

Research Project (IT 4010) 4th year

Research Logbook

TeaBot

Tea Plantation Preservation Using an Intelligent Robot

2023-044

IT20011970

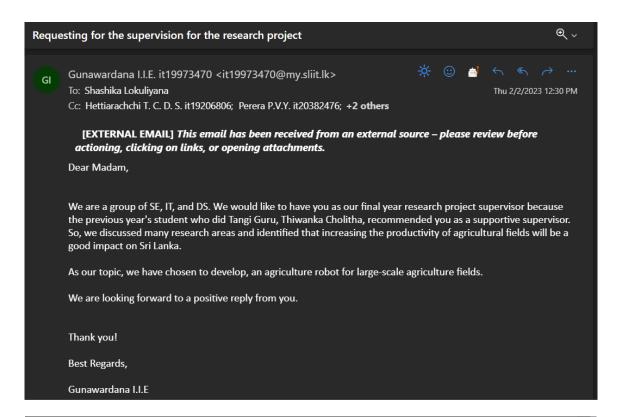
Bamunusinghe G.P.

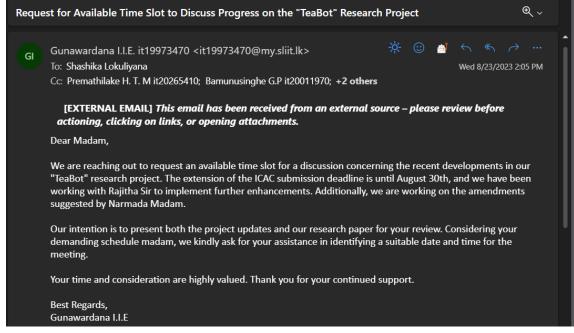
In partial fulfillment of the requirements for the Bachelor of Science Special Honors Degree in Software Engineering 30.10.2023

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- 1 Supervisor, Co-Supervisor, External Supervisor Meetings, Emails, andMessages
- 1.1 Meetings with Supervisor and co-supervisor





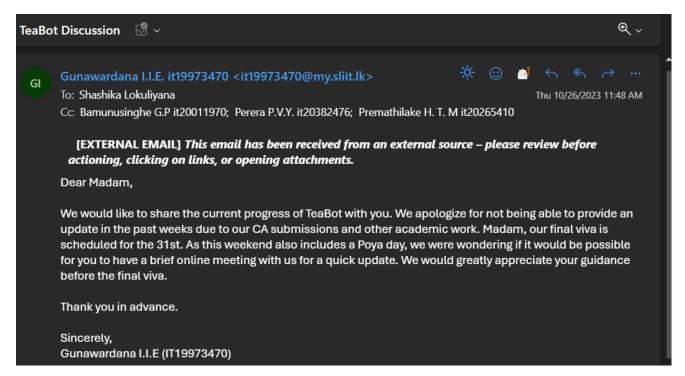
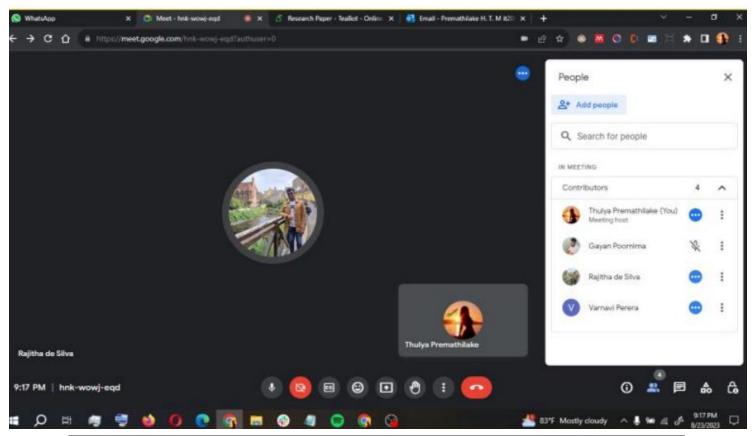


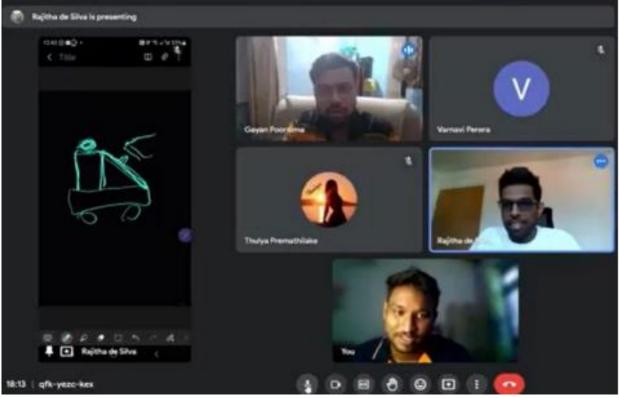
Figure 1.1.1: NBQSA Meeting

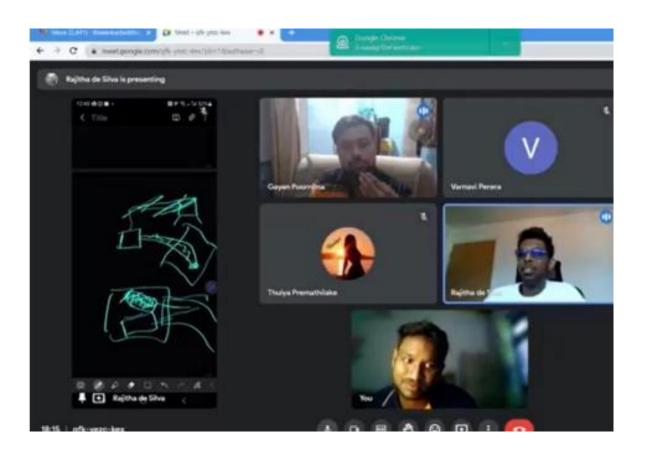
• The emails send to our supervisor and co-supervisor requesting time slots for meetings are represented in this section.

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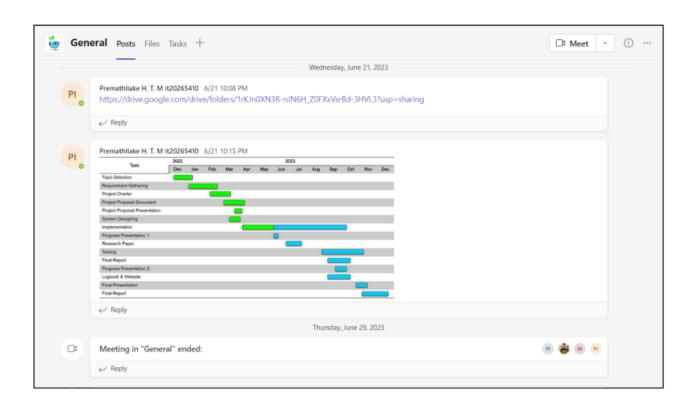
1.2 Meetings with External Supervisor

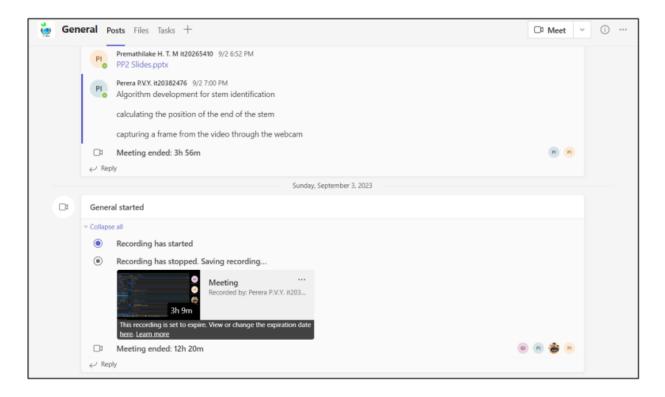




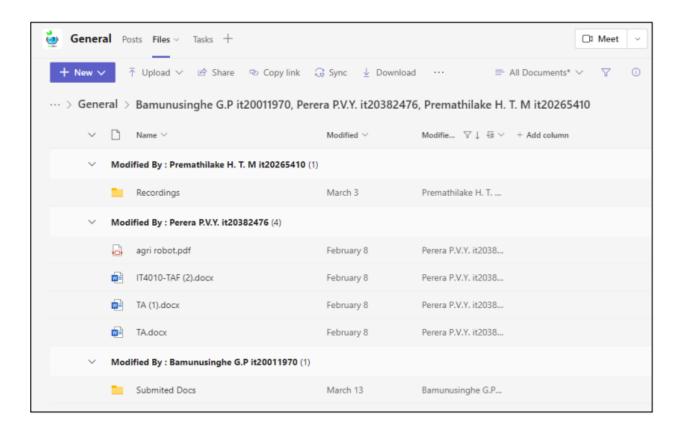


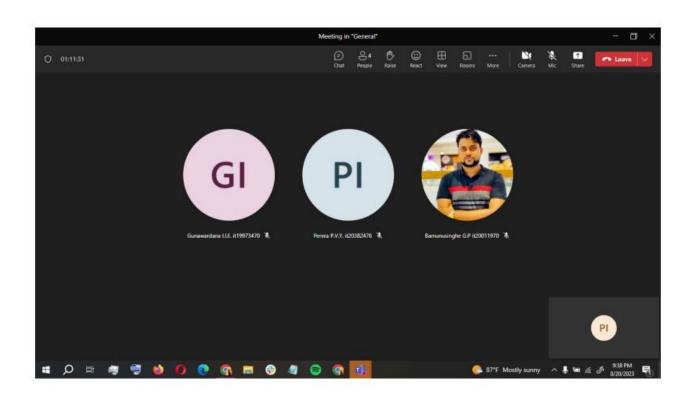
1.3 Meetings with the team

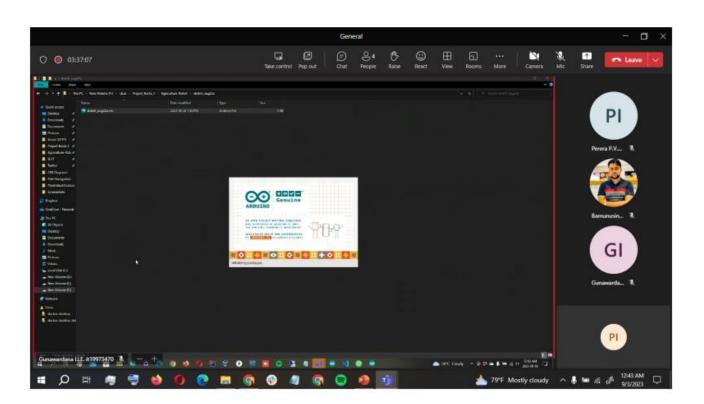






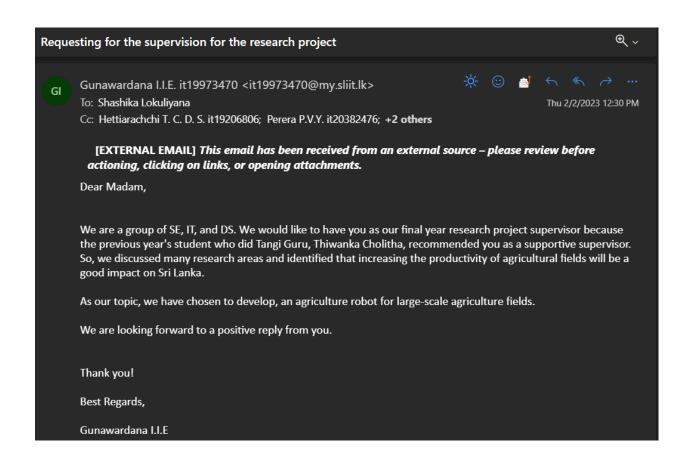


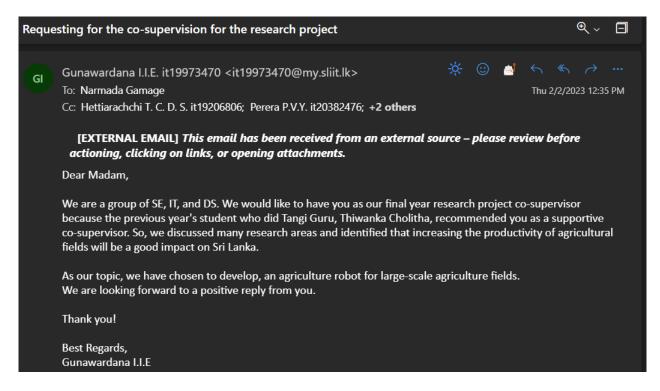


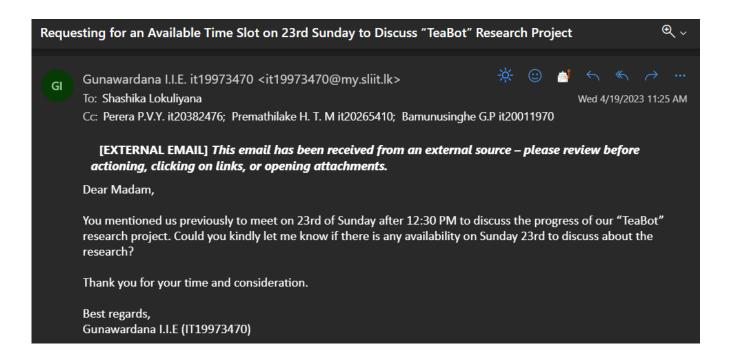


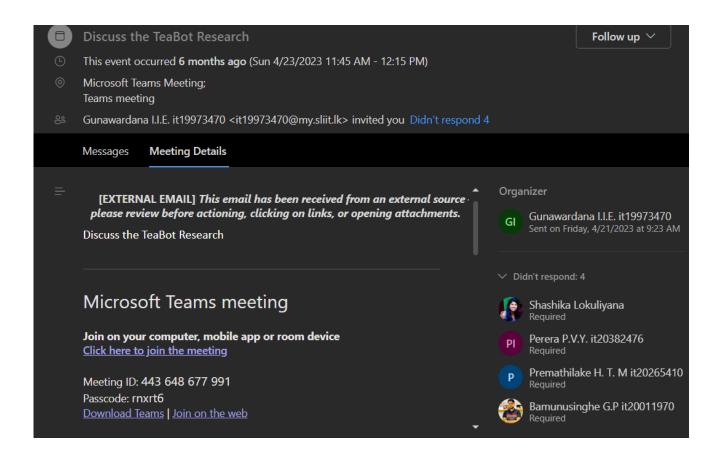


1.4 Emails to the Supervisor

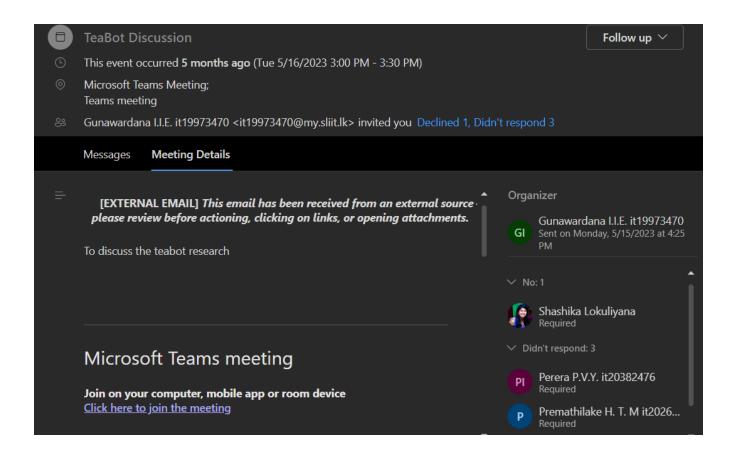


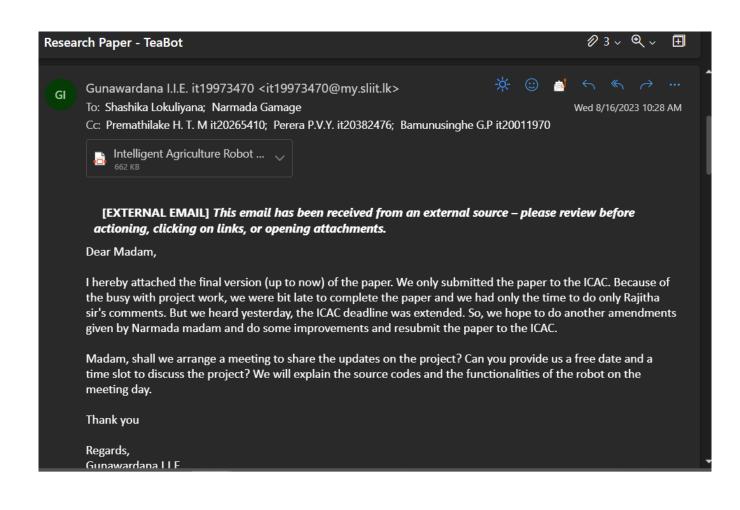












Request for Available Time Slot to Discuss Progress on the "TeaBot" Research Project





Gunawardana I.I.E. it19973470 <it19973470@my.sliit.lk>









To: Shashika Lokuliyana

Cc: Premathilake H. T. M it20265410; Bamunusinghe G.P it20011970; +2 others

[EXTERNAL EMAIL] This email has been received from an external source - please review before actioning, clicking on links, or opening attachments.

Dear Madam,

We are reaching out to request an available time slot for a discussion concerning the recent developments in our "TeaBot" research project. The extension of the ICAC submission deadline is until August 30th, and we have been working with Rajitha Sir to implement further enhancements. Additionally, we are working on the amendments suggested by Narmada Madam.

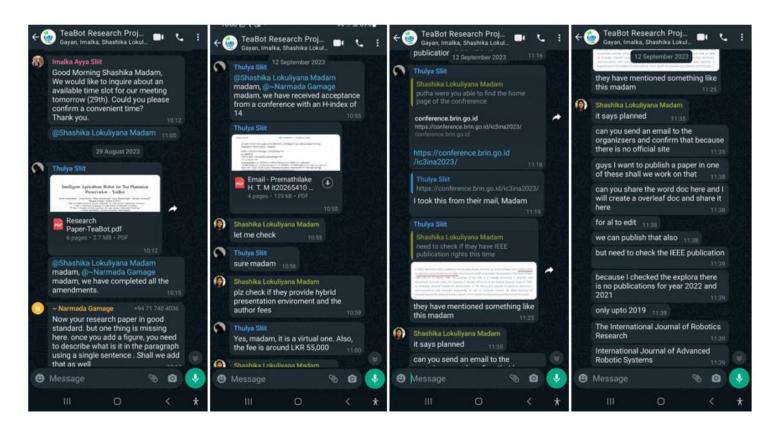
Our intention is to present both the project updates and our research paper for your review. Considering your demanding schedule madam, we kindly ask for your assistance in identifying a suitable date and time for the meeting.

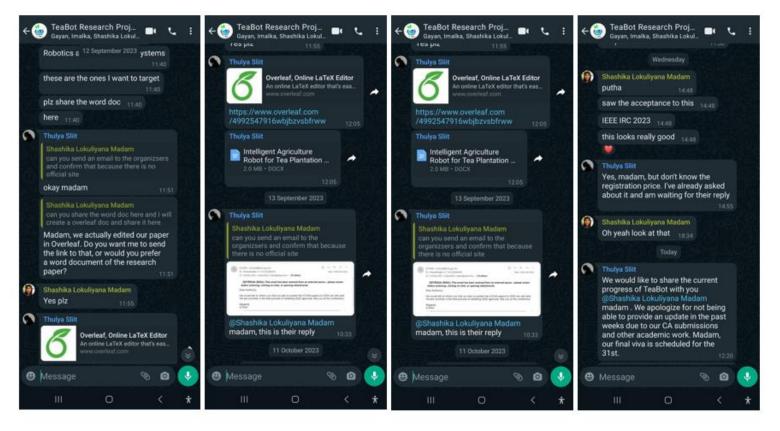
Your time and consideration are highly valued. Thank you for your continued support.

Best Regards, Gunawardana I.I.E

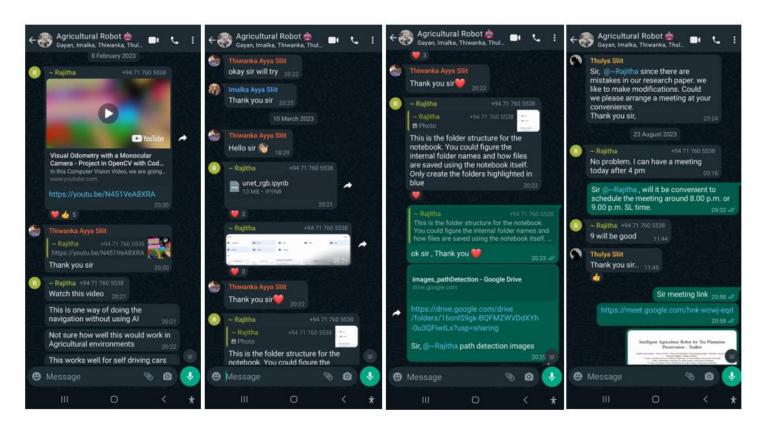
1.5 Messages

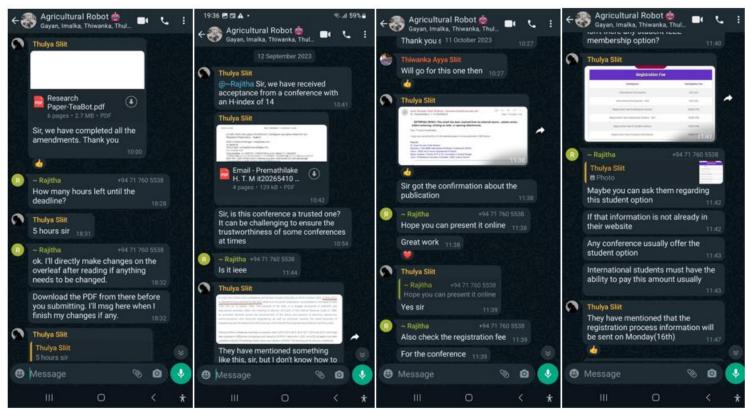
1.5.1 Messages with the supervisor



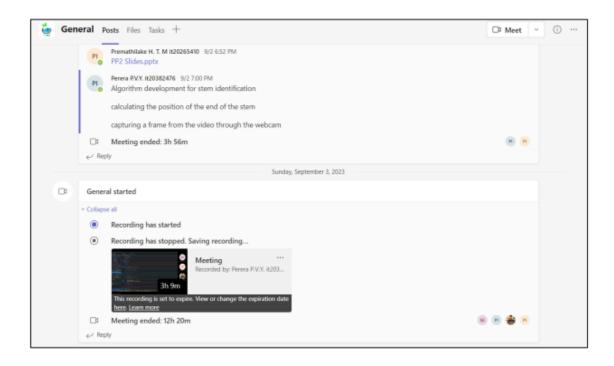


1.5.2 Messages with the External Supervisor





1.5.3 Messages in the official TeaBot Group





2 Individual Project Logs

2.1 MS Planner

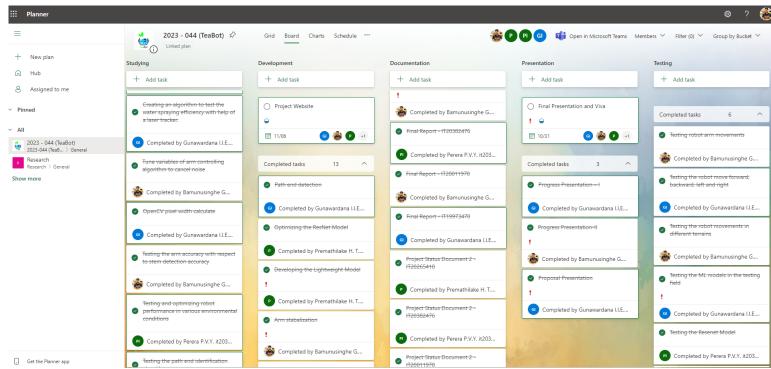


Figure 1: MS planner tasks

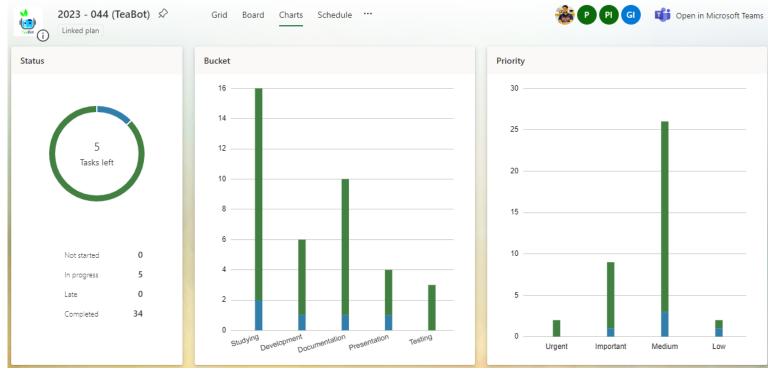
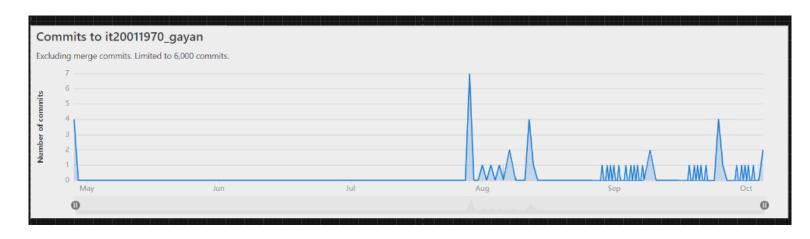


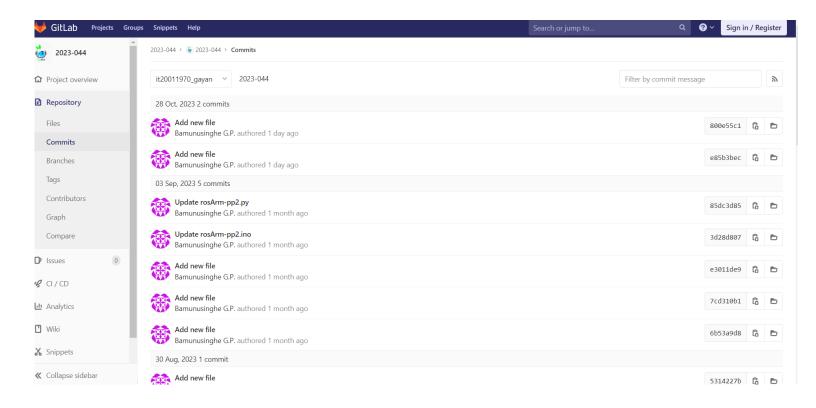
Figure 2: Chart View of Tasks



Figure 3: Completed Tasks on Teams Charts

2.2 Git Lab





3 Monthly Progress

3.1 2021 November 1st to 30th

• Finding different research topics and started with the 1st day of November because the topic submission due on 10th of February, and we had our first Research Project Lecture on the 10th of November 2022. The topics were mind mapped with the components that we can do. In the meantime, we tried to find a supervisor, co-supervisor, and external supervisor. This month was utilized to have discussions and select a good topic. All the topics were discussed one by one with the supervisors and the components. After selecting the topic, the scope of the research team finalized to continue with the selected topic. Conducted a SWOT analysis to find what are the lacking parts to improve as a team.

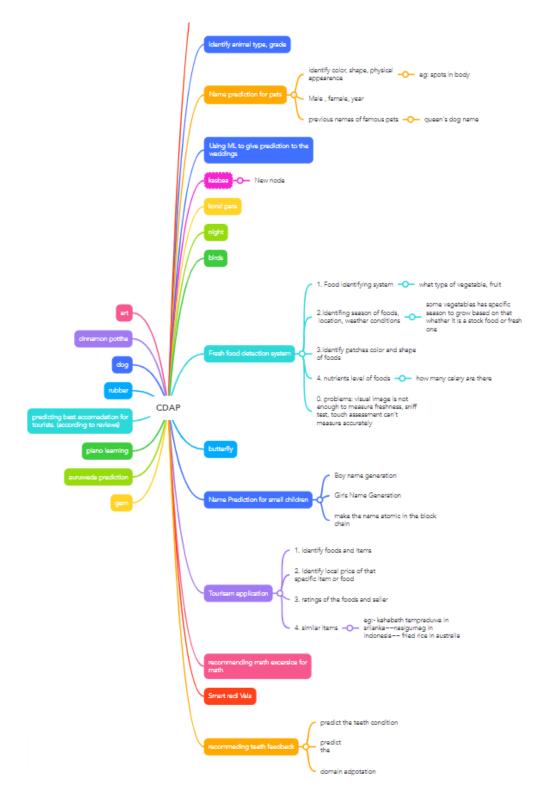


Figure 4:Mind Maps for Topic Selection

3.2 2022 January 1st to 31st

• The topic evaluation submission was due on the 12th of December. So, the preparation of the topic evaluation started on the 1st of December. Until the 12th of December, the topic evaluation form was well fine-tuned. The document was submitted on the 12th of December and waited for the topic evaluation results. The results were released on the 28th of December. After viewing the results project charter creation will be started on the 1st of January.



IT4010 - Research Project - 2023 Topic Assessment Form

Project ID:

TMP-23-044

 Topic 	(12 words max)
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"TeaBot" - Tea plantation preservation using an intelligent robot.

2. Research group the project belongs to

Autonomous Intelligent Machines and Systems (AIMS)

3. Research area the project belongs to

Robotics (R)

4. If a continuation of a previous project:

Project ID	
Year	

5. Team member details

Student Name	Student ID	Specialization
Leader: Gunawardana I.I.E	IT19973470	SE
Member 2: Bamunusinghe G.P	IT20011970	SE
Member 3: Premathilake H.T.M	IT20265410	ІТ
Member 4: Perera P.V.Y	IT20382476	DS

After the topic was selected with minor corrections the project charter and the cover sheet
were created to be submitted on the 30th of January. After the project charter and the
coversheetsubmission, the proposal draft creation started because the due date is on the 24th
of March.

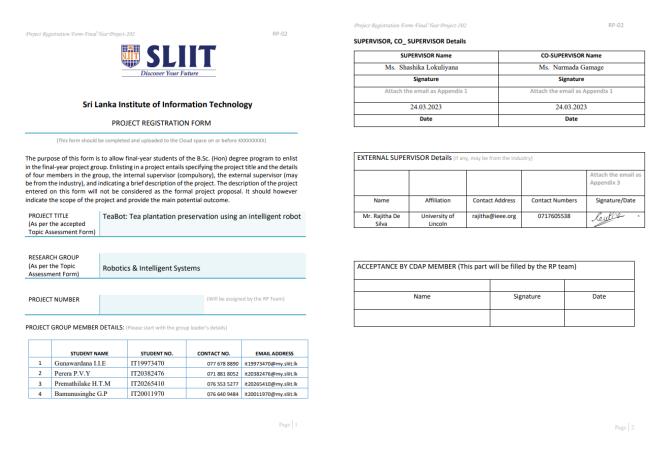


Figure 3.2.2: Project Cover Sheet

• After the proposal draft document slides were created to do the proposal presentations because the presentations were on the 27th of March.

3.3 February 1st to 28th

- The suggested solution is weighed against various robot arm designs that might be required for a robot.
- In this month we got ready for our proposal presentation which will be held on 27th March.

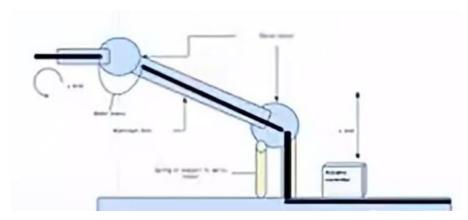
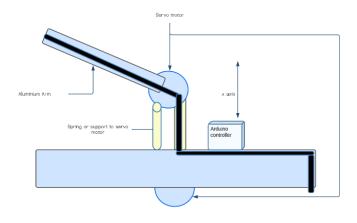


Figure 5:First prototype design







Figure~7: Final~prototype~design

3.4 2022 March 1st - 31st

- The proposal presentation was held on the 27th of March 2023, and the proposal report was prepared during this phrase.
- The panel approval was received for the project.
- The report was submitted.
- In the later part of the month implementation of the project is carried out.

3.5 2022 April 1st to 30th

- After getting the panel approval the development was started.
- We visited several tea estates and analyzed the tea plantations and gap between two tea paths.
- The first cardboard robot arm prototype has been built and tested for functionality based on measurements of the robot arm.

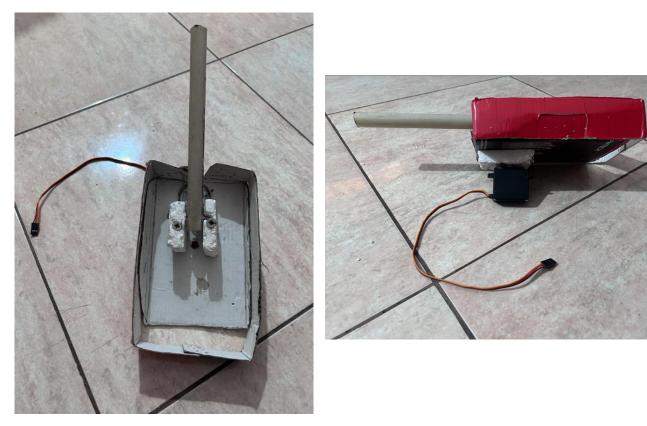


Figure 8: Cardboard prototype

Basic Functionalities of arm rotation, weight of the arm, and Arduino code testing has started. This
was created to check the basic functionalities.

3.6 2022 May 1st to 31st

- The mechanical design for this presentation needs to be created, and we have our PP1 presentation on the 22nd.
- Previously, cardboard boxes were used for prototyping. It is difficult to test those with cardboard boxes in terms of adjacency. As a result, a mechanical design was made in order to prototype the arm and complete the design of its components.



Figure 9: Mechanical design side view

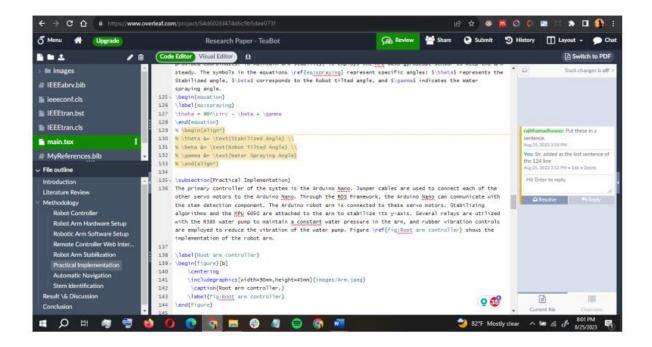


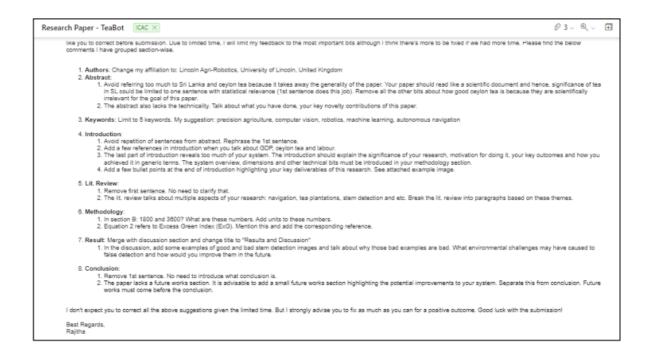
Figure 10: Mechanical design back view

Figure 11: Mechanical interior view

3.7 2022 June 1st to 30st

- After the PP1 presentation the comments were viewed necessary adjustments were made
- The draft of the research paper was created and submitted.
- Designed robot arm for the integration.





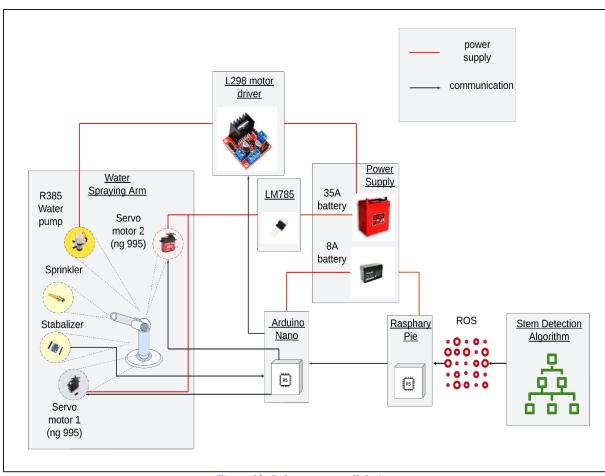


Figure 12: Robot arm overall design

3.8 2022 July 1st to 31th

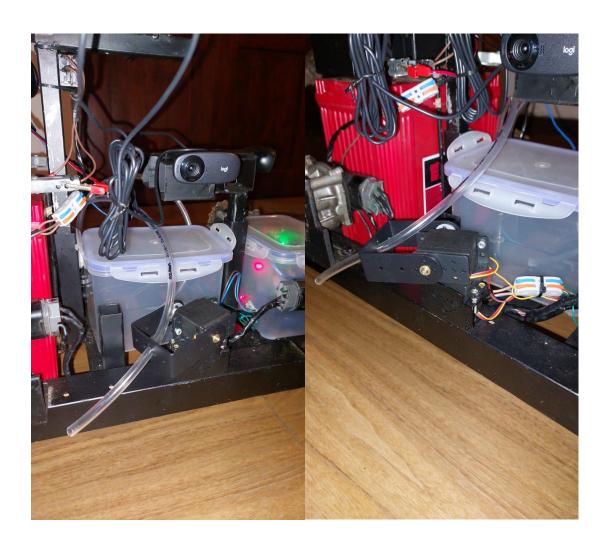
- Final report draft submission was held in 10th of September, and the PP2 was scheduled to 4th of September.
- During this month we prepared the final reports
- Integrated the project and tested it in the real environment.



Figure 13: Robot arm field testing

3.9 2022 August 1st 31st

- As a result of delays in both plant identification and plant watering, the stem detection algorithm for the robot arm is modified from a machine learning model to a computer vision algorithm during integration.
- The robot arm was modified, and the integration was once more adjusted.
- Watering speed was optimized.
- Reduce the length of the arm.

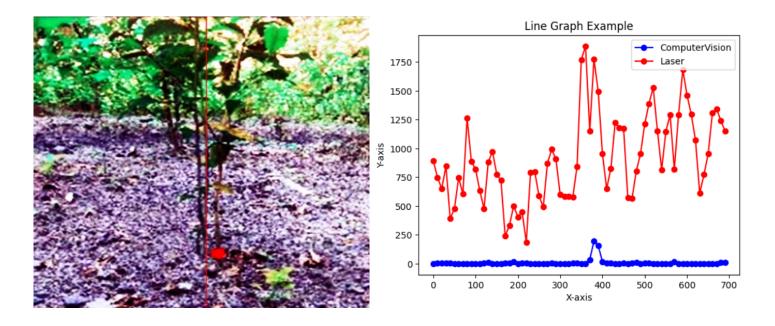


3.10 2022 September 1st to 31st

- The robot arm's pp2 integration is complete, and it operates flawlessly with computer vision coordinates and has a quick watering speed.
- 90% of the overall arm is completed and optimized.
- We prepared and submitted a Status Document-2 on the same date as the PP2 viva. This document provided a succinct status report on the project's progress, highlighting our accomplishments, milestones attained, and any modifications made in response to input from the PP2 viva.

3.11 2022 October 1st to 31st

- Laser module of the arm is installed.
- User color separation of the laser pointer to identify the coordinates of the arm.
- Robot arm optimization is completed for the final presentation.



3.12 2022 November 1st 15th

- Our research paper was completed and published.
- The final report is proofread and will be submitted on the 27th.
- Research website submission to CDAP.