Recorded at time: 1539701296.876 base_footprint world Broadcaster: /robot_state_publisher_arm Broadcaster: /vrpn_client_node Average rate: 10000.000 Hz Average rate: 120.290 Hz Most recent transform: 1539701296.867 (0.009 sec old) Most recent transform: 0.000 (1539701296.876 sec old) Buffer length: 4.980 sec Buffer length: 0.000 sec base_link omnigrasper Broadcaster: /robot_state_publisher_arm Average rate: 10000.000 Hz Most recent transform: 0.000 (1539701296.876 sec old) Buffer length: 0.000 sec plate_link Broadcaster: /robot_state_publisher_arm Average rate: 10000.000 Hz Most recent transform: 0.000 (1539701296.876 sec old) Buffer length: 0.000 sec arm_base Broadcaster: /robot_state_publisher_arm Average rate: 10000.000 Hz Most recent transform: 0.000 (1539701296.876 sec old) Buffer length: 0.000 sec arm_0 Broadcaster: /robot_state_publisher_arm Average rate: 30.212 Hz Most recent transform: 1539701296.866 (0.010 sec old) Buffer length: 4.965 sec arm_1 Broadcaster: /robot_state_publisher_arm Average rate: 30.212 Hz Most recent transform: 1539701296.866 (0.010 sec old) Buffer length: 4.965 sec arm_2 Broadcaster: /robot_state_publisher_arm Broadcaster: /robot_state_publisher_arm Average rate: 10000.000 Hz Average rate: 30.212 Hz Most recent transform: 0.000 (1539701296.876 sec old) Most recent transform: 1539701296.866 (0.010 sec old) Buffer length: 4.965 sec Buffer length: 0.000 sec arm_3 arm_2_sub Broadcaster: /robot_state_publisher_arm Broadcaster: /robot_state_publisher_arm Average rate: 30.212 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (1539701296.876 sec old) Most recent transform: 1539701296.866 (0.010 sec old) Buffer length: 4.965 sec Buffer length: 0.000 sec arm_3_sub arm_4 Broadcaster: /robot_state_publisher_arm Average rate: 30.212 Hz Most recent transform: 1539701296.866 (0.010 sec old) Buffer length: 4.965 sec arm_5 Broadcaster: /robot_state_publisher_arm Average rate: 10000.000 Hz Most recent transform: 0.000 (1539701296.876 sec old) Buffer length: 0.000 sec arm_link Broadcaster: /robot_state_publisher_arm Average rate: 10000.000 Hz Most recent transform: 0.000 (1539701296.876 sec old) Buffer length: 0.000 sec versaball_link

view_frames Result