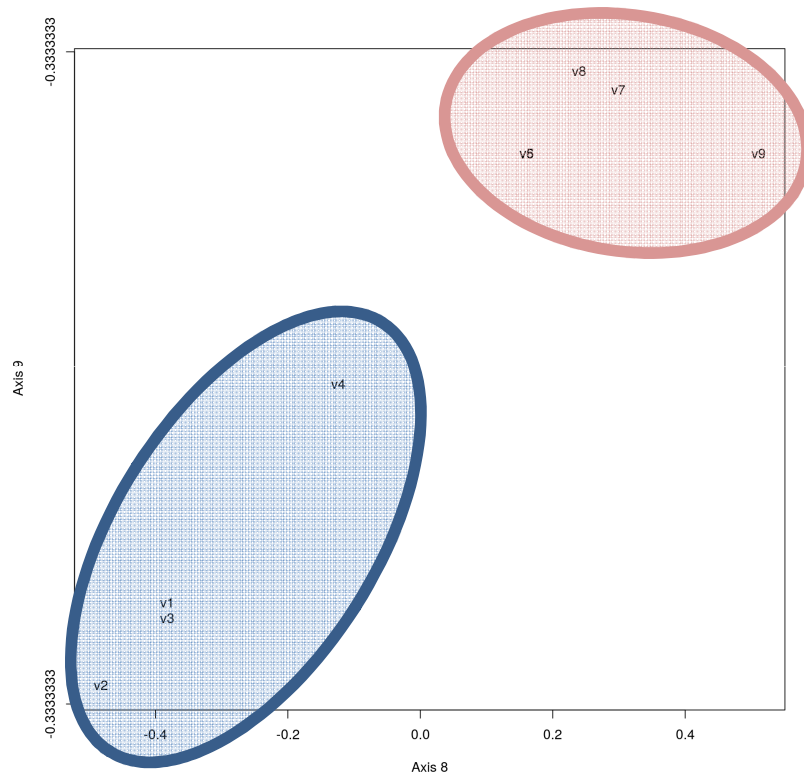
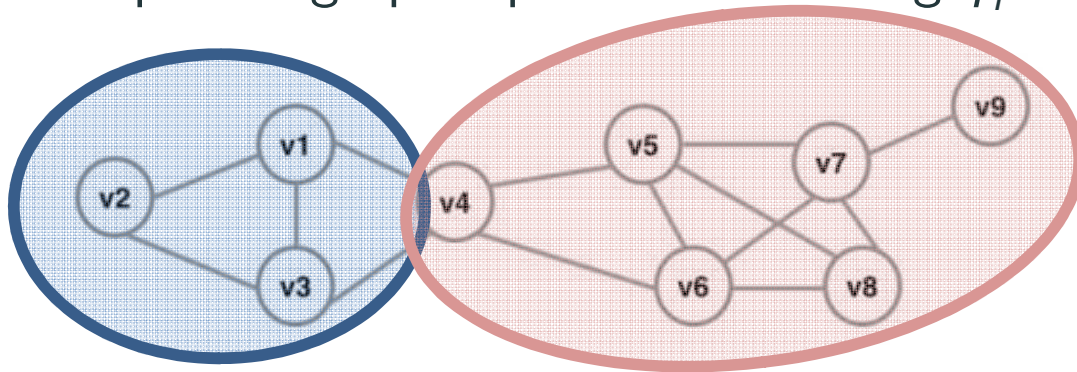
Goal: minimize the number of cut edges

### Spectral Partitionning Algorithm

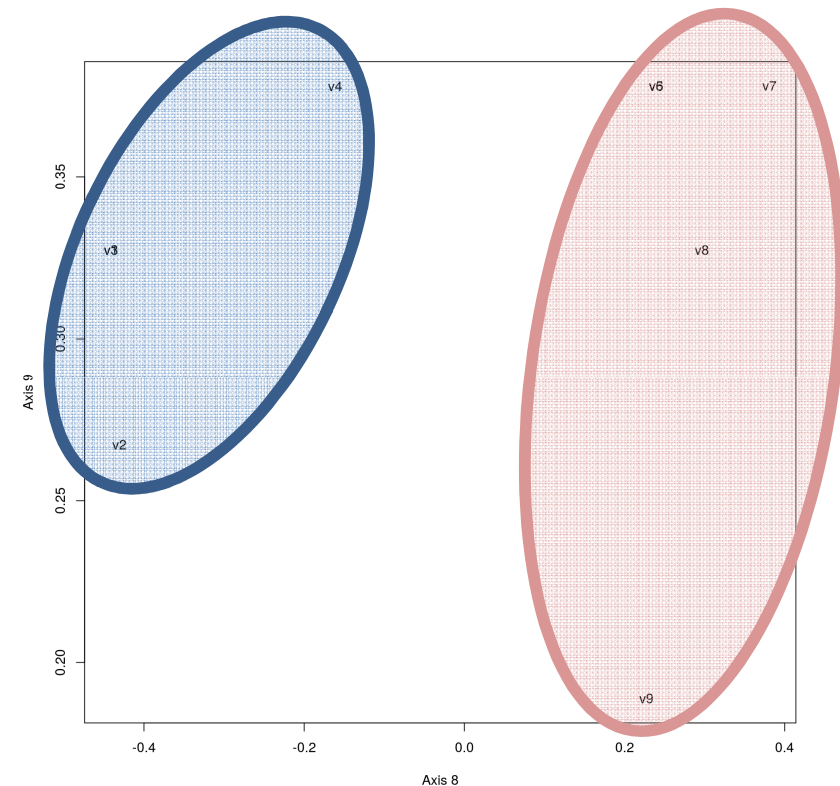
1. Create  $L(G)$
2. Compute  $(\lambda_1, \vec{q}_1)$  eigenpair of  $L(G)$
3. Choose

$$x(i) \leftarrow \text{sign}(\vec{q}_1(i))$$

Spectral graph representation using  $\vec{q}_i$  as coordinates



Laplacian



normalized Laplacian